- SV-iS7 is the official name for the iS7 series inverters.
- This operation manual is intended for users with basic knowledge of electricity and electric devices.
- Keep this manual near the product for future reference whenever setting change, maintenance or service is required.
- Ensure that the field operators and service engineers can easily access this manual.
- For detailed information about the optional extension boards, including the specifications and the
 requirements for installation and operation, refer to the instruction manuals that are supplied with the
 products.

Safety Information

Read and follow all safety instructions in this manual precisely to avoid unsafe operating conditions, property damage, personal injury, or death.

Safety symbols in this manual



Indicates an imminently hazardous situation which, if not avoided, will result in severe injury or death.

⚠ Warning

Indicates a potentially hazardous situation which, if not avoided, could result in injury or death.

① Caution

Indicates a potentially hazardous situation which, if not avoided, could result in minor injury or property damage.

Safety information

▲ Danger

- Do not open the cover of the equipment while it is on or operating. Likewise, do not operate the
 inverter while the cover is open. Exposure of the high voltage terminals or the charging area to the
 external environment may result in an electric shock. Do not remove any covers or touch the internal
 circuit boards (PCBs) or electrical contacts on the product when the power is on or during operation.
 Doing so may result in serious injury, death, or serious property damage.
- Do not open the cover of the equipment, even when the power supply to the inverter has been turned off, unless it is necessary for maintenance or regular inspection. Opening the cover may result in an electric shock even when the power supply is off.
- The equipment may hold a charge long after the power supply has been turned off. Use a multi-meter
 to make sure that the remaining voltage is below 30 VDC before working on the inverter, motor, or
 motor cable.

- This equipment must be grounded for safe and proper operation.
- Do not supply power to a faulty inverter. If you find that the inverter is faulty, disconnect the power supply and have the inverter professionally repaired.
- The inverter becomes hot during operation. Avoid touching the inverter until it has cooled to avoid burns.
- Do not allow foreign objects, such as screws, metal chips, debris, water, or oil, to get inside the inverter. Allowing foreign objects inside the inverter may cause the inverter to malfunction or result in a fire.
- Do not operate the inverter with wet hands. Doing so may result in electric shock.

① Caution

- Do not modify the interior workings of the inverter. Doing so will void the warranty.
- Do not use cables with damages or cracks on the protective insulation when wiring the inverter. Damaged insulation may cause misoperation, an electric shock or a fire.
- Do not place heavy objects on top of electric cables. Doing so may damage the cable and result in an
 electric shock.

Note

[English]

The maximum allowed prospective short-circuit current at the input power connection is defined in IEC 60439-1 as 100 kA. The drive is suitable for use in a circuit capable of delivering not more than 100 kA RMS at the drive's maximum rated voltage, depending on the selected MCCB. RMS symmetrical amperes for recommended MCCB are the following table.

[French]

Le courant maximum de court-circuit présumé autorisé au connecteur d'alimentation électrique est défini dans la norme IEC 60439-1 comme égal à 100 kA. L'entraînement convient pour une utilisation dans un circuit capable de délivrer pas plus de 100 kA RMS à la tension nominale maximale de l'entraînement. Le tableau suivant indique le MCCB recommandé selon le courant RMS symétrique en ampères.

Working Voltage	UTE100 (E/N)	UTS150 (N/H/L)	UTS250 (N/H/L)		UTS4 (N/H/L		
240V(50/60Hz)	50/65kA	65/100/150kA	65/100/150)kA	65/100	0/150kA	
480V(50/60Hz)	25/35kA	35/65/100kA	35/65/100k	00kA 35/65/		100kA	
Working Voltage	ABS33c	ABS53c	ABS63c	ABS ²	103c	ABS203c	ABS403c
240V(50/60Hz)	30kA	35kA	35kA	85kA		85kA	75kA
480V(50/60Hz)	7.5kA	10kA	10kA	26kA		26kA	35kA

About This Manual

This operation manual describes the specifications of the SV-iS7 series inverters and provides detailed information required for the installation, operation, and maintenance of the products.

This operation manual is intended for users with a basic knowledge of electricity and electric devices. Read this manual carefully to install, operate, and maintain the products safely and properly.

The following table lists the chapters in this manual, and brief descriptions of the information provided:

Chapter	Chapter name	Information provided
1	About the Product	Basic information about the product that is required for safe installation and operation
2	Technical Specifications	Product ratings and I/O types
3	Installing the Inverter	Information required for the installation of the product, including considerations for installation locations and operation environment
4	Connecting the Cables	Information required for connecting power supply and signal cables
5	Peripheral Devices	Information about the peripheral devices that can be connected to the input and output terminals of the product
6	Using the Keypad	Information about the keypad display and the operation keys on the keypad
7	Basic Functions	Information about configuring the inverter to run the basic functions
8	Learning Advanced Features	Information about configuring the inverter for advanced system application
9	Using Monitor Functions	Information about monitoring the inverter for operation statuses and trip conditions
10	Using Protection Features	Information about the functions to protect the motor and the inverter
11	Communication Function	Specifications for the RS-485 network communication between inverters and other devices
12	Troubleshooting and Maintenance	Information about identifying the failures and anomalies during operation and resolving them
13	Table of Functions	Table of all functions with brief descriptions
14	Functional Safety	Information about the products compliant with the safety standards, and the safety functions
15	Classified Product	Information about the products approved for marine application
16	Using a Single Phase Power Source	Considerations for operating the inverter with a single phase power source

Table of Contents

1	Abou	ıt the Product	.1
•	1.1	Preparing for Installation and Operation	.1 .3 .3
		1.1.5 Connecting the Cables	
	1.2	Part Names	
		12.1 Interior and Exterior View (IP 21 Model Types Less than 22 kW [200 V] / Less than 75 kW [400 V])	,
		122 Interior and Exterior View (IP 54 Model Types Less than 22 kW [200/400 V]))
		1.2.3 Interior and Exterior View (Model Types 30 kW and up [200 V] / 90 kW and up [400 V])	.6
2	Tech	nical Specifications	7
	2.1	Input and Output Specifications 200 V Class (0.75–22 kW)	7
	2.2	Input and Output Specifications 200 V Class (30–75 kW)	
	2.3	Input and Output Specifications 400 V Class (0.75–22 kW)	
	2.4	Input and Output Specifications 400 V Class (30–160 kW)1	
	2.5	Input and Output Specifications 400 V Class (185–375 kW)	
	2.6	Product Specification Details1	
		2.6.1 Control	3
		2.62 Operation1	
		2.6.3 Protection Function	
_	14	2.6.4 Structure and Operating Environment Control	
3	insta	lling the Inverter1	1
	3.1	Installation Considerations1	
	3.2	Selecting and Preparing a Site for Installation1	
	3.3	Exterior and Dimensions (UL Enclosed Type 1, IP21 Type)2	
	3.4	Exterior and Dimensions (UL Enclosed Type 12, IP54 Type)	6
	3.5	Frame Dimensions and Weight (UL Enclosed Type 1, IP 21 Type)4	-0
	3.6	Frame Dimensions and Weight (UL Enclosed Type 12, IP54 Type)4	-2
	3.7	Installation Procedures for UL Enclosed Type12 and IP54 Type Products.4	
		3.7.1 Disassembling the Keypad Cover and Keypad4	
		3.72 Disassembling the IP54 Front Cover	
		3.7.3 Mounting the Inverter	
		3.7.4 Connecting the Power Cables4 3.7.5 Reassembling the IP54 Front Cover and the Keypad4	
4	Conn	necting the Cables4 Profit Cover and the Neypad4	
-	4.1	Removing the Front Cover for Cable Connection4	
	4 . I	4.1.1 IP 21 Type Products	
		4.1.1 IF 21 Type F10uucis4	J

	4.1.2	IP 54 Type Products	51
	4.1.3	90–375 kW, 400 V and 30–75 kW, 200 V Products	52
4.2	Acti	vating and Deactivating the Built-in EMC Filter	53
	4.2.1	Up to 7.5 kW Inverters	
	4.2.2	11–22 kW Inverters	
4.3	Pred	cautions for Wiring the Inverter	57
4.4	Gro	und Connection	58
4.5	Terr	ninal Wiring Diagram	59
	4.5.1	Up to 7.5 kW Inverters	59
	4.5.2	11–22 kW Inverters	59
	4.5.3	30–75 kW Inverters	
	4.5.4	90–160 kW Inverters	
	4.5.5	185–220 kW Inverters	
	4.5.6	280–375 kW Inverters	
4.6		necting Cables to the Power Terminal Block	
	4.6.1	0.75–22 kW (200 V/400 V)	
	4.6.2	30–75 kW (200 V/400 V)	
	4.6.3	90–160 kW (400 V)	
	4.6.4	185–220 kW (400 V)	
17	4.6.5	280–375 kW (200 V/400 V)	
4.7	•	cifications of the Power Terminal Block and Exterior Fuse	
	4.7.1 4.7.2	Cable Length between the Inverter and the Motor	
4.8		Protective Measures for the Inverter and the Motortrol Terminal Wiring for iSZ Inverters Peted for Up To 22 IAW	
4.0	4.8.1	trol Terminal Wiring for iS7 Inverters Rated for Up To 22 kW NPN Mode (Sink)	
	4.8.1 4.8.2	PNP Mode (Surce)	
	4.8.3	0.75–22 kW (Basic I/O)	
4.9		trol Terminal Wiring for iS7 Inverters Rated for 30 kW or More	
4.10		ninal Inputs for Inverter Operation	
4.11		le Specifications for Control Block Wiring	
4.12		trol Terminal Wiring for iS7 Extension I/O (Optional)	
4.12		· · · /	
_		ninal Inputs for Inverter Operation	
4.14		le Specifications for Control Block Wiring	
4.15		ing the Built-in Surge Filter	
4.16		vating or Deactivating the Surge Filter	
	4.16.1	iS7 30–75KW (400 V) Inverters	
4.47	4.16.2	iS7 90–375 kW (400V) Inverters	
4.17		t-Installation Checklist	
4.18		Run	
	4.18.1	Entering Easy Start Mode	
	4.18.2	Setting the Basic Parameters in Easy Start Mode	
Dente	4.18.3	Checking the Inverter Operation	
•		evices	
5.1	Wiri	ng Switch, Electronic Contactor, and Reactor Specifications	87

5

		5.1.1	Wiring Switch, Short Circuit Switch, and Electronic Contactor	
		5.1.2	Reactors	89
		5.1.3	Dynamic Braking Unit (DBU) and Resistor	
		5.1.4	DB Unit Dimensions	
		5.1.5	Indicators on the DB unit	
		5.1.6	DB Resistors	
		5.1.7	DB Resistor Dimensions	
		5.1.8	Keypad Extension Cable for Remote Control (Optional)	
6	Using	the Ke	eypad	109
	6.1	Abo	out the Keypad	109
		6.1.1	Dimensions	109
		6.1.2	Key Functions	
		6.1.3	Display Items	
		6.1.4	Display Item List	
	6.2	Mer	nu Items	
		6.2.1	Parameter Mode	
		6.2.2	User & Macro Mode	
	6.3	Nav	rigating Modes	
	0.0	6.3.1	Mode Navigation at the Factory Default	
		6.3.2	Mode Navigation with User/Macro Mode and Trip Mode	
	6.4		rigating Modes and Parameters	
	0	6.4.1	Group Navigation in Parameter mode	
		6.4.2	Group Shift in User & Macro Mode	
	6.5		rigating through Codes (Function Items)	
	0.0	6.5.1	Code Navigation in Monitor Mode	
		6.5.2	Code Navigation (function items) in Other Modes and Groups	
		6.5.3	Code Navigation Using Jump Code	
	6.6		ting Parameters	
	0.0	6.6.1	Parameter Settings in Monitor Mode	
		6.6.2	Parameter Settings in Other Modes and Groups	
	6.7		nitoring Operating Status	
	0.1	6.7.1	Using Monitor Mode	
		6.7.1	Monitoring Items	
		6.7.3	Using the Status Display	
	6.8		nitoring Faults	
	0.0		y	
		6.8.1 6.8.2	Faults during Inverter Operation Multiple Faults at a Time during Inverter Operation	
		6.8.3	Saving and Monitoring the Fault Trip History	
	6.9		alizing Parameters	
7				
7	Basic	Functi	ions	137
	7.1	Sett	ting Frequency References	
		7.1.1	Keypad as the Source (KeyPad-1 setting)	138
		7.1.2	Keypad as the Source (KeyPad-2 setting)	138
		7.1.3	V1 Terminal as the Source	138
		7.1.4	Setting a Frequency Reference Using an I/O Expansion Module	

		(Terminal V2/I2)	148
	7.1.5	Setting a Frequency with Pulse Input (with an optional encoder mod	ule)
	7.1.6	Setting a Frequency Reference via RS-485 Communication	150 152
7.2		juency Hold by Analog Input	
7.3		nging the Displayed Units (Hz↔Rpm)	
7.4		ing Multi-Step Frequency	
7. 5		nmand Source Configuration	
1.5	7.5.1	The Keypad as a Command Input Device	
	7.5.1	The Terminal Block as a Command Input Device (Fwd/Rev run commands)	
	7.5.3	The Terminal Block as a Command Input Device (Run and Rotation Direction Commands)	
	7.5.4	RS-485 Communication as a Command Input Device	160
7.6	Loca	al/Remote Mode Switching	160
7.7	Forv	vard or Reverse Run Prevention	162
7.8	Pow	er-on Run	163
7.9	Res	et and Restart	164
7.10	Setti	ng Acceleration and Deceleration Times	165
	7.10.1	Acc/Dec Time Based on Maximum Frequency	
	7.10.2	Acc/Dec Time Based on Operation Frequency	167
	7.10.3	Multi-Step Acc/Dec Time Configuration	
	7.10.4	Configuring Acc/Dec Time Switch Frequency	169
7.11		Dec Pattern Configuration	
7.12	•	pping the Acc/Dec Operation	
7.13		(Voltage/Frequency) Control	
	7.13.1	Linear V/F Pattern Operation	
	7.13.2	Square Reduction V/F Pattern Operation	
- 44	7.13.3	User V/F Pattern Operation	
7.14		ue Boost	
	7.14.1		1/8
	7.14.2 7.14.3	Auto Torque Boost	
7.15	_	out Voltage Setting	
7.13 7.16	-	t Mode Setting	
7.10	7.16.1	· · · · · · · · · · · · · · · · · · ·	
	7.16.1 7.16.2	Acceleration StartStart After DC Braking	
7.17		Mode Setting	
7.17	7.17.1	Deceleration Stop	
	7.17.1	Stop after DC Braking	
	7.17.3	Free Run Stop	
	7.17.4	Power Braking	
7.18		juency Limit	
	7.18.1	Frequency Limit Using Maximum Frequency and Start Frequency	
	7.18.2	Frequency Limit Using Upper and Lower Limit Frequency Values	
		• • •	

		7.18.3 Frequency Jump	189
	7.19	2 nd Operation Mode Setting	
	7.20	Multi-function Input Terminal Control	192
	7.21	Expanded I/O Control with an Optional I/O Expansion Module	193
8	Learn	ing Advanced Features	194
	8.1	Operating with Auxiliary References	194
	8.2	Jog Operation	199
		82.1 Jog Operation 1-Forward Jog via Multi-function Terminal	199
		822 Jog Operation 2-Forward/Reverse Jog via Multi-function Terminal	
		823 Jog Operation via Keypad Input	
	8.3	Up/down Operation	
	8.4	3-Wire Operation	
	8.5	Safe Operation Mode	
	8.6	Dwell Operation	
	8.7	Slip Compensation Operation	
	8.8	PID Control	
		8.8.1 PID Basic Operation	
		8.8.2 Pre-PID Operation	
		8.8.3 PID Sleep Mode	
	8.9	8.8.4 PID Switching (PID Openloop)	
	8.10	V/F Operation Using Speed Sensor	
	8.11	Sensorless-1 Vector Control	
	8.12	Sensorless-1 Vector Control	
	8.13	Vector Control Mode Operation	
	8.14	Torque Control	
	8.15	Droop Control	
	8.16	Speed / Torque Control Switching	
	8.17	Kinetic Energy Buffering	
	8.18	Energy Saving Operation	
	0.10	8.18.1 Manual Energy Saving Operation	
		8.18.2 Automatic Energy Saving Operation	
	8.19	Speed Search Operation	
	8.20	Auto Restart Settings	
	8.21	Operational Noise Settings (Carrier Frequency Settings)	
	8.22	2nd Motor Operation	
	8.23	Supply Power Transition	
	8.24	Cooling Fan Control	
	8.25	Input Power Frequency Settings	
	8.26	Input Power Voltage Settings	
	8.27	Read, Write, and Save Parameters	
	8.28	Parameter Initialization	

	8.29	Para	meter viewing and Lock Options	258
		8.29.1	Parameter View Lock	258
		8.29.2	Parameter Lock	259
		8.29.3	Changed Parameter Display	260
	8.30	User	Group	260
	8.31	Macr	o Selection	262
	8.32	Easy	Start	263
	8.33	Conf	ig (CNF) Mode	264
	8.34		r Settings	
	8.35		erse Operation	
	8.36		e Control	
	8.37		-function Output On/Off Control	
	8.38		C function	
	0.00	8.38.1	Basic MMC Operation	
		8.38.2	Auto Change Operation	
		8.38.3	Interlock Operation	
		8.38.4	Bypass Operation (Regular Bypass)	
	8.39	Pres	s Regeneration Prevention (To evade control operation in the	status of
		regei	neration during press)	278
	8.40	Anti-	Hunting Regulator	279
	8.41	Fire I	Mode	280
	8.42	Dyna	amic Braking (DB) Resistor Operation Reference Voltage	282
	8.43	kW/F	HP Unit Selection	282
9	Using	Monito	r Functions	284
	9.1	Moni	toring the Operating Status via the Keypad	284
	0.1	9.1.1	Selecting Monitor Mode Display	
		9.1.2	Displaying Output Power	
		9.1.3	Selecting Load Speed Display	
		9.1.4	Selecting Hz/Rpm Display	
		9.1.5	Selecting Status Display	
		9.1.6	Monitoring Output Frequency	
	9.2	Moni	toring Fault Status Using Keypad	
		9.2.1	Monitoring Current Fault Status	
		9.2.2	Monitoring Fault Trip History	290
	9.3	Anal	og output	291
		9.3.1	Voltage Output (0–10 V)	
		9.3.2	Current Output (4–20 mA)	293
		9.3.3	Voltage Output (-10-+10V) Using an I/O Expansion Module	296
		9.3.4	Current Output (4–20 mA/0–20 mA) Using an I/O Expansion M	
	9.4		y Output and Multi-function Output Terminal Settings	
	9.5		trip output using multi-function output terminals and relays	
	9.6	Outp	ut Terminal Delay Time and Terminal Types	
		9.6.1	Output Terminal Delay Time	
		9.6.2	Setting the Output Terminal Type	305

	9.7	Oper	ation Time Monitor	306
	9.8	Settir	ng the Keypad Language	307
10	Using	Protect	tion Features	308
	10.1	Moto	r Protection	308
		10.1.1	Electrothermal Motor Overheating Prevention (ETH)	
		10.1.2	Overload Early Warning and Trip	
		10.1.3	Stall Prevention and Flux Braking	
		10.1.4	Motor Overheat Sensor Input	315
	10.2	Inver	ter and Sequence Protection	316
		10.2.1	Open-phase Protection	
		10.2.2	External Trip Signal	
		10.2.3	Inverter Overload Protection (IOLT)	
		10.2.4	Keypad Command Loss	
		10.2.5	Speed Command Loss	
		10.2.6	Dynamic Braking (DB) Resistor Configuration	
		10.2.7	Underload Warning and Failure	324
		10.2.8	Overspeed Fault	
		10.2.9 10.2.10	Speed Deviation FaultSpeed Sensor (Encoder) Fault Detection	
		10.2.10		320 327
		-	Low Voltage Fault Trip	
			Output Block via the Multi-Function Terminal	
			Trip Status Reset	
			Operation Mode On Optional Expansion Module Fault Trip	
			No Motor Trip	
		10.2.17	Low Voltage Fault Trip 2 During Operation	330
	10.3	List c	of Faults and Warnings	331
11	Comm	nunicati	on Function	334
	11.1	Intro	duction	334
	11.2		ifications	
	11.3	•	munication System Configuration	
	11.4		•	
			C Settings	
	11.5		ng Operation Command and Frequency	
	11.6		mand Loss Protection	
	11.7		ng Virtual Multi-Function inputs	
	11.8		ng Parameters Defined by Communication	
	11.9		munication Frame Monitoring	
	11.10	Spec	ial communication Area Settings	341
	11.11	Para	meter Group for Periodical Data Transmission	342
	11.12	Para	meter Group for Transmission of Macro Group and User Group at	
			Mode	
	11.13	Com	munication Protocol	344
		11.13.1	LS INV 485 Protocol	344
		11.13.2	Modbus-RTU protocol	350

		11.13.3	iS7/iS5/iG5/iG5A Compatible Common Area Parameter	352
			Expansion Common Area Parameter	
12	Troub	leshoot	ing and Maintenance	369
	12.1	Prote	ection Functions	369
		12.1.1	Protection from Output Current and Input Voltage	
		12.1.2	Abnormal Circuit Conditions and External Signals	
		12.1.3	Keypad and Optional Expansion Modules	
	12.2		ning Messages	
	12.3		bleshooting Fault Trips	
	12.4	•	acing the Cooling Fan	
		12.4.1	Products Rated below 7.5 kW	
		12.4.2	Products Rated at 11-15 kW 200 V/400 V and 18.5-22 kW 400 V	
		12.4.3	Products Rated at more than 30 kW (200 V) / 90 kW (400 V), and	
	12.5	Daily	22 kW (200 V) / 30–75 kW (200/400 V) and Regular Inspection Lists	
13	_		tions	
IJ				
	13.1		meter Mode – DRV Group (→DRV)	
	13.2		meter Mode – Basic Function Group (→BAS)	
	13.3		meter Mode – Expansion Function Group (PAR→ADV)	
	13.4		meter Mode – Control Function Group (→CON)	
	13.5		meter Mode – Input Terminal Block Function Group (→IN)	
	13.6		meter Mode – Output Terminal Block Function Group (→OUT)	
	13.7		meter Mode – Communication Function Group (→COM)	
	13.8		meter Mode – Applied Function Group (→APP)	
	13.9		meter Mode – Option Module Function Group (→APO)	
	13.10		meter Mode – Protective Function Group (→PRT)	
	13.11	Para	meter Mode – 2nd Motor Function Group (→M2)	419
	13.12	Trip I	Mode (TRP Current (or Last-x))	420
	13.13	Conf	ig Mode (CNF)	420
	13.14		/Macro Mode – Draw Operation Function Group→MC1	
	13.15	User	/Macro mode – Traverse Operation Function Group (→MC2)	424
14	Safety	Funtio	n STO(Safe Torque Off)	425
	14.1	Safe	ty Standard Product	425
	14.2	Abou	t the Safety Function	425
		14.2.1	Safety Function Wiring Diagram	
		14.2.2	Installing the Safety Board to 0.75–160 kW Product	
		14.2.3	Installing the Safety Board to 185–375 kW Product	
		14.2.4	Safety Function Terminal Description	
4E	Merrica	14.2.5	Cable Specification for Signal Terminal Block Wiring	
15			cation	
	15.1		(Det Norske Veritas) Marine Certification Details	
	15.2	Bure	au Veritas (Marine & Offshore Division) Marine Certification Deta	ıls.429

	15.3	ABS Marine Certification Details	429
	15.4	KR Marine Certification Details	429
	15.5	Marine Certification Models for SV-iS7 Products	430
16	Using	a Single Phase Power Source	432
	16.1	Single Phase Rating	432
	16.2	Power(HP), Input Current and Output Current	
	16.3	Input Frequency and Voltage Tolerance	434
	16.4	Wiring and Peripheral Device	434
	16.5	Other Considerations	437
17	Storag	je and Disposal	438
	17.1	Storage	438
	17.2	Disposal	438
Pro	duct W	arranty	442
Ind	ex		444

1 About the Product

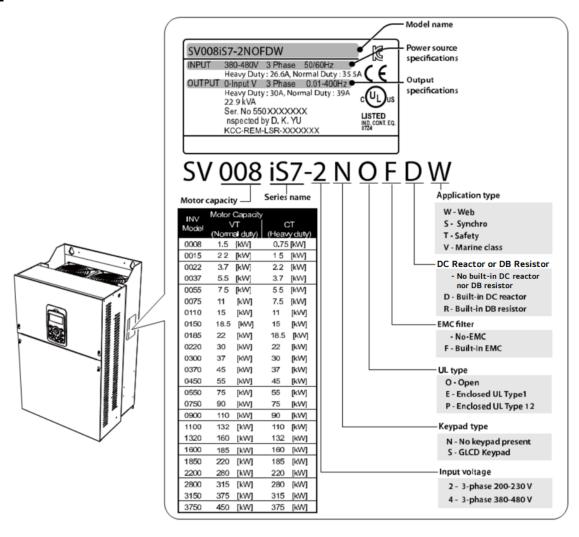
This chapter provides details on product identification and part names. To install the inverter correctly and safely, carefully read and follow the instructions.

1.1 Preparing for Installation and Operation

1.1.1 Identifying the Product

Check the product name, open the packaging, and then confirm that the product is free from defects. Contact your supplier if you have any issues or questions about your product.

The iS7 inverter is manufactured in a range of product groups based on drive capacity and power source specifications. The product name and specifications are detailed on the rating plate. Check the rating plate before installing the product and make sure that the product meets your requirements.



Note1) Optional conduit parts are available for the Enclosed UL Type 1 models (0.75-75 kW products).

Note2) Built-in DB resistor is available only for the Web application models (0.75–3.7 kW products).

Note3) To use safety function, please buy 0.75-160kW product including safety option. However 185-375kW product users have to buy safety option and apply to standard products because safety option is not included.

1.1.2 Checking the Product for Defects or Damage

If you suspect that the product has been mishandled or damaged in any way, contact the LS ELECTRIC Customer Support center with the phone numbers listed on the back cover of this manual.

1.1.3 Preparing the Product for Installation and Operation

Preparation steps for installation and operation may slightly vary by product type and application. Refer to the manual and prepare the product accordingly.

1.1.4 Installing the Product

Refer to the installation section of this manual and install the product correctly considering the installation and operating conditions at the installation location, such as installation clearances, to prevent premature deterioration or performance loss.

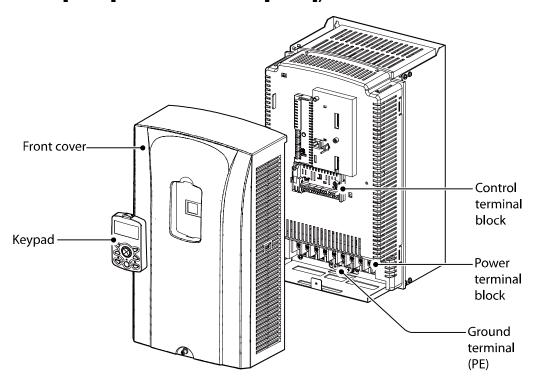
1.1.5 Connecting the Cables

Connect the power input/output and signal cables to the terminal block according to the instructions provided in this manual. Ensure that all the cables are connected correctly before supplying power to the product. Incorrect cable connections may damage the product.

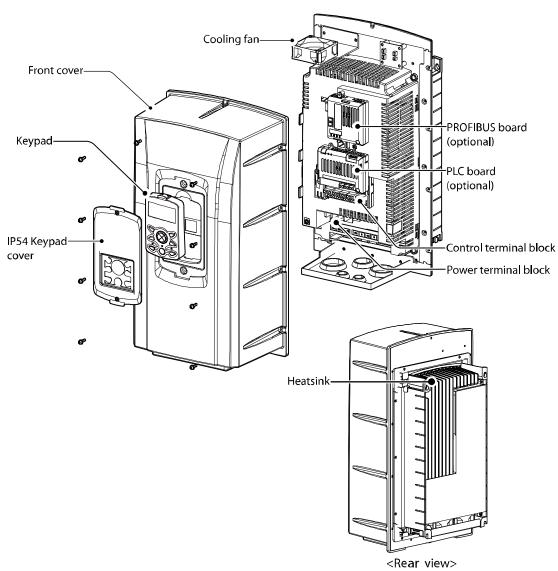
1.2 **Part Names**

The illustration below displays part names. Details may vary between product groups.

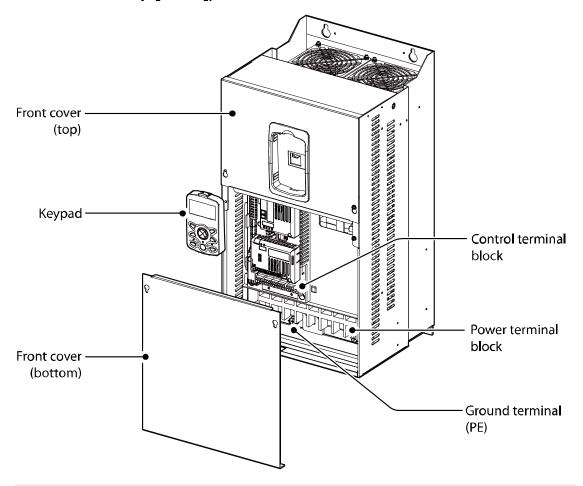
1.2.1 Interior and Exterior View (IP 21 Model Types Less than 22 kW [200 V] / Less than 75 kW [400 V])



1.2.2 Interior and Exterior View (IP 54 Model Types Less than 22 kW [200/400 V])



Interior and Exterior View (Model Types 30 kW and up [200 V] / 90 1.2.3 kW and up [400 V])



Note

Refer to the installation manual provided with the optional module products before installing communication modules in the inverter.

2 Technical Specifications

2.1 Input and Output Specifications 200 V Class (0.75–22 kW)

Model SV	xxx iS7–2x		000	8 00	15	0022	0037	0055	0075	0110	0150	0185	0220	
	Normal load	, HP	2	3		5	7.5	10	15	20	25	30	40	
Applied	Normal load	kW	1.5	2.2	2	3.7	5.5	7.5	11	15	18.5	22	30	
Motor	Hooverload	HP	1	2		3	5	7.5	10	15	20	25	30	
	Heavy load	kW	0.7	5 1.	5	2.2	3.7	5.5	7.5	11	15	18.5	22	
	Rated Capa	acity (kV	۱.9	3.0	0	4.5	6.1	9.1	12.2	17.5	22.9	28.2	33.5	
	Rated	Norma load	8	12	<u>)</u>	16	24	32	46	60	74	88	124	
Rated output	Current (A)	Heavy load	5	8		12	16	24	32	46	60	74	88	
	Output Fred	quency	0-4	0-400 Hz (Sensorless-1: 0-300 Hz, Sensorless-2, Vector: 0.1-120 Hz)										
	Output Volta	age (V)	3-P	3-Phase 200–230 V										
	Working Vo	ltage (V	3-P	hase 2	200-	-230 VA	AC (-15	%–+10	%)					
	Input Frequ	ency	50-	-60 Hz	(±5	5%)								
Rated input	Rated	Norma load	6.8	10).6	14.9	21.3	28.6	41.2	54.7	69.7	82.9	116.1	
Current (A)		Heavy load	4.3	6.9	9	11.2	14.9	22.1	28.6	44.3	55.9	70.8	85.3	

- Only the heavy duty ratings apply to model types without a built-in DC resistor (NON-DCR).
- The standard used for 200 V inverters is based on a 220 V supply voltage.
- The rated output current is limited based on the carrier frequency set at CON-04.
- The output frequency is limited to 0–300 Hz if DRV-09 (control mode) is set to "3 (Sensorless-1)," and to 0–120 Hz if DRV-09 (control mode) is set to "4 (Sensorless-3)."
- The maximum output voltage cannot exceed the input voltage of the power source.

Input and Output Specifications 200 V Class (30-75 2.2 kW)

Model SV	xxx iS7–2x		0300	0370	0450	0550	0750					
	Namedia	HP	50	60	75	100	125					
Applied	Normal load	kW	37	45	55	75	90					
Motor	Hooverload	HP	40	50	60	75	100					
	Heavy load	kW	30	37	45	55	75					
	Rated Capa	city (kVA)	46	57	69	84	116					
	Rated Current	Normal load	146	180	220	288	345					
Rated output	(A)	Heavy load	116	146	180	220	288					
	Output Freq	uency	0–400 Hz)	Hz (Ser	nsorless	-1: 0–30	00 Hz, S	ensorle	ess-2, \	/ector:	0.1–12	20
	Output Volta	age (V)	3-Phase 200–230 V									
	Working Vo	tage (V)	3-Phas	se 200–2	230 VA	C (-15%-	-+10%)					
	Input Freque	ency	50–60	Hz (±5%	%)							
Rated input	Rated	Normal load	152	190	231	302	362					
	(,,)	Heavy load	121	154	191	233	305					

- The standard motor capacity is based on a standard 4-pole motor.
- The standard used for 200 V inverters is based on a 200 V supply voltage.
- The rated output current is limited based on the carrier frequency set at CON-04.
- The output frequency is limited to 0-300 Hz if DRV-09 (control mode) is set to "3 (Sensorless-1)," and to 0-120 Hz if DRV-09 (control mode) is set to "4 (Sensorless-3)."
- The maximum output voltage cannot exceed the input voltage of the power source.

2.3 Input and Output Specifications 400 V Class (0.75–22 kW)

Model SV	xxx iS7–2x			8000	0015	0022	0037	0055	0075	0110	0150	0185	0220
	Normal load	٦	HP	2	3	5	7.5	10	15	20	25	30	40
Applied	Normanioad	u	kW	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30
Motor	Hooverload		HP	1	2	3	5	7.5	10	15	20	25	30
	Heavy load		kW	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22
	Rated Capa	acity	(kVA)	1.9	3.0	4.5	6.1	9.1	12.2	18.3	22.9	29.7	34.3
5	Rated Current	No loa	ormal ad	4	6	8	12	16	24	30	39	45	61
Rated output	(A)	He loa	eavy ad	2.5	4	6	8	12	16	24	30	39	45
	Output Fred	quen	псу	0–400 Hz (Sensorless-1: 0–300Hz, Sensorless-2, Vector: 0.1–120Hz)									
	Output Volt	age	(V)	3-Phase 380–480 V									
	Working Vo	oltage	e (V)	3-Pha	se 380-	-480 VA	AC (-15	%–+10	%)				
	Input Frequ	ienc	у	50–60	Hz (±5	5%)							
Rated input	Rated	No loa	ormal ad	3.7	5.7	7.7	11.1	14.7	21.9	26.4	35.5	41.1	55.7
Current (A)	He loa	avy ad	2.2	3.6	5.5	7.5	11.0	14.4	22.0	26.6	35.6	41.6	

- Only the heavy duty ratings apply to model types without a built-in DC resistor (NON- DCR).
- The standard motor capacity is based on a standard 4-pole motor.
- The standard used for 400 V inverters is based on a 440 V supply voltage.
- The rated output current is limited based on the carrier frequency set at CON-04.
- The output frequency is limited to 0-300 Hz if DRV-09 (control mode) is set to "3 (Sensorless-1)," and to 0-120 Hz if DRV-09 (control mode) is set to "4 (Sensorless-3)."
- The maximum output voltage cannot exceed the input voltage of the power source.

Input and Output Specifications 400 V Class (30–160 2.4 kW)

Model SV	xxx iS7–4x		0300	0370	0450	0550	0750	0900	1100	1320	1600	
	Namallaa	_ HP	50	60	75	100	125	150	200	250	300	
Applied	Applied Normal load	kW	37	45	55	75	90	110	132	160	185	
Motor	Hoovy lood	HP	40	50	60	75	100	125	150	200	250	
	Heavy load	kW	30	37	45	55	75	90	110	132	160	
	Rated Capa	acity (kVA	46	57	69	84	116	139	170	201	248	
	Rated Current	Normal load	75	91	110	152	183	223	264	325	370	
Rated output	(A)	Heavy load	61	75	91	110	152	183	223	264	325	
	Output Free	quency	0–400 Hz)	0–400 Hz (Sensorless-1: 0–300 Hz, Sensorless-2, Vector: 0.1–120 Hz)								
	Output Volt	age (V)	3-Pha	3-Phase 380–480 V								
	Working Vo	ltage (V)	3-Pha	ase 380	–480 V	AC (-15	5%–+10	%)				
	Input Frequ	ency	50–60) Hz (±	5%)							
Rated input Rated	Normal load	67.5	81.7	101.8	143.6	173.4	2129	254.2	315.3	359.3		
Current (A)	_	Heavy load	55.5	67.9	82.4	1026	143.4	174.7	213.5	255.6	316.3	

- The standard used for 400 V inverters is based on a 440 V supply voltage.
- The rated output current is limited based on the carrier frequency set at CON-04.
- The output frequency is limited to 0–300 Hz if DRV-09 (control mode) is set to "3 (Sensorless-1)," and to 0-120 Hz if DRV-09 (control mode) is set to "4 (Sensorless-3)."
- The maximum output voltage cannot exceed the input voltage of the power source.

2.5 Input and Output Specifications 400 V Class (185–375 kW)

Model SV	xxx iS7–4x		1850	2200	2800	3150	3750					
	Normal load	, HP	350	400	500	-	-					
Applied	Normai ioa	kW	220	280	315	375	450					
Motor	Hoovelood	HP	300	350	400	500	-					
	Heavy load	kW	185	220	280	315	375					
	Rated Capa	acity (kVA)	286	329	416	467	557					
5	Rated Current	Normal load	432	547	613	731	877					
Rated output	(A)	Heavy load	370	432	547	613	731					
	Output Free	quency	0-400) Hz (Ser	sorless	s-1: 0 <u>–</u> 3	00 Hz,	Sens	orless-2	, Vecto	r: 0–120	Hz)
	Output Volt	age (V)	3-Pha	se 380–	180 V							
	Working Vo	oltage (V)	3-Pha	se 380–4	180 VA	C (-15%	<u>-</u> +10%	5)				
	Input Frequ	iency	50–60) Hz (±5%	6)							
Rated input	Rated Current	Normal load	463	590	673	796	948					
	(A)	Heavy load	404	466	605	674	798					

- The standard motor capacity is based on a standard 4-pole motor.
- The standard used for 400 V inverters is based on a 440 V supply voltage.
- The rated output current is limited based on the carrier frequency set at CON-04.
- The output frequency is limited to 0–300 Hz if DRV-09 (control mode) is set to "3 (Sensorless-1)," and to 0–120 Hz if DRV-09 (control mode) is set to "4 (Sensorless-3)."
- The maximum output voltage cannot exceed the input voltage of the power source.

Note

[English]

The maximum allowed prospective short-circuit current at the input power connection is defined in IEC 60439-1 as 100 kA. The drive is suitable for use in a circuit capable of delivering not more than 100 kA RMS at the drive's maximum rated voltage, depending on the selected MCCB. RMS symmetrical amperes for recommended MCCB are the following table.

[French]

Le courant maximum de court-circuit présumé autorisé au connecteur d'alimentation électrique est défini dans la norme IEC 60439-1 comme égal à 100 kA. L'entraînement convient pour une utilisation dans un circuit capable de délivrer pas plus de 100 kA RMS à la tension nominale maximale de l'entraînement. Le tableau suivant indique le MCCB recommandé selon le courant RMS symétrique en ampères.

Working Voltage	UTE100 (E/N)	UTS150 (N/H/L)	UTS250 (N/H/L)		UTS4 (N/H/L		
240V(50/60Hz)	50/65kA	65/100/150kA	65/100/150)kA	65/100	0/150kA	
480V(50/60Hz)	25/35kA	35/65/100kA	35/65/100k	κA	35/65/	100kA	
Working Voltage	ABS33c	ABS53c	ABS63c	ABS ²	103c	ABS203c	ABS403c
240V(50/60Hz)	30kA	35kA	35kA	85kA		85kA	75kA
480V(50/60Hz)	7.5kA	10kA	10kA	26kA		26kA	35kA

Product Specification Details 2.6

2.6.1 Control

Items		Description
	Control modes	V/F control, V/F PG, slip compensation, sensorless vector-1, sensorless vector-2, vector control
	Frequency settings resolution	Digital command: 0.01 Hz Analog command: 0.06 Hz (maximum frequency: 60 Hz)
Control	Frequency accuracy	Digital command: 0.01% of maximum output frequency Analog command: 0.1% of maximum output frequency
	V/F pattern	Linear, square reduction, user V/F
	Overload capacity	Rated current for heavy duty operation: 150% for 1 min Rated current for normal duty operation: 110% for 1 min
	Torque boost	Manual torque boost, automatic torque boost

Only the heavy load ratings apply to 0.75-22 kW model types without a built-in DC resistor (NON-DCR).

2.6.2 Operation

Items			Description	
	Operatio	n types	Select from keypad, terminal strip, or operation.	network communication
	Frequen settings	су	Analog type: -10–10 V, 0–10 V, 0–20 Digital type: keypad	mA
Operation	Operatio	n function	 PID control 3-wire operation Frequency limit Second function Reverse rotation prevention Inverter bypass Flying start Power braking Leakage reduction Easy start 	 Up-down operation DC braking Frequency jump Slip compensation Automatic restart Automatic tuning Energy buffering Flux braking MMC
	lanut	Multi-	Select NPN (Sink) or PNP (Source) r	mode.
	Input	function terminal	Forward direction operation	Reverse direction

Items			Description	
		(8 EA) P1–P8*	 Reset Emergency stop Multi-step speed frequency-high/med/low DC braking during stop Frequency increase 3-wire operation Acceleration/deceleration/stop Operation by keypad input during an operation by network communication 	operation External trip Jog operation Multi-step acc/dechigh/med/low Second motor selection Frequency reduction Transition from PID to general operation Analog command frequency fix
		Multi- function open collector terminal	Fault output and inverter operation status output	Less than DC 26 V, 100 mA
	Output	Multi- function relay terminal	status output	N.O.: Less than AC 250 V 1A, DC 30 V, 3A N.C.: Less than AC 250 V 1A, DC 30 V 1A
		Analog output	DC 0–10 V, 0–20 mA: Select output typ voltage, or DC voltage.	pe from frequency, current,

^{*} Set the Input Group codes IN-65 through IN-72 to configure the multi-function terminal functions.

2.6.3 Protection Function

Items		Description
Protection function	Trips	 Over voltage Low voltage Over current Earth current detection Inverter overheat Motor overheat Output imaging Overload protection Network communication error Lost command Hardware failure Cooling fan failure Pre-PID failure No motor trip External trip Other safety functions
	Alarms	 Stall prevention Overload Light load Encoder error Fan failure Keypad command loss Speed command loss
	Instantaneous blackout	Less than 15 ms (CT) [Less than 8 ms (VT)]: Continue operation (must be within the rated input voltage and rated output range). Over 15 ms (CT) [Over 8 ms (VT)]: Automatically restart

2.6.4 Structure and Operating Environment Control

Items		Description						
	Cooling type	Forced cooling: 0.75–15 kW (200/400 V class), 22 kW (400 V class) Inhalation cooling: 22–75 kW (200 V class), 30–375 kW (400 V class)						
Structure/	Protection structure	- 0.75–22 kW (200V), 0.75–75 kW (400 V): Open type IP 21 (default), UL enclosed type 1 (optional)* - 30–75 kW (200 V), 90–375 kW (400 V): Open type IP 00 - 0.75–22 kW, frame types 2, 4 and others.: Enclosed IP54 type, UL enclosed type 12						
environment	Ambient temperature	 CT load (heavy duty): -10–50°C VT load (normal duty): -10–40°C No ice or frost should be present. Working under normal load at 50°C (122°F), it is recommended that less than 80% load is applied. IP54 product: -10–40°C No ice or frost should be present. 						

Items		Description
	Storage temperature.	-20°C–65°C (-4–149°F)
	Ambient humidity	Relative humidity less than 95% RH (to prevent condensation from forming)
	Operation altitude	Maximum 1000m above sea level for standard operation. From 1000 to 4000m, the rated input voltage and rated output current of the drive must be derated by 1% for every 100m.
	Oscillation	Less than 5.9 m/sec ² (0.6 G).
	Surrounding environment	Prevent contact with corrosive gases, inflammable gases, oil stains, dust, and other pollutants (Pollution Degree 2 Environment).

^{*} UL Enclosed type 1 when an optional conduit box is installed. The 30–75 kW (200 V class) product is regarded as UL Open type IP 20 when an optional conduit box is installed.

3 Installing the Inverter

3.1 Installation Considerations

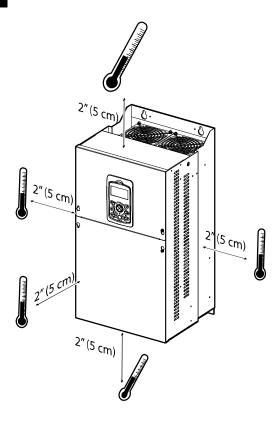
Inverters are composed of various precision electronic devices, and therefore the installation environment can significantly impact the lifespan and reliability of the product. The table below details the ideal operation and installation conditions for the inverter.

Items	Description
	CT load (heavy duty): -10°C–50°C
Ambient Temperature*	VT load (normal duty): -10°C–40°C
	IP54 model types: -10°C-40°C
Ambient Humidity	90% relative humidity (no condensation)
Storage Temperature	- 4–149°F (-20–65°C)
Environmental Factors	An environment free from corrosive or flammable gases, oil residue, or dust (pollution degree 2)
Altitude/Vibration	Lower than 3,280 ft (1,000 m) above sea level/less than 0.6 G (5.9 m/sec2)
Air Pressure	70–106 kPa

^{*}The ambient temperature is the temperature measured at a point 2" (5 cm) from the surface of the inverter. No ice or frost should be present.

① Caution

- Do not transport the inverter by lifting with the inverter's covers or plastic surfaces. The inverter may tip
 over if covers break, causing injuries or damage to the product. Always support the inverter using the
 metal frames when moving it.
- Hi-capacity inverters are very heavy and bulky. Use an appropriate transport method that is suitable
 for the weight. Do not place heavy objects on top of electric cables. Doing so may damage the cable
 and result in an electric shock.
- Do not install the inverter on the floor or mount it sideways against a wall. The inverter must be installed vertically, on a wall or inside a panel, with its rear flat on the mounting surface.



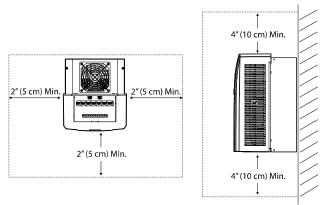
① Caution

Do not allow the ambient temperature to exceed the allowable range while operating the inverter.

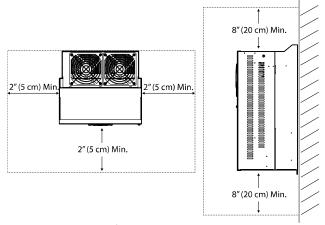
3.2 Selecting and Preparing a Site for Installation

When selecting an installation location, consider the following requirements:

- The inverter must be installed on a wall that can support the inverter's weight.
- The location must be free from vibration. Vibrations can adversely affect the operation of the inverter.
- The inverter can become very hot during operation. Install the inverter on a surface that is fire resistant or flame retardant with sufficient clearance around the inverter to allow for air circulation. The illustrations below detail the required installation clearances.



<Clearance requirements for model types with less than 30 kW capacity'>



<Clearance requirements for model types with more than 30 kW capacity>

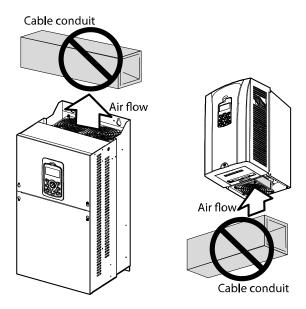
① Caution

Install the inverter on a non-flammable surface, and do not place flammable material near the inverter. Otherwise, a fire may result.

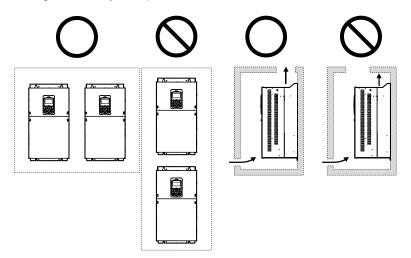
Note

Model types with capacities of 30 kW or more require a minimum of 8" clearance above and below the unit.

Ensure that the cable conduits do not obstruct the air flow to and from the cooling fan.



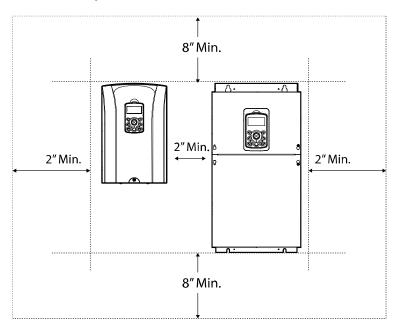
Ensure sufficient air circulation is provided around the inverter when it is installed. If the inverter is to be installed inside a panel, enclosure, or cabinet rack, carefully consider the position of the inverter's cooling fan and vents. The cooling fan must be positioned to efficiently dissipate the heat generated by the operation of the inverter.



Note

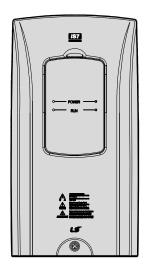
In order to meet EMC standards, 200 V, 30-75 kW model types and model types with capacities of 90 kW or more should be installed inside a metal cabinet.

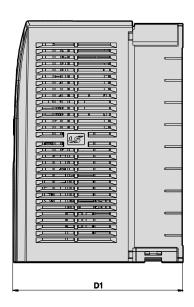
If you are installing multiple inverters of different ratings, provide sufficient clearance to meet the clearance specifications of the larger inverter. The iS7 inverters rated for up to 30 kW may be installed side by side.

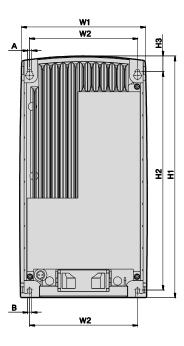


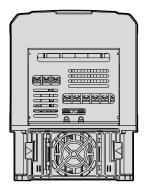
Exterior and Dimensions (UL Enclosed Type 1, IP21 3.3 Type)

SV0008-0037iS7 (200 V/400 V)





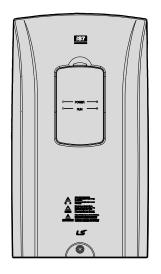


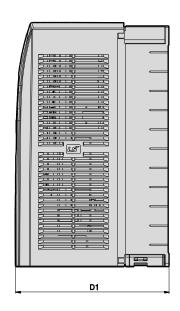


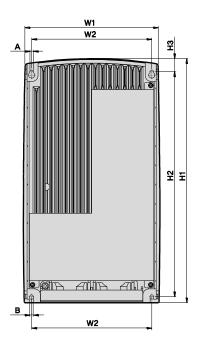
Units: mm (inch)

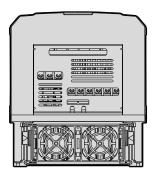
Inverter Capacity	W1	W2	H1	H2	Н3	D1	A	В
SV0008-0037 iS7 - 2/4	150	127	284	257	18	200	5	5
	(5.90)	(5.00)	(11.18)	(10.11)	(0.70)	(7.87)	(0.19)	(0.19)

SV0055-0075iS7 (200 V/400 V)





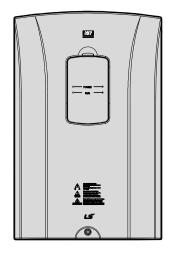


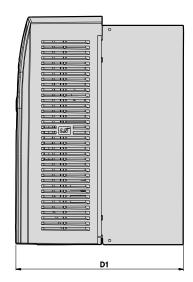


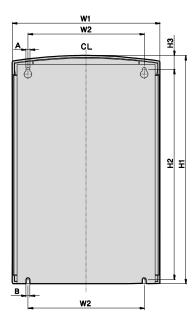
Units: mm (inch)

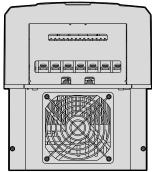
Inverter Capacity	W1	W2	H1	H2	Н3	D1	Α	В
SV0055-0075 iS7 - 2/4	200	176	355	327	19	225	5	5
	(7.87)	(6.92)	(13.97)	(12.87)	(0.74)	(8.85)	(0.19)	(0.19)

SV0110-0150iS7 (200 V/400 V)





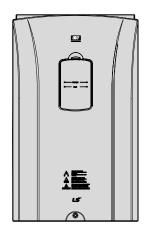


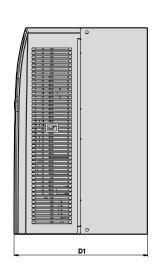


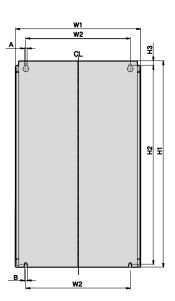
Units: mm (inch)

Inverter Capacity	W1	W2	H1	H2	H3	D1	A	В
SV0110-0150 iS7- 2/4	250	214.6	385	355	23.6	284	6.5	6.5
	(9.84)	(8.44)	(15.15)	(13.97)	(0.92)	(11.18)	(0.25)	(0.25)

SV0185-0220iS7 (200 V/400 V)



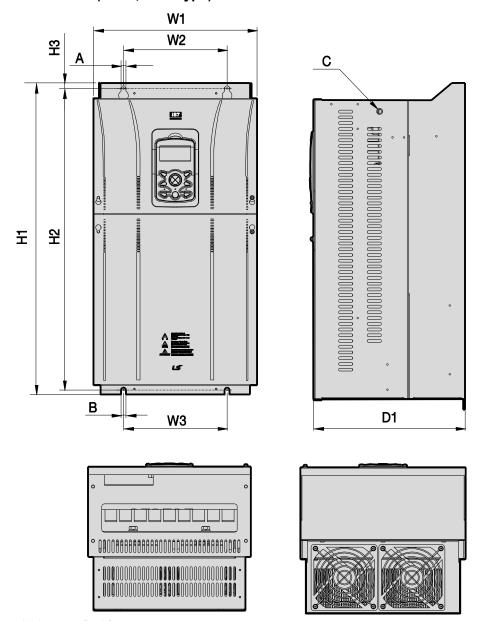






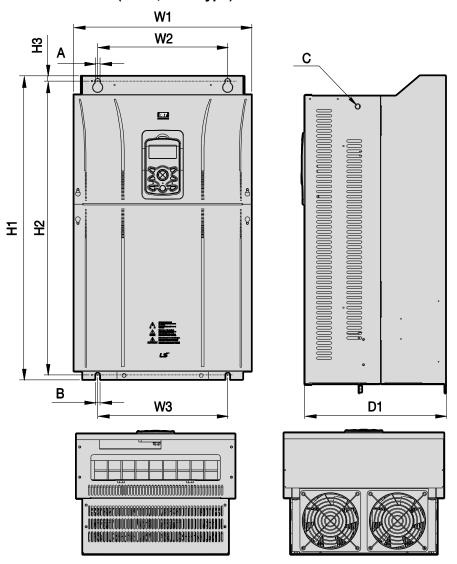
Inverter Capacity	W1	W2	H1	H2	Н3	D1	Α	В
SV0185-0220iS7- 2/4	280	243.5	461.6	445	10.1	298	6.5	6.5
	(11.02)	(9.58)	(18.17)	(17.51)	(0.39)	(11.73)	(0.25)	(0.25)

SV0300-iS7 (200 V, IP00 Type)



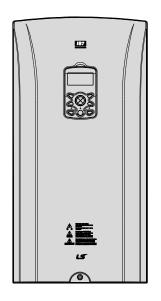
Inverter Capacity	W1	W2	W3	H1	H2	Н3	D1	A	В	С
SV0300 iS7-2	300 (11.81)	190 (7.48)	190 (7.48)	570 (22.44)	552 (21.73)	10 (0.39)	265.2 (10.44)	10 (0.39)	10 (0.39)	M8

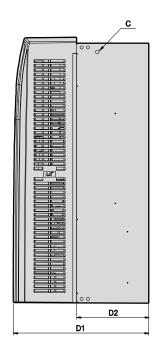
SV0370-0450iS7 (200 V, IP00 Type)

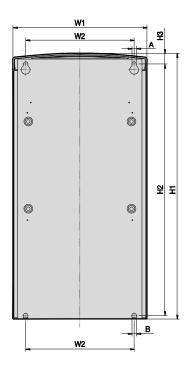


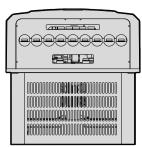
Inverter Capacity	W1	W2	W3	H1	H2	H3	D1	A	В	С
SV0370-0450	370	270	270	630	609	11	281.2	10	10	M10
iS7-2	(14.56)	(10.63)	(10.63)	(24.8)	(23.97)	(0.43)	(11.07)	(0.39)	(0.39)	

SV0300-0450iS7 (400 V)



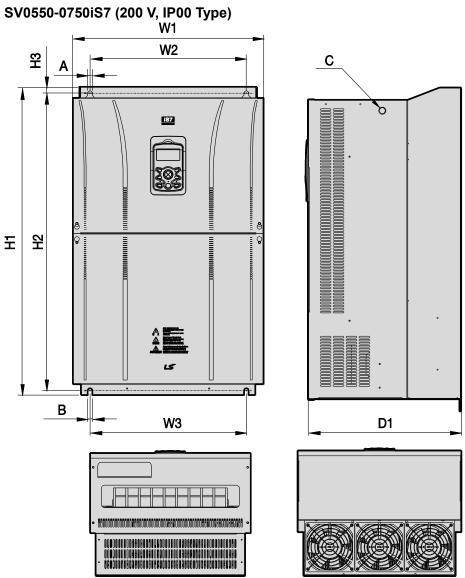






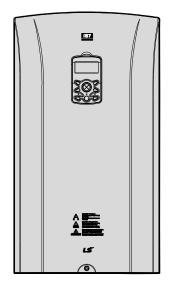
Units: mm (inch)

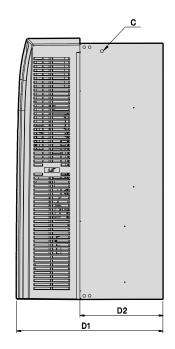
Inverter Capacity	W1	W2	H1	H2	Н3	D1	D2	A	В	С
						DCR typ	е			
SV300-450	300.1	242.8	594.1	562	24.1	303.2 (11.93)	161 (6.33)	10	10	MO
iS7-4	(11.81) (9.55)	(23.38)	(22.12)	(0.94)	Non-DCR type		(0.39)	(0.39)	M8	
						271.2 (10.67)	129 (5.78)			

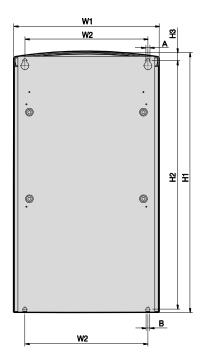


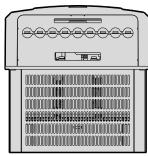
Inverter Capacity	W1	W2	W3	H1	H2	Н3	D1	A	В	С
SV0550-0750 iS7-2	465 (18.3)	381 (15.0)	381 (15.0)	750 (29.52)	723.5 (28.48)	15.5 (0.61)	355.6 (14.0)		11 (0.43)	M16

SV0550-0750iS7 (400 V)





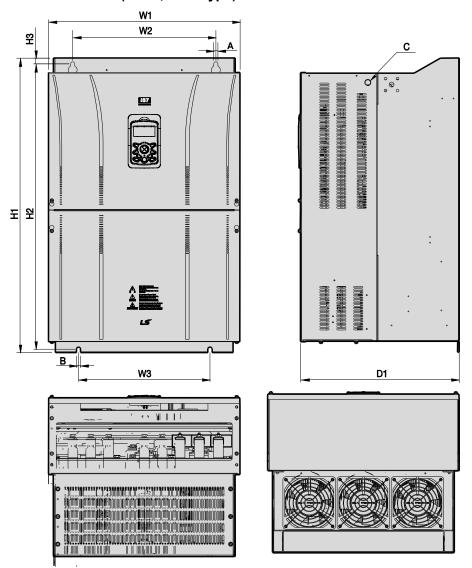




Units: mm (inch)

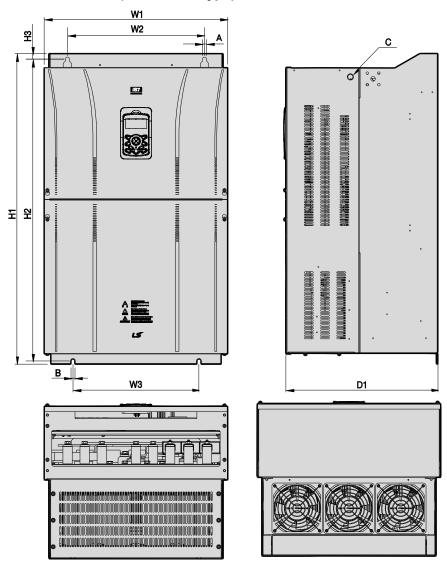
Inverter Capacity	W1	W2	H1	H2	Н3	D1	D2	A	В	С
						DCR typ	е			
SV0550-0750	370.1	312.8	663.5	631.4	24.1	373.3 (14.69)	211.5 (8.32)	10	10	M8
157-4	(14.57) (12.31)	(26.12)	(24.85)	(0.94)	Non-DCR type		(0.39)	(0.39)	IVIO	
						312.4 (12.29)	150.6 (5.92)			

SV0900-1100iS7 (400 V, IP00 Type)



Inverter Capacity	W1	W2	W3	H1	H2	Н3	D1	Α	В	С
SV0900-1100	510	381	350	783.5	759	15.5	422.6	11	11	M16
iS7-4	(20.07)	(15.0)	(13.77)	(30.84)	(29.88)	(0.61)	(16.63)	(0.43)	(0.43)	

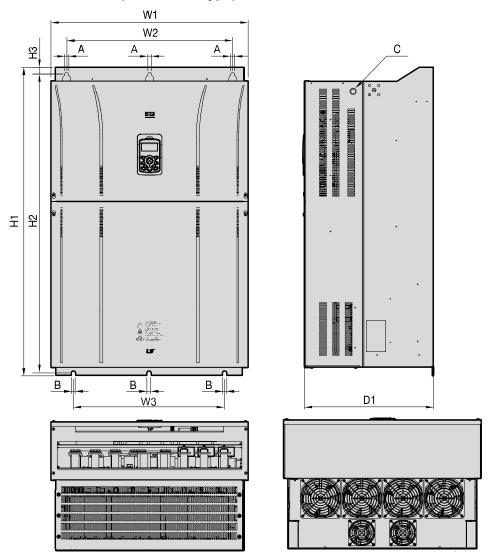
SV1320-1600iS7 (400 V, IP00 Type)



Units: mm (inch)

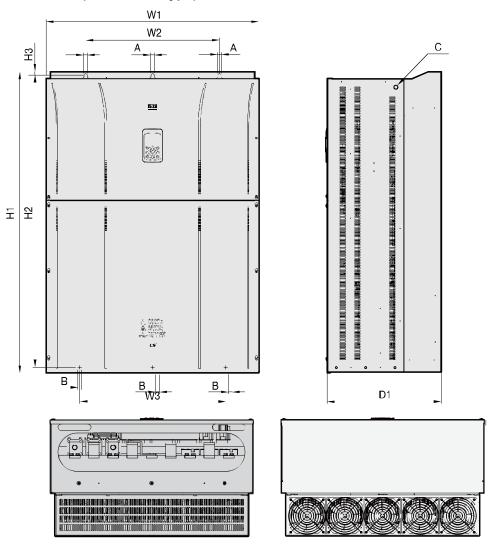
Inverter Capacity	W1	W2	W3	H1	H2	Н3	D1	A	В	С
SV1320–1600 iS7-4	510 (20.07)	381 (15.0)	350 (13.77)	861 (33.89)	836.5 (32.93)		422.6 (16.63)	11 (0.43)	11 (0.43)	M16

SV1850-2200iS7 (400 V, IP00 Type)



lnv	verter Capacity	W1	W2	W3	H1	H2	Н3	D1	Α	В	С
	/1850/ 200iS7-4	690 (27.16)	581 (22.87)	528 (20.79)	1078 (42.44)	1043.5 (41.08)		450 (17.72)	14 (0.55)	15 (0.59)	M20

SV2800iS7 (400 V, IP00 Type)

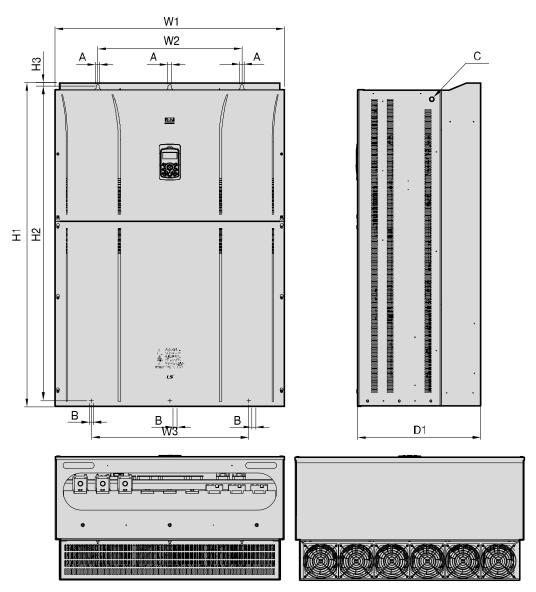


Units: mm (inch)

Inverter Capacity	W1	W2	W3	H1	H2	Н3	D1	A	В	С
SV2800iS7-4	771 (30.35)	500 (19.69)	500 (19.69)	1138 (44.80)	1110 (43.70)	15 (0.59)	440 (17.32)	13 (0.51)	13 (0.51)	M16

For 280 kW model types, I volts are supplied with the product.

SV3150-3750iS7 (400 V, IP00 Type)



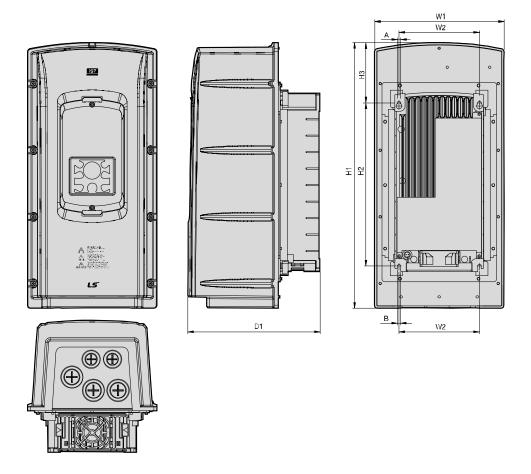
Units: mm (inch)

Inverter Capacity	W1	W2	W3	H1	H2	H3	D1	Α	В	С
SV3150/ 3750iS7-4	922 (36.30)	580 (22.83)	580 (22.83)	1302.5 (51.28)	1271.5 (50.06)	-	495 (19.49)	14 (0.55)	14 (0.55)	M16

For 315-375 kW model types, I volts are supplied with the product.

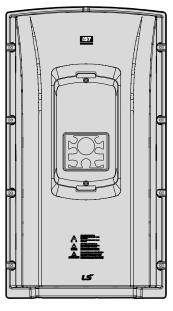
Exterior and Dimensions (UL Enclosed Type 12, IP54 3.4 Type)

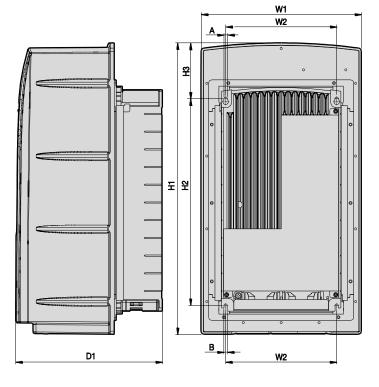
SV0008-0037iS7 (200 V/400 V)

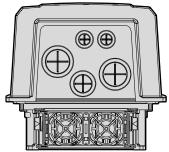


Inverter Capacity	W1	W2	H1	H2	H3	D1	Α	В
SV0008–0037 iS7-2/4	204.2	127	419	257	95.1	208	5	5
	(8.03)	(5.0)	(16.49)	(10.11)	(3.74)	(8.18)	(0.19)	(0.19)

SV0055-0075iS7 (200 V/400 V)

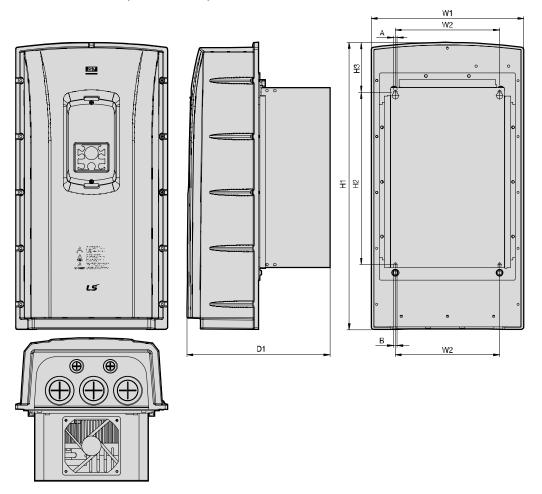






Inverter Capacity	W1	W2	H1	H2	H3	D1	Α	В
SV0055–0075 iS7-2/4	254	176	460.6	327	88.1	232.3	5	5
	(10.0)	(6.92)	(18.13)	(12.87)	(3.46)	(9.14)	(0.19)	(0.19)

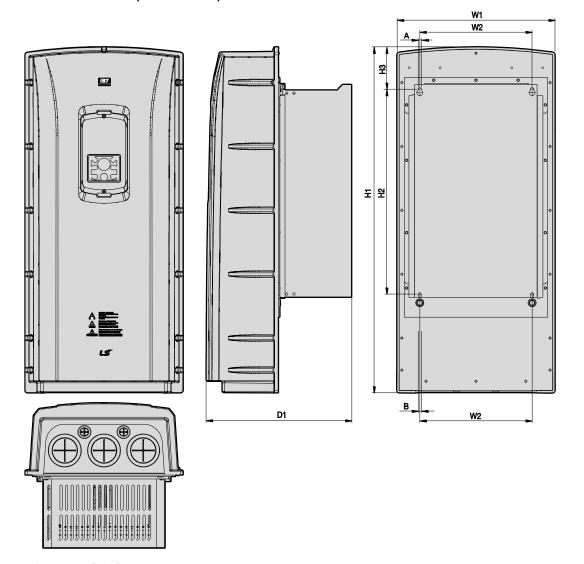
SV0110-0150iS7 (200 V/400 V)



Units: mm (inch)

Inverter Capacity	W1	W2	H1	H2	Н3	D1	Α	В
SV0110-0150 iS7-2/4	313.1	214.6	590.8	355	101.7	294.4	6.5	6.5
	(12.32)	(8.44)	(23.25)	(13.97)	(4.0)	(11.59)	(0.25)	(0.25)

SV0185-0220iS7 (200 V/400 V)



Inverter Capacity	W1	W2	H1	H2	H3	D1	Α	В
SV0185-0220 iS7-2/4	343.2 (13.51)	243.5 (9.58)	750.8 (29.55)	445 (17.51)		315.5 (12.42)	6.5 (0.25)	6.5 (0.25)

Frame Dimensions and Weight (UL Enclosed Type 1, 3.5 IP 21 Type)

Inverter Capacity	W[mm]	H[mm]	D[mm]	Weight[Kg] w/ built-in EMC and DCR	Weight[Kg] w/ built-in EMC	Weight[Kg] w/ built-in DCR	Weight[Kg] non-DCR types
SV0008iS7-2/4	150	284	200	5.5	4.5	5.0	4.5
SV0015iS7-2/4	150	284	200	5.5	4.5	5.0	4.5
SV0022iS7-2/4	150	284	200	5.5	4.5	5.0	4.5
SV0037iS7-2/4	150	284	200	5.5	4.5	5.0	4.5
SV0055iS7-2/4	200	355	225	10	8.4	9.3	7.7
SV0075iS7-2/4	200	355	225	10	8.4	9.3	7.7
SV0110iS7-2/4	250	385	284	20	17.2	16.8	14
SV0150iS7-2/4	250	385	284	20	17.2	16.8	14
SV0185iS7-2	280	461.6	298	30	27	25.9	22.9
SV0220iS7-2	280	461.6	298	30	25.8	25.9	22.9
SV0185iS7-4	280	461.6	298	27.4	23.5	23.3	19.7
SV0220iS7-4	280	461.6	298	27.4	23.5	23.5	20.1
SV0300iS7-2	300	570	265.2	-	-	-	29.5
SV0370iS7-2	370	630	281.2	-	-	-	44
SV0450iS7-2	370	630	281.2	-	-	-	44
SV0550iS7-2	465	750	355.6	-	-	-	72.5
SV0750iS7-2	465	750	355.6	-	-	-	72.5

Note

- The weight specified in the table indicates the total weight of the product without packaging, which includes the built-in parts, such as the EMC filter and DCR.
- The built-in EMC filter and DCR are not available for 30-75 kW (200 V) products.

Inverter Capacity	W[mm]	H[mm]	D[mm]	Weight[Kg] w/ built-in EMC and DCR	Weight[Kg] w/ built-in EMC	Weight[Kg] w/ built-in DCR	Weight[Kg] non-DCR types
SV0300iS7-4	300	594	300.4	-	-	41	28
SV0370iS7-4	300	594	300.4	-	-	41	28
SV0450iS7-4	300	594	300.4	-	-	41	28
SV0550iS7-4	370	663.4	371	-	-	63	45
SV0750iS7-4	370	663.4	371	-	-	63	45
SV0900iS7-4	510	784	423	-	-	101	-
SV1100iS7-4	510	784	423	-	-	101	-
SV1320iS7-4	510	861	423	-	-	114	-
SV1600iS7-4	510	861	423	-	-	114	-
SV1850iS7-4	690	1078	450	-	-	200	-
SV2200iS7-4	690	1078	450	-	-	200	-
SV2800iS7-4	771	1138	440	-	-	-	252
SV3150iS7-4	922	1302.5	495	-	-	-	352
SV3750iS7-4	922	1302.5	495	-	-	-	352

Note

- The weight specified in the table indicates the total weight of the product without packaging, which includes built-in parts, such as the EMC filter and DCR.
- 300-220 kW (400 V) products have built-in DCR only.
- 280-375 kW (400 V) products are provided without a built-in EMC filter and DCR.

Frame Dimensions and Weight (UL Enclosed Type 3.6 12, IP54 Type)

Inverter Capacity	W[mm]	H[mm]	D[mm]	Weight[Kg] w/ built-in EMC and DCR	Weight[Kg] w/ built-in EMC	Weight[Kg] w/ built-in DCR	Weight[Kg] non-DCR types
SV0008iS7-2/4	204	419	208	8.2	7.2	7.7	6.7
SV0015iS7-2/4	204	419	208	8.2	7.2	7.7	6.7
SV0022iS7-2/4	204	419	208	8.2	7.2	7.7	6.7
SV0037iS7-2/4	204	419	208	8.2	7.2	7.7	6.7
SV0055iS7-2/4	254	461	232	12.8	10.2	12.1	9.5
SV0075iS7-2/4	254	461	232	12.9	10.3	12.2	9.6
SV0110iS7-2/4	313	591	294	25.6	22.8	22.4	19.6
SV0150iS7-2/4	313	591	294	25.9	23.1	22.7	19.9
SV0185iS7-2	343	751	316	38.3	34.2	34.1	29.9
SV0220iS7-2	34	751	316	38.3	34.2	34.1	29.9
SV0185iS7-4	343	751	316	34.9	31	31	27.1
SV0220iS7-4	343	751	316	34.9	31	31	27.1

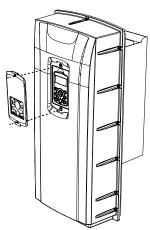
Note

- The weight specified in the table indicates the total weight of the product without packaging, which includes the built-in parts, such as the EMC filter and DCR.
- Only 0.75-22 kW products are available in IP 54 Type specifications.

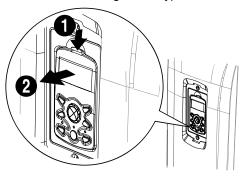
3.7 Installation Procedures for UL Enclosed Type12 and IP54 Type Products

3.7.1 Disassembling the Keypad Cover and Keypad

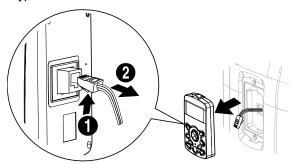
1 Loosen the screws that secure the keypad cover and remove the keypad cover.



2 Depress the tab at the top of the keypad and gently lift the keypad from the inverter to remove it. Be careful not to damage the keypad cable.

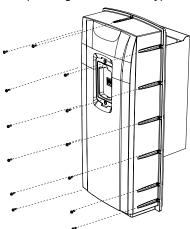


Depress the tab on the keypad cable connector and disconnect the cable from the back of the 3 keypad.

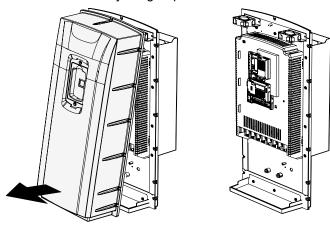


Disassembling the IP54 Front Cover 3.7.2

Loosen the screws that secure the front cover to the chassis. There are 9–13 screws on the cover depending on the model type.

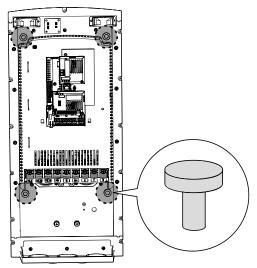


Remove the cover by lifting it upwards from the bottom. 2

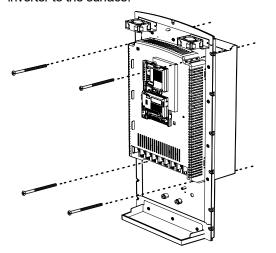


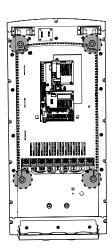
3.7.3 **Mounting the Inverter**

Remove the 4 rubber feet from the corners.



Place the inverter on a flat wall or in a cabinet, and use 4 screws or bolts to securely fix the inverter to the surface.

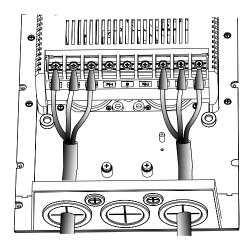




3.7.4 **Connecting the Power Cables**

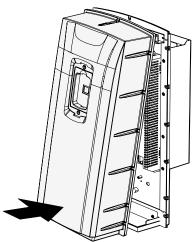
Connect the power cables to the input (R, S, T) and output (U, V, W) terminals. Then, tighten the terminal screws.

Refer to <u>4 Connecting the Cables</u> on page <u>49</u> for detailed information.

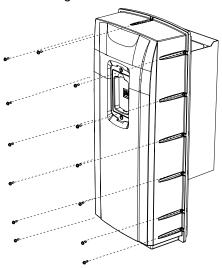


Reassembling the IP54 Front Cover and the Keypad 3.7.5

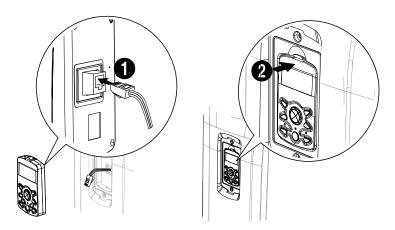
Place the front cover on the chassis and align the screw holes on each side.



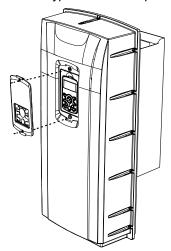
Insert and tighten the screws. There are 9–13 screws on the cover depending on the model type. 2



Connect the signal cable to the keypad, align the lower part of the keypad to the bottom of the 3 keypad receptacle, and then push the top part of the keypad into the chassis until the keypad snaps into place.



Place the keypad cover on top of the keypad, and secure it using 2 screws.



Connecting the Cables

Connect cables to the power and signal terminal blocks of the inverter.

Caution

ESD (Electrostatic discharge) from the human body may damage sensitive electronic components on the PCB. Therefore, be extremely careful not to touch the PCB or the components on the PCB with bare hands while you work on the I/O PCB.

To prevent damage to the PCB from ESD, touch a metal object with your hands to discharge any electricity before working on the PCB, or wear an anti-static wrist strap and ground it on a metal object.

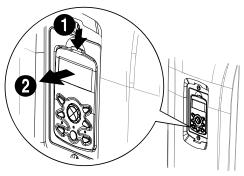
4.1 Removing the Front Cover for Cable Connection

A Danger

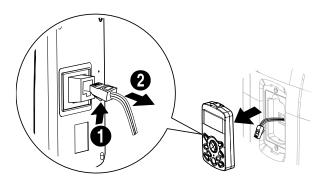
Wait at least 10 minutes before opening the covers and exposing the terminal connections. Before working on the inverter, test the connections to ensure the DC voltage has been fully discharged. Personal injury or death by electric shock may result if the DC voltage has not been discharged.

4.1.1 **IP 21 Type Products**

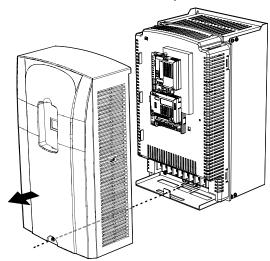
Depress the tab at the top of the keypad and gently lift the keypad from the inverter to remove it. Be careful not to damage the keypad cable.



2 Depress the tab on the keypad cable connector and disconnect the cable from the back of the keypad.

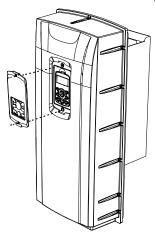


Loosen the screw from the bottom part of the front cover, and then remove the front cover. 3

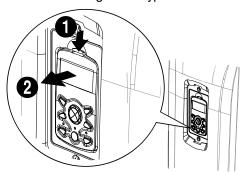


4.1.2 IP 54 Type Products

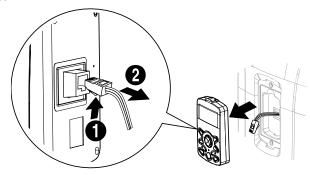
Loosen the two screws securing the keypad cover, and then remove the keypad cover.



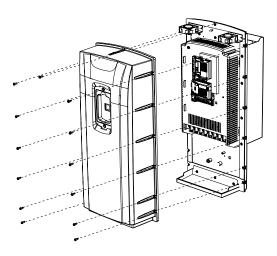
Depress the tab at the top of the keypad and gently lift the keypad from the inverter to remove it. 2 Be careful not to damage the keypad cable.



Depress the tab on the keypad cable connector and disconnect the cable from the back of the 3 keypad.



Remove the screws from each side of the front cover, and then remove the front cover.

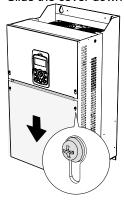


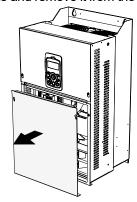
90-375 kW, 400 V and 30-75 kW, 200 V Products 4.1.3

Loosen the two screws on the front cover.



Slide the cover downwards and remove it from the inverter.





4.2 Activating and Deactivating the Built-in EMC Filter

Some iS-7 inverter models have built-in EMC filters to reduce conductive and radiational noise at the inverter input. Refer to <u>1.1.1 Identifying the Product</u> on page <u>1</u> and check your inverter's model type and specifications to see if it has a built-in EMC filter.

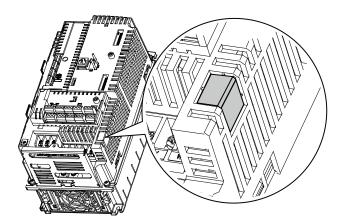
If your inverter has a built-in EMC filter, refer to the following instructions to activate or deactivate it.



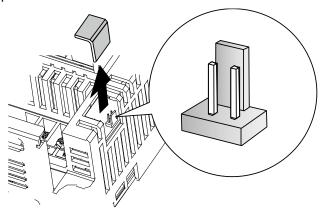
Do not activate the EMC filter if the inverter uses a power source with an asymmetrical grounding structure, for example a grounded delta connection. Personal injury or death by electric shock may result if the power source is not grounded properly.

4.2.1 Up to 7.5 kW Inverters

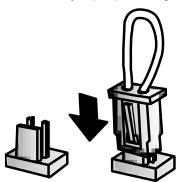
1 Locate the plastic knockout cap that covers the EMC filter switch (jumper SW1).



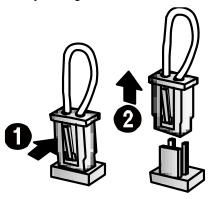
2 Remove the knockout cap and locate the jumper switch. The EMC filter will be deactivated if the two jumper pins are not connected.



Connect the two jumper pins using a short circuit connector to activate the EMC filter. 3

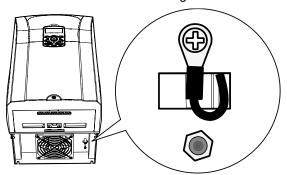


To remove the short circuit connector and deactivate the EMC filter, pull the connector while pressing the latch on the side of the connector. Use pliers or tweezers if you cannot reach the latch with your fingers.



11-22 kW Inverters 4.2.2

Locate the EMC filter cable and the ground terminal at the bottom of the inverter.



The EMC filter is deactivated if the EMC filter cable is connected to the insulated stud.



<EMC filter is turned OFF>

Remove the EMC filter cable from the insulated stud and connect it to the ground terminal (metal) to activate the EMC filter.



<EMC filter is turned ON>

An EMC filter prevents electromagnetic interference by reducing radio emissions from the inverter. Using an EMC filter is not always recommended, as it increases current leakage. If an inverter uses a power source with an asymmetrical grounding connection, the EMC filter must be turned off.

Before using the inverter, confirm the power supply's grounding system. Disable the EMC filter if the power source has an asymmetrical grounding connection.

Connecting the Cables

Asymmetrical Grounding Connection								
One phase of a delta connection is grounded	R(L1) S(L2) T(L3)	Intermediate grounding point on one phase of a delta connection	R(L1) S(L2) T(L3)					
The end of a single phase is grounded	L N	A 3-phase connection without grounding	R(L1)					

Note

• When the EMC Filter is deactivated, the Y-CAP is disconnected from Ground

4.3 Precautions for Wiring the Inverter

⚠ Warning

- Do not connect power to the inverter until installation has been fully completed and the inverter is ready to be operated. Doing so may result in electric shock.
- Wiring and inspection of wiring must be performed by an authorized engineer.

① Caution

- Install the inverter before connecting the cables.
- Ensure that no metal debris, such as wire clippings, remain inside the inverter. Metal debris in the inverter can cause inverter failure.
- Power supply cables must be connected to the R, S, and T terminals. Connecting power cables to other terminals will damage the inverter.
- Use insulated ring lugs when connecting cables to R/S/T and U/V/W terminals.
- The inverter's power terminal connections can cause harmonics that may interfere with other communication devices located near the inverter. To reduce interference, the installation of noise filters or line filters may be required.
- To avoid circuit interruption or damaging connected equipment, do not install phase-advanced condensers, surge protection, or electronic noise filters on the output side of the inverter.
- To avoid circuit interruption or damaging connected equipment, do not install magnetic contactors on the output side of the inverter.
- Make sure that the total cable length does not exceed 495 ft (150 m). For inverters < = 3.7 kW capacity, ensure that the total cable length does not exceed 165 ft (50 m). Long cable runs can cause reduced motor torque in low frequency applications due to voltage drop. Long cable runs also increase a circuit's susceptibility to stray capacitance and may trigger over-current protection devices or result in the malfunction of equipment connected to the inverter.
- Route the signal cables away from the power cables. Otherwise, signal errors may occur due to electric interference.
- Tighten terminal screws to their specified torques. Loose terminal block screws may allow the cables
 to disconnect and cause a short circuit or inverter failure. Refer to <u>4.7 Specifications of the Power</u>
 <u>Terminal Block and Exterior Fuse</u> on page <u>6666</u> for torque specifications.
- Do not place heavy objects on top of electric cables. Heavy objects may damage the cable and result in electric shock.
- Use cables with the largest cross-sectional area, appropriate for power terminal wiring, to ensure that voltage drops do not exceed 2%.
- Use copper cables rated at 600 V, 75°C for power terminal wiring.
- Use copper cables rated at 300 V, 75°C for control terminal wiring.
- If you need to rewire the terminals due to wiring-related faults, ensure that the inverter keypad display is turned off and the charge lamp under the terminal cover is off before working on wiring connections. The inverter may hold a high-voltage electric charge long after the power supply has been turned off.

Ground Connection 4.4

Install ground connections for the inverter and the motor by following the correct specifications to ensure safe and accurate operation. Using the inverter and the motor without the specified grounding connections may result in electric shock.

① Caution

- Do not use the ground terminal as the signal (control) ground.
- Do not share the ground connection with other machines that consume a large amount of power, such as a welding machine.
- Connect the ground cable to the nearest earth contact and keep the cable length as short as possible.

Because the inverter is a high-frequency switching device, leakage current may occur during operation. To avoid the danger of electrocution due to current leakage, the inverter must be properly grounded. Ground connection must be made to the specified ground terminal on the inverter. Do not connect ground cables to chassis screws.

Note

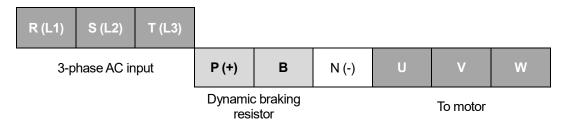
- 200 V products require Class 3 grounding. Resistance to ground must be ≤ 100 Ω .
- 400 V products require Special Class 3 grounding. Resistance to ground must be ≤ 10 Ω .

The following table lists the minimum ground cable specifications that must be met to properly ground the inverters.

Invertor Canacity	Grounding wire size (mm²)				
Inverter Capacity	200 V class	400 V class			
0.75–3.7kW	4	2.5			
5.5–7.5 kW	6	4			
11–15 kW	16	10			
18.5–22 kW	25	16			
30–45 kW	25	16			
55–75 kW	35	35			
90–110 kW	-	60			
132–220 kW	-	100			
280–315 kW	-	185			
375 kW	-	240			

4.5 Terminal Wiring Diagram

4.5.1 Up to 7.5 kW Inverters



4.5.2 11-22 kW Inverters

R (L1)	S (L2)	T (L3)	P (+)	В	N (-)	U	V	W
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4.5.3 30-75 kW Inverters

R (L1)	S (L2)	T (L3)	P1 (+)	P2 (+)	N (-)	U	V	W
--------	--------	--------	--------	--------	-------	---	---	---

4.5.4 90-160 kW Inverters

R (L1) S ((L2) T (L3)	P2 (+)	N (-)	U	V	W
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4.5.5 185-220 kW Inverters

R (L1)	S (L2)	T (L3)	P2 (+)	N (-)	U	V	W
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4.5.6 280-375 kW Inverters

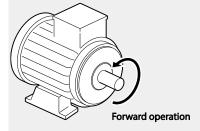
R (L1) S (L2	T (L3)	P1 (+)	P2 (+)	N (-)	U	V	W
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Note

- Inverters with a rated capacity of 11 kW or more are equipped with linearly arranged terminal blocks.
- 0.75–22 kW inverters have built-in DC reactors. The installation of an external DC reactor is not necessary for these inverters.
- The inverter must be properly grounded using the ground terminal.

Note

If the forward command (Fx) is turned on, the motor should rotate counterclockwise when viewed from the load side of the motor. If the motor rotates in the reverse direction, switch the cables at the U and V terminals.



Remarque

Si la commande avant (Fx) est activée, le moteur doit tourner dans le sens anti-horaire si on le regarde côté charge du moteur. Si le moteur tourne dans le sens inverse, inverser les câbles aux bornes U et V.

Connecting Cables to the Power Terminal Block 4.6

① Caution

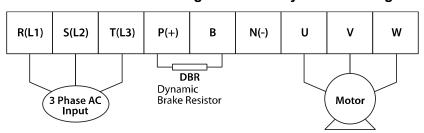
Power supply cables must be connected to the R, S, and T terminals. Connecting power cables to other terminals will damage the inverter.

Note

The motor will rotate in the opposite direction if the U, V, and W terminals are connected in a wrong phase order.

0.75-22 kW (200 V/400 V) 4.6.1

Cable connection for utilizing the built-in dynamic braking unit

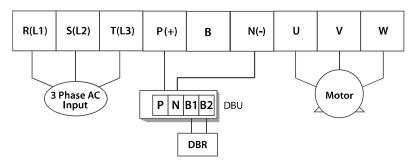


Connect the cables from the dynamic braking unit to the P (+) and B terminals to utilize the built-in dynamic braking unit.

Terminal Symbol	Terminal Name	Description
R (L1), S (L2), T (L3)	AC power supply input terminals	AC input terminals
P (+)	(+) DC voltage terminal	(+) DC link voltage terminal
N (-)	(-) DC voltage terminal	(-) DC link voltage terminal.
P (+), B	Dynamic braking resistor terminals	Dynamic braking resistor terminals
U, V, W	Inverter output terminals	Output terminals to a 3-phase induction motor

Cable connection for utilizing the optional dynamic braking unit

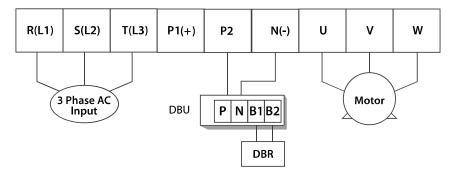
Connect the cables from dynamic braking unit to P (+) and N (-) terminals to utilize the optional dynamic braking unit. Do not connect cables to B terminal.



Terminal Symbol	Terminal Name	Description
R (L1), S (L2), T (L3)	AC power supply input terminals	AC input terminals
P (+)	(+) DC voltage terminal	(+) DC link voltage terminal
N (-)	(-) DC voltage terminal	(-) DC link voltage terminal.
P (+), B	Dynamic braking resistor terminals	Dynamic braking resistor terminals
U, V, W	Inverter output terminals	Output terminals to a 3-phase induction motor

30-75 kW (200 V/400 V)

Connect the cables from the dynamic braking unit to the P (+) and B terminals to utilize the built-in dynamic braking unit.



In 30-75 kW 200 V model types, the P1 and P2 terminals are connected with a jumper pin.

Terminal Symbol	Terminal Name	Description
R (L1), S (L2), T (L3)	AC power supply input terminals	AC input terminals

Terminal Symbol	Terminal Name	Description
P1 (+)	(+) DC voltage terminal	(+) DC link voltage terminal
P2, N (-)	Dynamic braking resistor terminal / DC common*	Dynamic braking resistor terminals
N (-)	(-) DC voltage terminal	(-) DC link voltage terminal
U, V, W	Inverter output terminals	Output terminals to a 3-phase induction motor

^{*}Contact LS ELECTRIC Customer Support before configuring the P2 (+) and N (-) terminals as the DC common source. There are a few factors that require special attention for this application.

Note

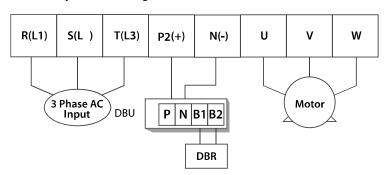
External DC reactors cannot be used with 30–75 kW inverters. To use a DC reactor with these inverters, purchase a 30–75 kW inverter that has a built-in DC reactor.

① Caution

- When a built-in DCR unit is present, the P1 (+) and P (-) terminals are connected to the reactor's input
 and output terminals respectively.
- If your product does not have a built-in DCR unit, the P2 (+) and N (-) terminals may be used as the common DC source. Do not use the P1 (+) terminal as the common DC source, as this may result in product damage.
- Use the P2 (+) and N (-) terminals to connect a dynamic braking resistor to the inverter. Do not connect the dynamic braking unit to the P1 (+) terminal, as this may result in product damage.
- Contact LS ELECTRIC Customer Support before configuring the N (-) terminal as the DC common source. There are a few factors that require special attention for this application.

4.6.3 90–160 kW (400 V)

Connect the cables from the dynamic braking unit to the P2 (+) and N (-) terminals to utilize an external dynamic braking unit.

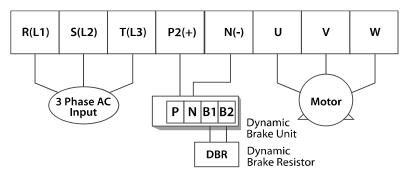


Terminal Symbol	Terminal Name	Description

Terminal Symbol	Terminal Name	Description	
R (L1), S (L2), T (L3)	AC power supply input terminals	AC input terminals	
N (-)	(-) DC voltage terminal	(-) DC link voltage terminal	
P2 (+), N (-)	Dynamic braking resistor terminal	Dynamic braking resistor terminals	
U. V. W	Inverter output terminals	Output terminals to a 3-phase induction	
O, v, vv	inverter output terminals	motor	

4.6.4 185-220 kW (400 V)

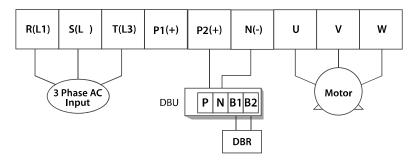
Connect the cables from the dynamic braking unit to the P2 (+) and N (-) terminals to utilize an external dynamic braking unit.



Terminal Symbol	Terminal Name	Description
R (L1), S (L2), T (L3)	AC power supply input terminals	AC input terminals
N (-)	(-) DC voltage terminal	(-) DC link voltage terminal
P2 (+), N (-)	Dynamic braking resistor terminal	Dynamic braking resistor terminals
U, V, W	Inverter output terminals	Output terminals to a 3-phase induction motor

4.6.5 280–375 kW (200 V/400 V)

Connect the cables from the dynamic braking unit to the P2 (+) and N (-) terminals to utilize the built-in dynamic braking unit.



Terminal Symbol	Terminal Name	Description
R (L1), S (L2), T (L3)	AC power supply input terminals	AC input terminals
P1 (+)	(+) DC voltage terminal	(+) DC link voltage terminal
P2/N (-)	Dynamic braking resistor terminal / DC common*	Dynamic braking resistor terminals
N (-)	(-) DC voltage terminal	(-) DC link voltage terminal
U, V, W	Inverter output terminals	Output terminals to a 3-phase induction motor

^{*}Contact LS ELECTRIC Customer Support before configuring the P2 (+) and N (-) terminals as the DC common source. There are a few factors that require special attention for this application.

① Caution

- Apply rated torques to the terminal screws. Loose screws may cause the terminals to short circuit and malfunction. Tightening the screws too much may damage the terminals and cause them to short circuit and malfunction.
- Only use copper wires with a 600 V, 75 °C rating for the power terminal wiring, and a 300 V, 75 °C rating for the control terminal wiring.
- Power supply wiring must be connected to the R, S, and T terminals. Connecting them to the U, V, W terminals causes internal damage to the inverter. The motor should be connected to the U, V, and W terminals. Arrangement of the phase sequence is not necessary.

4.7 Specifications of the Power Terminal Block and Exterior Fuse

				Cable ²⁾					
Inverter	capacity	Terminal	Screw torque ¹⁾	mm²		AWG or	kcmil	Exterior fuse	
	p,	screw size	(Kgf·cm)	R,S,T	U,V,W	R,S,T	U,V,W	Current	Voltage
	0.75 kW	M4	7.1–12	2.5	2.5	14	14	10 A	500 V
	1.5 kW	M4	7.1–12	2.5	2.5	14	14	15 A	500 V
	2.2 kW	M4	7.1–12	2.5	2.5	14	14	20 A	500 V
	3.7 kW	M4	7.1–12	4	4	12	12	32 A	500 V
	5.5 kW	M4	7.1–12	6	6	10	10	50 A	500 V
	7.5 kW	M4	7.1–12	10	10	8	8	63 A	500 V
	11 kW	M6	30.6–38.2	16	16	6	6	80 A	500 V
200V	15 kW	M6	30.6–38.2	25	25	4	4	100 A	500 V
	18.5 kW	M8	61.2-91.8	35	35	2	2	125 A	500 V
	22 kW	M8	61.2-91.8	50	50	1	1	160 A	500 V
	30 kW	M8	61.2 – 91.8	70	70	1/0	1/0	200 A	500 V
	37 kW	M8	61.2 – 91.8	95	95	2/0	2/0	250 A	500 V
	45 kW	M8	61.2 – 91.8	95	95	2/0	2/0	350 A	500 V
	55 kW	M10	89.7 – 122.0	120	120	3/0	3/0	400 A	500 V
	75 kW	M10	89.7 – 122.0	150	150	4/0	4/0	450 A	500 V
	0.75– 1.5kW	M4	7.1–12	2.5	2.5	14	14	10 A	500 V
	2.2 kW	M4	7.1–12	2.5	2.5	14	14	15 A	500 V
	3.7 kW	M4	7.1–12	2.5	2.5	14	14	20 A	500 V
	5.5 kW	M4	7.1–12	4	2.5	12	14	32 A	500 V
	7.5 kW	M4	7.1–12	4	4	12	12	35 A	500 V
	11 kW	M5	24.5–31.8	6	6	10	10	50 A	500 V
	15 kW	M5	24.5–31.8	10	10	8	8	63 A	500 V
	18.5 kW	M6	30.6–38.2	16	10	6	8	70 A	500 V
	22 kW	M6	30.6–38.2	25	16	4	6	100 A	500 V
	30 kW	M8	61.2–91.8	25	25	4	4	125 A	500 V
400V	37 kW	M8	61.2–91.8	25	35	4	2	125 A	500 V
400V	45 kW	M8	61.2–91.8	50	50	1	1	160 A	500 V
	55 kW	M8	61.2–91.8	70	70	1/0	1/0	200 A	500 V
	75 kW	M8	61.2–91.8	95	95	2/0	2/0	250 A	500 V
	90 kW	M12	182.4–215.0	100	100	4/0	4/0	350 A	500 V
	110 kW	M12	182.4–215.0	100	100	4/0	4/0	400 A	500 V
	132 kW	M12	182.4–215.0	150	150	300	300	450 A	500 V
	160 kW	M12	182.4–215.0	200	200	400	400	450 A	500 V
	185 kW	M12	182.4–215.0	200	200	400	400	620 A	500 V
	220 kW	M12	182.4–215.0	250	250	500	500	800 A	500 V
	280 kW	M12	182.4–215.0	325	325	650	650	1000 A	500 V
	315 kW	M12	182.4–215.0	2x200	2x200	2x400	2x400	1200 A	500 V
	375 kW	M12	182.4–215.0	2x250	2x250	2x500	2x500	1400 A	500 V

¹⁾ Apply rated torques to the terminal screws. Loose screws may cause the terminals to short circuit and malfunction.

2) Only use copper wires with a 600 V, 75°C rating for the power terminal wiring.

4.7.1 Cable Length between the Inverter and the Motor

The maximum cable lengths of the inverter and the motor are listed in <Table 1) Maximum cable length by inverter capacity>.

Make sure that the total cable length does not exceed 495 ft (150 m). For inverters with a capacity of less than 3.7 kW, ensure that the total cable length does not exceed 165 ft (50 m). Long cable runs can cause reduced motor torque in low frequency applications due to voltage drop. Long cable runs also increase a circuit's susceptibility to stray capacitance and may trigger over-current protection devices, or result in the malfunction of equipment connected to the inverter.

<Table 1) Maximum Cable Length by Inverter Capacity>

Inverter capacity	Up to 3.7 kW	5.5 kW or more
Maximum cable length	< 164 ft (50 m)	< 492 ft (150 m)

The following table lists maximum carrier frequencies available for model types with a rated capacity of 5.5 kW or more.

<Table 2) Maximum Carrier Frequency according to Cable Length>

Distance	< 165 ft (50 m)	< 330 ft (100 m)	> 330 ft (100 m)
Allowed Carrier Frequency	<15 kHz	<5 kHz	<2.5 kHz

Depending on the system layout and operating conditions at the installation site, high peak output voltage may result.

- a) If the output peak voltage is too high even when the motor cable length is shorter than the maximum recommended cable length for the inverter capacity:
 - use a motor with a high insulation rating.
 - install an output circuit filter (micro surge filter).
 - install a dv/dt filter, or a sine wave filter.
- b) If the cable length is too long:
 - use thicker cables to prevent voltage drop. [Voltage Drop (V) = [$\sqrt{3}$ X cable resistance (m Ω /m) X cable length (m) X current (A)] / 1000]
 - do not use 3-core cables.
 - use a lower carrier frequency.

4.7.2 Protective Measures for the Inverter and the Motor

The inverter output voltage pulse, regardless of the actual output frequency, is identical to the DC link voltage pulse, which has a very short rising time. When the power is transmitted through the output cables, the output peak voltage can rise up to twice the total DC link voltage (2.8 times the main power voltage).

If a switching device (a magnetic contactor or relay) is connected to the output side of the inverter, high-voltage surges may result whenever a switch is made, regardless of the length of the motor cable.

Such high-voltage surges can damage the inverter's output components (such as the current sensor), motor cables, and the motor itself. To protect the inverter and the motor from such damage caused by a high-voltage surge, do not install switching devices in the output side of the inverter. You can install an output reactor, dv/dt filter, or sine wave filter to protect the inverter and motor from a surge voltage.

An output surge with a high switching frequency and fast rising time causes a motor shaft current that runs through the motor bearing. It slowly corrodes the surface of the motor bearing, eventually seizing up the motor.

To decrease the motor shaft current and protect the motor insulation, refer to <Table 1) Maximum cable length by inverter capacity>. Install a dv/dt filter or sine wave filter if possible, regardless of the length of the motor cable.

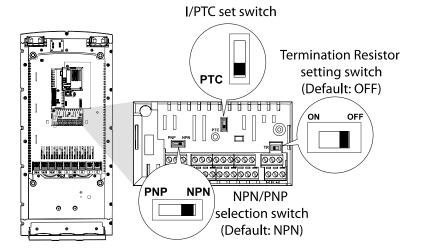
① Caution

Only use Class H or RK5 UL listed input fuses and UL listed breakers. See the table above for the voltage and current ratings for the fuses and breakers.

Utiliser UNIQUEMENT des fusibles d'entrée homologués de Classe H ou RK5 UL et des disjoncteurs UL. Se reporter au tableau ci-dessus pour la tension et le courant nominal des fusibless et des disjoncteurs.

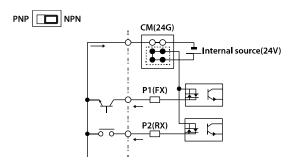
4.8 Control Terminal Wiring for iS7 Inverters Rated for Up To 22 kW

The iS7 inverter supports both PNP (Source) and NPN (Sink) modes for sequence inputs at the terminal. Select an appropriate mode to suit your requirements using the PNP/NPN selection switch above the control terminal block. Refer to the following information for detailed applications.



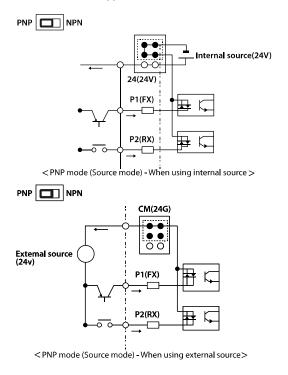
4.8.1 NPN Mode (Sink)

Select NPN using the PNP/NPN selection switch. The factory default setting is NPN mode. CM (24V GND) is the common ground terminal for all terminal inputs.



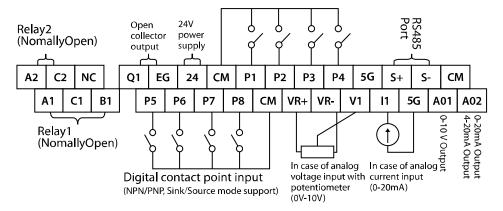
4.8.2 PNP Mode (Source)

Select PNP using the PNP/NPN selection switch. The factory default setting is NPN mode. CM (24 V GND) is the common ground terminal for all terminal inputs, and 24 is the 24 V internal source. If you are using an external 24 V source, select PNP (sink) mode and build a circuit that connects the external source (-) and the CM terminal.



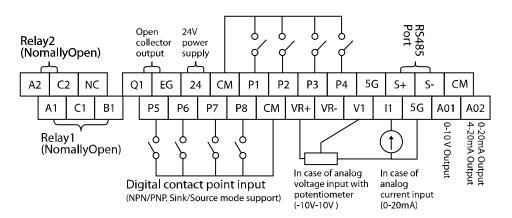
4.8.3 0.75-22 kW (Basic I/O)

Wiring Examples



Default Functions Assigned for the Multi-Function Terminals

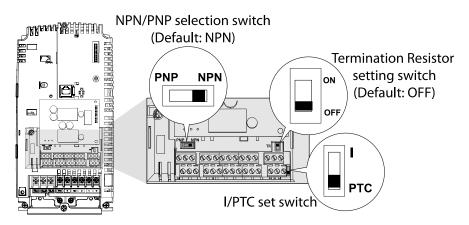
P1	P2	P3	P4	P5	P6	P7	P8
FX	RX	BX	RST	Sp-L	Sp-M	Sp-H	JOG



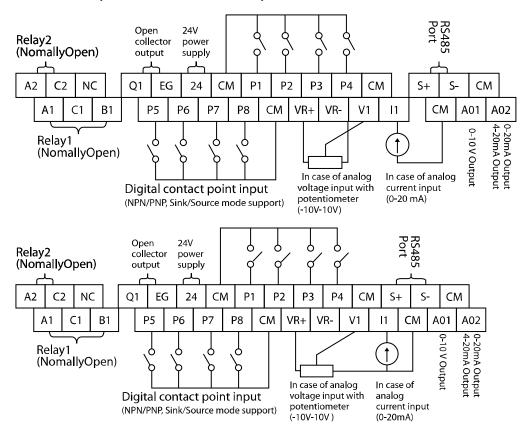
Note

- The TR (termination resistor) switch is used to terminate the RS485 network connection (120 Ω). Please turn on the TR switch of the last positioned Drive and turn off the TR switch of the remaining drives
- For analog voltage input, use a potentiometer rated at 0.5W, 1kOhm.
- Refer to 13 Table of Functions on page 381 for the multi-function terminal configurations.

4.9 Control Terminal Wiring for iS7 Inverters Rated for 30 kW or More



30-375 kW (control terminal block)



Note

- The TR (termination resistor) switch is used to terminate the RS485 network connection (120 Ω).
 Please turn on the TR switch of the last positioned Drive and turn off the TR switch of the remaining drives
- Use a potentiometer rated for 0.5 W, 1 kΩ.

If the analog voltage (V) or current (I) input is used to set the frequency reference, the analog input is reflected when the input is actually received. For instance, the voltage input 0 V at V1 does not indicate that no input is received at V1, but it means that 0 V input is actually received at V1.

Note

When you use the analog voltage input, the bipolar input range (-10 - +10V), in comparison to the unipolar input range (0-10V), allows for more accurate input control with smaller increments.

① Caution

If the analog input is interrupted when setting a frequency reference using the analog voltage (V) input and no voltage input is received at the terminal, an offset voltage may be applied to keep the frequency reference at approximately 4–5 Hz.

4.10 Terminal Inputs for Inverter Operation

Input	Туре	Symbol	Name	Description
	Terminal input	P1–P8	Multi-function input1–	Configurable for multi-function input terminals. Refer to <u>13 Table of Functions</u> on page <u>381</u> for the multi-function terminal configurations.
		СМ	Common sequence	Common terminal for terminal inputs (5G common terminal is used for analog frequency inputs only).
		VR(+)	Potentiometer frequency reference (+)	Used to setup or modify a frequency reference via the analog voltage or current input. Maximum output is +12 V, 100 mA.
Input signal		VR(-)	Potentiometer frequency reference (-)	Used to setup or modify a frequency reference via the analog voltage or current input. Maximum output is -12 V, 100 mA.
dul	Analog input	V1	Voltage input for frequency reference	Used to setup or modify a frequency reference via the analog voltage input terminal. Unipolar: 0–10 V Bipolar: -10–10 V Input resistance 20 kΩ
		l1	Current input for frequency reference	Used to setup or modify a frequency reference via the current input terminals. Input current: DC 0–20 mA Input resistance 249 Ω

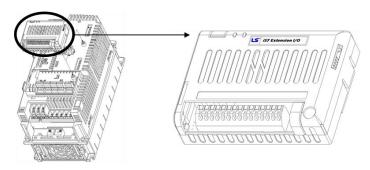
Input	Туре	Symbol	Name	Description	
		5G	Frequency setting common terminal	Common terminal for analog voltage and current terminals (CM common terminal is used for terminal inputs only).	
	Analog	AO1	Multi-function analog voltage output terminal	Used to send inverter output information to external devices. Output voltage: 0–10 V Maximum output voltage: 10 V Maximum output current: 10 mA	
0	output	AO2	Multi-function analog current output terminal	Used to send inverter output information to external devices. Output current: 4–20 mA (0–20 mA) Maximum output current: 20 mA	
		Q1	Multi-function terminal (open collector)	DC 26 V, below 100 mA	
ы	Output Signal	EG	Common terminal for open collector	Common ground contact for an open collector (with external power source).	
ıt Sigr		24	External 24 V power source	Maximum output current: 150 mA	
Outp		СМ	External 24 V common	Common ground contact for the external 24 V power source.	
	Terminal output	A1, B1,C1	Fault signal output	Sends out alarm signals when the inverter's safety features are activated (below AC 250 V 5 A, DC 30 V 5 A). Fault condition: A1 and C1 contacts are connected (B1 and C1 open connection) Normal operation: B1 and C1 contacts are connected (A1 and C1 open connection)	
		A2, C2	Multi-function relay2 output A contact	Outputs the signal while running. User defined multi- function output terminal. (<ac 250="" 30="" 5="" <="" a="" a)<="" dc="" td="" v,=""></ac>	
		S+,S- ,CM	RS-485 signal line	Used to send or receive RS-485 signals. Refer to <u>11</u> <u>Communication Function</u> on page <u>334</u> .	

4.11 Cable Specifications for Control Block Wiring

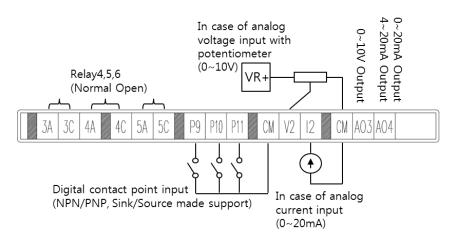
Terminal Name			size ¹⁾	Sussifications
Termina	INAME	mm ²	AWG	Specifications
P1–P8	Multi-function input terminal			-
CM	Common terminal input (5G common is used for analog frequency inputs only).			Common earth for multi-function input terminal
VR+	Analog frequency setting (+) power	0.33–	16–22	Output voltage: +12 V Maximum output voltage: 100 mA
VR-	Analog frequency setting (-) power	1.25	10-22	Output voltage: -12 V Maximum output voltage: 100 mA
V1	Multi-function analog voltage input terminal			Input voltage: 0–10 V or -10–10 V
I 1	Multi-function analog current input terminal			0–20 mA input Internal resistance: 249 Ω
AO1	Multi-function analog voltage output terminal			Maximum output voltage: 10 V Maximum output current: 10 mA
AO2	Multi-function analog current output terminal		14–22	Maximum output current: 20 mA
5G	Frequency setting common terminal (CM common terminal is used for terminal inputs only).	0.33– 2.0		Common terminal of analog frequency setting signal and analog current and voltage terminals
Q1	Multi-function terminal (open collector)			DC 26 V, below 100 mA
EG	Ground terminal for external power			Common terminal for an open collector external power source
24	External 24 V power supply	0.33-		Maximum output current: 150 mA
CM	24 V common	1.25	16–22	Common terminal for external 24 V power source
A1	Multi-function relay 1 output A			Below AC 250 V/5 A, Below DC 30 V/5 A
B1	Multi-function relay 1 output B			Below AC 250 V/5 A, Below DC 30 V/5 A
C1	Multi-function relay 1 common terminal	0.33– 2.0	14–22	Below AC 250 V/5 A, Below DC 30 V/5 A
A2	Multi-function relay 2 output A	2.0		Below AC 250 V/5 A, Below DC 30 V/5 A
C2	Multi-function relay 2 common terminal			Below AC 250 V/5 A, Below DC 30 V/5 A
S+,S-	RS485 signal input terminal			RS485 signal line
СМ	RS485 common terminal	0.75	18	For multi-connections, RS485 power ground (shield) connection terminal

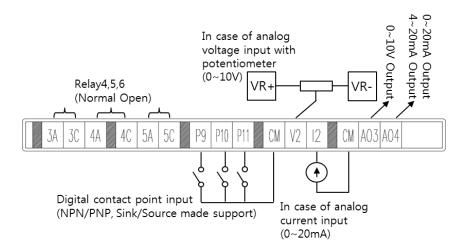
¹⁾ Use shielded, twisted-pair cables.

4.12 Control Terminal Wiring for iS7 Extension I/O (Optional)



Extension I/O (control terminal block)





4.13 Terminal Inputs for Inverter Operation

Input	Туре	Symbol	Name	Description		
	Terminal input	P9–P11	Multi-function input9– 11	Configurable for multi-function input terminals. Refer to <u>13 Table of Functions</u> on page <u>381</u> for the multi-function terminal configurations.		
		CM	Common sequence	Common terminal for terminal inputs		
Input signal	Analog	V2	Voltage input for frequency reference	Used to setup or modify a frequency reference via the analog voltage input terminal. Unipolar: 0–10 V Bipolar: -10–10 V Input resistance 20 kΩ		
	input	12	Current input for frequency reference	Used to setup or modify a frequency reference via the current input terminals. Input current: DC 0–20 mA Input resistance 249 Ω		
	Analog	AO3	Multi-function analog voltage output terminal	Used to send inverter output information to external devices. Output voltage: -10–10 V Maximum output voltage: 10 V Maximum output current: 10 mA		
Output Signal	output	AO4	Multi-function analog current output terminal	Used to send inverter output information to external devices. Output current: 4–20 mA (0–20 mA) Maximum output current: 20 mA		
Outpu		1.3A 3(.	Multi-function relay3 output A contact	Outhoute the circulation manipul Heaviletined multi		
	Terminal	4A, 4C	Multi-function relay4 output A contact	Outputs the signal while running. User defined multi- function output terminal. (<ac 250="" 30="" 5="" <="" a="" a)<="" dc="" td="" v,=""></ac>		
	output	5A, 5C	Multi-function relay5 output A contact	(\AC 250 V, 5A/\ DC 50 V, 5A)		
		СМ	External 24 V common	Common ground contact for the external 24V power source.		

4.14 Cable Specifications for Control Block Wiring

Termina	Terminal Name			Specifications
P9– P11	Multi-function input terminal			-
СМ	Common terminal input (5G common is used for analog frequency inputs only).			Common earth for multi-function input terminal
V2	Multi-function analog voltage input terminal			Input voltage: 0–10 V or -10–10 V
12	Multi-function analog current input terminal			0–20 mA input Internal resistance: 249 Ω
AO3	Multi-function analog voltage output terminal			Maximum output voltage: 10 V Maximum output current: 10 mA
AO4	Multi-function analog current output terminal	0.33– 1.25	16–22	Maximum output current: 20 mA
СМ	24 V common			Common terminal for external 24 V power source
3A	Multi-function relay 3 output A			Below AC 250 V/5 A, Below DC 30 V/5 A
3C	Multi-function relay 3 common terminal			Below AC 250 V/5 A, Below DC 30 V/5 A
4A	Multi-function relay 4 output A			Below AC 250 V/5 A, Below DC 30 V/5 A
4C	Multi-function relay 4 common terminal			Below AC 250 V/5 A, Below DC 30 V/5 A
5A	Multi-function relay 5 output A			Below AC 250 V/5 A, Below DC 30 V/5 A
5C	Multi-function relay 5 common terminal			Below AC 250 V/5 A, Below DC 30 V/5 A

²⁾ Use shielded, twisted-pair cables.

4.15 Setting the Built-in Surge Filter

The iS7 series inverters have a built-in surge filter between the input phases and the ground connection to absorb and mitigate surge current. This filter consists of a Y-CAP and multiple varistors.

However, in a non-grounded power system where specific ground faults occur frequently, adequate measures are required to avoid inverter damage.

Refer to the following table for details on how to prevent damage to specific power systems.

Power supply system and ground type	Varistors and Y-CAP connection	Effect
Directly grounded system	2-pin connector (on)	Reduced voltage stress and noise
Non-grounded or impedance ground system	2-pin connector (off)	Reduced risk of inverter damage if ground fault occurs

Note

Not EMC Filter built-in type 0.75–22 KW (200/400 V) products do not support this function.

① Caution

- You can deactivate the built-in surge filter if there is no risk of surge voltage occurring in the system.
- In order to prevent accidents, remove the jumper switch after the internal voltage of the inverter is completely discharged.

4.16 Activating or Deactivating the Surge Filter

4.16.1 iS7 30-75KW (400 V) Inverters

Contact LS ELECTRIC Customer Support and ask for assistance to deactivate the built-in surge filter for the 30-75 KW (400 V) inverters.

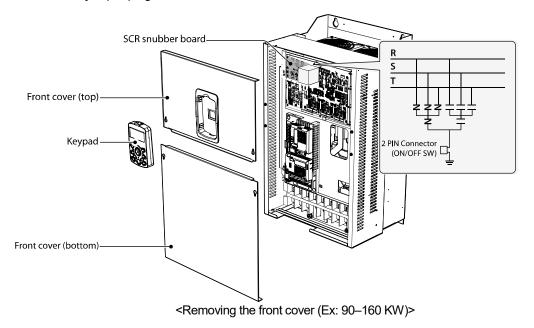
4.16.2 iS7 90-375 kW (400V) Inverters

Remove the keypad and the screws from the front cover, and then remove the front cover.

① Caution

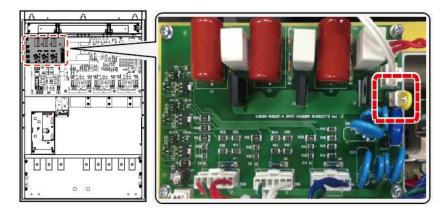
Be careful not to open the front cover with the keypad attached, as this can damage the keypad cable.

Refer to the figure below and locate the SCR snubber board. On the circuit board, activate or deactivate the surge filter by connecting the two jumper pins or breaking the connection between the two pins using a jumper plug. The filter is turned on when the jumper plug is installed, and it is turned off when the jumper plug is removed.

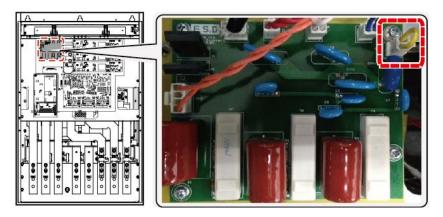


Refer to the following figures to locate the jumper switch on the SCR snubber board and install or remove the jumper cap to activate or deactivate the built-in surge filter.

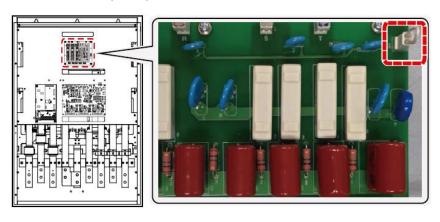
SV900-1600iS7 (400 V)



SV1850-2200iS7 (400 V)



SV2800-3750iS7 (400 V)



4.17 Post-Installation Checklist

After completing the installation, check the items in the following table to make sure that the inverter has been safely and correctly installed.

Items	Check Point	Result
	Is the installation location appropriate?	
Installation	Does the environment meet the inverter's operating conditions?	
Location/Power I/O Verification	Does the power source match the inverter's rated input?	
70 verification	Is the inverter's rated output sufficient to supply the equipment? (Certain circumstances will result in degraded performance.	
	Is a circuit breaker installed on the input side of the inverter?	
	Is the circuit breaker correctly rated?	
	Are the power source cables correctly connected to the R/S/T terminals of the inverter? (Caution: connecting the power source to the U/V/W terminals may damage the inverter.)	
	Are the motor output cables connected in the correct phase rotation (U/V/W)? (Caution: motors will rotate in the reverse direction if three-phase cables are not wired in the correct phase rotation.)	
Power Terminal	Are the cables used in the power terminal connections correctly rated?	
Wiring	Is the inverter grounded correctly?	
	Are the power terminal screws and the ground terminal screws tightened to their specified torques?	
	Are the overload protection circuits installed correctly on the motors (if multiple motors are run using one inverter)?	
	Is the inverter separated from the power source by a magnetic contactor (if a braking resistor is in use)?	
	Are advanced-phase capacitors, surge protection, and electromagnetic interference filters installed correctly? (These devices MUST not be installed on the output side of the inverter.)	
	Are STP (shielded twisted pair) cables used for control terminal wiring?	
	Is the shielding of the STP wiring properly grounded?	
Control Terminal	If 3-wire operation is required, are the multi-function input terminals defined prior to the installation of the control wiring connections?	
Wiring	Are the control cables properly wired?	
	Are the control terminal screws tightened to their specified torques?	
	Is the total cable length of all control wiring < 328 ft (100 m) for model types	

Items	Check Point	Result
	rated at 3.7 kW and below, and 984 ft (300 m) for model types rated at more than 3.7 kW?	
	Is the total length of safety wiring < 100 ft (30 m)?	
	Are optional modules connected correctly?	
	Is there any debris left inside the inverter?	
Miscellaneous	Are any cables contacting adjacent terminals, creating a potential short circuit risk?	
	Are the control terminal connections separated from the power terminal connections?	
	Have the capacitors been replaced if they have been in use for > 2 years?	
	Has a fuse been installed for the power source?	
	Are the connections to the motor separated from other connections?	

Note

STP (Shielded Twisted Pair) cables have a highly conductive, shielded screen around twisted-pair cables. STP cables protect conductors from electromagnetic interference.

4.18 Test Run

When you turn on the iS7 inverter for the first time, it starts in Easy Start mode to help you configure the basic parameters required for inverter operation.

4.18.1 Entering Easy Start Mode

The inverter starts in Easy Start mode when you turn on the inverter for the first time, or when the inverter is turned on following a parameter initialization.

Note

- Before setting the parameter values for a user application, initialize the parameter settings to make sure that the default setting is applied to all parameters.
- If you initialized all parameters after an inverter trip occurred, the inverter starts in Easy Start mode after it is reset, regardless of the pending trip condition.
- Easy Start mode is not available while the inverter is already running.

4.18.2 Setting the Basic Parameters in Easy Start Mode

Refer to the following sequence table to understand the Easy Start sequence and configure the basic parameters according to the instructions.

Sequence	Instruction
Start Easy Set	Select "Yes" to start the inverter in Easy Start mode (select "No" to start the inverter in Monitor mode).
CNF-01 Language Sel	Select the keypad display language (only English is available at the moment).
DRV-14 Motor Capacity	Set the motor capacity. (Ex: 0.75 kW, 1.5 kW)
BAS-11 Pole Number	Set the number of poles in the motor.
BAS-15 Rated Volt	Set the rated motor voltage. Set this value to "0 V" if the rated motor voltage is identical to the input voltage.
BAS-10 60/50 Hz Sel	Set the rated motor frequency.
BAS19 AC Input Volt	Set the inverter input voltage.
DRV-06 Cmd Source	Set the source of the frequency reference. (Ex: KEYPAD, FX/RX-1, FX/RX-2, etc.)
DRV-01 Cmd Frequency	Set the frequency reference. (Ex: 50 Hz, 60 Hz, etc.)

Note

While you are in Easy Start mode, you can press the [ESC] key on the keypad to cancel Easy Start mode and enter Monitor mode.

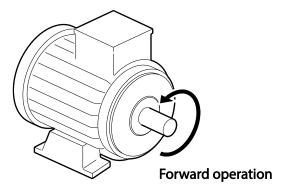
4.18.3 Checking the Inverter Operation

① Caution

Using an inverter, you can easily operate a motor at a high speed. Before operating a motor using an inverter, ensure that the set speed is within the motor's rated speed.

Follow the instructions to ensure that the motor operates correctly according to the inverter settings, and adjust the settings if required.

- 1 Set DRV-06 (CMD source) to "0 (KEYPAD)."
- 2 Set DRV-07 (Freq Ref Src) to "0 (Keypad-1)."
- 3 Set DRV-01 (CMD Frequency) to a temporary speed (Ex: 60 Hz).
- 4 Press the FWD key on the keypad, and ensure that the motor is rotating in the correct direction. When the forward command (Fx) is on, the motor should rotate counterclockwise when viewed from the load side of the motor. If the motor rotates in the reverse direction, switch the cables at the U and V terminals.



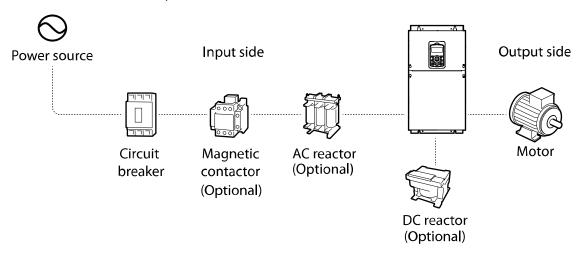
① Caution

Ensure that the input power is within the inverter's rated input voltage range during operation.

Peripheral Devices

The reference diagram below shows a typical system configuration showing the inverter and peripheral devices.

Prior to installing the inverter, ensure that the product is suitable for the application (power rating, capacity, etc.). Also, ensure that all of the required peripherals and optional devices (resistor brakes, contactors, noise filters, etc.) are available.



Caution

- Figures in this manual are shown with covers or circuit breakers removed to show a more detailed view of the installation arrangements. Install covers and circuit breakers before operating the inverter. Operate the product according to the instructions in this manual.
- Supply input power within the voltage range approved for the inverter's rating.
- Do not start or stop the inverter using a magnetic contactor installed in the input power supply.
- If the inverter is damaged and loses control, the machine may cause a dangerous situation. Install an additional safety device, such as an emergency brake, to prevent these situations.
- High levels of current draw during power-on can affect the system. Ensure that correctly rated circuit breakers are installed to operate safely during power-on situations.
- Reactors can be installed to improve the power factor. Note that reactors may be installed within 32.8 ft (10 m) of the power source if the input power exceeds 1000 kVA.
- 400 V class inverters require a motor with reinforced insulation. Micro surge voltages generated at the motor terminals may deteriorate the motor insulation.

Wiring Switch, Electronic Contactor, and Reactor 5.1 **Specifications**

5.1.1 Wiring Switch, Short Circuit Switch, and Electronic Contactor

	Wiring Switch				Short Circuit Switch		Electronic Contactor	
Inverter	METASOL		SUSOL SHORT CIRCUIT SWITCH Electronic Conta		ontactor			
Capacity	Model	Rated	Model	Rated	Model	Rated	Model	Rated
	Model	current[A]	Model	current[A]	Model	current[A]	wodei	current[A]
0008iS7-2	ABS33c	15	UTE100	15	EBS33c	15	MC-9b	11
0015iS7-2	ABS33c	15	UTE100	15	EBS33c	15	MC-12b	13
0022iS7-2	ABS33c	30	UTE100	30	EBS33c	30	MC-18b	18
0037iS7-2	ABS33c	30	UTE100	30	EBS33c	30	MC-32a	32
0055iS7-2	ABS53c	50	UTS150	50	EBS53c	50	MC-40a	40
0075iS7-2	ABS63c	60	UTS150	60	EBS63c	60	MC-50a	55
0110iS7-2	ABS103c	100	UTS150	100	EBS103c	100	MC-65a	65
0150iS7-2	ABS103c	125	UTS150	125	EBS203c	125	MC-100a	105
0185iS7-2	ABS203c	150	UTS150	150	EBS203c	150	MC-130a	130
0220iS7-2	ABS203c	175	UTS250	175	EBS203c	175	MC-150a	150
0300iS7-2	ABS203c	225	UTS250	225	EBS203c	225	MC-150a	150
0370iS7-2	ABS403c	300	UTS400	300	EBS403c	300	MC-225a	225
0450iS7-2	ABS403c	350	UTS400	350	EBS403c	350	MC-330a	330
0550iS7-2	ABS603c	500	UTS600	500	EBS603c	500	MC-400a	400
0750iS7-2	ABS603c	630	UTS600	600	EBS603c	630	MC-630a	630
0008iS7-4	ABS33c	15	UTE100	15	EBS33c	15	MC-9b	9
0015iS7-4	ABS33c	15	UTE100	15	EBS33c	15	MC-9b	9
0022iS7-4	ABS33c	15	UTE100	15	EBS33c	15	MC-12b	12
0037iS7-4	ABS33c	15	UTE100	15	EBS33c	15	MC-18b	18
0055iS7-4	ABS33c	30	UTE100	30	EBS33c	30	MC-22b	22
0075iS7-4	ABS33c	30	UTE100	30	EBS33c	30	MC-32a	32
0110iS7-4	ABS53c	50	UTS150	50	EBS53c	50	MC-40a	40
0150iS7-4	ABS63c	60	UTS150	60	EBS63c	60	MC-50a	50
0185iS7-4	ABS103c	80	UTS150	80	EBS103c	75	MC-65a	65
0220iS7-4	ABS103c	100	UTS150	100	EBS103c	100	MC-65a	65
0300iS7-4	ABS103c	125	UTS150	125	EBS203c	125	MC-100a	105
0370iS7-4	ABS203c	150	UTS150	150	EBS203c	150	MC-130a	130
0450iS7-4	ABS203c	175	UTS250	175	EBS203c	175	MC-150a	150
0550iS7-4	ABS203c	225	UTS250	225	EBS203c	225	MC-185a	185
0750iS7-4	ABS403c	300	UTS400	300	EBS403c	300	MC-225a	225
0900iS7-4	ABS403c	400	UTS400	400	EBS403c	400	MC-330a	330
1100iS7-4	ABS603c	500	UTS600	500	EBS603c	500	MC-400a	400
1320iS7-4	ABS603c	630	UTS600	600	EBS603c	630	MC-400a	400
1600iS7-4	ABS603c	630	UTS600	600	EBS603c	630	MC-630a	630
1850iS7-4	ABS803c	800	UTS800	800	EBS803c	800	MC-630a	630

	Wiring Switch			Short Circuit Switch		Electronic Contactor		
Inverter	METASOL		SUSOL		Short Circuit Switch		Electronic Contactor	
Capacity	Model	Rated current[A]	Model	Rated current[A]	Model	Rated current[A]	Model	Rated current[A]
2200iS7-4	ABS803c	800	UTS800	800	EBS803c	800	MC-800a	800
2800iS7-4	ABS1003b	1000	UTS120 0	1000	EBS1003c	1000	1000A	1000
3150iS7-4	ABS1203b	1200	UTS120 0	1200	EBS1203c	1200	1200A	1200
3750iS7-4	1400A	1400	1400A	1400	1400A	1400	1400A	1400

① Caution

Only use Class H or RK5 UL listed input fuses and UL listed breakers. See the table above for the voltage and current ratings for the fuses and breakers.

Utiliser UNIQUEMENT des fusibles d'entrée homologués de Classe H ou RK5 UL et des disjoncteurs UL. Se reporter au tableau ci-dessus pour la tension et le courant nominal des fusibless et des disjoncteurs.

Note

- If you install the recommended reactors, you can maintain the power factor above 85%, and keep the THD below 40% for operations at the rated load. Improvements are reduced at lighter loads.
- Cable impedance affects the input power factor and occurrence of harmonic waves. The input power factor and THD improvement of the reactors may be lower depending on the transformer capacity, the transformer impedance, and the cable length.
- Refer to the specifications table and install recommended reactors. Although a higher inductance value (L) of the reactor results in an improvement in the power factor and better suppression of harmonic effects, power loss increases at the same time due to voltage drop.
- The capacity of built-in DC reactors in some iS7 inverter models is based on the normal duty load factor. Therefore, improvements may be reduced during a heavy duty operation.

5.1.2 Reactors

DC Reactor Specifications

The iS7 200 V/ 400 V 30–75 kW, 400 V/280–375 kW models are not supplied with a built-in DC reactor. Refer to the following specifications tables for different models to choose an appropriate DC reactor for your application.

<200V/30-75kW>

Inverter conceity	DC reactor specifications			
Inverter capacity	mH	A		
0300iS7-2	0.24	200		
0370iS7-2	0.2	240		
0450iS7-2	0.17	280		
0550iS7-2	0.12	360		
0750iS7-2	0.1	500		

<400V/30-75kW>

(For Non-DCR products, remove the P1 and P2 shorting pins to install the DC reactor.)

Invertor conscitu	DC reactor specifications			
Inverter capacity	mH	Α		
0300iS7-4	0.98	75		
0370iS7-4	0.87	90		
0450iS7-4	0.55	110		
0550iS7-4	0.47	150		
0750iS7-4	0.48	180		

<400V/280-375 kW>

Invertor consoity	DC reactor specifications			
Inverter capacity	mH	A		
2800iS7-4	0.09	836		
3150iS7-4	0.076	996		
3750iS7-4	0.064	1195		

Note

All iS7 models, other than the 200 V/30-75 kW and 400 V/280-375 kW models, may be provided with an optional built-in DC reactor.

AC Reactor Specifications

You can install an AC reactor to prevent the capacitors and generators from overheating or being damaged when the power source voltage is unbalanced.

When you install an AC reactor, connect the AC reactor cables to the R, S, and T terminals on the inverter. Installation of an AC reactor is not necessary if a DC reactor is already installed in the inverter.

To avoid power loss resulting from the incorrect installation of an AC reactor, contact LS ELECTRIC Customer Support to ensure that your model type and application requires the installation of an AC reactor.

Refer to the following specifications tables to choose an appropriate AC reactor for your application.

	AC reactor specifications				
Inverter capacity	Heavy duty		Normal duty		
	mH	Α	mH	А	
0008iS7-2	2.13	5.7	1.20	10	
0015iS7-2	1.20	10	0.88	14	
0022iS7-2	0.88	14	0.56	20	
0037iS7-2	0.56	20	0.39	30	
0055iS7-2	0.39	30	0.28	40	
0075iS7-2	0.28	40	0.20	59	
0110iS7-2	0.20	59	0.15	75	
0150iS7-2	0.15	75	0.12	96	
0185iS7-2	0.12	96	0.10	112	
0220iS7-2	0.10	112	0.07	160	
0300iS7-2	0.07	160	0.05	200	
0370iS7-2	0.05	200	0.044	240	
0450iS7-2	0.044	240	0.038	280	
0550iS7-2	0.038	280	0.026	360	
0750iS7-2	0.026	360	0.02	500	
0008iS7-4	8.63	2.8	4.81	4.8	
0015iS7-4	4.81	4.8	3.23	7.5	
0022iS7-4	3.23	7.5	2.34	10	
0037iS7-4	2.34	10	1.22	15	
0055iS7-4	1.22	15	1.14	20	
0075iS7-4	1.14	20	0.81	30	

	AC reactor specifications				
Inverter capacity	Heavy duty		Normal duty		
	mH	A	mH	A	
0110iS7-4	0.81	30	0.61	38	
0150iS7-4	0.61	38	0.45	50	
0185iS7-4	0.45	50	0.39	58	
0220iS7-4	0.39	58	0.287	80	
0300iS7-4	0.287	80	0.232	98	
0370iS7-4	0.232	98	0.195	118	
0450iS7-4	0.195	118	0.157	142	
0550iS7-4	0.157	142	0.122	196	
0750iS7-4	0.122	196	0.096	237	
0900iS7-4	0.096	237	0.081	289	
1100iS7-4	0.081	289	0.069	341	
1320iS7-4	0.069	341	0.057	420	
1600iS7-4	0.057	420	0.042	558	
1850iS7-4	0.042	558	0.042	558	
2200iS7-4	0.042	558	0.029	799	
2800iS7-4	0.029	799	0.029	799	
3150iS7-4	0.029	799	0.024	952	
3750iS7-4	0.024	952	0.024	952	

5.1.3 Dynamic Braking Unit (DBU) and Resistor

Dynamic Braking Unit Specifications

UL form	Voltage	Capacity of applied motor	Braking unit	Reference-Terminal arrangement & dimensions
		30–37 kW	SV370DBU-2U	
	200 V	45–55 kW	SV550DBU-2U	
		75 kW	SV370DBU-2U, 2Set	
		30–37 kW	SV370DBU-4U	
UL type		45–55 kW	SV550DBU-4U	Group 1
	400 \	75 kW	SV750DBU-4U	
	400 V	90 kW	SV550DBU-4U, 2Set	
		110–132 kW	SV750DBU-4U, 2Set	
		160 kW	SV750DBU-4U, 3Set	
	400 V	45–55 kW, 75 kW	SV075DB-4	Group 3
		185–220 kW	SV2200DB-4 Note 1)	0
		280–375 Kw	SV2200DB-4, 2Set	Group 4
	2221	20 27 144/	LSLV0370DBU-2LN	Group 5
		200.17	30–37 kW	LSLV0370DBU-2HN
	200 V	45–55 kW,	LSLV0750DBU-2LN	Group 5
		75 kW	LSLV0750DBU-2HN	Group 6
Non III tuno	•	20. 27 144	LSLV0370DBU-4LN	Group 5
Non UL type		30–37 kW	LSLV0370DBU-4HN	Group 6
		45–55 kW,	LSLV0750DBU-4LN	Group 5
		75 kW	LSLV0750DBU-4HN	Group 6
	400 V	90 kW	LSLV0900DBU-4HN	
	.55 %	110–132 kW	LSLV1320DBU-4HN	
		160 kW	LSLV1600DBU-4HN	Group 6
		185–220 kW	LSLV2200DBU-4HN	
		280–375 kW	LSLV2200DBU-4HN, 2Set	

Note 1) For model types with a rated capacity of 180 kW and above, contact LS ELECTRIC Customer Support for detailed information.

Note

- The 0.75–22kW (200 V/400 V) models are provided with a built-in dynamic braking unit. Installation of additional dynamic braking units is not necessary for these models.
- Refer to the instruction manual provided by the manufacturer before installing a dynamic braking unit. There may be specification changes that are not reflected in the table provided with this manual.
- For detailed specifications of UL type DB units, such as resistance/wattage/braking torque/%ED, refer to the table in <u>5.1.6 DB Resistors</u> on page <u>102</u>. For non UL type DB units, refer to the instruction manual provided by the manufacturer.

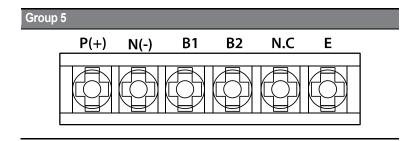
DBU Terminal Arrangement

Group 1						Group 2				
P N	G	B1	B2		G	N	B2	P/B1		

Terminal	Description
G	Ground Terminal
B2	Connect to the B2 terminal of a braking resistor.
B1	Connect to the B1 terminal of a braking resistor.
N	Connect to the N terminal of an inverter.
Р	Connect to the P1 terminal of an inverter.

Group 3 (75 kW DB unit)	Group 4 (220 kW DB unit)		
	$ \begin{array}{c c} & & & & G \\ & \otimes & & \otimes \\ \hline \otimes & & \otimes & & \otimes \\ P & \otimes & B1 & \otimes & & \otimes \\ \hline \otimes & & \otimes & & \otimes \\ \hline & & \otimes & & \otimes \\ \hline \end{array} $		

Terminal	Description
G	Ground Terminal
B2	Connect to the B2 terminal of a braking resistor.
B1	Connect to the B1 terminal of a braking resistor.
N	Connect to the N terminal of an inverter.
Р	Connect to the P terminal of an inverter.



Terminal	Description				
P (+)	Connect to the P terminal of an inverter.				
N (-)	Connect to the N terminal of an inverter.				
B1	Connect to the B1 terminal of a braking resistor.				
B2	Connect to the B2 terminal of a braking resistor.				
N.C	Not used				
Е	Ground terminal				

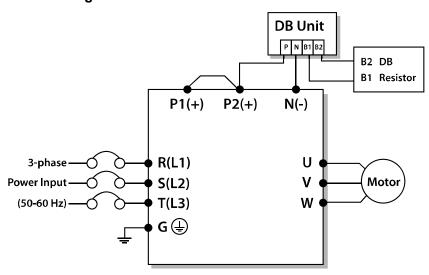
Group 6 A frame (37 kW, 75 kW-4) P(+) N(-) B1 B2 N.C E P(+) N(-) B1 B2 D R.C E

Terminal	Description
P (+)	Connect to the P terminal of an inverter (DC bus).
N (-)	Connect to the N terminal of an inverter (DC bus).
B1	Connect to the B1 terminal of an external braking resistor.
B2	Connect to the B2 terminal of an external braking resistor.
N.C	Not used
Е	Ground terminal

Note

Refer to the instruction manual that is supplied with the DB unit to choose appropriate DB resistors for installation.

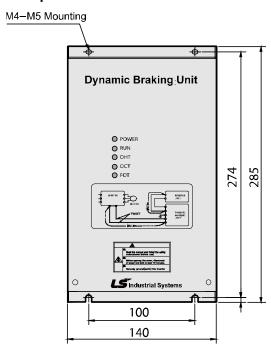
Basic Wiring Connection for the DB Unit and DB Resistor

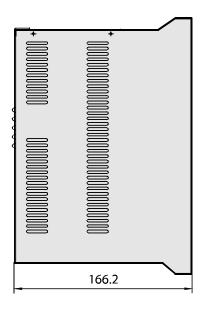


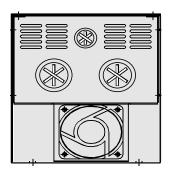
DB Unit Terminal Description

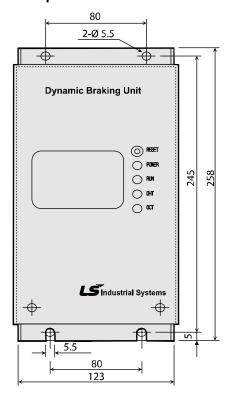
DB Unit Terminal	Description
B1	Connect to the B1 terminal of a DB resistor.
B2	Connect to the B2 terminal of a DB resistor.

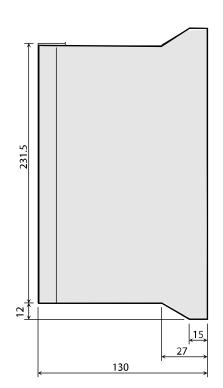
5.1.4 DB Unit Dimensions

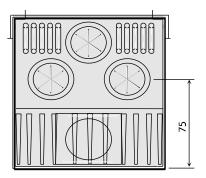


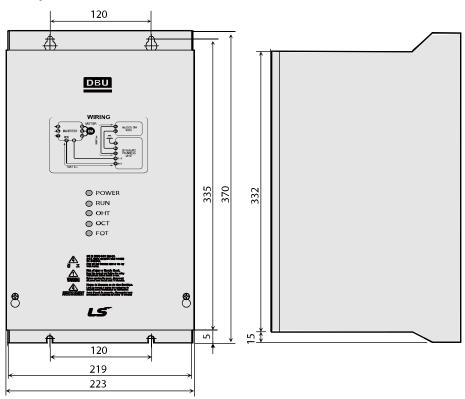


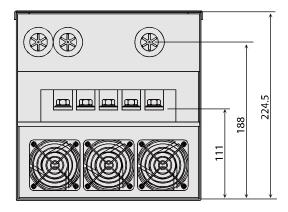


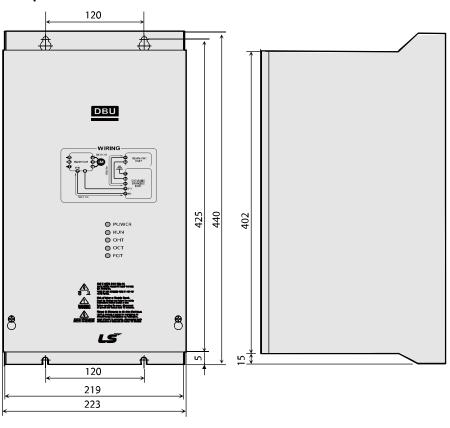


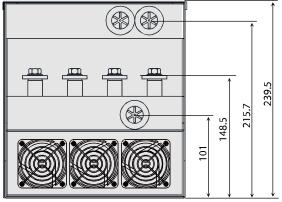


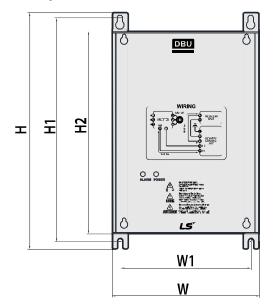


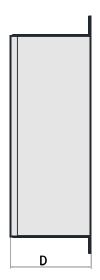


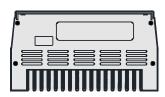




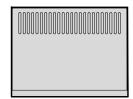


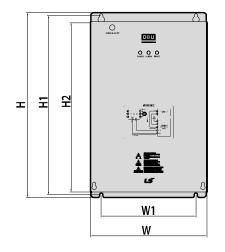


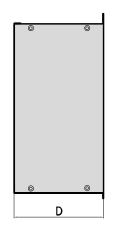


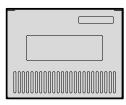


Voltage	Motor capacity	Dimensions (mm)				Hole position		Weight	Hole size
[V]	[kW]	W	Н	H2	D	W1	H1	[kg]	(φ)
	15					125		1.50	
220	22		227.4	192	76.4		215.4	1.55	- M4
220	37	140						1.57	
	75							1.84	
	15							1.53	
440	22							1.55	
440	37							1.56	
	75							1.85	









Frame	Voltage	Motor capacity	%ED	Dimensions (mm)			Hole position		Weight	Hole size	
	[V]	[kW]		W	Н	H2	D	W1	H1	[kg]	(φ)
Α	220	37	50					160	208.5	3.77	
	440	37	50	200	219	190	165.2			3.84	M6
		75	50							3.98	
	220	75	50	215	340	311		175	329.5	8.26	
В		90	50							8.48	
Ь	440	90	50							8.30	
	440	132	50							8.40	
С	440	160	50	240	380	351		200	369.5	9.40	
	440	220	50	240		301			309.5	9.70	

5.1.5 Indicators on the DB unit

On a DB unit, there are three LED indicators (one red and two green indicators) that indicate the operating condition of the DB unit.

Indicator name	Color	Location	Description					
Power indicator	Red	Middle	Turns on when the main power is supplied to the unit (if a DB un is connected to an inverter, the power indicator is turned on when the main power is supplied to the inverter).					
RUN indicator	Green	Right	Turns on when the DB unit is regenerating.					
OHT indicator	Green LLeft		Turns on when the overheating protection function is enabled. If the DB unit temperature exceeds the maximum allowed operating temperature, the overheating protection function is activated to cut off the input to the DB unit (the power indicator on the DB unit is turned off).					

5.1.6 **DB Resistors**

The following table lists type A DB unit specifications for your reference. For type B and type C DB unit specifications, refer to the instruction manuals that are supplied with the DB units.

Before installing a DB resistor, refer to the instruction manuals provided by the manufacturer to choose an appropriate type of DB resistor.

Note

When you double the duty cycle (%ED) of a DB unit, the wattage ratings of the optional DB resistor must be doubled accordingly.

	Inverter capacity (kW)	Resistance [ohm]	Wattage [W]	Туре	Reference	Wiring [mm²]	Model Type
	0.75	150	150	-		1.25	-
	1.5	60	300	-		1.25	-
	2.2	50	400	TYPE 1		2.5	MCRF400W50
2	3.7	33	600	TYPE 2	150%	2.5	MCRF600W33
2	5.5	20	800	TYPE 3	braking	2.5	MCRF800W20
0	7.5	15	1200	TYPE 5	torque,	4	MCRF1200W15
V	11	10	2400	TYPE 6	5%ED	4	MCRF-ST2400W10
С	15	8	2400	TYPE 6		10	MCRF-ST2400W8
Ī	18.5	5	3600	TYPE 7		20	MCRF-ST3600W5
а	22	5	3600	TYPE 7		20	MCRF-ST3600W5
S	30	5	5000	-		-	-
5	37	4.5	7000	-	100%	-	-
	45	3.5	10000	-	braking torque,	-	-
	55	3.0	15000	-	10%ED	-	-
	75	2.5	20000	-		-	-
	0.75	600	150	-		1.25	-
	1.5	300	300	-		2	-
	2.2	200	400	TYPE 1		2.5	MCRF400W200
	3.7	130	600	TYPE 2	150%	2.5	MCRF600W130
	5.5	85	1000	TYPE 4	braking	2.5	MCRF1000W85
	7.5	60	1200	TYPE 5	torque,	2.5	MCRF1200W60
	11	40	2000	TYPE 6	5%ED	2.5	MCRF-ST2000W40
	15	30	2400	TYPE 6		4	MCRF-ST2400W30
4	18.5	20	3600	TYPE 7		6	MCRF-ST3600W20
0	22	20	3600	TYPE 7		6	MCRF-ST3600W20
V	30	16.9	6,400	-		-	-
С	37	16.9	6,400	-		-	-
ı	45	11.4	9,600	-		-	-
а	55	11.4	9,600	-		-	-
s s	75	8.4	12,800	-		-	-
5	90	4.5	15,000	-	100%	-	-
	110	3.5	17,000	-	braking torque,	-	-
	132	3,0	20,000	-	10%ED	-	-
	160	2.5	25,000	-		-	-
	185	2	30,000	-		-	-
	220	2	30,000	-		-	-
	280	1.5	40,000	-		-	-
	315	1	60,000	-		-	-

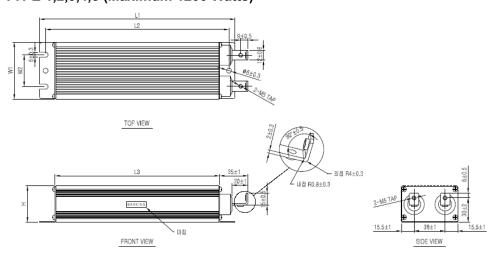
Inverter capacity (kW)	Resistance [ohm]	Wattage [W]	Туре	Reference	Wiring [mm²]	Model Type
375	1	60,000	-		-	-

① Caution

- If you install multiple DB units in parallel, the combined resistance value must match the resistance value in the table above.
- If an appropriate braking resistor type is not listed in the table, find a braking resistor with equivalent resistance and wattage values that are suggested in the table above.

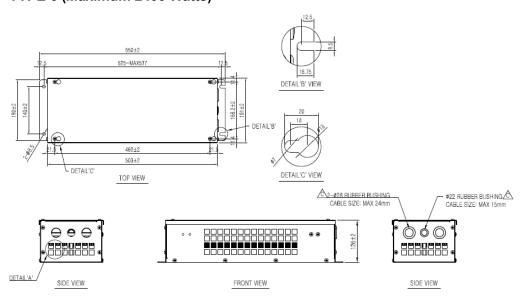
DB Resistor Dimensions

TYPE 1,2,3,4,5 (Maximum 1200 Watts)

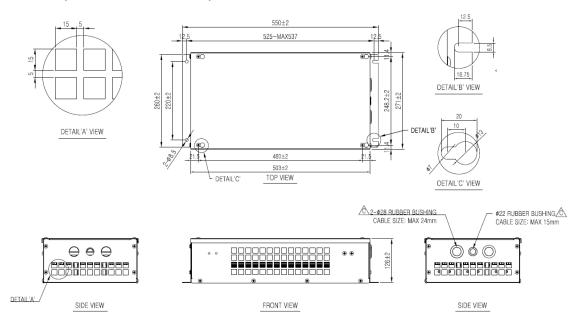


TYPE	Size [mn	Size [mm]						
	W	Н	D	Α	В	С		
1	220	175	152	70	39	45		
2	260	245	222	70	39	45		
3	300	285	262	70	39	45		
4	340	325	302	70	39	45		
5	400	385	362	70	39	45		

TYPE 6 (Maximum 2400 Watts)

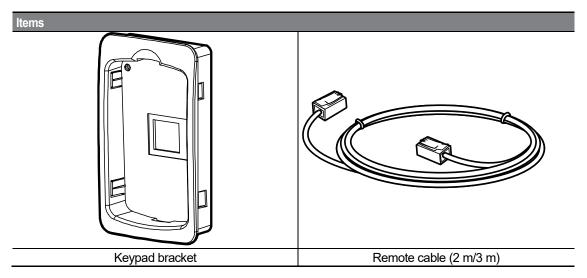


TYPE 7 (Maximum 3600 Watts)

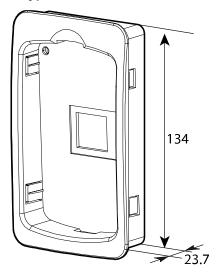


5.1.8 Keypad Extension Cable for Remote Control (Optional)

Included items



Keypad Bracket Dimensions

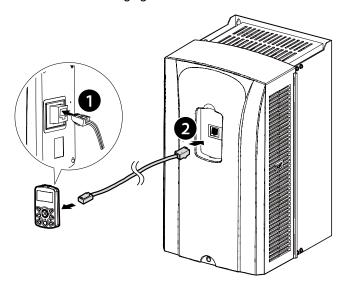


Remote Cable Specifications

Model type	Part name
64110009	INV, iS7 REMOTE CABLE (2 M)
64110010	INV, iS7 REMOTE CABLE (3 M)

Installing the Remote Cable

Refer to the following figure to install the remote cable to extend the keypad cable length.



If a "Line Check" message is displayed on the keypad display and the keypad is not operating correctly after installing the remote cable, check the cable connection on both sides.

① Caution

Do not extend the keypad cable using a third-party extension cable. The keypad may not operate correctly due to voltage drop and electromagnetic interference.

Note

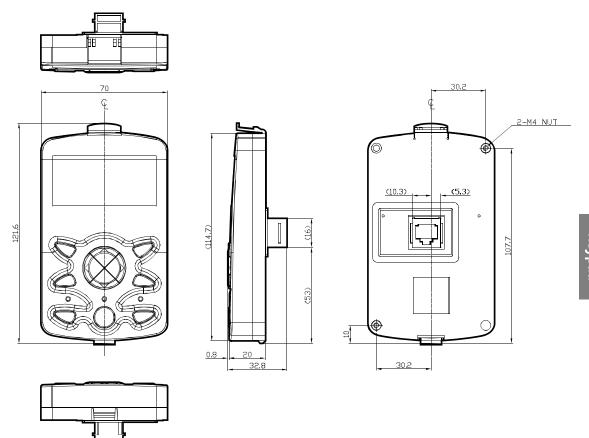
- Ensure that the cable length between the keypad and the inverter does not exceed 10 ft (3.04 m). Cable connections longer than 10 ft (3.04 m) may cause signal errors.
- Install a ferrite clamp to protect signal cables from electromagnetic interference (Ex. Wurth Electronics ferrite clamp PN742732).

6 Using the Keypad

6.1 About the Keypad

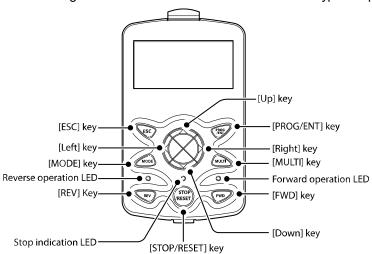
A keypad is used to set inverter parameters, monitor the inverter's status, and operate the inverter.

6.1.1 Dimensions



6.1.2 **Key Functions**

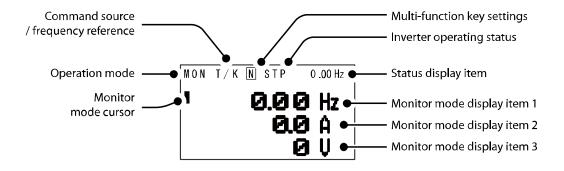
The following table lists the names and functions of the keypad's operation keys.



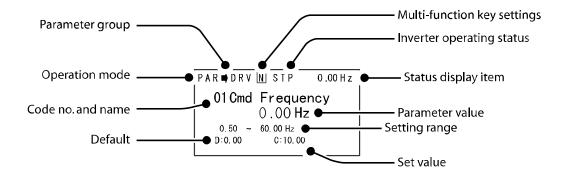
Section	Buttons	Key Name	Function Description	
	MODE	[MODE] key	Used to switch between modes.	
	PROG	[PROG/ENT] key	If this button is pressed once, the parameter can be edited at the status of the editable parameter code. If this button is pressed after modification, it will save the modified data.	
		[Up] key	Switch between codes, or increase or decrease parameter	
		[Down] key	values.	
		[Left] key	Switch between groups or move the cursor during	
		[Right] key	parameter setup or modification.	
	(EY ESC)	[MULTI] key	Used to register jog or user codes.	
KEY		[ESC] key	If you press this key before pressing the [PROG / ENT] key, it will revert the parameter value to the previous value. If you press this key while editing the codes in any function group, the keypad will display the first code of the function group. If you press this key while moving through the modes, the keypad will display Monitor mode.	
		[FWD] key	Used to operate the motor in the forward direction.	
	REV	[REV] key	Used to operate the motor in the reverse direction.	
	STOP /RESET	[STOP/RESET] key	Used to stop the operation and release a fault.	

6.1.3 Display Items

Monitor Mode



Parameter Mode



6.1.4 Display Item List

The following table lists the items in the display.

Item	Description
Mode display items	Displays the current mode's display items. For more details, refer to 6.3 Navigating Modes on page 117.
Parameter group items	Displays the current parameter group's items. For more details, refer to 6.4 Navigating Modes and Parameters on page 120.

Item	Description
Command source / frequency reference items	Displays the types of sequences and the number of steps during an auto sequence operation.
Status display items	Displays the output frequency, output voltage, and current. For more details, refer to <u>0</u> <u>Display</u> Items on pages <u>111</u> .
Monitor mode display items	Displays the current operation status. For more details, refer to <u>0</u> <u>Display</u> Items on pages <u>111</u> .

Monitor display items

The following table lists display icons and their names and functions.

No	Function	Display	Description
		MON	Monitor mode
		PAR	Parameter mode
1	Operation mode	U&M	User-defined and Macro mode
		TRP	Trip mode
		CNF	Configuration mode
		K	Keypad operation command
		0	FieldBus communication option operation command
2	Command source	Α	Application option operation command
	Course	R	Built-in 485 operation command
		Т	Terminal block operation command
		K	Keypad frequency command
		V	V1 input frequency command
		I	I1 input frequency command
		Р	Pulse input frequency command
		U	Frequency command during UP operation (Up-Down operation)
3	Frequency reference	D	Frequency command during DOWN operation (Up-Down operation)
	reference	s	Frequency command during STOP operation (Up-Down operation)
		0	FBus Option frequency command
		X	V2 and I2 frequency commands for sub-terminal block
		J	Jog frequency command
		R	Internal 485 frequency command
		1-9 A-F	Multi-step frequency command
4	Multi-function	JOG key	Used to switch to Keypad JOG mode
4	key settings	Local/Remote	Used to select local or remote operation

No	Function	Display	Description
		User Group Select key	Used to register parameters as a user group in Parameter mode or delete parameters in the user group.
		STP	Motor stopped
		FWD	Operating in the forward direction
		REV	Operating in the reverse direction
		DC	DC output
5	Inverter operating	WAN	Warning
3	status	STL	Stalling
		SPS	Speed Search
		OSS	Software over current controlled
		OSH	Hardware over current controlled
		TUN	Auto tuning

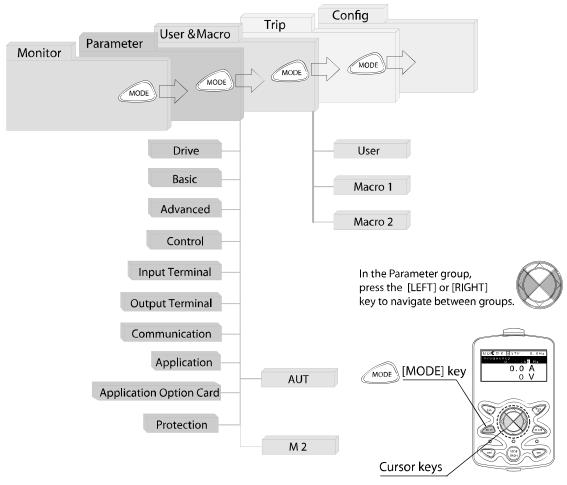
*OSS / OSH may cause overcurrent when the load is too large or when the acceleration/deceleration time is short. The inverter monitors the output current so that an overcurrent trip does not occur and also performs overcurrent suppression.

At this time, the output frequency is automatically changed to reduce the output current or the inverter output is temporarily cut off to prevent overcurrent.

Menu Items 6.2

The SV-iS7 series inverter uses 5 modes to monitor or configure different functions. Each mode has its own function items suitable for the desired properties. The parameters in Parameter mode and User & Macro mode are divided into smaller groups of relevant functions.

Press the [MODE] key to navigate between groups.



Mode	Display	Description
Monitor mode	MON	Displays the inverter's operation status information. You can monitor the frequency setting, operating frequency display, output current, voltage, etc.
Parameter mode	PAR	Used to configure the functions required to operate the inverter. These functions are divided into 12 groups based on purpose and complexity.
User & Macro mode	U&M	Used to define User and Macro groups. These user-definable groups allow specific functions of the inverter to be grouped and managed in separate groups. This mode will not be displayed when navigating through modes if no User groups or Macro groups have been defined.
Trip mode	TRP	Used to monitor the inverter's fault trip information, including the previous fault trip history. When a fault trip occurs during inverter operation, the operation frequency, output current, and output voltage of the inverter at the time of the fault can be monitored. This mode will not be displayed if the inverter is not at fault and a fault trip history does not exist.
Configuration mode	CNF	Used to configure the inverter features that are not directly related to the operation of the inverter. The settings you can configure in Configuration mode include keypad display language options, monitor mode environment settings, communication module display settings, and parameter duplication and initialization.

6.2.1 Parameter Mode

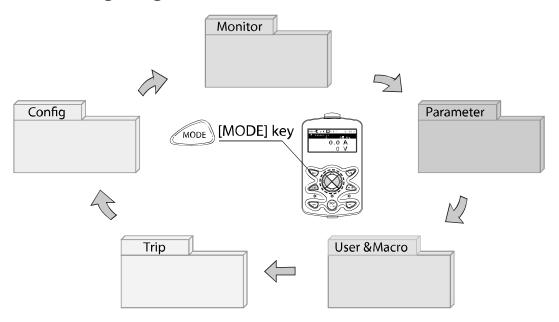
Mode	Display	Description
Drive group	DRV	Includes frequency/acceleration/deceleration time setting, operation command selection, etc.
Basic group	BAS	Configures basic operation parameters. These parameters include motor parameters and multi-step frequency parameters.
Advanced function group	ADV	Configures acceleration or deceleration, patterns, and frequency limits.
Control function group	CON	Configures functions related to sensorless and vector control.
Input terminal function group	IN	Configures input terminal–related features, including digital multi–functional inputs and analog inputs.
Output terminal function group	OUT	Configures the inverter output terminal block-related features, including the relay and analog outputs.
Communication function group	СОМ	Configures the communication features for the RS-485, if one is installed.
Application function group	APP	Configures the features related to PID control and auto sequence operation.
Auto Sequence run	AUT	Configures the necessary features for auto sequence operation.

Mode	Display	Description
group		This group will be displayed if the auto sequence operation in the APP group is selected.
Application option group	APO	Configures the encoder and PLC option module-related features if they are installed.
Protection group	PRT	Configures motor and inverter protection features.
Motor 2 function group (Motor 2)	M2	Configures the secondary motor-related features. This group will be displayed when Motor #2 is selected from the multi-function input terminal functions.

6.2.2 User & Macro Mode

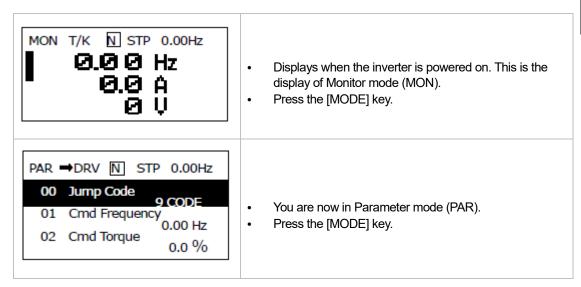
Group	Display	Description
User group	USR	Used to group frequently accessed function parameters. User parameter groups can be configured using the multi-function key on the keypad.
Macro group	MCx	This provides different factory preset groups of functions based on the type of load. Group MC1, MC2, or MC3 will be displayed when the user selects the desired load type. Macro groups can be selected in CNF mode. For more details, refer to 11.12 Parameter Group for Transmission of Macro Group and User Group at U&M Mode on page

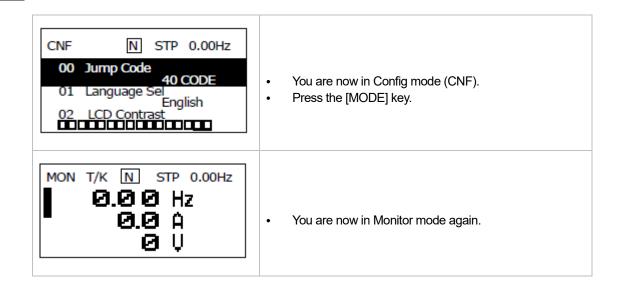
6.3 **Navigating Modes**



6.3.1 Mode Navigation at the Factory Default

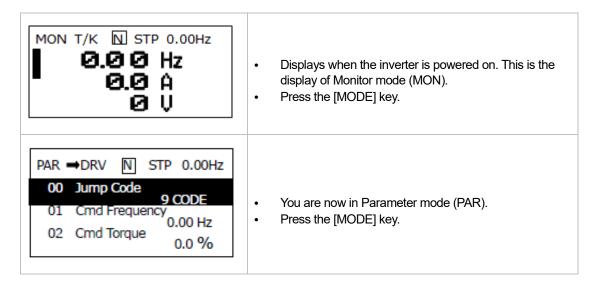
You can change the display to navigate modes by using the [MODE] key. The User & Macro Mode and Trip Mode are not displayed when the inverter is set to the factory default settings. For more details, refer to 11.12 Parameter Group for Transmission of Macro Group and User Group at U&M Mode on page 344.

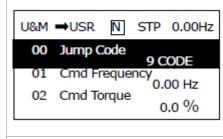




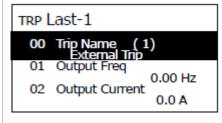
6.3.2 Mode Navigation with User/Macro Mode and Trip Mode

If you register a user code or set the macro function using the [MULTI] key, the User & Macro mode will be displayed, unlike the factory default settings during mode navigation. In addition, when a trip occurs during operation, Trip mode will be displayed. The trip information will also be saved in the trip mode history if you release the trip using the RESET function. The two modes for mode navigation are as follows.

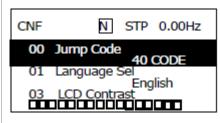




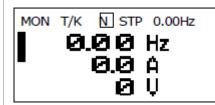
- You are now in User & Macro mode (U&M).
- Press the [MODE] key.



- You are now in Trip mode (TRP).
- Press the [MODE] key.



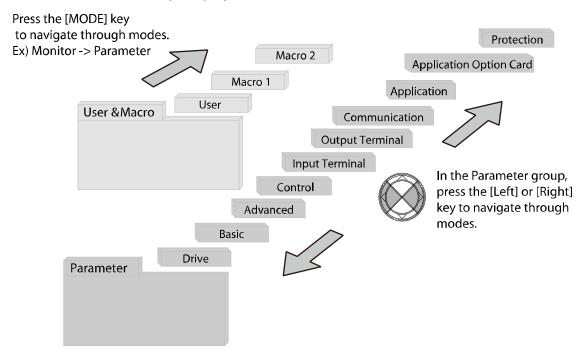
- You are now in Config mode (CNF).
- Press the [MODE] key.



You are now in Monitor mode again.

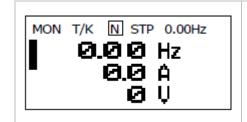
Navigating Modes and Parameters 6.4

You can navigate modes by using the [Left] or [Right] keys after navigating to the Parameter Mode or User & Macro Mode via the [Mode] key.



Group Navigation in Parameter mode 6.4.1

If you press the [Right] key in Parameter mode, the display will change as shown below. If you press the [Left] key, the display order will be reversed.



- Displays when the inverter is powered on. This is the display of Monitor mode (MON).
- Press the [MODE] key.

PAR ⇒DRV N STP 0.00Hz 00 Jump Code 9 CODE 01 Cmd Frequency 0.00 Hz 02 Cmd Torque 0.0 %

- You are now in Parameter mode (PAR).
- The Drive Group (DRV) of Parameter mode is displayed.
- Press the [Right] key.

STP 0.00Hz PAR ⇒BAS Ν 00 Jump Code 20 CODE 01 Aux Ref Src

02 Cmd 2nd Src

None

Fx/Rx-1

Linear

- You are now in the Basic Function Group (BAS).
 - Press the [Right] key.

PAR →ADV STP 0.00Hz 00 Jump Code 24 CODE 01 Acc Pattern Linear 02 Dec Pattern

- You are now in the Advanced Function Group (ADV).
- Press the [Right] key 7 times.

PAR ⇒PRT N STP 0.00Hz 00 Jump Code 40 CODE Load Phase Loss

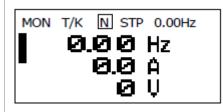
- The group sequence will change and the Protection Function Group (PRT) will be displayed.
- Press the [Right] key.

STP 0.00Hz PAR ⇒DRV Ν 00 Jump Code 9 CODE 01 Cmd Frequency 0.00 Hz 02 Cmd Torque 0.0%

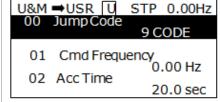
You are now in the Drive group (DRV) of the Parameter group again.

6.4.2 **Group Shift in User & Macro Mode**

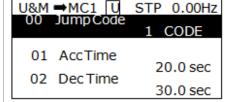
To navigate to User & Macro Mode, the user code should be registered or the macro function should be selected. For more details on how to register the user code and macro group, refer to 11.12 Parameter Group for Transmission of Macro Group and User Group at U&M Mode on page 344. If the user code is registered and the macro function is selected, you can navigate to the group as shown below.



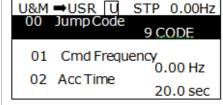
- Displays when the inverter is powered on. This is the display of Monitor mode (MON).
- Press the [MODE] key twice.



- You are now in the User & Macro mode (U&M).
- The User Group (USR) is displayed.
- Press the [Right] key.



- You are now in the Macro group (MC1).
- Press the [Right] key.

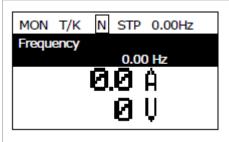


You are now in the User Group (USR) again.

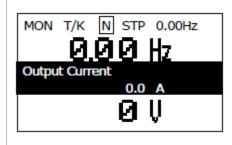
6.5 **Navigating through Codes (Function Items)**

6.5.1 **Code Navigation in Monitor Mode**

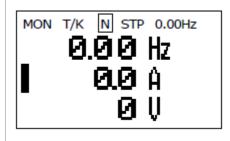
To display the frequency, output current, and output voltage, press the [Up] or [Down] keys to scroll through the items.



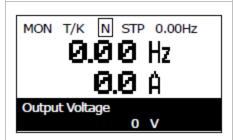
- Displays when the inverter is powered on. This display is in Monitor mode.
- The cursor is located at the frequency item.
- Press the [Down] key.



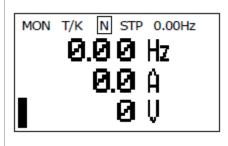
- The second display item displays the output current.
 - Do not press any key for approximately 2 seconds after navigation.



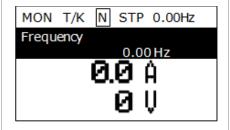
- The output current text has disappeared and the cursor has moved to the second display item.
- Press the [Down] key.



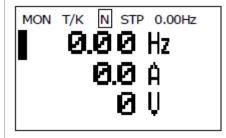
- The third display item displays the output voltage.
- Do not press any key for approximately 2 seconds after navigation.



- The output voltage text has disappeared and the cursor has moved to the third display item.
- Press the [Up] key twice.



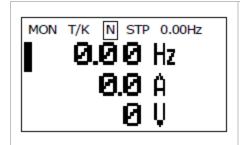
The first item displays the frequency.



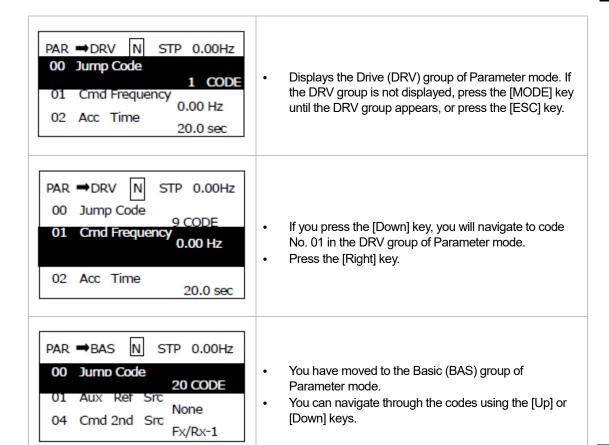
The frequency text has disappeared and the cursor has moved to the first display item.

Code Navigation (function items) in Other Modes and Groups 6.5.2

Using the [Up] and [Down] keys: The following example demonstrates how to navigate through the codes in the Drive (DRV) group and the Basic [BAS] group of Parameter mode. Code navigation in other modes is the same as follows.

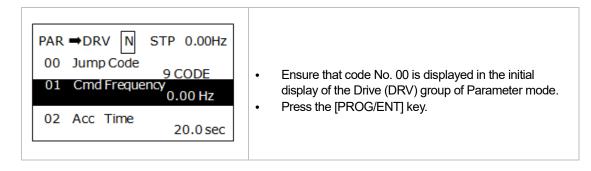


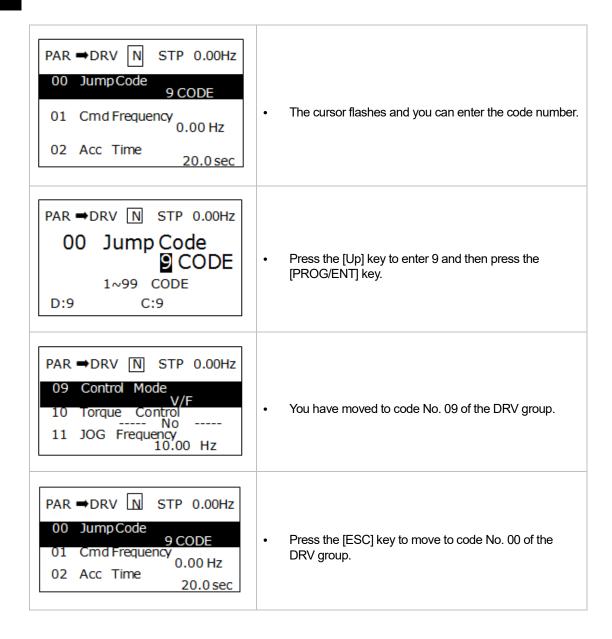
- Displays when the inverter is powered on. This display is in Monitor mode.
- Press the [Down] key.



Code Navigation Using Jump Code 6.5.3

In the Parameter mode and User/Macro mode groups, you can use the Jump Code Entry item to move to a desired code. It is quicker to move to a large code number using the Jump Code Entry item rather than the [Up] and [Down] keys. The following example demonstrates how to move to code No. 09 of the Drive (DRV) group.

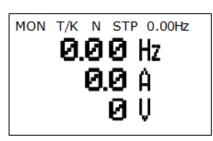




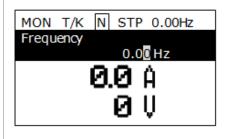
6.6 Setting Parameters

6.6.1 **Parameter Settings in Monitor Mode**

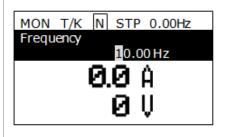
You can set some parameters, such as the frequency, in Monitor mode. The following example demonstrates how to set the frequency.



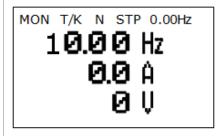
- Ensure that the cursor is at the frequency item. Also, ensure that the frequency can be set to 09 in the Drive (DRV) group using the keypad.
- Press the [PROG/ENT] key.



- Detailed information of the item is displayed and the cursor flashes.
- Press the [Left] or [Right] keys to move the cursor to the desired location to set the frequency.



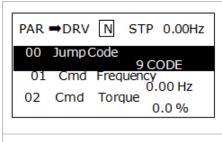
- Press the [Up] key to set the frequency to 10 Hz.
- Press the [PROG/ENT] key.



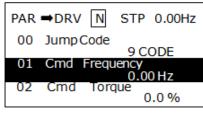
The frequency reference is set to 10 Hz.

Parameter Settings in Other Modes and Groups 6.6.2

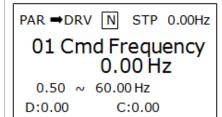
The following example demonstrates how to change the frequency of the Drive (DRV) group in Parameter mode. The frequency in the other modes or groups can be set as follows.



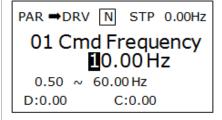
- This is the initial display in Parameter mode.
- Press the [Down] key.



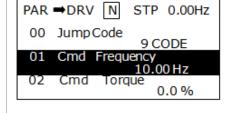
- You have moved to the 01 frequency setting code.
- Press the [PROG/ENT] key.



- The cursor flashes and you can enter the desired frequency.
- If the frequency reference is set to 10 Hz, press the [Left] or [Right] keys to move the cursor to the desired place.



Press the [Up] key to enter 10 Hz and then press the [PROG/ENT] key.

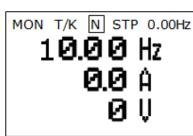


The frequency reference is set to 10 Hz.

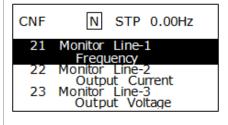
6.7 **Monitoring Operating Status**

6.7.1 **Using Monitor Mode**

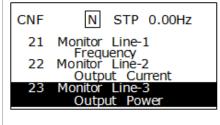
Three items can be displayed in Monitor mode at a time. Also, some items, such as the frequency item, can be edited. You can select the displayed items in Configuration (CNF) mode.



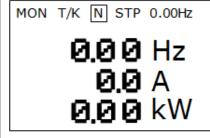
- This is the initial display in Monitor mode.
- The frequency, current, and voltage are set as the default monitor items.
- The frequency reference is displayed when the inverter operation has stopped, and the operating frequency is displayed when the inverter is operating.



- You can set the items to display in Monitor mode in sequence from 21 to 23 in Configuration (CNF) mode.
- Press the [Down] key to move to code No. 23



Change the code No. 23 item in Monitor mode to the output power.



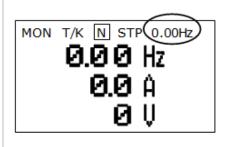
Ensure that the third displayed item in Monitor mode is changed to the output power.

6.7.2 Monitoring Items

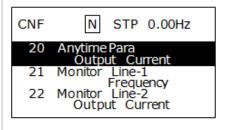
Mode	Code	Function Display	Setting Range		Initial Value
	20	Anytime Para	0	Frequency	0: Frequency
	21	Monitor Line-1	1	Speed	0: Frequency
	22	Monitor Line-2	2	Output Current	2:Output Current
			3	Output Voltage	
			4	Output Power	
			5	WHour Counter	
			6	DCLink Voltage	
			7	DI Status	
			8	DO Status	
			9	V1 Monitor [V]	
		Monitor Line-3	10	V1 Monitor [%]	
	23		11	I1 Monitor [mA]	
CNF			12	I1 Monitor [%]	
CIVI			13	V2 Monitor [V]	
			14	V2 Monitor [%]	3:Output Voltage
			15	I2 Monitor [mA]	
			16	I2 Monitor [%]	
			17	PID Output	
			18	PID Ref Value	
			19	PID Fdb Value	
			20	Torque	
			21	Torque Limit	
			22	Trq Bias Ref	
			23	Speed Limit	
			24	Load Speed	
			25	Temperature	

6.7.3 **Using the Status Display**

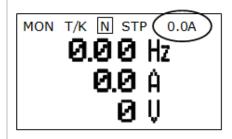
The items displayed on the right-top of the display are shown in other modes, including Monitor mode. If you register a desired variable in the display, you can monitor it at any time regardless of the mode navigation or change.



- This is the initial display of Monitor mode.
- When the inverter settings are set to the factory default, the status item displays the frequency.



- Select the item to display in the status display in code 20 of Configuration (CNF) mode.
- Press the [PROG/ENT] key to change the item to the output current.
- The unit at the top of the display is changed from hertz (frequency) to amps (current).



Ensure that the unit in the status display is changed to amps (current) in Monitor mode.

Monitoring Faults 6.8

6.8.1 **Faults during Inverter Operation**

TRP current

Over Voltage (01)

01 Output Freq

48.30 Hz

02 Output Current

33.3 A

If a fault trip occurs during inverter operation, the inverter enters Trip mode automatically and displays the type of fault trip that has occurred.

TRP Last-1

01 Output Freq

48.30 Hz

02 Output Current

33.3 A

03 Inverter State

Stop

Press the [Down] key to view the information on the inverter at the time of the fault, including the output frequency, current, and operating status.

MON T/K N STP 0.0A

0.00 Hz

When the inverter is reset and the fault trip is released, the keypad display returns to the screen that was displayed before the fault trip occurred.

6.8.2 Multiple Faults at a Time during Inverter Operation

TRP current Voltage (02)

- Output Freq 48.30 Hz 02 Output Current 33.3 A
- If multiple fault trips occur at the same time, the number of fault trips that occurred is displayed next to the fault trip type.
- Press the [PROG/ENT] key.

TRP current Name (

- 0 Over Voltage 1 Externa Trip
- The types of all the fault trips are displayed.
- Press the [PROG/ENT] key.

TRP current

Voltage (02)

Output Freq 48.30 Hz 02 Output Current 33.3 A

The display mode that was shown before you checked the fault information is displayed.

Saving and Monitoring the Fault Trip History 6.8.3

Previous fault trips can be saved in Trip mode. You can save up to 5 previous fault trips. Fault trips caused by resetting the inverter, as well as low voltage faults caused by the inverter being switched off, are also saved.

If there are more than 5 fault trips, the oldest 5 fault trips are automatically deleted.

TRP current

Over Voltage (02)

01 Output Freq

48.30 Hz

02 Output Current

33.3 A

If a fault trip occurs during inverter operation, the inverter enters Trip mode and displays the type of fault trip that has occurred.

MON T/K N STP 0.0A

0.00 Hz

- If you press the [STOP/RESET] key or an input is entered on the terminal, the fault trip is automatically saved and the display status that was displayed before the fault trip occurred is displayed.
- Press the [MODE] key to move to Trip mode.

TRP current

00 Trip Name (2)

Over Voltage

01 Output Freq

48.30 Hz

02 Output Current

33.3 A

- The most recent fault trip is saved in the Last-1 code.
- Press the [Right] key.

TRP current

00 Trip Name (1) External Trip

01 Output Freq

48.30 Hz

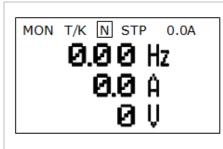
02 Output Current

33.3 A

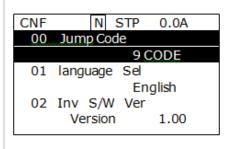
- The previous fault trips are saved in the Last-2 code.
- If another fault trip occurs, the previous fault trips saved in the Last-2 code move to the Last-3 code.

6.9 **Initializing Parameters**

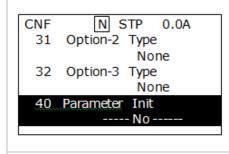
You can initialize the changed parameters. In addition to initializing the entire parameter, you can also select the individual parameter mode to be initialized.



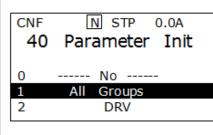
Monitor mode is displayed.



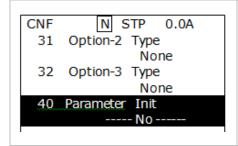
Press the [MODE] key to move to Configuration (CNF) mode.



- Press the [Down] key to move to code No. 40.
- Press the [PROG/ENT] key.



Of the parameter items to initialize, select All Groups and then press the [PROG/ENT] key.



The Parameter Initialization option is displayed again when the initialization is complete.

7 Basic Functions

7.1 Setting Frequency References

The iS7 inverter provides several methods to set up and modify a frequency reference for an operation. The keypad, analog inputs [for example voltage (V1) and current (I1) signals], or RS-485 (digital signals from higher-level controllers, such as PCs or PLCs) can be used.

Group	Code	Name	LCD Display	Param	neter Setting	Setting Range	Unit
				0	KeyPad-1		
				1	KeyPad-2	0-9	
				2	V1		
		Frequency reference source	For a Def One	3	I1		
DRV	07			4	V2		
DKV	07		Freq Ref Src	5	12		-
				6	Int 485		
				7	Encoder		
				8	Field Bus		
				9	Pulse		

Keypad as the Source (KeyPad-1 setting) 7.1.1

You can modify the frequency reference using the keypad and apply changes by pressing the [ENT/PROG] key. To use the keypad as a frequency reference input source, go to DRV-07 (Frequency reference source) and change the parameter value to "0 (Keypad-1)". Input the frequency reference for an operation at DRV-01 (Frequency reference).

Group	Code	Name	LCD Display	Paramet	er Setting	Setting Range	Unit
DDV	01	Frequency reference Cmd Frequency 0.00			0.00-max. frequency*	Hz	
DRV	07	Frequency reference source	Freq Ref Src	0	KeyPad-1	0–9	-

^{*} You cannot set a frequency reference that exceeds the max. frequency, as configured with DRV-20.

Keypad as the Source (KeyPad-2 setting) 7.1.2

You can use the [UP] and [DOWN] cursor keys to modify a frequency reference. To use this as a second option, set the keypad as the source of the frequency reference by going to DRV-07 (Frequency reference source) and changing the parameter value to "1 (Keypad-2)". This allows frequency reference values to be increased or decreased by pressing the [UP] and [DOWN] cursor keys.

Group	Code	Name	LCD Display	Pa	rameter Setting	Setting Range	Unit
	01	Frequency reference	Cmd Frequency	nd Frequency 0.00		0.00-max. frequency *	Hz
DRV	07	Frequency reference source	Freq Ref Src	1	KeyPad-2	0–9	-

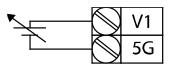
^{*} You cannot set a frequency reference that exceeds the max. frequency, as configured with DRV-20.

V1 Terminal as the Source 7.1.3

You can set and modify a frequency reference by setting voltage inputs when using the V1 terminal. Use voltage inputs ranging from 0-10 V (unipolar) for forward-only operations. Use voltage inputs ranging from -10 to +10 V (bipolar) for both directions, with negative voltage inputs used for reverse operations.

7.1.3.1 Setting a Frequency Reference for 0–10 V Input

Set IN-06 (V1 Polarity) to "0 (unipolar)". Use a voltage output from an external source or use the voltage output from the VR terminal to provide inputs to V1. Refer to the diagrams below for the wiring required for each application.



	VR+
├	V1
4	5G

[External source application] [Internal source (VR) application]

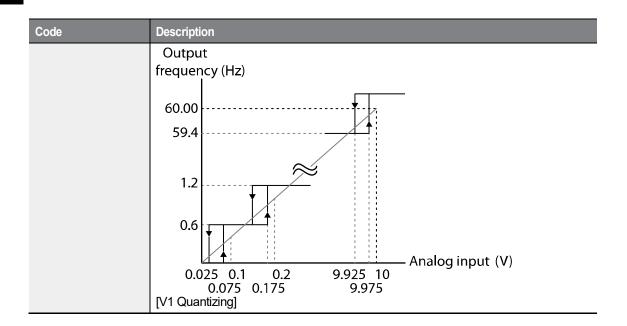
Group	Code	Name	LCD Display	Parame	eter Setting	Setting Range	Unit
DRV	07	Frequency reference source	Freq Ref Src	2	V1	0–9	-
	01	Frequency at maximum analog input	Freq at 100%	Maxim frequer		0.00– max. frequency	Hz
	05	V1 input monitor	V1 Monitor[V]	0.00		0.00-10.00	V
	06	V1 polarity options	V1 Polarity	0	Unipolar	0–1	-
	07	V1 input filter time constant	V1 Filter	10		0–10000	ms
	08	V1 minimum input voltage	V1 volt x1	0.00		0.00–10.00	V
IN	09	V1 output at minimum voltage (%)	V1 Perc y1	0.00		0.00–100.00	%
	10	V1 maximum input voltage	V1 Volt x2	10.00		0 .00– 10.00	V
	11	V1 output at maximum voltage (%)	V1 Perc y2	100.00		0–100	%
	16	Rotation direction options	V1 Inverting	0	No	0–1	-
	17	V1 quantizing level	V1 Quantizing	0.04		0.00*, 0.04– 10.00	%

^{*} Quantizing is disabled if "0" is selected.

0-10 V Input Voltage Setting Details

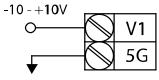
Code	Description		
IN-01 Freq at 100%	 Configures the frequency reference at the maximum input voltage when a potentiometer is connected to the control terminal block. A frequency set with code IN-01 becomes the maximum frequency only if the value set in code IN-11 (or IN-15) is 100%. Set code IN-01 to 40.00 and use default values for codes IN-02–IN-16. The motor will run at 40.00 Hz when a 10 V input is provided at V1. Set code IN-11 to 50.00 and use default values for codes IN-01–IN-16. The motor will run at 30.00 Hz (50% of the default maximum frequency–60 Hz) when a 10 V input is provided at V1. 		
IN-05 V1 Monitor[V]	Configures the inverter to monitor the input voltage at V1.		
IN-07 V1 Filter	The V1 filter may be used when there are large variations between reference frequencies. Variations can be mitigated by increasing the time constant, but this requires an increased response time. The value t (time) indicates the time required for the frequency to reach 63% of the reference, when external input voltages are provided in multiple steps. V1 input from external source Frequency 100% 63% V1 Filter(t) [V1 Filter]		
IN-08 V1 volt x1– IN-11 V1 Perc y2	These parameters are used to configure the gradient level and offset values of the output frequency, based on the input voltage.		

Code	Description				
	Frequency reference				
	In.11				
	In.09 V1 input				
IN-16 V1 Inverting	Inverts the direction of rotation. Set this code to "1 (Yes)" if you need the motor to run in the opposite direction from the current rotation.				
IN-17 V1 Quantizing					
	As a result, the output frequency will be different at acceleration and deceleration, mitigating the effect of analog input changes over the output frequency (ripples).				



7.1.3.2 Setting a Frequency Reference for -10-+10 V Input

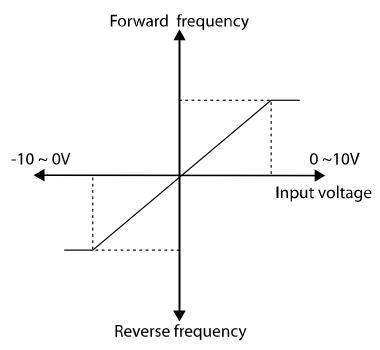
Set DRV-07 (Frequency reference source) to "2 (V1)", and then set IN-06 (V1 Polarity) to "1 (bipolar)". Use the output voltage from an external source to provide an input to V1.



VR+ V1 VR-

[External source application] [V1 terminal wiring]

[Internal source (VR) application]



[Bipolar input voltage and output frequency]

Group	Code	Name	LCD Display	Paran	neter Setting	Setting Range	Unit
DRV	07	Frequency reference source	Freq Ref Src	2	V1	0–9	-
	01	Frequency at maximum analog input	Freq at 100%	60.00		0-max. frequency	Hz
IN	05	V1 input monitor	V1 Monitor	0.00		0.00-10.00 V	V
	06	V1 polarity options	V1 Polarity	1	Bipolar	0–1	-
	12	V1 minimum input	V1- volt x1	0.00		0.00–10.00 V	V

Group	Code	Name	LCD Display	Parameter Setting	Setting Range	Unit
		voltage				
	13	V1 output at minimum voltage (%)	V1- Perc y1	0.00	-100.00-0.00%	%
	14	V1 maximum input voltage	V1- Volt x2	-10.00	-10.00–0.00 V	V
	15	V1 output at maximum voltage (%)	V1- Perc y2	-100.00	-100.00-0.00%	%

Rotational Directions for Different Voltage Inputs

Command / Voltage	Input voltage			
Input	0–10 V	-10–0 V		
FWD	Forward	Reverse		
REV	Reverse	Forward		

10-10 V Voltage Input Setting Details

Code	Description
IN-12 V1- volt x1- IN-15 V1- Perc y2	Sets the gradient level and offset value of the output frequency in relation to the input voltage. These codes are displayed only when IN-06 is set to "1 (bipolar)". As an example, if the minimum input voltage (at V1) is set to "-2 (V)" with 10% output ratio, and the maximum voltage is set to "-8 (V)" with an 80% output ratio, the output frequency will vary within the range of 6–48 Hz. V1 input IN-14 IN-12 -8V -8V -8V IN-15
	Frequency reference

Code	Description
	For details about the 0-+10 V analog inputs, refer to the code descriptions IN-08 V1 volt x1-IN-11 V1 Perc y2 on page <u>143</u>

7.1.3.3 **Setting a Reference Frequency using Input Current (I1)**

You can set and modify a frequency reference using input current at the I1 terminal. Set DRV-07 (Frequency reference source) to "3 (I1)" and apply an input current of 0-20 mA to I1.

Group	Code	Name	LCD Display	Paramete	er Setting	Setting Range	Unit
DRV	07	Frequency reference source	Freq Ref Src	3	I1	0–9	-
	01	Frequency at maximum analog input	Freq at 100%	60.00		0–max. frequency	Hz
	20	I1 input monitor	11 Monitor	0.00		0.00–20.00	mA
	22	I1 input filter time constant	I1 Filter	10		0–10000	ms
	23	I1 minimum input current	I1 Curr x1	4.00		0.00–20.00	mA
IN	24	I1 output at minimum current (%)	I1 Perc y1	0.00		0–100	%
	25	I1 maximum input current	I1 Curr x2	20.00		4.00–20.00	mA
	26	I1 output at maximum current (%)	I1 Perc y2	100.00		0.00-100.00	%
	31	I1 rotation direction options	I1 Inverting	0	No	0–1	-
	32	I1 quantizing level	I1 Quantizing	0.04		0.00*, 0.04– 10.00	%

^{*} Quantizing is disabled if "0" is selected.

Input Current (I1) Setting Details

Code	Description
IN-01 Freq at 100%	 Configures the frequency reference for operation at the maximum current (when IN-26 is set to 100%). If IN-01 is set to 40.00, and default settings are used for IN-23–26, an input current of 20 mA (max) to I1 will produce a frequency reference of 40.00 Hz. If IN-26 is set to 50.00, and default settings are used for IN-01 (60 Hz) and IN-23–26, an input current of 20 mA (max) to I1 will produce a frequency reference of 30.00 Hz (50% of 60 Hz).
IN-20 I1 Monitor	Used to monitor the input current at I1.
IN-22 I1 Filter	Configures the time for the operation frequency to reach 63% of the target frequency based on the input current at I1.
IN-23 I1 Curr x1– IN-26 I1 Perc y2	Configures the gradient level and offset value of the output frequency. Frequency reference IN-26 IN-24 IN-23 IN-25 [Gradient and offset configuration based on output frequency]
IN-32 I1 Quantizing	Same as V1 Quantizing. For more details, refer to <u>7.1.3.1 Setting a Frequency</u> <u>Reference for 0–10 V Input</u> on page <u>139</u> .



7.1.4 Setting a Frequency Reference Using an I/O Expansion Module (Terminal V2/I2)

After installing an optional I/O I/O expansion moduleto the iS7 inverter, you can set and modify a frequency reference using the input voltage or current at the V2/I2 terminal.

7.1.4.1 Setting a Reference Frequency using Input Voltage at V2 Terminal

Set the DRV-07 (Frequency reference source) to "4 (V2)" and apply an input voltage of -10-+12 V to the V2 terminal.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
DRV	07	Frequency reference source	Freq Ref Src	4	V2	0–9	-
	35	V2 input display	V2 Monitor	0.00		-10.00-+10.00	V
	37	V2 input filter time constant	V2 Filter	10		0–10000	ms
	38	Minimum V2 input voltage	V2 Volt x1	0.00		0.00–10.00	V
	39	Output% at minimum V2 voltage	V2 Perc y1	0.00		0.00-100.00	%
	40	Maximum V2 input voltage V2 Volt x2 10.00	0.00–10.00		V		
	41	Output% at maximum V2 voltage	V2 Perc y2	100.00		0.00–100.00	%
IN	42	Minimum V2 input voltage'	V2 -Volt x1'	0.00		0–10	V
	43	Output% at minimum V2 voltage'	V2 -Perc y1'	0.00		0–100	%
	44	Maximum V2 input voltage'	V2 -Volt x2'	-10.00		0–10	V
	45	Output% at maximum V2' voltage	V2 -Perc y2'	-100.00		-100–0	%
	46 Invert V2 rotational direction V2 Inverting No			No/Yes	-		
	47	V2 quantizing level	V2 Quantizing	0.04		0.00*, 0.04– 10.00	%

^{*} Quantizing is disabled if "0" is selected.

7.1.4.2 Setting a Reference Frequency using Input Current at I2 Terminal

Set the DRV-07 (Frequency reference source) to "5 (I2)" and apply an input voltage of 0–20 mA to the I2 terminal.

Group	Code	Name	LCD Display	Parameto	er Setting	Setting Range	Unit
DRV	07	Frequency reference source	Freq Ref Src	5	12	0–9	-
	50	I2 input monitor	I2 Monitor	0.00		0.00-20.00	mA
	52	I2 input filter time constant	I2 Filter	10		0–10000	ms
	53	I2 minimum input current	I2 Curr x1	4.00		0.00–20.00	mA
	54	I2 output at minimum current (%)	I2 Perc y1	0.00		0–100	%
	55	I2 maximum input current	I2 Curr x2	20.00		4.00–20.00	mA
	56	I2 output at maximum current (%)	I2 Perc y2	100.00		0.00-100.00	%
	61	I2 rotation direction options	I2 Inverting	0	No	0–1	-
	62	I2 quantizing level	I2 Quantizing	0.04		0.00*, 0.04– 10.00	%

^{*} Quantizing is disabled if "0" is selected.

Setting a Frequency with Pulse Input (with an optional encoder 7.1.5 module)

After installing an optional encoder module, you can set a frequency reference by setting DRV-07 (Frequency reference source) to "9 (Pulse)" and providing a pulse frequency of 0-32.00 kHz to the pulse input terminal.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
DRV	07	Frequency reference source	Freq Ref Src	7	Encoder	0–9	-
IN	01	Frequency at maximum analog input	Freq at 100%	60.00		0.00-max. frequency	Hz
	01	Encoder option mode	Enc Opt Mode	2	Reference	0-2	-
	04	Encoder type selection	Enc Type Sel	0	-	0-2	-
	05	Encoder pulse selection	Enc Pulse Sel	2	А	0-2	-
	06	Encoder pulse number	Enc Pulse Num	-		10-5000	-
APO	09	Pulse input display	Pulse Monitor	-		-	kHz
	10	Encoder filter time constant	Enc Filter	10		0-10000	ms
	93	Minimum pulse input	Enc Pulse x1	0.0		0-100	kHz
	94	Minimum pulse Output%	Enc Perc Y1	0.00		0-100	%
	95 Maximum pulse input Enc Pulse x2 100.0			0-200	kHz		
	96	Maximum pulse Output%	Enc Perc y2	100.00)	0-100	%

^{*} Quantizing is disabled if "0" is selected.

Pulse Input Setting Details

Code	Description						
APO-01 Enc Opt Mode	Sets the encoder option mode. Set APO-01 to "2 (Reference)" to receive a pulse input for the frequency reference.						
APO-04 Enc Type Sel	Sets the output type.						
APO-05 Enc Pulse Sel	Selects the encoder pulse to use.						
APO-06 Enc Pulse Num	Sets the number of pulses that is appropriate for the encoder specification.						
APO-09 Pulse Monitor	Displays the pulse frequency supplied at the encoder option module when APO-1 is set to "2 (Reference)".						
APO-10 Enc Filter	Sets the time for the pulse input to reach 63% of its nominal frequency (when the pulse frequency is supplied in multiple steps).						
	Configures the gradient level and offset values for the output frequency.						
	Frequency reference						
APO-11 Enc Pulse x1–IN-96 Enc Perc y2	IN-24 IN-23 IN-25 I1Input						

Setting a Frequency Reference via RS-485 Communication 7.1.6

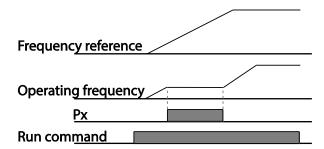
Control the inverter with upper-level controllers, such as PCs or PLCs, via RS-485 communication. Set DRV-07 (Frequency reference source) to "6 (Int 485)" and use the RS-485 signal input terminals (S+/S-/SG) for communication. For more details, refer to 11 Communication Function on page 334.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
DRV	07	Frequency reference source	Freq Ref Src	6 Int 485		0–9	-
	01	Integrated RS-485 communication inverter Int485 S		-	1	1–250	-
				0	ModBus RTU		
	02	Integrated communication protocol	Int485 Proto	1	ModBus ASCII	0–2	-
СОМ				2	LS Inv 485		
- CO	04	Integrated communication speed	Int485 BaudR	3	9600 bps	1200–38400	bps
				0	D8/PN/S1		
	04	Integrated	Int485 Mode	1	D8/PN/S2	0–3	
	04	communication frame configuration		2	D8/PE/S1	U-S	-
				3	D8/PO/S1		

7.2 Frequency Hold by Analog Input

If you set a frequency reference via the analog input at the control terminal block, you can hold the operation frequency of the inverter by assigning a multi-function input as the analog frequency hold terminal. The operation frequency will be linked to the analog input signal.

Group	Code	Name	LCD Display	Para	ameter Setting	Setting Range	Unit
				0	Keypad-1		
				1	Keypad-2		
				2	V1		
				3	I1		
DDV	07	Frequency reference source	Freq Ref Src	4	V2	0–9	
DRV	07			5	12		-
				6	Int 485		
				7	Encoder		
				8	Field Bus		
				9	PLC		
IN	65– 75	Px terminal configuration	Px Define(Px: P1–P8 [optional: P9–P11]) [Optional P9– 11]	21	Analog Hold	65–75	-



7.3 **Changing the Displayed Units (Hz→Rpm)**

You can change the units used to display the operational speed of the inverter by setting DRV-21 (Speed unit selection) to "0 (Hz Display)" or "1 (Rpm Display)".

Group	Code	Name	LCD Display	Parameter Setting		Parameter Setting S		Setting Range	Unit
DRV	21	Speed unit selection	Hz/Rpm Sel	0	Hz Display	0.1			
DKV				1	Rpm Display	0-1	_		

Setting Multi-Step Frequency 7.4

Multi-step operations can be carried out by assigning different speeds (or frequencies) to the Px terminals. Step 0 uses the frequency reference source set at DRV-07. Px terminal parameter values 7 (Speed-L), 8 (Speed-M), 9 (Speed-H), and 10 (Speed-X) are recognized as binary commands and work in combination with Fx or Rx run commands. The inverter operates according to the frequencies set at BAS-50-64 (multi-step frequency 1-15) and the binary command combinations.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit				
DRV	07	Frequency reference source	Freq Ref Src	-		-		-		-	-
BAS	50–64	Multi-step frequency 1–15	Step Freq - x	-		-	Hz				
		-75 Px terminal configuration	Px Define (Px: P1– P8 [optional: P9– P11]) [Optional P9–P11]	7	Speed-L		-				
	65–75			8	Speed-M	0–51	-				
	00-75			9	Speed-H	0-31					
IN			F9=F11]	10	Speed-X		-				
	89	Multi-step command delay time	InCheck Time	1		1–5000	ms				

Multi-step Frequency Setting Details

Code	Description							
BAS Group 50–64	Configure multi-step frequency 1–15.							
IN-65–75 Px Define	Choose the te (IN-65–75) to Provided that	rminals to set 7 (Speed-L), 8 terminals P6, ectively, the fo	up as multi-st 3 (Speed-M), 9 P7, and P8 ha	9 (Speed-lave been s	and then set the H), or 10 (Speed set to Speed-L, S tion will be available	-X). Speed-M and		
	[An example of	of a multi-step	operation]					
	Speed	Fx/Rx	(F	P8	P7	P6		
	0	✓		-	-			
	1	✓ ✓		-	- ✓	<u> </u>		
	3	V ✓		-	∨			
	4	√	,	/	-	- '		
	5	✓	,	/	-	✓		
	6	✓	,	/	✓	-		
	7	✓	,	√	✓	✓		
	By setting the Speed-X, you can configure up to 16 multi-step speeds, where the highest bit is Speed-X.							
	Speed	Fx/Rx	P8	P7	P6	P5		
	0	✓	-	-	-			

Code	Description							
	1	✓	-	-	-	✓		
	2	✓	-	-	✓	-		
	3	✓	-	-	✓	✓		
	4	✓	-	✓	-	-		
	5	✓	-	✓	-	✓		
	6	✓	-	✓	✓	-		
	7	✓	-	✓	✓	✓		
	8	✓	✓	-	-	-		
	9	✓	✓	-	-	✓		
	10	✓	✓	-	✓	-		
	11	✓	✓	-	✓	✓		
	12	✓	✓	✓	-	-		
	13	✓	✓	✓	-	✓		
	14	✓	✓	✓	✓	-		
	15	✓	✓	✓	✓	✓		
IN-89 InCheck Time	receiving an ir After IN-89 is search for input	Set a time interval for the inverter to check for additional terminal block inputs after receiving an input signal. After IN-89 is set to 100 ms and an input signal is received at P6, the inverter will search for inputs at other terminals for 100 ms, before proceeding to accelerate or decelerate based on the configuration at P6.						

7.5 Command Source Configuration

Various devices can be selected as command input devices for the iS7 inverter. Input devices available include the keypad, multi-function input terminal, RS-485 communication, and field bus adapter.

Group	Code	Name	LCD Display	Para	meter Setting	Setting Range	Unit			
							0	Keypad		
			1	Fx/Rx-1						
DDV			Cmd Source	Consid Courses	Cmd Course	Cmd Source	2	Fx/Rx-2	0–5	
DRV	06	Command Source		3	Int 485	0-5	-			
					4	Field Bus				
				5	PLC					

7.5.1 The Keypad as a Command Input Device

Set DRV-06 to "0 (Keypad)" to select the keypad as the command source.

Since the keypad is now the command source, forward or reverse operation starts when the [FWD] or [REV] key is pressed, and it stops when the [STOP/RESET] key is pressed.

Group	Code	Name	LCD Display	splay Parameter Setting		Setting Range	Unit
DRV	06	Command source	Cmd Source	0	KeyPad	0–5	-

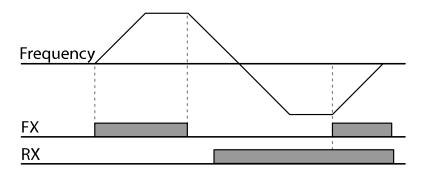
The Terminal Block as a Command Input Device (Fwd/Rev run 7.5.2 commands)

Multi-function terminals can be selected as a command input device. This is configured by setting DRV-06 (command source) to "1 (Fx/Rx-1)". Select two terminals for the forward and reverse operations, and then set the relevant codes (2 of the 11 multi-function terminal codes, IN-65-75 for P1–P8 [optional: P9–P11]) to "1 (Fx)" and "2 (Rx)" respectively. This application enables both terminals to be turned on or off at the same time, constituting a stop command that will cause the inverter to stop operating.

Group	Code	Name	LCD Display Parameter Setting		eter Setting	Setting Range	Unit
DRV	06	Command source	source Cmd Source 1		Fx/Rx-1	0–5	-
	Px terminal	Px Define(Px:	1	Fx			
IN	65–75	configuration	P1– P8 [optional: P9–P11])	2	Rx	0–51	-
	88	Delay time setting	Run On Delay	-	1.00	0.00-100.00	Sec

Fwd/Rev Command by Multi-function Terminal – Setting Details

Code	Description
DRV-06 Cmd Source	Set to "1 (Fx/Rx-1)".
IN-65–75 Px Define	Assign a terminal for forward (Fx) operation. Assign a terminal for reverse (Rx) operation.
IN-88 Run On Delay	Set the delay time if the inverter operation needs to be synchronized with other sequences. When the run command input (Fx/Rx) is given, the operation begins after the set time has elapsed.



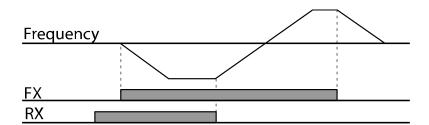
7.5.3 The Terminal Block as a Command Input Device (Run and Rotation Direction Commands)

Multi-function terminals can be selected as a command input device. This is configured by setting DRV-06 (command source) to "2 (Fx/Rx-2)". Select two terminals for run and rotation direction commands, and then set the relevant codes (2 of the 11 multi-function terminal codes, IN-65–75 for P1–P11 [optional: P9–P11]) to "1 (Fx)" and "2 (Rx)" respectively. This application uses an Fx input as a run command, and an Rx input to change a motor's rotation direction (On: Rx, Off: Fx).

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
DRV	06	Command source	ce Cmd Source		Fx/Rx-2	0–5	-
		Px Define (Px:	1	Fx			
IN	65–75	Px terminal configuration	P1–P8 [optional: P9– P11])	2	Rx	-	-
	88	Delay time setting	Run On Delay	-	1.00	0.00-100.00	Sec

Run Command and Fwd/Rev Change Command Using Multi-function Terminal – Setting Details

Code	Description
DRV-06 Cmd Source	Set to "2 (Fx/Rx-2)".
IN-65–75 Px Define	Assign a terminal for the run command (Fx). Assign a terminal for changing the rotation direction (Rx).
IN-88 Run On Delay	Set the delay time if the inverter operation needs to be synchronized with other sequences. When the run command input (Fx/Rx) is given, the operation begins after the set time has elapsed.



RS-485 Communication as a Command Input Device 7.5.4

Internal RS-485 communication can be selected as a command input device by setting DRV-06 (command source) in the Drive group to "3 (Int 485)". This configuration uses upper level controllers, such as PCs or PLCs, to control the inverter by transmitting and receiving signals via the S+, S-, and RS-485 signal input terminals at the terminal block. For more details, refer to 11 Communication Function on page 334.

Group	Code	Name	LCD Display Parameter Setting		ameter Setting	Setting Range	Unit
DRV	06	Command source	Cmd Source	3	Int 485	0–5	-
	04	Integrated communication inverter ID	Int485 St ID	1		1–250	-
СОМ	05	Integrated communication protocol	Int485 Proto	0	ModBus RTU	-	-
	06	Integrated communication speed	Int485 BaudR	3	9600 bps	1200–38400	bps
	07	Integrated communication frame setup	Int485 Mode	0	D8/PN/S1	-	-

7.6 **Local/Remote Mode Switching**

Local/remote mode switching is useful for checking the inverter's operation, or to perform an inspection while retaining all parameter values. Also, in an emergency, it can also be used to override controls and operate the system manually using the keypad.

The [MULTI] key is a programmable key that can be configured to carry out multiple functions.

(1) Caution

Use local/remote operation mode switching only when it is necessary. Improper mode switching may interrupt the inverter's operation.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
CNF	42	[MULTI] key functions	Multi-Key Sel	2	Local/Remote	-	-
DRV	06	Command source	Cmd Source	1	Fx/Rx-1	0–5	-

Local/Remote Mode Switching Setting Details

Code	Description
	Set CNF-42 to "2(Local/Remote)" to perform local/remote mode switching using the [MULTI] key.
	Once the parameter is set, "R" (remote) is displayed on the keypad, and the inverter will automatically begin operating in remote mode. Changing from local to remote operation will not alter any previously configured parameter values and the operation of the inverter will not change.
CNF-42 [MULTI] key functions	Press the [MULTI] key to switch the operation mode to "local." "L" (local) is displayed on the keypad, and the command source and frequency source indication on the keypad (in MON mode) changes to "K/K." The inverter stops operating if it was previously running in remote mode, and you can operate the inverter using the keypad.
	Press the [MULTI] key again to switch the operation mode back to "remote." "R" (remote) is displayed again on the keypad, and the command source and frequency source indication on the keypad (in MON mode) changes according to the previous parameter settings. The inverter is now ready to operate in remote mode, and the inverter operation may vary depending on the type of input source.

Note

Local/Remote Operation

- Full control of the inverter is available with the keypad during local operation.
- During local operation, jog commands will only work if one of the multi-function terminals (Px: P1–P11, codes IN-65–75) is set to "13 (RUN Enable)" and the relevant terminal is turned on.
- During remote operation, the inverter will operate according to the previously set frequency reference source and the command received from the input device.
- If ADV-10 (power-on run) is set to "0 (No)", the inverter will not operate on power-on even when the following terminals are turned on:
 - Fwd/Rev run (Fx/Rx) terminal
 - Fwd/Rev jog terminal (Fwd jog/Rev Jog)
 - Pre-excitation terminal

To operate the inverter manually with the keypad, switch to local mode. Use caution when switching back to remote operation mode as the inverter will stop operating. If ADV-10 (power-on run) is set to "0 (No)", a command through the input terminals will work only after all the terminals listed above have been turned off and then turned on again.



If the inverter has been reset to clear a fault trip during an operation, the inverter will switch to local operation mode at power-on, and full control of the inverter will be with the keypad. The inverter will stop operating when operation mode is switched from "local" to "remote". In this case, a run command through an input terminal will work only after all the input terminals have been turned off.

Inverter Operation During Local/Remote Switching

Switching operation mode from "remote" to "local" while the inverter is running will cause the inverter to stop operating. Switching operation mode from "local" to "remote", however, will cause the inverter to operate based on the command source:

- Analog commands via terminal input: The inverter will continue to run without interruption based on the command at the terminal block. If a reverse operation (Rx) signal is ON at the terminal block at startup, the inverter will operate in the reverse direction even if it was running in the forward direction in local operation mode before the reset.
- Digital source commands: All command sources, except terminal block command sources (which are analog sources), are digital command sources that include the keypad, LCD keypad, and communication sources. The inverter stops operating when switching to remote operation mode, and then starts operating when the next command is given.

7.7 Forward or Reverse Run Prevention

The rotation direction of motors can be configured to prevent motors from running in a forward or reverse direction. When reverse direction prevention is configured, pressing the [REV] key on the keypad will cause the motor to decelerate to 0 Hz and stop.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
		0	None				
ADV	09	Run prevention options	Run Prevent	1	Forward Prev	0–2	-
		35		2	Reverse Prev		

Forward/Reverse Run Prevention Setting Details

Code	Description					
	Choos	e a direction to prevent.				
	Settin	ng	Description			
ADV-09 Run	0 None		Do not set run prevention.			
Prevent	1	Forward Prev	Set forward run prevention.			
	2	Reverse Prev	Set reverse run prevention.			

7.8 Power-on Run

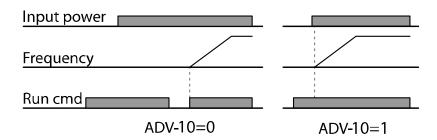
The Power-on Run feature can be set up to start an inverter operation after powering up based on the run commands by terminal inputs (if they are configured).

① Caution

Use caution when operating the inverter with Power-on Run enabled as the motor will begin rotating when the inverter starts up.

To enable Power-on Run, set DRV-06 (command source) to "1 (Fx/Rx-1)" or "2 (Fx/Rx-2)" and ADV-10 to "1". If a run command via a terminal input is on, the inverter starts operating according to the terminal input settings as soon as it is turned on.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
DRV	06	Command source	Cmd Source	1, 2	Fx/Rx-1 or Fx/Rx-2	0–5	-
ADV	10	Power-on run	Power-on Run	1	Yes	0–1	-



Note

• To prevent a repeat fault trip from occurring when a load, such as a fan, is free-running on a Power-on Run, set CON-71 (speed search options) bit 4 to "1". The inverter will perform a speed search at the



- beginning of the operation. If the speed search is not enabled, the inverter will start its operation in a normal V/F pattern and accelerate the motor.
- If the inverter has been turned on without Power-on Run enabled, the terminal block command must be first turned off, and then turned on again to begin the inverter's operation.

7.9 Reset and Restart

The reset and restart operations can be set up for inverter operation following a fault trip, based on the terminal block operation command (if it is configured).

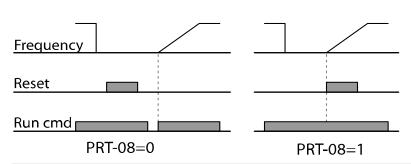
① Caution

- Use caution when operating the inverter with reset and restart enabled as the motor will begin rotating when the inverter starts up.
- Stop the frequency reference signal if you do not want the inverter to run again after a reset.

Set PRT-08 (RST Restart) to "1 (yes)" to allow the inverter to start operating after it is reset if a fault trip occurs. PRT-10 (Retry Delay) sets the delay time for a restart (the time the inverter will wait before it restarts).

The number of auto-restarts (PRT-09) refers to the number of times the inverter will try restarting its operation. If fault trips occur again after a restart, the retry number counts down each time the inverter restarts until the number becomes "0". Once the inverter restarts successfully after the initial fault trip, the inverter does not restart until the next fault trip occurs. The number of auto-restarts set at PRT-09 that decreased after a restart reverts to the original setting value if successful operation continues for a certain period of time.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
DRV	06	Command source	Cmd Source	1	Fx/Rx-1	1–2	-
				2	Fx/Rx-2		
PRT	08	Reset restart setup	RST Restart	1	Yes	No(0) [default] / Yes(1)	-
	09	No. of auto restart	Retry Number	1		0–10	-
	10	Auto restart delay time	Retry Delay	1.0		0–60.0	sec



Note

- To prevent a repeat fault trip from occurring, set the CON-71 (Speed search options) bit 2 to "1". The
 inverter will perform a speed search at the beginning of the operation. If the speed search is not
 enabled, the inverter will start its operation in a normal V/F pattern and accelerate the motor.
- If the inverter has been turned on without "reset and restart" enabled, the terminal block command must first be turned off and then turned on again to begin inverter operation.

7.10 Setting Acceleration and Deceleration Times

7.10.1 Acc/Dec Time Based on Maximum Frequency

Regardless of the operating frequency, acc/dec time values can be set based on the maximum frequency. To set acc/dec time values based on the maximum frequency, set BAS-08 (Acc/Dec reference) to "0 (Max Freq)".

The acceleration time set at DRV-03 (Acceleration time) refers to the time required for the inverter to reach the maximum frequency from a stopped state (0 Hz). Likewise, the value set at DRV-04 (Deceleration time) refers to the time required to return to a stopped state (0 Hz) from the maximum frequency.

Group	Code	Name	LCD Display	Parameter Setting			Setting Range	Unit
	03	Acceleration	Acc Time	75 k	75 kW and less		0.0–600.0	000
	03	time	ACC TIME	90 l	90 kW and up 60		0.0-000.0	sec
DRV	04	Deceleration Dec Time		75 kW and less 30.0		0.0–600.0	000	
DIXV	04	time	Dec IIIIle	90 kW and up 9		90.0	0.0-000.0	sec
	20	Maximum frequency	Max Freq	60.00			0.00-400.00	Hz
BAS	08	Acc/Dec reference	Ramp T Mode	0	Max Freq		Max Freq/Delta Freq	-
	09	Time scale	Time scale	1	0.1		0-2 (0.01/0.1/1)	sec

Acc/Dec Time Based on Maximum Frequency - Setting Details



Code	Description				
	Set BAS-08 to "0 (Max Freq)" to setup acc/dec time based on maximum frequency.				
	Configuration	Description			
	0 Max Freq	Set the acc/dec time based on the maximum frequency.			
	1 Delta Freq	Set the acc/dec time based on the operating frequency.			
BAS-08 Ramp T Mode	seconds, and the f Therefore, the time Max. Freq. Frequency Run cmd Acc	maximum frequency is 60.00 Hz, the acc/dec times are set to 5 requency reference for operation is set at 30 Hz (half of 60 Hz). e required to reach 30 Hz is 2.5 seconds (half of 5 seconds).			
	accurate acc/dec ti	for all time-related values. It is particularly useful when more mes are required, due to load characteristics, or when the ge needs to be extended.			
BAS-09 Time scale	Configuration	Description			
	0 0.01 sec	Sets 0.01 second as the minimum unit.			
	1 0.1 sec	Sets 0.1 second as the minimum unit.			
	2 1 sec	Sets 1 second as the minimum unit.			

① Caution

Note that the range of maximum time values may change automatically when the units are changed. If for example, the acceleration time is set to 6000 seconds, a time scale change from 1 second to 0.01 second will result in a modified acceleration time of 60.00 seconds.

7.10.2 Acc/Dec Time Based on Operation Frequency

Acc/Dec times can be set based on the time required to reach the next frequency from the existing operation frequency. To set the acc/dec time values based on the existing operation frequency, set BAS-08 (Acc/Dec reference) to "1 (Delta Freq)".

Group	Code	Name	LCD Display	Set	tings	Setting Range	Unit
DRV	03	Acceleration time	Acc Time	20.	.0	0.0 - 600.0	sec
DRV	04 Deceleration time		Dec Time	30.0		0.0 - 600.0	sec
BAS	80	Acc/Dec reference	Ramp T Mode	1	Delta Freq	Max Freq/Delta Freq	-

Acc/Dec Time Based on Operation Frequency-Setting Details

Code	Description	
BAS-08 Ramp T Mode	Configuration 0 Max Freq 1 Delta Freq If the acc/dec times used in the operation	Delta Freq)" to set acc/dec times based on operation frequency. Description Set the acc/dec time based on the maximum frequency. Set the acc/dec time based on the operating frequency. Set the acc/dec time based on the operating frequency. set are set to 5 seconds, and multiple frequency references are on in 2 steps, at 10 Hz and 30 Hz, each acceleration stage will fer to the graph below). 30Hz 10Hz 5 7 12 time

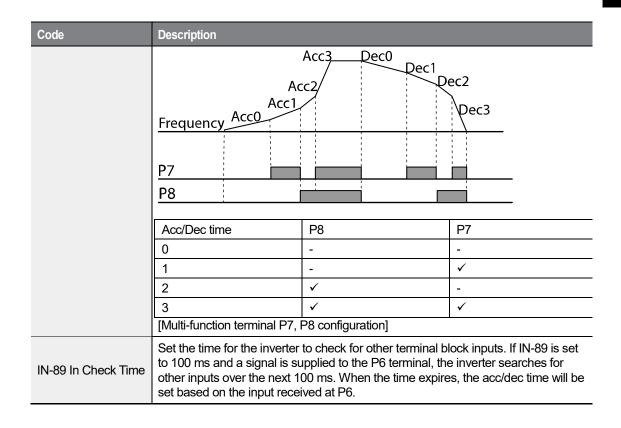
7.10.3 Multi-Step Acc/Dec Time Configuration

The acc/dec times can be configured via a multi-function terminal by setting the ACC (acceleration time) and DEC (deceleration time) codes in the DRV group.

Group	Code	Name	LCD Display	Parameter Setting			Setting Range	Unit
	03	Acceleration time	Acc Time	75 kW a	75 kW and less		0.0–600.0	sec
DRV	03	Acceleration time	Acc Time	90 kW a	and up	60.0	0.0-000.0	Sec
DICV	04	Deceleration time	Dec Time	75 kW a	and less	30.0	0.0–600.0	000
	04	Deceleration time	Dec Time	90 kW a	90 kW and up 90.0		0.0-000.0	sec
BAS	70, 72, 74	Multi-step acceleration time1–3	Acc Time-x	x.xx			0.0–600.0	sec
BAS	71, 73, 75	Multi-step deceleration time1–3	Dec Time-x	x.xx			0.0–600.0	sec
			Px Define	11 XCEL-L				
	65– 75	Px terminal configuration	(Px: P1–P8 [optional:	12	XCEL-N	Л	-	-
IN	'		P9–P11])	49	XCEL-H			
	89	Multi-step command delay time	In Check Time	1			1–5000	ms

Acc/Dec Time Setup via Multi-function Terminals - Setting Details

Code	Description	Description				
BAS-70, 72, 74 Acc Time 1–3	Set multi-step accelera	Set multi-step acceleration time 1–3.				
BAS-71, 73, 75 Dec Time 1–3	Set multi-step decelera	Set multi-step deceleration time 1–3.				
	Choose and configure	the terminals to use for multi-step acc/dec time inputs.				
	Configuration	Description				
	11 XCEL-L	Acc/Dec command-L				
	12 XCEL-M	Acc/Dec command-M				
IN-65–75 Px Define (P1–P8	49 XCEL-H	Acc/Dec command-H				
[optional P9–P11])	acc/dec commands are recognized as binary code inputs and will control the acceleration and deceleration based on parameter values set at BAS-70–75 If, for example, the P7 and P8 terminals are set as XCEL-L and XCEL-M respectively, the following operation will be available.					



7.10.4 Configuring Acc/Dec Time Switch Frequency

By configuring the switch frequency, you can switch between two different sets of acc/dec times (acc/dec gradients) without configuring the multi-function terminals.

Group	Code	Name	LCD Display	Parameter Setting	Setting Range	Unit
DRV	03	Acceleration time	Acc Time	10.0	0.0–600.0	sec
DRV	04	Deceleration time	Dec Time	10.0	0.0-600.0	sec
D.4.0	70	Multi-step acceleration time1	Acc Time-1	20.0	0.0–600.0	sec
BAS	71	Multi-step deceleration time1	Dec Time-1	20.0	0.0–600.0	sec
ADV	60	Acc/dec time switch frequency	Xcel Change Fr	30.00	0–Maximum frequency	Hz/RPM

Acc/Dec Time Switch Frequency Setting Details

Code	Description
ADV-60 Xcel Change Fr	After the acc/dec switch frequency has been set, the acc/dec gradients configured at BAS-70 and 71 will be used when the inverter's operation frequency is at or below the switch frequency. If the operation frequency exceeds the switch frequency, the gradient level configured for the acceleration and deceleration times (set at DRV-03 and DRV-04) will be used. If you configure the P1–P8 [optional: P9–P11]) multi-function input terminals for multi-step acc/dec gradients (XCEL-L, XCEL-M, XCEL-H), the inverter will operate based on the acc/dec inputs at the terminals regardless of the acc/dec switch frequency configurations. DRV-03 DRV-04 ADV-60 BAS-70 Frequency Run cmd

7.11 Acc/Dec Pattern Configuration

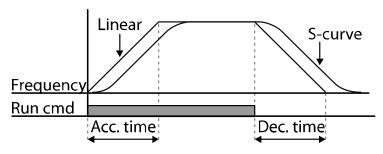
The acc/dec gradient level patterns can be configured to enhance and smooth out the inverter's acceleration and deceleration curves. A linear pattern features a linear increase or decrease to the output frequency, at a fixed rate. An S-curve pattern offers a smoother and more gradual increase or decrease of output frequency, ideal for lift-type loads or elevator doors, etc. The S-curve gradient level can be adjusted using codes ADV-03–06 in the advanced group.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
BAS	08	Acc/dec reference	Ramp T mode	0	Max Freq	0–1	-
	01	Acceleration pattern	Acc Pattern	0	Linear	0–1	
	UI	Acceleration pattern	Accrattem	1	S-curve	0-1	-
	02	Deceleration nattern	Dec Pattern	0	Linear	0–1	
		Deceleration pattern	Dec Pallem	1	S-curve	0-1	
ADV	03	S-curve acc start gradient	Acc S Start	40		1–100	%
	04	S-curve acc end gradient	Acc S End	40		1–100	%
	05	S-curve dec start gradient	Dec S Start	40		1–100	%
	06	S-curve dec end gradient	Dec S End	40		1–100	%

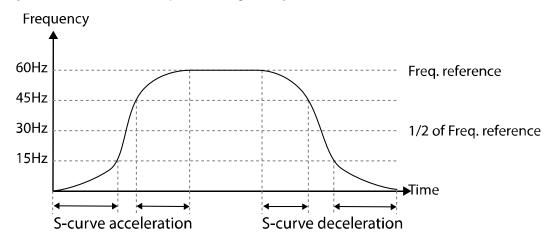
Acc/Dec Pattern Setting Details

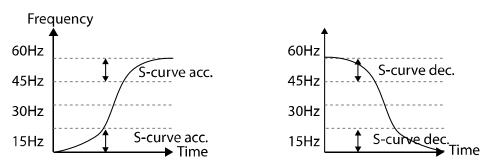
Code	Description
ADV-03 Acc S Start	Sets the gradient level as acceleration starts when using an S-curve, acc/dec pattern. ADV-03 defines the S-curve gradient level as a percentage up to half of the total acceleration. If the frequency reference and maximum frequency are set at 60 Hz and ADV-03 is set to 50%, ADV-03 configures the acceleration up to 30 Hz (half of 60 Hz). The inverter will perform S-curve acceleration in the 0-15 Hz frequency range (50% of 30 Hz). Linear acceleration will be applied to the remaining acceleration within the 15–30 Hz frequency range.
ADV-04 Acc S End	Sets the gradient level as acceleration ends when using an S-curve acc/dec pattern. ADV-03 defines S-curve gradient level as a percentage, above half of the total acceleration. If the frequency reference and the maximum frequency are set at 60 Hz and ADV-04 is set to 50%, setting ADV-04 configures acceleration to increase from 30 Hz (half of 60 Hz) to 60 Hz (end of acceleration). Linear acceleration will be applied within the 30-45 Hz frequency range. The inverter will perform an S-curve

Code	Description
	acceleration for the remaining acceleration in the 45–60 Hz frequency range.
	Sets the rate of S-curve deceleration. Configuration for codes ADV-05 and ADV-06 may be performed the same way as configuring codes ADV-03 and ADV-04.



[Acceleration / deceleration pattern configuration]





[Acceleration / deceleration S-curve pattern configuration]

Note

The actual acc/dec time during an S-curve application

The actual acceleration time = user-configured acceleration time + user-configured acceleration time x starting gradient level/2 + user-configured acceleration time x ending gradient level/2.

The actual deceleration time = user-configured deceleration time + user-configured deceleration time x starting gradient level/2 + user-configured deceleration time x ending gradient level/2.

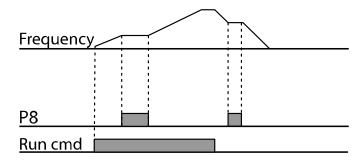
① Caution

Note that actual acc/dec times become greater than the user-defined acc/dec times when S-curve acc/dec patterns are in use.

7.12 Stopping the Acc/Dec Operation

Configure the multi-function input terminals to stop acceleration or deceleration and operate the inverter at a fixed frequency.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
IN	65–75		Px Define (Px: P1–P8 [optional: P9–P11])	25	XCEL Stop	0–51	-



7.13 V/F (Voltage/Frequency) Control

Configure the inverter's output voltages, gradient levels, and output patterns to achieve a target output frequency with the V/F control. The amount of torque boost used during low frequency operations can also be adjusted.

7.13.1 Linear V/F Pattern Operation

A linear V/F pattern configures the inverter to increase or decrease the output voltage at a fixed rate for different operation frequencies based on V/F characteristics. A linear V/F pattern is particularly useful when a constant torque load is applied.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
	09	Control mode	Control Mode	0	V/F	-	-
DRV	18	Base frequency	Base Freq	60.0	00	30.00-400.00	Hz
	19	Start frequency	Start frequency Start Freq 0.5)	0.01–10.00	Hz
BAS	07	V/F pattern	V/F Pattern	0	Linear	-	-

Linear V/F Pattern Setting Details

Code	Description		
DRV-18 Base Freq	Sets the base frequency. A base frequency is the inverter's output frequency when running at its rated voltage. Refer to the motor's rating plate to set this parameter value.		
DRV-19 Start Freq	Sets the start frequency. A start frequency is a frequency at which the inverter starts voltage output. The inverter does not produce an output voltage while the frequency reference is lower than the set frequency. However, if a deceleration stop is made while operating above the start frequency, the output voltage will continue until the operation frequency reaches a full stop (0 Hz). Base Freq. Inverter's rated voltage Voltage Run cmd		

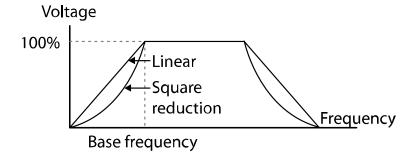
7.13.2 Square Reduction V/F Pattern Operation

Square reduction V/F pattern is ideal for loads such as fans and pumps. It provides non-linear acceleration and deceleration patterns to sustain torque throughout the entire frequency range.

Group	Code	Name	LCD Display	Param	eter Setting	Setting Range	Unit
DAC 07	07	V/F pattern	V/F Pattern	1	Square	0.0	
BAS	07	v/r pallem		3	Square2	0–3	-

Square Reduction V/F pattern Operation - Setting Details

Code	Description					
		Sets the parameter value to "1 (Square)" or "2 (Square2)" depending on the load's start characteristics.				
	Setti	ing	Function			
BAS-07 V/F Pattern	1	Square	The inverter produces an output voltage proportionate to 1.5 square of the operation frequency.			
	3 Square2	The inverter produces an output voltage proportionate to 2 square of the operation frequency. This setup is ideal for variable torque loads, such as fans or pumps.				



7.13.3 User V/F Pattern Operation

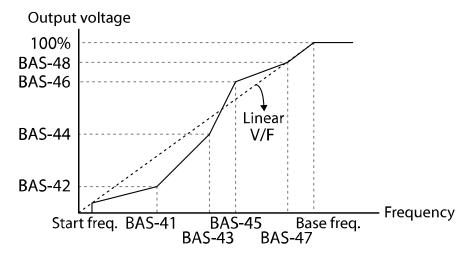
The iS7 inverter allows the configuration of user-defined V/F patterns to suit the load characteristics of a specific motor.

Group	Code	Name	LCD Display	Parame	eter Setting	Setting Range	Unit
	07	V/F pattern	V/F Pattern	2 Us	ser V/F	0–2	-
	41	User frequency 1	User Freq 1	15.00		0-Maximum frequency	Hz
	42	User voltage 1	User Volt 1	User Volt 1 25 (0–100%	%
	43	User frequency 2	User Freq 2	30.00		0-Maximum frequency	Hz
BAS	44	User voltage 2	User Volt 2	50		0–100%	%
	45	User frequency 3	User Freq 3	45.00		0–Maximum frequency	Hz
	46	User voltage 3	User Volt 3	75		0–100%	%
	47	User frequency 4	User Freq 4	60		0-Maximum frequency	Hz
	48	User voltage 4	User Volt 4	100		0–100%	%

User V/F pattern Setting Details

Code	Description
BAS-41 User Freq 1 -BAS-48 User Volt 4	

The 100% output voltage in the figure below is based on the parameter settings of BAS-15 (motor rated voltage). If BAS-15 is set to "0," it will be based on the input voltage.



① Caution

- When a normal induction motor is in use, care must be taken not to change the output pattern from a linear V/F pattern. Non-linear V/F patterns may cause insufficient motor torque or motor overheating due to over-excitation.
- When a user V/F pattern is in use, the forward torque boost (DRV-16) and reverse torque boost (DRV-17) will not operate.

7.14 Torque Boost

7.14.1 Manual Torque Boost

Manual torque boost enables users to adjust the output voltage during low-speed operation or motor start. You can increase the low-speed torque or improve motor-starting properties by manually increasing the output voltage. Configure the manual torque boost while running loads that require a high starting torque, such as lift-type loads.

Group	Code	Name	LCD Display	Para	ameter Setting	Setting Range	Unit
	15	Torque boost options	Torque Boost	0	Manual	0–1	-
DRV	16	Forward torque boost	Fwd Boost*	2.0		0.0–15.0	%
	17	Reverse torque boost	Rev Boost*	2.0		0.0–15.0	%

^{*} For 90 kW-160 kW model types, the default setting value is 1.0 [%].

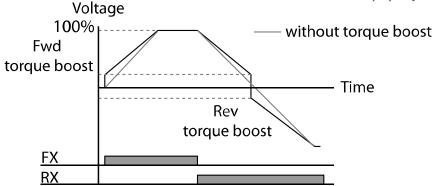
Manual Torque Boost Setting Details

Code	Description
DRV-16 Fwd Boost	Sets the torque boost for forward operation.
DRV-17 Rev Boost	Sets the torque boost for reverse operation.

Output Voltage = Output voltage affected by DRV-16,17 Manual torque boost parameter

= V/F voltage + Boosted voltage

= $(Maximum\ voltage\ -\ Boosted\ voltage) \times \frac{current\ frequency}{Respective} + Boosted\ voltage$



Caution

Excessive torque boost will result in over-excitation and motor overheating.

7.14.2 Auto Torque Boost

Set DRV-15 to "1 (Auto)" to enable auto torque boost. While manual torque boost adjusts the inverter output based on the setting values, regardless of the type of load used during the operation, auto torque boost enables the inverter to automatically calculate the amount of output voltage required for the torque boost based on the entered motor parameters.

Because auto torque boost requires motor-related parameters, such as stator resistance, inductance, and no-load current, auto tuning (BAS-20) has to be performed before the auto torque boost can be configured. Similarly to manual torque boost, configure auto torque boost while running a load that requires high starting torque, such as lift-type loads. Refer to 8.9 Auto Tuning on page 220.

Group	Code	Name	LCD Display	Pai	rameter Setting	Setting Range	Unit
DRV	15	Torque boost mode	Torque Boost	1	Auto	0–2	-
BAS	20	Auto tuning	Auto Tuning	2	Rs+Lsigma	0–3	-

7.14.3 Advanced Auto Torque Boost

Manual Torque Boost, regardless of load characteristics, outputs the inverter voltage according to the torque boost amount set by the user. Auto Torque Boost automatically calculates the boost amount, but auto tuning the motor is required. For Advanced Auto Torque Boost, the inverter outputs the inverter voltage by adjusting the boost amount according to the load itself without auto tuning the motor.

Advanced Automatic Torque Boost is adjusted according to the load determined by the Adv ATB M Gain, Adv ATB G Gain of DRV-27 and 28 values and it can be used when starting torque is insufficient or when excessive current flows..

Group	Cod e	Name	LCD Display	Par	rameter Setting	Setting Range	Unit
DRV	15	Torque boost mode	Torque Boost	2	Advanced Auto	0–2	-
	16	Fwd Boost Note1)	Fwd Boost	2.0		0-15	%
	17	Rev Boost Note2)	Boost Note2) Rev Boost			0-15	%
	26	Adv ATB Filter	Adv ATB Filter	100		1-1000	msec
	27	Adv ATB M Gain	Adv ATB M Gain	50.	0	0-300.0	%
	28	Adv ATB G Gain	Adv ATB G Gain	50.	0	0-300.0	%

^{*} Note 1, Note 2) For 90 kW – 160 kW products, the factory shipment value is 1.0 [%].

Advanced Auto Torque Boost Setting Details

Code	Description
Code	Description

Code	Description
DRV-16 Fwd Boost	Adjusts the torque boost amount for forward rotation
DRV-17 Rev Boost	Adjusts the torque boost amount for reverse rotation.
DRV-26 Adv ATB Filter	Filter gain for calculating the Auto Torque Boost value.
DRV-27 Adv ATB M Gain	Gain for calculating the reverse Auto Torque Boost value.
DRV-28 Adv ATB G Gain	Gain for calculating the regeneration Auto Torque Boost value.

If there is no load, the additional voltage amount due to Auto Torque Boost is 0, which gives the same result as the normal manual boost.

When the load is applied, the amount of compensation voltage varies depending on the operation and reverse directions.

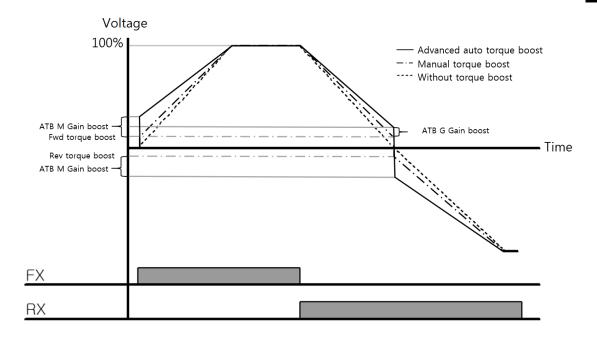
If you set the DRV-16 and DRV-17 values differently when using Advanced Auto Torque Boost at no load, a current hunting operation may occur.

Output voltage = Primary output voltage + Secondary output voltage

- · Primary output voltage
- = Output voltage affected by DRV-16,17 Manual torque boost parameter
- = $(Maximum\ voltage\ -\ Boosted\ voltage) \times \frac{Current\ frequency}{Base\ frequency} + Boosted\ voltage$
- · Secondary output voltage
- = Output voltage affected by DRV-27,28 ATB M/G Gain parameter and motor load
- = Motor rated slip frequency $\times \frac{\text{Motor max phase voltage}}{\text{Base frequency}} \times ATB \ M/G \ Gain \times$

Current output current

Motor rated current



① Caution

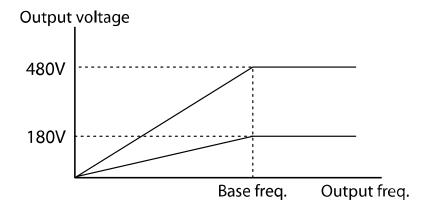
If the torque boost amount is set too large, overheating of the motor due to over-excitation will occur.

7.15 Output Voltage Setting

Output voltage settings are required when a motor's rated voltage differs from the input voltage to the inverter. Set BAS-15 to configure the motor's rated operating voltage. The set voltage becomes the output voltage of the inverter's base frequency. When the inverter operates above the base frequency, and when the motor's voltage rating is lower than the input voltage at the inverter, the inverter adjusts the voltage and supplies the motor with the voltage set at BAS-15 (motor-rated voltage). If the motor's rated voltage is higher than the input voltage at the inverter, the inverter will supply the inverter input voltage to the motor.

If BAS-15 (motor-rated voltage) is set to "0," the inverter corrects the output voltage based on the input voltage in the stopped condition. If the frequency is higher than the base frequency andwhen the input voltage is lower than the parameter setting, the input voltage will be the inverter output voltage.

(Group	Code	Name	LCD Display	Parameter Setting	Setting Range	Unit
E	BAS	15	Motor rated voltage	Rated Volt	220	0, 180–480	V



7.16 Start Mode Setting

Select the start mode to use when the operation command is input with the motor in the stopped condition.

7.16.1 Acceleration Start

Acceleration start is a general acceleration mode. If there are no extra settings applied, the motor accelerates directly to the frequency reference when the command is input.

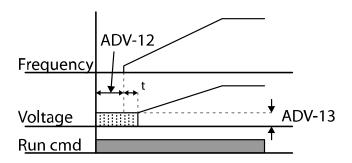
Group	Code	Name	LCD Display	Paramet	er Setting	Setting Range	Unit
ADV	07	Start mode	Start mode	0	Acc	-	-

7.16.2 Start After DC Braking

This start mode supplies a DC voltage for a set amount of time to provide DC braking before an inverter starts to accelerate a motor. If the motor continues to rotate due to inertia, DC braking will stop the motor, allowing the motor to accelerate from a stop. DC braking can also be used with a mechanical brake connected to a motor shaft when a constant torque load is applied, if a constant torque is required after the mechanical brake is released.

Group	Code	Name	LCD Display	Paramet	ter Setting	Setting Range	Unit
	07	Start mode	Start Mode	1	DC-Start	-	-
ADV	12	Start DC braking time	DC-Start Time	0.00		0.00-60.00	sec
	13	DC Injection Level	DC Inj Level	50		0–200	%

182



① Caution

The amount of DC braking required is based on the motor's rated current. Do not use DC braking resistance values that can cause current draw to exceed the rated current of the inverter. If the DC braking resistance is too high or brake time is too long, the motor may overheat or be damaged.

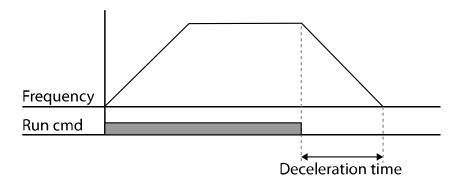
7.17 Stop Mode Setting

Select Stop mode to stop the inverter operation.

7.17.1 Deceleration Stop

Deceleration stop is a general stop mode. If there are no extra settings applied, the motor decelerates to 0 Hz and stops, as shown in the figure below.

Group	Code	Name	LCD Display	Paramete	r Setting	Setting Range	Unit
ADV	08	Stop mode	Stop Mode	0	Dec	-	-



7.17.2 Stop after DC Braking

When the operation frequency reaches the set value during deceleration (DC braking frequency) the inverter stops the motor by supplying DC power to the motor. With a stop command input, the inverter begins decelerating the motor. When the frequency reaches the DC braking frequency set at ADV-17, the inverter supplies DC voltage to the motor and stops it.

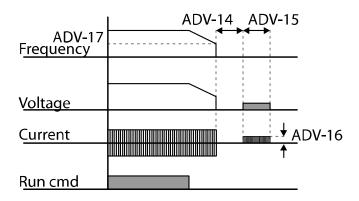
Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
	08	Stop mode	Stop Mode	0	Dec	0–4	-
	14	Output block time before braking	DC-Block Time	0.10		0.00-60.00	sec
ADV	15	DC braking time	DC-Brake Time	1.00		0–60	sec
	16	DC braking amount	DC-Brake Level	50		0–200	%
	17	DC braking frequency	DC-Brake Freq	5.00		0.00-60.00	Hz

Note

DC braking does not produce stop torque. Install appropriate peripheral devices if stop torque is required in your application.

DC Braking After Stop Setting Details

Code	Description
ADV-14 DC-Block Time	Sets the time to block the inverter output before DC braking. If the inertia of the load is great, or if the DC braking frequency (ADV-17) is set too high, a fault trip may occur due to overcurrent conditions when the inverter supplies DC voltage to the motor. Prevent overcurrent fault trips by adjusting the output block time before DC braking.
ADV-15 DC- Brake Time	Sets the time duration for the DC voltage supply to the motor.
ADV-16 DC- Brake Level	Sets the amount of DC braking to apply. The parameter setting is based on the rated current of the motor.
ADV-17 DC- Brake Freq	Sets the frequency to start DC braking. When the frequency is reached, the inverter starts deceleration. If the dwell frequency is set lower than the DC braking frequency, the dwell operation will not work and DC braking will start instead.



① Caution

- The motor can overheat or be damaged if an excessive amount of DC braking is applied to the motor or if the DC braking time is set to a high value.
- DC braking is configured based on the motor's rated current. To prevent overheating or damaging motors, do not set the current value higher than the inverter's rated current.

7.17.3 Free Run Stop

When the operation command is off, the inverter output turns off, and the load stops due to residual inertia.

Group	Code	Name	LCD Display	Param	neter Setting	Setting Range	Unit
ADV	08	Stop mode	Stop Mode	2	Free-Run	0–4	-
Frequency, voltage							
voltage /				<u>!</u>			
Run cmd							

① Caution

When there is high inertia on the output side and the motor is operating at high speed, the load's inertia will cause the motor to continue rotating even after the inverter output is blocked.



7.17.4 Power Braking

When the inverter's DC voltage rises above a specified level due to motor-regenerated energy, a control is made to either adjust the deceleration gradient level or reaccelerate the motor in order to reduce the regenerated energy. Power braking can be used when short deceleration times are needed without braking resistors, or when optimum deceleration is needed without causing an over voltage fault trip.

Group	Code	Name	LCD Display	Param	eter Setting	Setting Range	Unit
ADV	08	Stop mode	Stop Mode	4	Power Braking	-	-

① Caution

- To prevent overheating or damaging the motor, do not apply power braking to loads that require frequent deceleration.
- Stall prevention and power braking only operate during deceleration, and power braking takes priority over stall prevention. In other words, when both bit 3 of PRT-50 (stall prevention and flux braking) and ADV-08 (braking options) are set, power braking will take precedence.
- Note that if the deceleration time is too short or the inertia of the load is too great, an overvoltage fault trip may occur.
- Note that if a free run stop is used, the actual deceleration time may be longer than the preset deceleration time.

7.18 Frequency Limit

The operation frequency can be limited by setting a maximum frequency, start frequency, upper limit frequency, and lower limit frequency.

7.18.1 Frequency Limit Using Maximum Frequency and Start Frequency

Group	Code	Name	LCD Display	.CD Display Parameter Setting		Unit
DRV	19	Start frequency	Start Freq	0.50	0.01–10.00	Hz
טאע	20	Maximum frequency	Max Freq	60.00	40.00–400.00	Hz

Frequency Limit Using Maximum Frequency and Start Frequency - Setting Details

Code	Description
DRV-19 Start Freq	Sets the lower limit value for all speed unit parameters that are expressed in Hz or rpm. Any operation frequency input that is lower than the start frequency is treated as a 0 Hz input.
DRV-20 Max Freq	Sets an upper limit frequency to all speed unit parameters that are expressed in Hz or rpm, except for the base frequency (DRV-18). An operation frequency cannot be set higher than the maximum frequency.

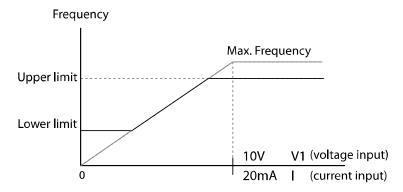
7.18.2 Frequency Limit Using Upper and Lower Limit Frequency Values

Group	Code	Name	LCD Display	Param	eter Setting	Setting Range	Unit
	24	Frequency limit	Freq Limit	0	No	No/Yes	-
AD)/	25	Frequency lower limit value	Freq Limit Lo	0.50		0.0–maximum frequency	Hz
ADV	26	Frequency upper limit value	Freq Limit Hi	60.00		0.5–maximum frequency	Hz
	34	Jog Freqency Limit	Jog Freq Limit	1	Yes	No/Yes	-

Frequency Limit Using Upper and Lower Limit Frequencies - Setting Details

Code	Description
ADV-24 Freq Limit	The initial setting is "0 (No)." Changing the setting to "1 (Yes)" allows you to set the lower limit frequency (ADV-25) and the upper limit frequency (ADV-26). When the setting is "0 (No)", codes ADV-25 and ADV-26 are not visible.
ADV-25 Freq Limit Lo ADV-26 Freq Limit Hi	Sets upper and lower frequency limits. All frequency selections are restricted to frequencies from within the upper and lower limits. This restriction also applies when you in input a frequency reference using the keypad.
ADV-34 Jog Freq Limit	This code allows you to select whether to use the frequency limit function with frequency upper/lower limits for jog operations. When ADV-34 is set to "Yes", the frequency limit is applied if the frequency limit function using the frequency upper/lower limits is set the same as a normal operation for jog operations. When ADV-34 is set to "No", the frequency limit value is not applied even if the frequency limit function using the frequency upper/lower limits is set for jog operations. However, the frequency limit for the maximum frequency and the start frequency applies.

without upper / lower limits



① Caution

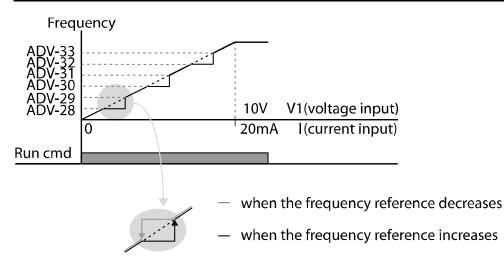
- When ADV-24 (Freq Limit) is set to "Yes," the frequency set at ADV-25 (Freq Limit Lo) is the minimum frequency (Low Freq). If ADV-24 (Freq Limit) is set to "No," the frequency set at DRV-19 (Start Freq) becomes the minimum frequency.
- When ADV-24 (Freq Limit) is set to "Yes," the frequency set at ADV-26 (Freq Limit Hi) is the maximum frequency (High Freq). If ADV-24 (Freq Limit) is set to "No," the frequency set at DRV-20 (Max Freq) becomes the maximum frequency.

7.18.3 Frequency Jump

Use frequency jump to avoid mechanical resonance frequencies. The inverter will avoid specific frequency ranges during acceleration and deceleration. Operation frequencies cannot be set within the preset frequency jump band.

When the operation frequency is increased while the frequency parameter setting value (voltage, current, RS-485 communication, keypad setting, etc.) is within a jump frequency band, the frequency will be maintained at the lower limit value of the frequency band. Then, the frequency will increase when the frequency parameter setting exceeds the range of frequencies used by the frequency jump band.

Group	Code	Name	LCD Display	Para	meter Setting	Setting Range	Unit
	27	Frequency jump	Jump Freq	0	No	No/Yes	-
	28	Jump frequency lower limit1	Jump Lo 1	10.00		0.00–Jump frequency upper limit 1	Hz
	29	Jump frequency upper limit1	Jump Hi 1	15.00		Jump frequency lower limit 1–Maximum frequency	Hz
ADV	30	Jump frequency lower limit 2	Jump Lo 2	20.00		0.00–Jump frequency upper limit 2	Hz
	31	Jump frequency upper limit 2	Jump Hi 2	25.00		Jump frequency lower limit 2–Maximum frequency	Hz
	32	Jump frequency lower limit 3	Jump Lo 3	30.00		0.00–Jump frequency upper limit 3	Hz
	33	Jump frequency upper limit 3	Jump Hi 3	35.00		Jump frequency lower limit 3–Maximum frequency	Hz





7.19 2nd Operation Mode Setting

Apply two types of operation modes and switch between them as required. For both the first and second command source, set the frequency after shifting operation commands to the multi-function input terminal. Mode switching can be used to stop remote control during an operation using the communication option and to switch the operation mode to operate via the local panel, or to operate the inverter from another remote control location.

Select one of the multi-function terminals from codes IN-65–75 and set the parameter value to "15 (2nd Source)".

Group	Code	Name LCD Display Parameter Setting		meter Setting	Unit	
	06	Command source	Cmd Source	1	Fx/Rx-1	-
DRV	07	Frequency reference source	Freq Ref Src	2	V1	-
	08	Torque reference source	Trq Ref Src	0	Keypad-1	
	04	2nd command source	Cmd 2nd Src	0	Keypad	-
BAS	05	2nd frequency reference source	Freq 2nd Src	0	KeyPad-1	-
	06	2nd torque reference source	Trq 2 nd Src	0	Keypad-1	
IN	65–75	Px terminal configuration	Px Define (Px: P1–P8 [optional: P9–P11])	15	2nd Source	-

2nd Operation Mode Setting Details

Code	Description
BAS-04 Cmd 2nd Src BAS-05 Freq 2nd Src	If signals are provided to the multi-function terminal set as the 2nd command source (2nd Source), the operation can be performed using the values set at BAS-04–05 instead of the values set at DRV-06 and DRV-07. The 2nd command source settings cannot be changed while operating with the 1st command source (Main Source).
BAS-06 Trq 2nd Src	If signals are provided to the multi-function terminal set as the 2nd command source (2nd Source), the operation can be performed using the torque reference set at BAS-06 instead of the value set at DRV-08. Codes DRV-08 and BAS-06 are visible only when DRV-09 (Control mode) is set to "sensorless" or "vector" control mode, and DRV-10 (Torque control) is set to "Yes."

① Caution

When you set the multi-function terminal to the 2nd command source (2nd Source) and input the
signal, the inverter's operation state changes according to the operation frequency and the operation
command configured for the 2nd command. Before shifting the input to the multi-function terminal,

- ensure that the 2nd command is correctly set. An overvoltage fault trip may occur if the deceleration time is too short or the inertia of the load is too high.
- Depending on the parameter settings, the inverter may stop operating when you switch command modes.

7.20 Multi-function Input Terminal Control

Filter time constants and the type of multi-function input terminals can be configured to improve the response of the input terminals.

Group	Code	Name	LCD Display	Parameter Setting	Setting Range	Unit
	85	Multi-function input terminal On filter	DI On Delay	0	0–10000	ms
INI	86	Multi-function input terminal Off filter	DI Off Delay	0	0–10000	ms
IN	87	Multi-function input terminal selection	DI NC/NO Sel	0000 0000*	-	-
	90	Multi-function input terminal status	DI Status	0000 0000*	-	-

^{*} From the last bit to the first, the bits are for multi-purpose inputs P1–P8 (the last bit is for input 1, and the first bit is for input 8).

Multi-function Input Terminal Control Setting Details

Code	Description	Description				
IN-85 DI On Delay, IN-86 DI Off Delay		When the terminal receives an On or Off input signal, it is recognized as an On or Off signal after the set delay time has elapsed.				
IN-87 DI NC/ NO Sel	correspor segment Open) co as a B ter	Selects terminal contact types for each input terminal. The position of the dot corresponds to the segment that is on as shown in the table below. With the bottor segment on, it indicates that the terminal is configured as an A terminal (Normally Open) contact. With the top segment on, it indicates that the terminal is configured as a B terminal (Normally Closed) contact. Terminals are numbered P1–P8, from right to left.				
	Type	B terminal status (Normally Closed)	A terminal status (Normally Open)			
	Keypad					
IN-90 DI Status	terminal a The Off c	the configuration of each contact. Whe at DRV-87, the On condition is indicate ondition is indicated when the bottom s are configured as B terminals, the segr are numbered P1–P8, from right to le	d by the top segment turning on. segment is turned on. When ment dots behave conversely.			
	Туре	A terminal setting (On)	A terminal setting (Off)			
	Keypad					

7.21 Expanded I/O Control with an Optional I/O Expansion Module

You can install an I/O expansion module to add 3 digital input and 3 digital output (relay output) multifunction terminals to the iS7 inverter. The following table lists the function codes to control the expanded I/O functions.

Group	Code	Name	LCD Display	Para	meter Setting	Unit
	73	Px terminal configuration (P9 terminal function)	P9 Define	0	None	-
IN	74	Px terminal configuration (P10 terminal function)	P10 Define	0	None	-
	75	Px terminal configuration (P11 terminal function)	P11 Define	0	None	-
	34	Multi-function relay-3	Relay 3	2	FDT-2	-
OUT	35	Multi-function relay-4	Relay 4	3	FDT-3	-
	36	Multi-function relay-5	Relay 5	4	FDT-4	-

Learning Advanced Features

This chapter describes the advanced features of the iS7 inverter.

Operating with Auxiliary References 8.1

Frequency references can be configured with various calculated conditions that use the main and auxiliary frequency references simultaneously. The main frequency reference is used as the operating frequency, while auxiliary references are used to modify and fine-tune the main reference.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
DRV	07	Frequency reference source	Freq Ref Src	0	Keypad-1	0–9	-
	01	Auxiliary frequency reference source	Aux Ref Src	1	V1	0–5	-
BAS	02	Auxiliary frequency reference calculation type	Aux Calc Type	0	M+(G*A)	0–7	-
	03	Auxiliary frequency reference gain	Aux Ref Gain	-	0.00	-200.0–200.0	%
IN	65–75	Px terminal configuration	Px Define	36	dis Aux Ref	0–48	-

^{*} Codes IN-01-16 must be set to the default values, and IN-06 (V1 Polarity), set to "1 (Bipolar)".

The table above lists the available calculated conditions for the main and auxiliary frequency references. Refer to the table to see how the calculations apply to an example where the DRV-07 Frq Src code has been set to "0 (Keypad-1)", and the inverter is operating at a main reference frequency of 30.00 Hz. Signals at -10 to +10 V are received at terminal V1, with the reference gain set at 5%. In this example, the resulting frequency reference is fine-tuned within the range of 27.00-33.00 Hz* (+/-5% of 60 Hz).

Auxiliary Reference Setting Details

Code	Description						
	Sets the input type to be used for the auxiliary frequency reference.						
	Cor	nfiguration	Description				
	0	None	Auxiliary frequency reference is disabled.				
BAS-01 Aux Ref Src	1	V1	Sets the V1 (voltage) terminal at the control terminal block as the source of the auxiliary frequency reference.				
Sic	2	I1	Sets the I1 (current) terminal at the control terminal block as the source of the auxiliary frequency reference.				
	3 V2	V2	Sets the V2 (voltage) terminal at the optional I/O expansion module as the source of the auxiliary frequency reference.				

Code	Description				
	4 I2 Sets the I2 (current) terminal at the optional I/O expansion module as the source of the auxiliary frequency reference.				
	5 Pulse Sets the pulse input terminal at the optional encoder module as the source of the auxiliary frequency reference.				
BAS-02 Aux Calc Type	Sets the auxiliary reference gain with BAS-03 (Aux Ref Gain) to configure the auxiliary reference and set BAS-02 to decide the percentage to be reflected when calculating the main reference. Note that items 4–7 below may result in either plus (+) or minus (-) references (forward or reverse operation) even when unipolar analog inputs are used.* Configuration Formula for frequency reference 0 M+(G*A) Main reference + (BAS-03 x BAS-01 x IN-01) 1 M*(G*A) Main reference x (BAS-03 x BAS-01) 2 M/(G*A) Main reference / (BAS-03 x BAS-01) 3 M+{M*(G*A)} Main reference + (Main reference x [BAS-03 x BAS-01]) 4 M+G*2*(A-50) Main reference + BAS-03 x 2 x (BAS-01–50) x IN-01 5 M*{G*2*(A-50)} Main reference x (BAS-03 x 2 x [BAS-01–50]) 6 M/{G*2*(A-50)} Main reference / (BAS-03 x 2 x [BAS-01–50]) 7 M+M*G*2* Main reference + Main reference x BAS-03 x 2 x (BAS-01–50)) M: Main frequency reference (Hz or rpm) G: Auxiliary reference gain (%) A: Auxiliary frequency reference (Hz or rpm) or gain (%) Note When the maximum frequency value is high, output frequency deviation may occur due to analog input variation and deviations in the calculations.				
BAS-03 Aux Ref Gain	Adjusts the size of the input (BAS-01 Aux Ref Src) configured for the auxiliary frequency.				
IN-65–75 Px Define Set one of the multi-function input terminals to "40 (dis Aux Ref)" and turn it on to disable the auxiliary frequency reference. The inverter will operate using the main frequency reference only.					
Command frequency M set at DRV-07 Function Auxiliary frequency A set at BAS-01 O Function Main, Aux, Gain frequency					



The auxiliary command frequency is turned off when the terminal input (Px) set to "40 (dis Aux Ref)" is on.

Auxiliary Reference Operation Ex #1

Keypad Frequency Setting is Main Frequency, and V1 Analog Voltage is Auxiliary Frequency

- Main frequency (DRV-07): Keypad (operation frequency 30 Hz)
- Maximum frequency setting (DRV-20): 400 Hz
- Auxiliary frequency setting (BAS-01): V1 [Display by percentage (%) or auxiliary frequency (Hz) depending on the operation setting condition]
- Auxiliary reference gain setting (BAS-03): 50%
- IN-01-32: Factory default

Example: An input voltage of 6 V is supplied to V1, and the frequency corresponding to 10 V is 60 Hz. The table below shows the auxiliary frequency A as 36 Hz [=60 Hz X (6 V/10 V)] or 60% [= 100% X (6 V/10 V)].

Se	tting *	Calculating final command frequency**
0	M[Hz]+(G[%]*A[Hz])	30 Hz(M)+(50%(G)x36 Hz(A))=48 Hz
1	M[Hz]*(G[%]*A[%])	30 Hz(M)x(50%(G)x60%(A))=9 Hz
2	M[Hz]/(G[%]*A[%])	30 Hz(M)/(50%(G)x60%(A))=100 Hz
3	M[Hz]+{M[Hz]*(G[%]*A[%])}	30 Hz(M)+{30[Hz]x(50%(G)x60%(A))}=39 Hz
4	M[Hz]+G[%]*2*(A[%]-50[%])[Hz]	30 Hz(M)+50%(G)x2x(60%(A)–50%)x60 Hz=36 Hz
5	M[HZ]*{G[%]*2*(A[%]-50[%])}	30 Hz(M)x{50%(G)x2x(60%(A)–50%)}=3 Hz
6	M[HZ]/{G[%]*2*(A[%]-50[%])}	30 Hz(M)/{50%(G)x2x(60%-50%)}=300 Hz
7	M[HZ]+M[HZ]*G[%]*2*(A[%]-50[%])	30 Hz(M)+30 Hz(M)x50%(G)x2x(60%(A)–50%)=33 Hz

^{*} M: Main frequency reference (Hz or rpm)/G: Auxiliary reference gain (%)/A: Auxiliary frequency reference (Hz or rpm) or gain (%).

^{**} If the frequency setting is changed to rpm, it is converted to rpm instead of Hz.

Auxiliary Reference Operation Ex #2

The Keypad Frequency Setting is the Main Frequency, and I2 Analog Voltage is the Auxiliary Frequency

- Main frequency (DRV-07): Keypad (Operation frequency 30 Hz)
- Maximum frequency setting (BAS-20): 400 Hz
- Auxiliary frequency setting (BAS-01): I1 [Display by percentage (%) or auxiliary frequency (Hz) depending on the operation setting condition]
- Auxiliary reference gain setting (BAS-03): 50%
- IN-01-32: Factory default

Example: An input current of 10.4 mA is applied to I1, with the frequency corresponding to 20 mA of 60 Hz. The table below shows auxiliary frequency A as 24 Hz [=60[Hz] X {(10.4[mA]-4[mA])/(20[mA] -4[mA])}] or 40% [=100[%] X {(10.4[mA] - 4[mA])/(20[mA] - 4[mA])}].

	tting*	Calculating final command frequency**
0	M[Hz]+(G[%]*A[Hz])	30 Hz(M)+(50%(G)x24 Hz(A))=42 Hz
1	M[Hz]*(G[%]*A[%])	30 Hz(M)x(50%(G)x40%(A))=6 Hz
2	M[Hz]/(G[%]*A[%])	30 Hz(M)/(50%(G)x40%(A))=150 Hz
3	M[Hz]+{M[Hz]*(G[%]*A[%])}	30 Hz(M)+{30[Hz]x(50%(G)x40%(A))}=36 Hz
4	M[Hz]+G[%]*2*(A[%]-50[%])[Hz]	30 Hz(M)+50%(G)x2x(40%(A)-50%)x60 Hz=24 Hz
5	M[HZ]*{G[%]*2*(A[%]-50[%])	30 Hz(M)x{50%(G)x2x(40%(A)–50%)}=-3 Hz (Reverse)
6	M[HZ]/{G[%]*2*(A[%]-50[%])}	30 Hz(M)/{50%(G)x2x(60%–40%)}=-300 Hz (Reverse)
7	M[HZ]+M[HZ]*G[%]*2*(A[%]-50[%])	30 Hz(M)+30 Hz(M)x50%(G)x2x (40%(A)–50%)=27 Hz

^{*} M: Main frequency reference (Hz or rpm)/G: Auxiliary reference gain (%)/A: Auxiliary frequency reference Hz or rpm) or gain (%).

^{**} If the frequency setting is changed to rpm, it is converted to rpm instead of Hz.

Auxiliary Reference Operation Ex #3

V1 is the Main Frequency, and I1 is the Auxiliary Frequency

- Main frequency (DRV-07): V1 (frequency command setting to 5 V and is set to 30 Hz)
- Maximum frequency setting (DRV-20): 400 Hz
- Auxiliary frequency (BAS-01): I1 [Display by percentage (%) or auxiliary frequency (Hz) depending on the operation setting condition]
- Auxiliary reference gain (BAS-03): 50%
- IN-01-32: Factory default

Example: An input current of 10.4 mA is applied to I1, with the frequency corresponding to 20 mA of 60 Hz. The table below shows auxiliary frequency A as 24 Hz [=60[Hz]x{(10.4[mA]-4[mA])/(20[mA]-4[mA])}] or 40% [=100[%] x {(10.4[mA] - 4[mA]) /(20 [mA] - 4[mA])}}.

	070 [100[70] X [(10.1[1111] 1[11111]) 7(20	
Set	ting*	Calculating final command frequency**
0	M[Hz]+(G[%]*A[Hz])	30 Hz(M)+(50%(G)x24 Hz(A))=42 Hz
1	M[Hz]*(G[%]*A[%])	30 Hz(M)x(50%(G)x40%(A))=6 Hz
2	M[Hz]/(G[%]*A[%])	30 Hz(M)/(50%(G)x40%(A))=150 Hz
3	M[Hz]+{M[Hz]*(G[%]*A[%])}	30 Hz(M)+{30[Hz]x(50%(G)x40%(A))}=36 Hz
4	M[Hz]+G[%]*2*(A[%]-50[%])[Hz]	30 Hz(M)+50%(G)x2x(40%(A)–50%)x60 Hz=24 Hz
5	M[HZ]*{G[%]*2*(A[%]-50[%])}	30 Hz(M)x{50%(G)x2x(40%(A)–50%)}=-3 Hz (Reverse)
6	M[HZ]/{G[%]*2*(A[%]-50[%])}	30 Hz(M)/{50%(G)x2x(60%-40%)}=-300 Hz(Reverse)
7	M[HZ]+M[HZ]*G[%]*2*(A[%]-50[%])	30 Hz(M)+30 Hz(M)x50%(G)x2x(40%(A)–50%)=27 Hz

^{*} M: Main frequency reference (Hz or rpm)/G: Auxiliary reference gain (%)/A: Auxiliary frequency reference (Hz or rpm) or gain (%).

Note

When the maximum frequency value is high, output frequency deviation may occur due to analog input variation and deviations in the calculations.

^{**}If the frequency setting is changed to rpm, it is converted to rpm instead of Hz.

Jog Operation 8.2

The jog operation allows for temporary control of the inverter. You can enter a jog operation command using the multi-function terminals.

The jog operation is the second-highest priority operation, after the dwell operation. If a jog operation is requested while operating the multi-step, up-down, or 3-wire operation modes, the jog operation overrides all other operation modes.

Jog Operation 1-Forward Jog via Multi-function Terminal 8.2.1

The jog operation is available using the multi-function terminal input. To start a forward jog operation, an Fx operation command must be entered. The table below lists parameter settings for a forward jog operation using the multi-function terminal input.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
DRV	11	Jog frequency	JOG Frequency	10.00		0.5– Max Freq	Hz
	12	Jog operation acceleration time	JOG Acc Time	20.00		0.00–600.00	sec
	13	Jog operation deceleration time	JOG Dec Time	30.00		0.00-600.00	sec
IN	65–75	Px terminal configuration	Px Define(Px: P1–P8 [optional: P9–P11])	6	JOG	-	-

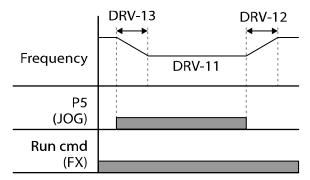
Forward Jog Details

Code	Description			
IN-65–75 Px Define	Select an input terminal from IN-65–75 (P1–P8 [optional: P9-P11]) and set it to "6 (Jog)". P1 FX P5 JOG [Terminal settings for jog operation using the P5 terminal]			
DRV-11 JOG Frequency	Sets the operation frequency.			
DRV-12 JOG Acc Time Sets the acceleration speed for a jog operation.				
DRV-13 JOG Dec Time	Sets the deceleration speed for a jog operation.			

If a signal is entered at the jog terminal while an Fx operation command is on, the operation



frequency changes to the jog frequency and the jog operation begins.

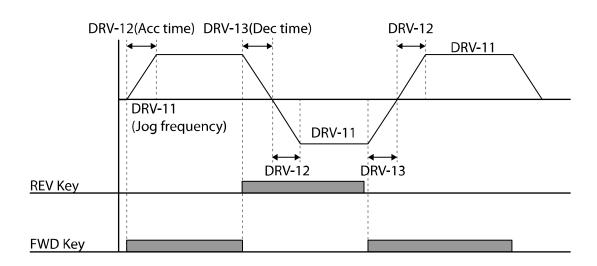


Jog Operation 2-Forward/Reverse Jog via Multi-function 8.2.2 **Terminal**

For jog operation 1, an operation command must be entered to start an operation, but while using jog operation 2, a terminal that is set for a forward or reverse jog also starts an operation.

The priorities for the frequency, acc/dec time and terminal block input during operation in relation to other operating modes (Dwell, 3-wire, up/down, etc.) are identical to jog operation 1. If a different operation command is entered during a jog operation, it is ignored and the operation maintains the jog frequency.

Group	Code	Name	LCD Display	Parameter setting		Setting Range	Unit
DRV	11	Jog frequency	JOG Frequency	10.00		0.5-Max Freq	Hz
	12	Jog operation acceleration time	JOG Acc Time	20.00		0.00-600.00	sec
	13	Operation deceleration time	JOG Dec Time	30.00		0.00-600.00	sec
IN	65–75	Px terminal configuration	Px Define (Px: P1–P8 [optional: P9–P11])	46	FWD JOG	-	-
				47	REV JOG		



8.2.3 Jog Operation via Keypad Input

The jog operation is available using the keypad input as well.

The priorities for the frequency, acc/dec time, and terminal block input during an operation in relation to other operating modes (Dwell, 3-wire, up/down, etc.) are identical to jog operations using the terminal input.

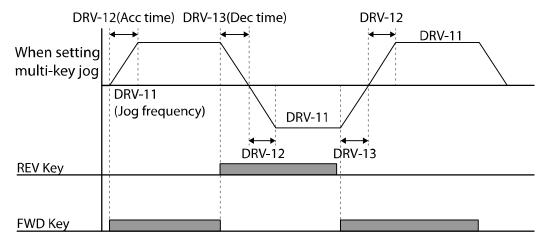
Group	Code	Name	LCD Display	Parameter setting	Setting Range	Unit
	11	Jog frequency	JOG Frequency	10.00	0.5-Max Freq	Hz
DRV	12	Jog operation acceleration time	JOG Acc Time	20.00	0.00–600.00	sec
	13	Operation deceleration time	JOG Dec Time	30.00	0.00-600.00	sec

The table below lists parameter settings for a forward jog operation using the keypad input.

MODE	Group	Code	LCD Display	Parameter Setting		Setting Range	Unit
CNF	-	42	Multi-Key Sel	1	JOG Key	-	-
PAR	DRV	06	Cmd Source	0	Keypad	0–5	sec

After setting CNF-42 to "1 (JOG Key)" and DRV-06 (in PAR mode) to "0 (Keypad)", you can start the jog operation using the keypad by pressing the [MULTI] key on the keypad.

When you press the [MULTI] key, "J" is displayed on the keypad indicating that a jog operation via the keypad is available. Press and hold the [FWD] or [REV] key to perform forward or reverse jog operations. Jog operations stop when you lift your finger from the [FWD] or [REV] key on the keypad.



8.3 **Up/down Operation**

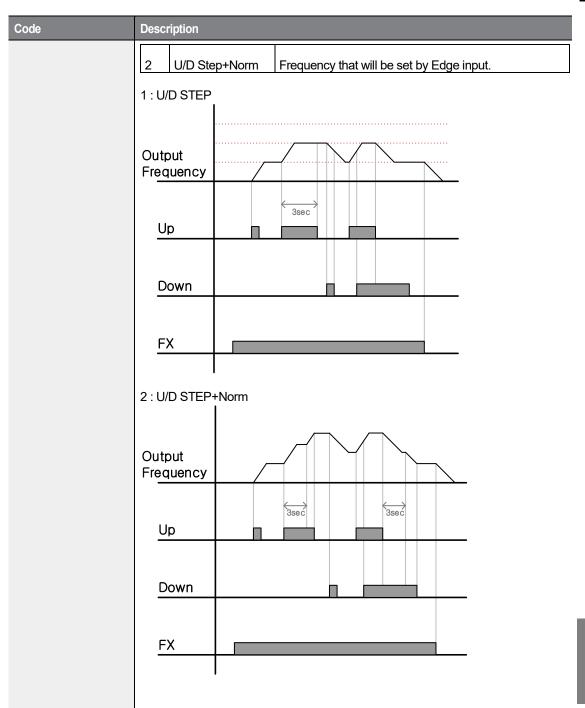
The acc/dec time can be controlled via the input at the multi-function terminal block. The up-down operation can be applied easily to a system that uses the upper-lower limit switch signals (such as those of a flow meter) for acc/dec commands.

Group	Code	Name	LCD Display	Para	ameter Setting	Setting Range	Unit
ADV	65	Up/down operation frequency save	U/D Save Mode	1	Yes	0–1	-
	85	Up/down mode Sel	U/D Mode Sel	0	U/D Normal	0:U/D Normal 1:U/D Step 2:U/D Step+Norm	-
	86	Up/down Step freqency	U/D Step Freq	-	0	0-maximum frequency	Hz
			Dy Define	17	Up		
IN	65–75	-75 Px terminal configuration	Px Define (Px: P1–P8	18	Down	0–51	
IIN	05-75		[optional: P9–P11])	19	U/D Save	0-31	
			P9_P []])	20	U/D Clear		

Up/down Operation Setting Details

(Do	elect two terminals for up				
ope	nen the Up terminal sign peration begins when the		celeration begins istant speed		
sto		ation begins when the Down signal in the doperation begins when both the lusters are time.			
IN-65–75 Px Define					
Fre	requency				
	7(UP) 8(Down)				
	un cmd (FX)				
aut		peration, the operating frequency is lowing conditions: The operation co the power is off.			
at a	You can also save the up/down operation frequency while the inverter is operated at a constant speed by setting one of the multi-function terminals (IN-65–75) to "19 (U/D Save)", or by setting ADV-65 to "1 (Yes)".				
If the	the up/down frequency s	eaving function is enabled for the ter ency will be saved as described in t			
	Save by keypad input (ADV-65) set to "1 (Yes)"	Save by keypad input (IN-65–75) set to "19 (U/D Save)"	U/D Save Result		
	X	X	X		
	0	X	0		
	X O	0	0		
	U	J	J		

Code	Description	
	ADV-65 U/D Sa	ave Mode: Yes
	Saved frequency	
	Output frequency	
	Up	
	Down	
	Clear	
	Run cmd(FX)	
	ADV-65 U/D Sa Saved frequency	ave Mode: No
	Output frequency	
	Up	
	Down	
	Save	
	Clear	
	Run cmd(FX)	
	the power source operation at the To delete the say the multi-function	ation command is turned on again, or when the inverter regains be or resumes to a normal operation from a fault trip, it resumes saved frequency. In the saved frequency, use the multi-function terminal block. Set one of the normal to "20 (U/D Clear)" and apply signals to it during a operation. The saved frequency and the up/down operation is be deleted.
	Configuration	Description
ADV-85 U/D Mode Sel	0 U/D Norm	Targeted Frequency increase or decrease based on Max/Min Frequency
	1 U/D Step	According to Edge input of up/down port, Frequency will be increase or decrease as much as ADV-86 setting date.

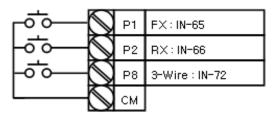


3-Wire Operation 8.4

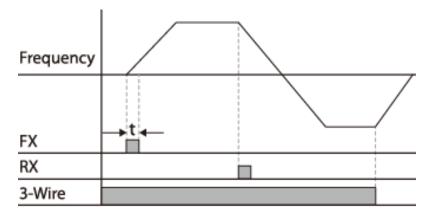
The 3-wire operation latches the signal input (the signal stays on after the button is released), and is used when operating the inverter with a push button.

Group	Code	Name	LCD Display	Para	ameter Setting	Setting Range	Unit
DRV	06	Command source	Cmd Source	1	Fx/Rx - 1	0–5	-
IN	65–75	Px terminal configuration	Px Define(Px: P1–P8 [optional: P9–P11])	14	3-Wire	0–51	-

To enable the 3-wire operation, the following circuit sequence is necessary. The minimum input time (t) for 3-wire operation is 1 ms, and the operation stops when both the forward and reverse operation commands are entered at the same time.



[Terminal connections for 3-wire operation]



[3-wire operation]

Safe Operation Mode 8.5

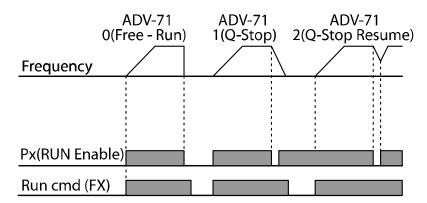
When the multi-function terminals are configured to operate in Safe mode, operation commands can be entered in Safe mode only. Safe mode is used to safely control the inverter through the multifunction terminals.

Group	Code	Name	LCD Display	Para	meter Setting	Setting Range	Unit
	70	Safe operation selection	Run En Mode	1	DI Dependent	Always Enable / DI Dependent	-
ADV	71	Safe operation stop mode	Run Dis Stop	0	Free-Run	0–2	-
	72	Safe operation deceleration time	Q-Stop Time	5.0		0.0–600.0	sec
IN	65–75	Px terminal configuration	Px Define(Px: P1–P8 [optional: P9–P11])	13	RUN Enable	0–51	-

Safe Operation Mode Setting Details

Code	Description						
IN-65–75 Px Define	From the multi-function terminals, select a terminal to operate in Safe mode and set it to "13 (RUN Enable)".						
ADV-70 Run En Mode	Setting Function O Always Enable Safe operation mode is deactivated. 1 DI Dependent Recognizes the operation command from a multifunction input terminal.						
	Set the operation of the inverter when the multi-function input terminal configured for Safe mode is off. When the Safe mode signal is given, the inverter decelerates according to the settings at the Q-Stop time. The inverter decelerates and stops according to the deceleration time (Dec Time) settings if the run command is off. Setting Function						
ADV 74 D Dia	Setting Function 1 Free-Run Blocks the inverter output when the multi-function terminal is off.						
ADV-71 Run Dis Stop	The deceleration time (Q-Stop Time) used in Safe mode. It stops after deceleration and then the operation can resume only when the operation command is entered again. The operation will not begin if only the multi-function terminal is on.						
	The inverter decelerates to the deceleration time (Q-Stop Time) in Safe operation mode. It stops after deceleration. Then, if the multi-function terminal is on, the operation resumes as soon as the operation						

Code	Description
	command is entered.
ADV-72 Q-Stop Time	Set the deceleration time when ADV-71 (Run Dis Stop) is set to "1 (Q-Stop)" or "2 (Q-Stop Resume)".

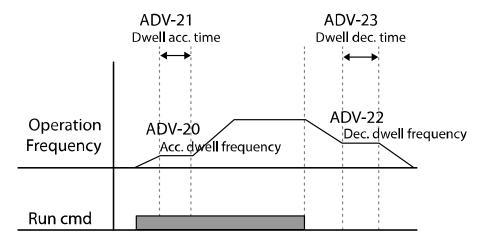


Dwell Operation 8.6

When DRV-09 (Control mode) is set to "0 (V/F mode)", a dwell operation may be used to maintain torque during inverter application, such as when enough torque is required before releasing mechanical brakes on lift-type loads. A dwell operation is based on the acc/dec dwell frequency and the dwell time set by the user. The following conditions also affect dwell operations.

- Acceleration Dwell Operation: When an operation command is given, acceleration continues until the acceleration dwell frequency and constant speed is reached within the acceleration dwell operation time (Acc Dwell Time). After the Acc Dwell Time has passed, acceleration is carried out based on the set acceleration time and operation speed.
- Deceleration Dwell Operation: When a stop command is given, deceleration continues until the deceleration dwell frequency and constant speed are reached within the deceleration dwell operation time (Dec Dwell Freg). After the set time has passed, deceleration is carried out based on the set deceleration time, and then the operation stops.

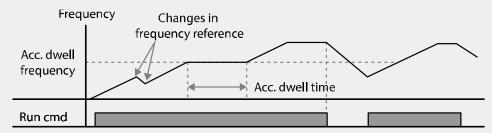
Group	Code	Name	LCD Display	Parameter Setting	Setting Range	Unit
	20	Dwell frequency during acceleration	Acc Dwell Freq	5.00	Start frequency – Maximum frequency	Hz
ADV	21	Operation time during acceleration	Acc Dwell Time	0.0	0.0–60.0	sec
ADV	22	Dwell frequency during deceleration	Dec Dwell Freq	5.00	Start frequency – Maximum frequency	Hz
	23	Operation time during deceleration	Dec Dwell Time	0.0	0 .0– 60.0	sec



Note

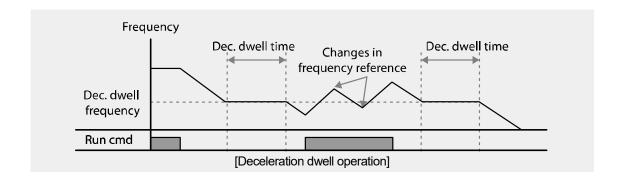
Dwell operations are not performed when:

- The dwell operation time is set to 0 sec or the dwell frequency is set to 0 Hz.
- Re-acceleration is attempted from a stop or during deceleration, since only the first acceleration dwell operation command is valid.



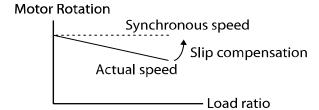
[Acceleration dwell operation]

Although a deceleration dwell operation is carried out whenever stop commands are entered and the
deceleration dwell frequency is passed through, it does not work during a deceleration operation by a
simple frequency change (which is not deceleration due to a stop operation), or during external brake
control applications.



8.7 **Slip Compensation Operation**

Slip refers to the variation between the setting frequency (synchronous speed) and motor rotation speed. As the load increases, there can be variations between the setting frequency and motor rotation speed. Slip compensation is used for loads that require compensation of these speed variations.*



*If DRV-09 is set to Sensorless, Vector, or V/F PG, the variation (slip) is automatically compensated.

Group	Code	Name	LCD Display	Pa	rameter Setting	Setting Range	Unit
	09	Control mode	Control Mode	2	Slip Compen	0–5	-
DRV	14	Motor Capacity	Motor Capacity	2	0.75 kW (0.75 kW based)	0.2–450	kW
	11	Number of motor poles	Pole Number	4		2–48	-
	12	Rated slip speed	Rated Slip	90	(0.75 kW based)	0–3000	rpm
BAS	13	Rated motor current	Rated Curr	3.0	6 (0.75 kW based)	1–10000	А
	14	Motor no-load current	Noload Curr	1.0	6 (0.75 kW based)	0.5–1000	А
	16	Motor efficiency	Efficiency	72	(0.75 kW based)	70–100	%
	17	Load Inertia ratio	Inertia Rate	0	(0.75 kW based)	0–8	-
ADV	92	SlipGain Mot-H	SlipGain Mot-H	50		0-200	%

Group	Code	Name	LCD Display	Parameter Setting	Setting Range	Unit
	93	SlipGain Gen-H	SlipGain Gen-H	50	0-200	%
	94	SlipGain Mot-L	SlipGain Mot-L	50	0-200	%
	95	SlipGain Gen-L	SlipGain Gen-L	50	0-200	%
	96	Slip Filter	Slip Filter	300	0-10000	msec
	97	Slip Comp Freq	Slip Comp Freq	5.00	0-60.00	Hz
	98	Slip Gain Freq	Slip Gain Freq	9.00	0-20.00	Hz

Slip Compensation Operation—Setting Details

Code	Description				
DRV-09 Control Mode	Sets DRV-09 to "2 (Slip Compen)" to carry out the slip compensation operation.				
DRV-14 Motor Capacity	Sets the capacity of the motor connected to the inverter.				
BAS-11 Pole Number	Enters the number of poles from the motor rating plate.				
BAS-12 Rated Slip	Enters the number of rated rotations from the motor rating plate.				
BAS-13 Rated Curr	Enters the rated current from the motor rating plate.				
BAS-14 Noload Curr	Enters the measured current when the load on the motor axis is removed and when the motor is operated at the rated frequency. If the no-load current is difficult to measure, enter a current equivalent to 30-50% of the rated motor current.				
BAS-16 Efficiency	Enters the efficiency from the motor rating place.				
BAS-17 Inertia Rate	If inertia rate < 10 x motor inertia, set BAS-16 to "0". If inertia rate = 10 x motor inertia, set BAS-16 to "1". If inertia rate > 10 x motor inertia, set BAS-16 to "2–8".				
ADV-92 Slip Gain Mot-H ADV-93 Slip Gain Gen-H	This is the slip compensation gain used in the region where the output frequency is higher than the slip compensation gain switching frequency (ADV-98). You can set the gain values differently for the reverse/regeneration operations.				
ADV-94 Slip Gain Mot-L ADV-95 Slip Gain Gen-L	This is the slip compensation gain used in the region where the output frequency is lower than the slip compensation gain switching frequency (ADV-98). You can set the gain values differently for the reverse/regeneration operations.				
ADV-96 Slip Filter	The filter time constant used when calculating the current required for slip compensation.				
ADV-97 Slip Comp Freq	You can set the frequency at which slip compensation starts. It is used when load compensation is not performed properly due to a low load compensation amount when stopped. At a constant speed, when it is above this frequency setting value, it calculates the real time slip to compensate the load. If it is below, it compensates the load				

Code	Description
	by using the previously calculated slip. When accelerating, the load is compensated by carrying out the sleep operation regardless of this frequency value. When decelerated, the load is compensated by using the previous calculated slip regardless of this frequency. When this value is set to 0, the slip operation is compensated in real time at all frequencies regardless of acceleration/deceleration and constant speed
ADV-98 Slip Gain Freq	Input using the rated speed of the motor nameplate

Note

The following is a formula for calculating the rated slip:

$$f_s = \frac{f_r \times 120}{P} - Rpm$$

 f_s = Rated slip frequency, f_r = Rated frequency

Rpm= Number of rated motor rotations, P= Number of motor poles

Ex.) If the rated frequency is 60 Hz, the rated revolution is 1740 rpm, and the pole number is 4:

$$f_s = \frac{60 \times 120}{4} - 1740 = 60rpm$$

PID Control 8.8

PID control is one of the most common auto-control methods. It uses a combination of proportional, integral, and differential (PID) controls that provide more effective control for automated systems. The functions of PID control that can be applied to the inverter operation are as follows:

Purpose	Function
Speed Control	Controls the speed by monitoring the current speed levels of the equipment or machinery being controlled. This control maintains a consistent speed or operates at the target speed.
Pressure Control	Controls the pressure by monitoring the current pressure levels of the equipment or machinery being controlled. This control maintains a consistent pressure or operates at the target pressure.
Flow Control	Controls the flow by monitoring the current amount of flow in the equipment or machinery being controlled. This control maintains a consistent flow or operates at a target flow.
Temperature Control	Controls the temperature by monitoring the current temperature levels of the equipment or machinery being controlled. This control maintains a consistent temperature or operates at the target temperature.

PID Basic Operation 8.8.1

PID operates by controlling the output frequency of the inverter, through automated system process control to maintain the speed, pressure, flow, temperature, or tension.

Group	Cod e	Name	LCD Display	Para	amete	er Setting	Setting Range	Unit
	01	Application mode	App Mode	2	2 Proc PID		0–4	-
	16	PID output monitor	PID Output	-			-	-
	17	PID reference monitor	PID Ref Value	-			-	-
	18	PID Feedback Value	PID Fdb Value	-			-	-
	19	PID reference setting	PID Ref Set	50.0	00		-100–100	%
	20	PID reference source	PID Ref Source	0	Ke	ypad	0–10	-
	21	PID feedback source	PID F/B source	0	V1		0–9	-
	22	PID proportional gain	PID P-Gain	-	50.	0	0–1000	%
	23	PID integral time	PID I-Time	-	10.0		0–200.0	sec
	24	PID differential time	PID D-Time	-	0		0–1000	ms
APP	25	PID feed forward gain	PID F-Gain	-	0.0		0–1000	%
	26	PID proportional gain scale	P Gain Scale	-	100	0.0	0–100	%
	27	PID output filter	PID Out LPF	-	0		0–10000	ms
	28	PID mode options	PID Mode	0	0	Process PID	0-1	-
	29	PID output upper limit	PID Limit Hi	-	60.00		APP-30 setting value–300	Hz
	30	PID output lower limit	PID Limit Lo	-	-60	.00	-300–APP-029 setting value	Hz
	31	PID output inversion	PID Out Inv	-	0	No	0–1	-
	32	PID output scale	PID Out Scale	-	100	0.0	0.1–1000	%
	34	Pre-PID start frequency	Pre-PID Freq	-	0.0	0	0-Max. Freq	Hz
	35	Feedback value to end Pre-PID operation	Pre-PID Exit	- 0.0			0–100	%

Group	Cod e	Name	LCD Display	Display Parameter Setting		Setting Range	Unit
	36	Pre-PID delay time	Pre-PID Delay	-	600	0–9999	sec
	37	PID sleep delay time	PID Sleep DT	-	60.0	0–999.9	sec
	38	PID sleep frequency	PID Sleep Freq	-	0.00	0-Max. Freq.	Hz
	39	PID wakeup level	PID WakeUp Lev	-	35	0–100	%
	40	PID wakeup mode option	PID WakeUp Mod	0	Below Level	0–2	-
	41	PID Rev Run Enable	PID Rev Run En	0	No	0-1	-
	42	PID unit option	PID Unit Sel	0	Hz	0–12	-
	43	PID gain unit	PID Unit Gain	-	100.0	0–300	%
	44	PID scale unit	PID Unit Scale	2	X 1	0–2	-
	45	PID proportional gain 2	PID P2-Gain	-	100.0	0–1000	%
			Px Define	22	I-Term Clear		
IN	65– 75	Px circuit function setting	(Px: P1–P8 [optional:	23	PID Openloop	0–51	-
			P9–P11])	24	P Gain2		

Note

- Normal PID output (PID OUT) is bipolar and is limited by APP-29 (PID Limit Hi) and APP-30 (PID Limit Lo) settings.
- If a PID change operation (changes from PID operation to normal operation) comes into multi-function inputs (P1-P11), the value of [%] is converted to [Hz] and is output.
- DRV-20 (MaxFreq) value equals 100% of PID output.

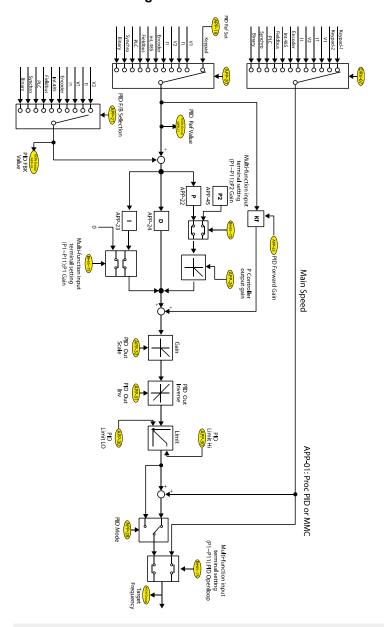
PID Basic Operation Setting Details

Code	Description
APP-01 App Mode	Sets the code to "2 (Proc PID)" to enable process PID.
APP-16 PID Output	Displays the existing output value of the PID controller. The unit, gain, and scale set at APP-42, APP-43, and APP-44 are applied on the display.
APP-17 PID Ref Value	Displays the existing reference value set for the PID controller. The unit, gain, and scale set at APP-42, APP-43, and APP-44 are applied on the display.
APP-18 PID Fdb Value	Displays the latest feedback value of the PID controller. The unit, gain, and scale set at APP-42, APP-43, and APP-44 are applied on the display.
APP-19 PID Ref Set	Sets the reference value when APP-20 (PID Ref Source) is set to "0 (Keypad)". If the reference source is set to any input other than the keypad, this value will

Code	Description					
	be ig	nored.				
	Set the reference input source for the PID control. If the V1 terminal is set as the PID feedback source at APP-21 (PID F/B Source), it cannot be set as the PID reference source. To set V1 as a reference source, change the feedback source settings first.					
	Set		Function	PID F/B Source		
	0	Keypad	Keypad	X		
	1	V1	Terminal input for -10–10 V input voltage	0		
	2	l1	Terminal input 0-20 mA input current	0		
	3	V2	[W/ optional I/O expansion module] Terminal input for -10–10 V input voltage	0		
APP-20 PID Ref Source	4	12	[W/ optional I/O expansion module] Terminal input 0-20 mA input current	0		
7 11 201 15 1 (6) 66 61 66	5	Int. 485	RS-485 input terminal	0		
	6	Encoder	[W/ optional encoder module] Pulse input terminal	0		
	7	FieldBus	[W/ optional communication module] Fieldbus Communication input	0		
	8	PLC	0			
	9	Synchro	[W/ optional synchronization module] Command via synchronization operation	0		
	10	Binary Type	[W/ optional BCD module] Command via BCD option module	Х		
	The PID reference source setting can be monitored at APP-17 (PID Ref Value) according to the information types for monitoring set at CNF-06–08.					
APP-21 PID F/B Source	keypa select PID f For e you r source	input source for the PID control. Keypad input (ke t be selected as the source of FB input. Also, the input input source at APP-19 (PID Ref Set) cannot be source. The V1 terminal is set as the PID reference source input types other than the V1 terminal as the PID ference. The V1 terminal is set as the PID reference source input types other than the V1 terminal as the PID ference.	nput type be set as the at APP-20, deedback			
APP-22 PID P-Gain, APP-26 P Gain Scale	atio for differences (errors) between the reference P-gain is set to 50%, then 50% of the difference (e e of P-gain is 0.0–1000.0%. You can set APP-26 (the input scale if a more accurate control is require	rror) is P-Gain				
APP-23 PID I-Time	Sets the time to output accumulated errors. When the error is 100%, the time taken for 100% output is set. When the integral time (PID I-Time) is set to 1 second, 100% output occurs after 1 second of the error and remains at 100%. Differences in a normal state can be reduced by PID I Time. When the multifunction terminal block is set to "21 (I-Term Clear)" and is turned on, all of the accumulated errors are deleted.					

Code	Description					
APP-24 PID D-Time	Sets the output volume for the rate of change in errors. If the differential time (PID D-Time) is set to 1 ms and the rate of change in errors per sec is 100%, output occurs at 1% per 10 ms.					
APP-25 PID F-Gain	Sets the ratio that to a faster respons		the PID output. Adjusting this value leads			
APP-27 PID Out LPF	Used when the PID controller output changes too quickly or the entire system is unstable, due to severe oscillation. In general, a lower value (default value is 0) is used to speed up response time, but in some cases a higher value increases stability. The higher the value, the more stable the PID controller output is, but the slower the response time.					
APP-28 PID Mode	Set APP-28 to "0 (Process PID)" to add certain target values to the PID output to produce the final output. Set APP-28 to "1 (Normal PID)" to use the PID output without additional processing (modification).					
APP-29 PID Limit Hi, APP-30 PID Limit Lo	Sets the values to limit the output of the PID controller.					
APP-32 PID Out Scale	Sets APP-32 to adjust the scale of the controller output.					
PID Rev Run En	Default is set to "No". When set to "No", the lower limit frequency limit is set to 0 Hz when the frequency is decreased via PID control, so that it does not reverse. If it is set to "Yes", when the frequency decreases by PID control, it falls below 0 Hz and operates in the reverse direction.					
	Set APP-42 to select the unit for the PID control.					
	Setting Unit	Application	Description			
	0 %	-	Displays certain values into as a percentage.			
APP-42 PID Unit Sel	1 Bar 2 mBar 3 Pa 4 kPa	- Pressure	Units for expressing different types of pressure.			
APP-42 PID UNIT Sei	5 Hz 6 rpm	Speed	Units for inverter output frequency or motor revolution.			
	7 V	Voltage	I luite for electric voltage, europt			
	8 I	Current	Units for electric voltage, current, electrical consumption, or consumed			
	9 kW	Electric power	power.			
	10 HP	Horse power	power.			
	11 °F 12 °C	11 °F Temperature Units for expressing temperature				
APP-43 PID Unit Gain, APP-44 PID Unit Scale	Adjust the unit value	ue and scale to fit	the unit selected at APP-42 (PID Unit Sel).			
APP-45 PID P2-Gain	Set APP-45 (PID P2-Gain) for an alternative PID controller gain and use the alternative gain via a terminal input. Set IN-65–75 to "23 (P Gain2)". When the selected terminal is on, the gain set at APP-45 is used instead of the gain set at APP-22 and APP-23.					

PID Control Block Diagram



Note

- If the PID switching operation (switching from PID operation to normal operation) is performed at the multi-function inputs (P1-P11), % values are converted into Hz values.
- The polarity of the Normal PID output PID OUT is unipolar, and is limited by APP-29 (PID Limit Hi) and APP-30 (PID Limit Lo).
- 100% is based on the setting at DRV-20 (maxFreq).

8.8.2 **Pre-PID Operation**

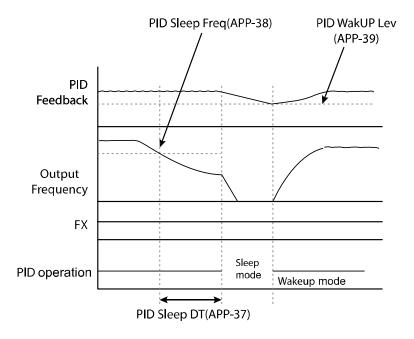
Pre-PID operation refers to a section of a PID operation where the inverter runs without PID control. The inverter accelerates to a set frequency and runs without PID control, and then the PID control begins after the PID output exceeds the set value at APP-35 (Pre-PID Exit).

Code	Description							
APP-34 Pre-PID Frq	Sets the target frequency to operate without PID control. The inverter continues running at the set frequency until the PID feedback exceeds the feedback value (%) set at APP-35.							
	Sets the feedback value of the PID control (PID reference) to stop pre-PID operation and start PID control.							
APP-35 Pre-PID Exit	PID Reference Feedback APP-35 Pre-PID Exit Output Frequency FX							
	PID operation ← Area1 → ← Area2 →							
APP-36 Pre-PID Delay	Sets the time until a pre-PID fault trip occurs. If a feedback smaller than the PID reference set at APP-35 is maintained for the set time, a pre-PID fail trip occurs and inverter output is stopped.							

8.8.3 **PID Sleep Mode**

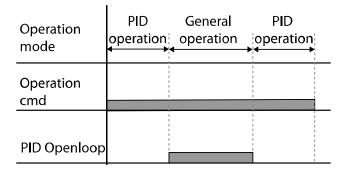
If an operation continues at a frequency lower than the PID operation conditions at APP-38 (Sleep Freq) for a set duration at APP-37 (PID Sleep DT), the inverter enters PID sleep mode. In PID sleep mode, the inverter resumes PID operation when the PID Wakeup level conditions set at APP-39 (PID WakeUp Lev) are met.

Code	Description
APP-37 PID Sleep DT, APP-38 PID Sleep Freq	Sets the PID sleep frequency and delay time. The inverter stops operation and enters sleep mode if an operation is maintained at a frequency lower than the sleep frequency set at APP-38 for the time set at APP-37.
	Sets the reference for PID wakeup at APP-39. If APP-40 is set to "0 (Below Level)", PID operation is resumed when the feedback volume is lower than the reference.
APP-39 PID WakeUp Lev, APP-40 PID WakeUp Mod	If APP-40 is set to "0 (Below level)", PID operation will resume when the feedback volume is lower than the reference. If APP-40 is set to "1 (Above Level)", PID operation will resume when the feedback volume is higher than the reference. If APP-40 is set to "2 (Beyond level)", PID operation will resume when the difference between the speed reference and the feedback is larger than the wakeup reference set at APP-39.



8.8.4 **PID Switching (PID Openloop)**

When one of the multi-function terminals (IN-65-75) is set to "22 (PID Openloop)" and is turned on, the PID operation stops and is switched to general operation. When the terminal turns off, the PID operation starts again.



8.9 **Auto Tuning**

The motor parameters can be measured automatically and can be used for an auto torque boost or sensorless vector control.

Example - Auto Tuning Based on 0.75 kW, 220 V Motor

Group	Code	Name	LCD Display	Parameter Setting		Unit
DRV	14	Motor capacity	Motor Capacity	2 0.75 k	W	kW
	11 Motor pole number Pole Number			4		-
	12	Rated slip speed	Rated Slip	40		Rpm
	13	Rated motor current	Rated Curr	3.6		Α
	14	Motor no-load current	Noload curr	1.6	1.6	
	15	Motor rated voltage	Rated Volt	220		V
BAS	16	Motor efficiency	Efficiency 72			%
	20	Auto tuning	Auto Tuning	0	None	-
	21	Stator resistance	Rs	2.600		Ω
	22	Leakage inductance	Lsigma	17.94		mH
	23	Stator inductance	Ls	15.44		mH
	24	Rotor time constant	Tr	145		ms
APO	01	Encoder option mode	Enc Opt Mode	0	None	

Auto Tuning Default Parameter Setting

Motor Capacit	y (kW)	Rated Current (A)	No-load Current (A)	Rated Slip Frequency (Hz)	Stator Resistance (Ω)	Leakage Inductance (mH)	Stator Inductance [mH]	Rotator Time constant [ms]
	0.2	1.1	0.8	3.33	14.0	40.4	385	93
	0.4	2.4	1.4	3.33	6.70	26.9	206	116
	0.75	3.4	1.7	3.00	2.600	17.94	174.4	145
	1.5	6.4	2.6	2.67	1.170	9.29	115.8	162
	2.2	8.6	3.3	2.33	0.840	6.63	90.7	183
	3.7	13.8	5.0	2.33	0.500	4.48	59.7	211
	5.5	21.0	7.1	1.50	0.314	3.19	41.5	250
	7.5	28.2	9.3	1.33	0.169	2.844	31.86	271
200 V	11	40.0	12.4	1.00	0.120	1.488	23.91	310
200 V	15	53.6	15.5	1.00	0.084	1.118	19.07	350
	18.5	65.6	19.0	1.00	0.068	0.819	15.59	390
	22	76.8	21.5	1.00	0.056	0.948	13.79	435
	30	104.6	29.3	1.00	0.042	0.711	10.12	530
	37	128.6	34.7	1.00	0.033	0.568	8.54	600
	45	156.0	42.1	1.00	0.028	0.474	7.04	630
	55	184.1	49.7	1.00	0.023	0.389	5.96	670
	75	244.5	61.1	1.00	0.016	0.284	4.85	800
	90	289.5	72.3	1.00	0.014	0.250	4.09	900
	0.2	0.7	0.5	3.33	28.00	121.2	1045	93
	0.4	1.4	8.0	3.33	14.0	80.8	610	116
	0.75	2.0	1.0	3.00	7.81	53.9	512	145
	1.5	3.7	1.5	2.67	3.52	27.9	346	162
	2.2	5.0	1.9	2.33	2.520	19.95	269.5	183
	3.7	8.0	2.9	2.33	1.500	13.45	177.8	211
400 V	5.5	12.1	4.1	1.50	0.940	9.62	124.5	250
400 V	7.5	16.3	5.4	1.33	0.520	8.53	95.2	271
	11	23.2	7.2	1.00	0.360	4.48	71.2	310
	15	31.0	9.0	1.00	0.250	3.38	57	350
	18.5	38.0	11.0	1.00	0.168	2.457	46.47	390
	22	44.5	12.5	1.00	0.168	2.844	41.1	435
	30	60.5	16.9	1.00	0.126	2.133	30.23	530
	37	74.4	20.1	1.00	0.101	1.704	25.49	600

Motor Capacity	/ (kW)	Rated Current (A)	No-load Current (A)	Rated Slip Frequency (Hz)	Stator Resistance (Ω)	Leakage Inductance (mH)	Stator Inductance [mH]	Rotator Time constant [ms]
	45	90.3	24.4	1.00	0.084	1.422	21.01	630
	55	106.6	28.8	1.00	0.069	1.167	17.79	670
	75	141.6	35.4	1.00	0.050	0.852	14.46	800
	90	167.6	41.9	1.00	0.039	0.715	12.22	900
	110	203.5	48.8	1.00	0.032	0.585	10.48	1000
	132	242.3	58.1	1.00	0.027	0.488	8.8	1100
	160	290.5	69.7	1.00	0.022	0.403	7.34	1200
	185	335.0	77.0	1.00	0.021	0.380	6.64	1250
	220	405	93.1	30	0.0163	0.293	5.467	1350
	280	530.7	116.7	30	0.0128	0.23	4.386	1400
	315	604	132.8	30	0.0114	0.204	3.854	1430
	375	729.7	153.2	30	0.0096	0.171	3.342	1470

Auto Tuning Parameter Setting Details

Code	Description			
DRV-14 Motor Capacity	Set the motor capacity. The maximum motor capacity is limited by the inverter's capacity.			
		uning type and run it. Select one of the options and then press the ey to run auto tuning. Function		
	0 None	The auto tuning function is disabled. Also, if you select one of the auto tuning options and run it, the parameter value will revert back to 0 when auto tuning is complete.		
BAS-20 Auto Tuning	1 All	Measures all motor parameters while the motor is rotating, including stator resistance (Rs), stator inductance (Lsigma), no-load current (Noload Curr), rotor time constant (Tr), etc. If an optional encoder module is installed, the inverter state is also measured (requires appropriate settings for encoder-related functions). Use this setting when DRV-09 (Control mode) is set to "5 (Vector)". Since the motor is rotating while the parameters are being measured, if the load is connected to the motor spindle, the parameters may not be measured accurately. For accurate measurements, remove the load attached to the motor spindle. If DRV-09 (Control mode) is set to "4 (Sensorless-2)", the rotor time constant (Tr) must be measured in a stopped position.		
	2 All (static type)	Measures all parameters while the motor is in the stopped position, including stator resistance (Rs), stator inductance (Lsigma), no-load		

Code	De	scription	
			current (Noload Curr), rotor time constant (Tr), etc. Use this setting when DRV-09 (Control mode) is set to "4 (Sensorless-2)". Since the motor is not rotating while the parameters are measured, the measurements are not affected when the load is connected to the motor spindle.
	3	Rs+Lsigma	Measures the stator resistance (Rs) and stator inductance (Lsigma) while the motor is not rotating. The measured values are used for auto torque boost and sensorless vector control. Since the motor is not rotating while the parameters are measured, the measurements are not affected when the load is connected to the motor spindle.
	4	Enc. Test	Runs auto tuning after installing the optional encoder to the inverter and connecting the encoder cables to the motor. Auto tuning checks the cable connection. Ensure that the encoder related parameters are correctly set before auto tuning.
	5	Tr	Uses this setting to measure the rotor time constant (Tr) when DRV-09 (Control mode) is set to "5 (Vector)". The motor rotates during auto tuning.
	6	Tr (Stdstl)	Uses this setting to measure the rotor time constant (Tr) when DRV-09 (Control mode) is set to "4 (Sensorless-2)". The motor does not rotate during auto tuning.
BAS-14 Noload Curr, BAS-21 Rs-BAS-24 Tr			arameters measured by auto tuning. For parameters that are not uto tuning measurement list, the default setting will be displayed.

① Caution

- Perform auto tuning ONLY after the motor has completely stopped running.
- Before you run auto tuning, check the motor pole number, rated slip, rated current, rated voltage, and efficiency on the motor's rating plate and enter the data. The default parameter setting is used for values that are not entered.

Note

Before checking the encoder status using auto tuning, ensure that the following parameters are correctly

Group	Code	Name	LCD Display	Parameter Setting		Unit
BAS	20	Auto tuning	Auto Tuning	3	Enc Test	0–6
450	01	Encoder option mode	Enc Opt Mode	1	Feedback	0–2
	04	Encoder type selection	Enc Type Sel	0	Line Driver	0–2
APO	05	Encoder pulse direction	Enc Pulse Sel	0	(A+B)	0–2
	06	Encoder pulse number	Enc Pulse Num	-	1024	10–5000

08 Encode	er feedback monito	r Enc Monitor	-	0	-
Encoder status checking	details				
Code	Description				
BAS-20 Auto Tuning	Sets the auto tuning type to "3 (Enc Test)" to check the encoder connection. The inverter operates in the Fx direction and accelerates to +20 Hz until it decelerates to 0 Hz and continues operating in the Rx direction, accelerating to -20 Hz. BAS-20 parameter value is automatically changed to "None" if a connection error is not detected. The "Enc reverse" message is displayed if the encoder connection is not correct. If this happens, you can change the APO-05 (ENC Pulse Sel) parameter setting to match the actual direction, or swap the two encoder cables that are connected to the motor.				
APO-01 ENC Opt Mode	Sets the encoder	option mode to "1 (Fe	ed-ba	ck)".	
APO-04 Enc Type Sel	Select an encode Setting 0 Line Driver	Output details Line driver output Line driver output Rotary encoder circuit A Phase output A Phase output output ov Totem pole output Rotary encoder circuit Totem pole output Conne	tion	A phase H $\frac{1}{2} + \frac{1}{4}$ A phase H $\frac{1}{2} + \frac{1}{4}$ B phase H $\frac{1}{2} + \frac{1}{4}$ P pha	
Al 0-04 Elic Type dei	1 Totem or Com	Sink current: Max.30mA Output Sink current: Max.10mA Ov	*1 ad + *2 T-	A phase L T + T T T T T T T T T	
	2 Open Collector	Open collector output NPN open collector output Rotary encoder circuit Conne +V Lo Output Sink curre Max.30m OV	tion /	A phase $\frac{1}{2} \pm \frac{1}{4} \pm \frac{1}{8}$ B phase $\frac{1}{4} \pm \frac{1}{8} \pm \frac{1}{8}$ CWClock wise) *CW: In a view of shaft	
APO-05 Enc Pulse Sel	n of the encoder outpu equency reference) / 1	•			
APO-06 Enc Pulse Num	Sets the number	of output pulses per o	ne mo	otor revolution.	
APO-08 Enc Monitor	Converts the end	oder output into moto	spee	d (Hz or RPM) for	monitoring.

8.10 V/F Operation Using Speed Sensor

You can install an optional encoder module to the inverter to enhance the accuracy of V/F control. Before operating the inverter, check the encoder connection by running an auto tuning operation.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
DRV	09	Control mode	Control Mode	1	V/F PG	0–5	-
	45	PG operation proportional gain	PG P-Gain	-	3000	0–9999	-
CON	46	PG operation integral gain	PG I-Gain	-	50	0–9999	-
	47	7 PG operation maximum slip PG Slip Max	PG Slip Max %	-	100	0–200	%
APO	01	Encoder option mode	Enc Opt Mode	1	Feed-back	0–2	-

V/F Operation Using Speed Sensor-Details

Code	Description
DRV-09 Control Mode	Sets the control mode to "1 (V/F PG)". This mode adds a speed controller to a regular V/F mode. The command frequency becomes the speed reference of the speed controller, and the feedback is used as the encoder input.
CON-45 PG P-Gain, CON-46 PG I-Gain	Sets the proportional and integral gain (P-Gain/I-gain) of the speed controller. Higher P-gain results in a faster response. However, excessively high P-gain may lead to unstable operation. Lower I-gain results in a faster response. However, excessively low P-gain may lead to unstable operation.
CON-47 PG Slip Max %	Sets the maximum slip for the speed controller as a percentage (%) based on the rated slip set at BAS-12 (Rated Slip). For example, if CON-47 is set to 90% when the rated slip set at BAS-12 is 30 rpm, the maximum slip for the speed controller becomes 27 rpm, (90% of 30 rpm,).

8.11 Sensorless-1 Vector Control

Sensorless-1 vector control mode provides high performance operation without requiring a speed sensor. Motor parameter information is required for sensorless-1 vector control mode. Before operating the inverter in sensorless-1 mode, run auto tuning first.

Group	Code	Name	LCD Display	Para	meter Setting	Unit
	09	Control mode	Control Mode	3	Sensorless-1	-
DRV	10	Torque control option	Torque Control	0	No	-

Group	Code	Name	LCD Display	Para	meter Setting	Unit
	14	Motor-rated capacity	Motor Capacity	х	x.xx	kW
	11	Motor pole number	Pole Number	-	4	-
	12	Motor-rated slip	Rated Slip	-	2.00	Hz
	13	Motor-rated current	Rated Curr	-	3.6	А
BAS	14	Motor No-load current	Noload curr	-	0.7	Α
	15	Motor-rated voltage	Rated Volt	-	220	V
	16	Motor efficiency	Efficiency	-	83	%
	20	Auto tuning options	Auto Tuning	2	Rs+Lsigma	-
CON	21	Sensorless speed controller proportional gain 1	ASR-SL P Gain1	ı	100.0	%
CON	22	Sensorless speed controller integral gain 1	ASR-SL I Gain1	-	150	ms

① Caution

- For sensorless-1 mode operation, the motor's rated capacity must match the inverter's rated capacity. If the inverter capacity is too large for the installed motor, run the motor in V/F mode.
- Sensorless-1 mode operation does not support multiple motor control (MMC) features. Do not connect multiple motors to one inverter that is operating in sensorless-1 mode.

Sensorless-1 Vector Control-Details

Code	Description
DRV-14 Motor Capacity, BAS-11 Pole Number, BAS-12 Rated Slip, BAS-13 Rated Curr, BAS-15 Rated Volt, BAS-16 Efficiency	Motor parameter information is required for sensorless-1 vector control mode. Check the motor's rating plate for the motor capacity and other performance-related information, set the relevant parameters, and then run auto tuning at BAS-20.
BAS-20 Auto Tuning	After setting all the parameter values (DRV-14 Motor Capacity, BAS-11 Pole Number, BAS-12 Rated Slip, BAS-13 Rated Curr, BAS-15 Rated Volt, and BAS-16 Efficiency), perform auto tuning. To perform astatic auto tuning when the motor does not rotate, set BAS-20 to 2 (Rs+Lsigma). The default motor no-load current is used, and the motor stator resistance (Rs) and leakage inductance (Lsigma) values are saved at BAS-21 and BAS-22.
	To perform rotating auto tuning , separate the load from the motor axis, if possible, and set BAS-20 to "1 (ALL)". The motor no-load current, motor stator resistance (Rs), and motor leakage inductance (Lsigma) values are

Code	Description			
	saved at BAS-14, BAS-21, and BAS-22 respectively.			
	Set the speed controller proportionately and integral gains for sensorless-1 vector control according to the default motor parameters and acc/dec time.			
CON-21 ASR-SL P Gain1, CON-22 ASR-SL I Gain1	① Caution			
Call	Appropriate controller gain values must be set based on the load characteristics. Motor overheating or an unstable system may result if the gain values are not properly set.			
	Selects the speed control and torque control modes. If you set DRV-10 (Torque control) to "1 (Yes)", the operation switches into torque control mode. Refer to <u>8.14 Torque Control</u> on page <u>236</u> for details.			
DRV-10 Torque Control	 Caution Torque control is not available during low-speed regeneration and low-speed operation under a light load. Select vector control mode instead. When the inverter is operated in torque control mode, do not switch between forward and reverse rotations. Overcurrent or Rx deceleration fault trips may result. When the inverter is operated in sensorless vector control mode, enable accelerating speed search by setting the CON-71 (Speed search) bits to "0001" if the inverter is expected to start or restart while the motor is free-running. 			

8.12 Sensorless-2 Vector Control

Similar to sensorless-1 vector control mode, sensorless-2 vector control mode provides highperformance inverter operation without requiring a speed sensor. It utilizes various gain values for more precise vector control.

Motor parameter information is required for sensorless-2 vector control mode. Before operating the inverter in sensorless-2 mode, run auto tuning first.

Group	Code	Name	LCD Display	Pá	Parameter Setting	
	09	Control mode	Control Mode	4	Sensorless-2	-
DRV	10	Torque control option	Torque Control	0	No	-
DITT	14	Motor-rated capacity	Motor Capacity	х	Varies depending on motor capacity.	kW
	11	Motor pole number	Pole Number	ı	4	-
BAS	12	Motor-rated slip	Rated Slip	•	Varies depending on motor capacity.	Hz

Group	Code	Name	LCD Display	P	arameter Setting	Unit
	13	Motor-rated current	Rated Curr	-	Varies depending on motor capacity.	А
	14	Motor No-load current	Noload curr	-	Varies depending on motor capacity.	А
	15	Motor-rated voltage	Rated Volt	-	220/380/440/480	V
	16	Motor efficiency	Efficiency	-	Varies depending on motor capacity.	%
	20	Auto tuning options	Auto Tuning	1	All	-
	20	Sensorless 2nd gain display setting	SL2 G View Sel	1	Yes	-
	21	Sensorless speed controller proportional gain1	ASR-SL P Gain1	-	Varies depending on motor capacity.	%
	22	Sensorless speed controller integral gain 1	ASR-SL I Gain1	-	Varies depending on motor capacity.	ms
	23	Senseless speed controller proportional gain 2	ASR-SL P Gain2	-	Varies depending on motor capacity.	%
	24	Sensorless2 speed controller integral gain 2	ASR-SL I Gain2	-	Varies depending on motor capacity.	%
	26	Sensorless2 measurer gain 1	Observer Gain1	-	10500	-
CON	27	Sensorless2 measurer gain 2	Observer Gain2	-	100.0	%
	28	Sensorless2 measurer gain 3	Observer Gain3	-	13000	-
	29	Sensorless2 speed estimator proportional gain 1	S-Est P Gain 1	-	Varies depending on motor capacity.	-
	30	Sensorless2 speed estimator integral gain 1	S-Est I Gain 1	-	Varies depending on motor capacity.	-
	31	Sensorless2 speed estimator proportional gain 2	S-Est P Gain 2	-	Varies depending on motor capacity.	%
	32	Sensorless2 speed estimator integral gain 2	S-Est I Gain 2	-	Varies depending on motor capacity.	%
	48	Current controller P gain	ACR P-Gain	-	1200	-
	49	Current controller I gain	ACR I-Gain	-	120	-

① Caution

- For sensorless-2 mode operation, the motor-rated capacity must match the inverter's rated capacity. If the inverter capacity is too large for the installed motor, run the motor in V/F mode.
- Sensorless-2 mode does not support multiple motor control (MMC) features. Do not connect multiple motors to one inverter that is operating in sensorless-1 mode.

Sensorless-2 Vector Control-Details

Code	Description
DRV-14 Motor Capacity, BAS-11 Pole Number, BAS-12 Rated Slip, BAS-13 Rated Curr, BAS-15 Rated Volt, BAS-16 Efficiency	Motor parameter information is required for sensorless-2 vector control mode. Check the motor's rating plate for the motor capacity and other performance related information, set the relevant parameters, and then run auto tuning at BAS-20.
BAS-20 Auto Tuning	After setting all the parameter values (DRV-14 Motor Capacity, BAS-11 Pole Number, BAS-12 Rated Slip, BAS-13 Rated Curr, BAS-15 Rated Volt, and BAS-16 Efficiency), perform a rotating auto tuning. To perform rotating auto tuning, separate the load from the motor axis, and set BAS-20 to "1 (ALL)". The motor stator resistance (Rs), leakage inductance (Lsigma), stator inductance (Ls), no-load current (Noload Curr), and rotor time constant (Tr) are saved in BAS-21, BAS-22, BAS-23, BAS-14, and BAS-24, respectively.
CON-20 SL2 G View Sel	Set CON-20 to "1 (Yes)" to view various medium speed* gains (CON-23 ASR-SL P Gain2, CON-24 ASR-SL I Gain2, CON-27 Observer Gain2, CON-28 Observer Gain3, CON-31 S-Est P Gain2, and CON-32 S-Est I Gain2) for user configuration. These parameters are not visible if CON-20 is set to "0 (No)". *Medium speed: A speed range that is approximately 50% of the base frequency.
CON-21 ASR-SL P Gain1, CON-22 ASR-SL I Gain1	Sets the speed controller proportionately and integral gain values for sensorless-2 vector control. The P-gain is proportionate to speed deviation. Increasing the P-gain increases torque output and immediately eliminates speed deviation. The I-gain is an integral gain which represents the time (ms) until the torque output is made under a steady speed deviation. Decreasing the I-gain can eliminate the speed deviation faster. After setting the speed controller gain values, observe the changes and finetune the values to improve the speed control waveforms. Note that vibration may result if the set P-gain value is too large or the set I-gain value is too small. If oscillation is observed in the waveform, first increase the I-gain, and then increase the P-gain to find the optimal values.
CON-23 ASR-SL P Gain2, CON-24 ASR-SL I Gain2	These codes are visible only when CON-20 is set to "1 (yes)". Set the speed controller proportionately and integral gain values for sensorless-2 vector control for operation speeds greater than 50% of the base frequency. CON-23 (ASR-SL P Gain2) and CON-24 (ASR-SL I Gain2) are set as percentage values (%) based on the proportionately set speed controller and integral gain1 values set at CON-21 (ASR-SL P Gain1) and CON-22 (ASR-SL I Gain1).

Code	Description
	Therefore, P-gain2 and I-gain2 values of less than 100% result in decreased responsiveness when the inverter is operating above medium speed.* For example, if both P-gain1 and P-gain2 are set to 50%, the actual P-gain2 value is 25% of the reference. Likewise, if I-gain1 is set to 100 ms and I-gain2 is set to 50%, the resulting I-gain 2 value becomes 200 ms. By default, the speed controller gain values are set according to the motor parameters and acceleration and deceleration times. *Medium speed: A speed range that is approximately 50% of the base frequency.
CON-26 Observer Gain1, CON-27 Observer Gain2, CON-28 Observer Gain3	These codes are visible only when CON-20 is set to "1 (yes)". The observer gain values may be adjusted by system engineers only. Sensorless-2 vector control mode requires the observers to estimate the motor's stator current and rotor magnetic flux. While observer gain1 (CON-26) is applied when the inverter operates at low to medium speeds, observer gain2 (CON-27) is applied when the inverter operates at medium to high speeds. Observer gain3 (CON-28) is applied in torque control mode.
CON-29 S-Est P Gain1, CON-30 S-Est I Gain1	Sets the speed estimator gain values for sensorless-2 vector control mode. Increase or decrease the speed estimator P-gain or I-gain by small increments if the displayed speed does not match the speed reference. You can also adjust the speed estimator gain values if the motor vibrates severely, or a high current ripple occurs at power on. Decrease the speed estimator P-gain or I-gain gradually to reduce the vibration or current ripple. By default, the speed estimator gains are set according to the default motor parameters and acceleration and deceleration times.
CON-31 S-Est P Gain2, CON-32 S-Est I Gain2	These codes are visible only when CON-20 is set to "1 (yes)". You can set the speed estimator gains to a frequency higher than the medium speed* in sensorless-2 vector control mode. CON-31 and CON-32 are set as percentage values of low-speed gain values set at CON-29 and CON-30. For example, if CON-29 S-Est P-Gain1 is 300 and CON-31 S-Est P-Gain2 is 40.0%, the speed estimator P-gain at higher than the actual medium speed is 120. By default, the speed estimator gains are set according to the default motor parameters and acceleration and deceleration times. *Medium speed: A speed range that is approximately 50% of the base frequency.
CON-34 SL2 OVM Perc	When the output voltage/input voltage ratio is below 100% (when the output voltage is not over modulated), the output voltage bears linear characteristics to the input voltage. In sensorless-2 control mode, you can set CON-34 (SL2 OVM Perc) to define a voltage range to be limited in the over modulated zone. By default, CON-34 (SL2 OVM Perc) is set as 120%. However, for a high-impact load where the load often exceeds the torque limit, such as a

Code	Description
	press load, you can increase the limit value to avoid frequent over current fault trips. Also, in areas where the power supply is unstable, the input voltage tends to be lower than the rated input voltage, which results in more frequent overcurrent (OC1) fault trips with aforementioned high-impact load applications. If this is the case, you can set CON-34 (SL2 OVM Perc) as 140–150% to avoid frequent fault trips.
CON-48 ACR P-Gain, CON-49 ACR I Gain	Sets the current PI controller P-gain and I-gain values.
DRV-10 Torque Control	Selects the speed control and torque control modes. If you set DRV-10 (Torque control) to "1 (Yes)", the operation switches to torque control mode. Refer to 8.14 Torque Control on page 236 for details. ① Caution • Torque control is not available during low-speed regeneration and low-speed operation under a light load. Select vector control mode instead. • When the inverter is operated in torque control mode, do not switch between forward and reverse rotations. Overcurrent or Rx deceleration fault trips may occur. • When the inverter is operated in sensorless vector control mode, enable accelerating speed search by setting the CON-71 (Speed search) bits to "0001," if the inverter is expected to start or restart while the motor is free-running.

① Caution

In sensorless-2 control mode, the motor may overheat or the system may become unstable if the gain values are not properly set.

Note

Sensorless-2 vector control mode is greatly affected by the motor and load characteristics. Therefore, it is sometimes necessary to adjust the controller gain values.

When a sensorless-2 vector control is operated in speed mode [DRV-10 (torque control) is set to "0 (No)". If the operation is unstable at extremely low speeds (below 2-3 Hz), or if the speed bounces during startup, increase the CON-22 (ASR-SL I Gain1) value to 200% of the default value. With a regenerative load, motor torque ripples may occur frequently. In this case, decrease the CON-21 (ASR-SL P Gain1) value to 50% of the default value. If this does not solve the problem, increase the CON-21 (ASR-SL P Gain1) value back to the default, and decrease the CON-30 (S-Est I Gain1) value to 50% of the default value.

8.13 Vector Control Mode Operation

With an optional encoder module installed to the inverter, vector control mode provides highly precise operation abilities.

Similar to sensorless-1 and sensorless-2 vector control modes, vector control mode requires motor parameter values for operation. Before operating the inverter in sensorless-2 mode, run auto tuning first.

Group	Code	Name LCD Display Para		ameter Setting	Unit	
	09	Control mode	Control Mode	5	Vector	-
DRV	21	Speed unit selection	Hz / rpm Sel	1	Rpm Display	-
BAS	20	Auto tuning	Auto Tuning	1	All	-
	09	Initial excitation time	PreExTime	-	1.0	sec
	10	Initial excitation power supply	Flux Force	-	100.0	%
	11	Continued operation duration	Hold Time	-	1.0	sec
	12	Speed controller proportional gain 1	ASR P Gain 1	-	50.0	%
	13	Speed controller integral gain 1	ASR I Gain 1	-	300	ms
	15	Speed controller proportional gain 2	ASR P Gain 2	-	50.0	%
	16	Speed controller integral gain 2	ASR I Gain 2	-	300	ms
	18	Gain exchange frequency	Gain Sw Freq	-	0.00	Hz
	19	Gain exchange time	Gain Sw Delay	-	0.10	sec
	51	Speed controller reference filter	ASR Ref LPF	-	0	ms
CON	52	Torque controller output filter	Torque Out LPF	-	0	ms
	53	Torque limit setting options	Torque Lmt Src	0	Keypad-1	-
	54	Forward offsetting torque limit	FWD +Trq Lmt	-	180	%
	55	Forward regenerative torque limit	FWD -Trq Lmt	-	180	%
	56	Reverse offsetting torque limit	REV +Trq Lmt	-	180	%
	57	Reverse regenerative torque limit	REV –Trq Lmt	-	180	%
	58	Torque bias setting options	Trq Bias Src	0	Keypad-1	-
	59	Torque bias	Torque Bias	-	0.0	%
	60	Torque bias	Trq BiasFF	-	0.0	%

Group	Code	Name	LCD Display	Parameter Setting		Unit
		compensation				
IN	65–75	PX terminal function setting	Px Define	36	Asr Gain 2	-
	65–75	PX terminal function setting	Px Define	37	ASR P/PI	-

① Caution

- For vector control mode operation, the motor-rated capacity must match the inverter's rated capacity. If the inverter capacity is too large for the installed motor, run the motor in V/F mode.
- Vector control mode does not support multiple motor control (MMC) features. Do not connect multiple motors to one inverter that is operating in vector control mode.

Vector Control Mode-Details

Code	Description				
DRV-14 Motor Capacity, BAS-11 Pole Number, BAS-12 Rated Slip, BAS-13 Rated Curr, BAS-15 Rated Volt, BAS-16 Efficiency	Motor parameter information is required for vector control mode operation. Check the motor's rating plate for the motor capacity and other performance-related information, set the relevant parameters, and then run auto tuning at BAS-20.				
APO-01 Enc Opt Mode	Sets the encoder option mode to "1 (feedback)".				
APO-04 Enc Type Sel	Sets the encoder's signal delivery options. Refer to the instruction manual supplied with the encoder and select one of the following options: 0: Line Driver / 1: Totem or Com / 2: Open Collect				
APO-05 Enc Pulse Sel	Sets the encoder output pulse options. Setting Description 0 (A+B) Fx operation 1 (A+B) Rx operation 2 A Frequency reference				
APO-06 Enc Pulse Num	Sets the number of pulses per rotation.				
APO-08 Enc Monitor	Converts the encoder output into motor rotation and displays in Hz or rpm units.				
BAS-20 Auto Tuning	To test the encoder: Sets the auto tuning type to "3 (Enc Test)" to check the encoder connection. The inverter operates in the Fx direction and accelerates to 20 Hz until it decelerates to 0 Hz and continues operating in the Rx direction, accelerating to 20 Hz. The BAS-20 parameter value is automatically changed to "None" if a connection error is not detected. The "Enc reverse" message is displayed if the encoder connection is not				

Code	Description				
	correct. If this happens, you can change the APO-05 (ENC Pulse Sel) parameter setting to match the actual direction, or swap the two encoder cables that are connected to the motor. To perform rotating auto tuning, separate the load from the motor axis, and set BAS-20 to "1 (ALL)". The motor stator resistance (Rs), leakage inductance (Lsigma), stator inductance (Ls), no-load current (Noload Curr) and rotor time constant (Tr) are saved in BAS-21, BAS-22, BAS-23, BAS-				
CON-09 PreExTime	14, and BAS-24 respectively. Sets the initial excitation time. Operation begins after the motor is excited to the rated speed.				
	Flux force may be used to reduce the initial excitation time. The motor flux increases based on a time constant. To reduce the time to reach the rated flux, you can supply a flux larger than the rating at first, and then reduce the amount of flux when the motor is excited close to the rated flux.				
	Motor flux				
CON-10 Flux Force	Excitation flux				
	Forced flux				
CON-12 ASR P Gain1, CON-13 ASR I Gain1	Sets the speed controller proportional and integral gain values. Increasing the P-gain increases responsiveness and torque output, while decreasing the I-gain increases responsiveness. However, note that excessively high P-gain or low I-gain settings may result in motor speed oscillation.				
CON-15 ASR P Gain2, CON-16 ASR I Gain2	These codes are used to configure the gains that are applied based on the load characteristics and motor speed. The switching of gain values is performed based on the switching frequency set at CON-18 and the switching time set at CON-19.				
CON-51 ASR Ref LPF	Sets the filter time constant that is used in vector speed mode for the speed controller.				
CON-52 Torque Out LPF	Sets the filter time constant that can be used in vector speed or vector torque mode. In vector speed mode, it is applied to the speed controller. In vector torque mode, it is applied to the torque reference.				

Code	Descri	ption				
CON-48 ACR P-Gain, CON-49 ACR I Gain			n values for the current PI controller. These gains are peed/torque modes and vector speed/torque modes.			
	Sets the multi-function terminals to control the gains and controllers.					
	Settin	g	Description			
IN-65–75 Px Define	36	ASR Gain2	When the terminal is on, gain switching takes place after the time set at CON-19 has passed.			
	37	ASR P/PI	When the terminal is on, the integral controller stops operating.			
		Sets the input source for the torque limit function. The torque limit function is used to limit the output to adjust the torque reference.				
	Settin	g	Description			
	0	Keypad-1	Sets the torque limit using the keypad (up to 200%			
CON-53 Torque Lmt Src	1	Keypad-2	of the motor rated torque).			
	3	V1 I1	Sets the torque limit using the analog terminals.			
	6	Int 485	Sets the torque limit using the built-in 485 communication device.			
IN-02 Torque at 100%	If CON becom (*Appl When	Sets the torque limit values for the analog input. If CON-53 is set to "2 (V1)" and IN-02 is set to "200%", the torque limit becomes 200% when 10 V input is supplied to V1.* (*Applies only if all V1 function parameters use default setting values.) When any device other than the keypad is selected as the torque limit input source, set CNF-21–23 to "21 (Torque Limit)".				
CON-33 FWD +Trq Lmt		Keypad-2)". Th	the torque limit when CON-53 is set to "0 (Keypad-1)" e torque limit can be set up to 200% of the motor rated			
CON-34 FWD –Trq Lmt	Setting Description					
CON-35 REV +Trq Lmt	FWD		Sets the torque limit for FX motoring operation.			
CON-36 REV -Trq Lmt			Sets the torque limit for FX regenerating operation.			
			Sets the torque limit for RX motoring operation.			
	[REV	Trq Lmt	Sets the torque limit for RX regenerating operation.			
	refere	nce.	rce for the offset setting to be added to the torque			
	Settin	Ť	Description			
	0	Keypad-1	Sets the torque bias using the keypad (-120% –			
CON-58 Trq Bias Src	1	Keypad-2	+120%, set at CON-59).			
	2	V1	Sets the torque bias using the analog terminals.			
	3	l1	(-120% –+120%, set at CON-59). The setting can be viewed in monitor mode. Set			
		11	CFG-06–08 to "21 (Torque bias)".			
CON-59 Torque Bias	Sets th	ne torque bias	value between -120%- +120%.			
IN-65–75 Px Define	Sets one of the multi-function terminals to "48 (Trq Bias)". Torque bias input via the keypad or analog input is applied only when this multi-function terminal is on.					

Code	Description
CON-60 Trq BiasFF	Sets the compensation volume to add to the bias to make up for the loss caused by motor rotation. Negative (-) values diminish the torque bias.
CON-11 Hold Time	When a run command stops, the inverter holds the zero speed output for the set time before the motor decelerates to a complete stop. Output Voltage Hold time
	Frequency
	Run cmd

8.14 Torque Control

You can use torque control to operate the inverter to produce a certain amount of torque as indicated by the torque reference. In torque control mode, the motor speed is decided by the amount of load because a motor can run at a constant speed when the output torque and torque load are equal. The motor speed increases when the output torque becomes greater than the torque load. You can set a speed limit to maintain the motor speed within a certain range. Note that torque control is not available during the speed control operations.

Group	Code	Name	LCD Display	Parai	neter Setting	Unit
	02	Torque command	Cmd Torque	-	0.0	%
DRV	08	Torque reference source	Trq Ref Src	0	Keypad-1	-
DKV	09	Control mode	Control Mode	5	Vector	-
	10	Torque control	Torque Control	1	Yes	-
BAS	20	Auto tuning	Auto Tuning	1	Yes	-
	35	SL2 L-ExcitLmt	SL2 L-ExcitLmt	-	10	%
	62	Speed limit setting options	Speed Lmt Src	0	Keypad-1	-
CON	63	Forward speed limit	FWD Speed Lmt	-	60.00	Hz
	64	Reverse speed limit	REV Speed Lmt	-	60.00	Hz
	65	Speed limit operation gain	Speed Lmt Gain	-	500	%
IN	65–75	PX terminal function setting	Px Define	35	Speed/Torque	-
	31–33	Multi-function relay, Multi-function output 1	Relay x or Q1	27	Torque Dect	-
OUT	59	Detected torque amount	TD Level	-	100	%
	60	Detected torque width	TD Band	-	5.0	%

Note

- Basic parameters for inverter operation must be correctly set before you can operate the inverter in torque control mode.
- Torque control is not available during low speed regeneration and light load operation. Operate the inverter in vector control mode instead.
- Do not switch between Fx and Rx operations while the inverter is operating in torque control mode. An overcurrent or reverse deceleration fault trip may occur as a result.

Torque Control-Details

	T					
Code	Description					
DRV-08 Trq Ref Src	Select the input source for the torque reference. Setting Description O Keypad-1 Sets the torque reference using the keypad (up to 180% of rated motor torque, set at CON-02). 2 V1 Sets the torque reference using the analog terminals. The torque reference changes based on the set value at IN-02 (Torque at 100%). For example, if IN-02 is set to 200%, the torque reference becomes 200% when 20 mA current is supplied. The setting can be viewed in monitor mode. Set CFG-06–08 to "19 (Torque Ref)". 6 Int485 Sets the torque reference using the built-in RS485 communication device.					
CON-02 CMD Torque	Sets the torque reference for keypad input.					
IN-02 Torque at 100%	Sets the torque reference for analog terminal input.					
CON-35 SL2 L- ExcitLmt	This is the ratio to improve the operating characteristics in the low torque/low speed range by lowering the magnetic flux current. However, if the value is set too low, stable sensorless control may not be possible.					
CON-62 Speed Lmt Src	Select the input source for the speed limit. Setting Description Keypad-1 Keypad-2 Lmt / CON-64 REV Speed Lmt). V1 Set the torque reference using the analog terminals, in the same manner as setting a frequency reference. The setting can be viewed in monitor mode. Set CNF-21–23 to "23 (Speed Limit)".					
CON-65 Speed Lmt Gain	Set the torque reference decrement rate between 100%–5000% for when the speed limit is exceeded.					
IN-65–75 Px Define	Sets one of the multi-function inputs to "35 (Speed/Torque)". Switching between torque control mode and speed (vector) control mode takes place when the terminal					

Code	Description
	is on.

8.15 Droop Control

Droop control is used to balance the load when operating multiple motors for a single load, or to prevent speed controller saturation in vector control mode.

Group	Code	Name	LCD Display	Param	Unit	
		Droop Perc	-	0.0	%	
CON	67	Droop start torque	Droop St Torque	-	100.0	%

Droop Control-Details

Code	Description				
CON-66 Droop Perc	Sets the percentage rate for the droop operation based on the rated torque.				
CON-67 Droop	Sets the torque to start droop operation. Based on the set value, the motor speed can be calculated as follows:				
start torque	Droop speed = Maximum frequency × DroopPerc × Torque reference - DroopStTorque 100% torque - DroopStTorque				

8.16 Speed / Torque Control Switching

Set one of the multi-function terminals to switch between speed and torque control modes. This function is only available in vector control mode.

Group	Code	Name	LCD Display	Param	Parameter Setting	
CON	Torque mode–speed mode switching acceleration time				20.0	sec
CON 69		Torque mode—speed mode switching deceleration time	SPD/TRQDec T	-	30.0	sec
IN	65– 75	PX terminal setting option	Px Define	35	Speed/Torque	-
	09	Control mode	Control Mode	5	Vector	-
DRV	10	Targue control	Torque Control	0	No	-
	10	Torque control	Torque Control	1	Yes	-

Set a multi-function input Px to "35 (Speed/Torque)".

If the terminal is on during a vector torque operation, where DRV-09 (Control Mode) is set to "5 (Vector)" and DRV-10 (Torque Control) is set to "1 (Yes)", the operation switches from torque to speed mode based on the acceleration and deceleration times set at CON-68 (SPD/TRQAcc T) and CON-69 (SPD/TRQDec T).

If the terminal is on during a vector speed operation, where DRV-09 (Control Mode) is set to "5 (Vector)" and DRV-10 (Torque Control) is set to "0 (No)", the operation switches from speed to torque mode.

8.17 Kinetic Energy Buffering

When the input power supply is disconnected, the inverter's DC link voltage decreases, and a low voltage trip occurs, blocking the output. A kinetic energy buffering operation uses regenerative energy generated by the motor during the blackout to maintain the DC link voltage. This extends the time for a low voltage trip to occur after an instantaneous power interruption.

Group	Code	Name	LCD Display	Parameter Setting		Setting range	Unit
				0	None		
	77	Kinetic energy buffering selection	KEB Select	1	KEB-1	0–2	-
				2	KEB-2		
	78	Kinetic energy buffering start level	KEB Start Lev	130		110–200	%
	79	Kinetic energy buffering stop level	KEB Stop Lev	135		130–210	%
CON	86	Kinetic energy buffering P- Gain	KEB P Gain	1500		0–20000	%
	87	Kinetic energy buffering I gain	KEB I Gain	500		1–20000	%
	88	Kinetic energy buffering slip gain	KEB Slip Gain	30.0		0–2000.0	%
	89	Kinetic energy buffering acceleration time	KEB Acc Time	10.0		0.0–600.0	Sec
IN	65– 75	PX terminal setting option	Px Define	50	KEB-1 Select	0–51	

Kinetic Energy Buffering Operation Setting Details

Code	Description						
	Select the kin	etic energy buffering operation when the input power is disconnected.					
	Note						
		ction terminal is set to "50 (KEB-1 Select)", KEB operation is available nput only. Set CON-77 to "0 (none)" in this case.					
	Setting	Function					
	0 None	General deceleration is carried out until a low voltage trip occurs.					
CON-77 KEB Select	1 KEB-1	If input power failure occurs, the inverter output frequency is controlled and the regeneration energy from the motor is charged by the inverter. Normal operation is resumed when the power is supplied again, using the acceleration time set at CON-89 (KEB Acc Time). DC Link Voltage CON-78 CON-79 CON-79 KEB Control Operation return (CON-89)					
		If input power failure occurs, the inverter output frequency is controlled and the regeneration energy from the motor is charged by the inverter. The motor decelerates and stops when the power is supplied again, using the deceleration time set at DRV-04 (Dec Time).					
	2 KEB-2	Voltage CON-78 CON-79					
		Output frequency KEB Control Dec stop(DRV-04)					
		PX(FX)					
CON-78 KEB Start Lev, CON-79 KEB Stop Lev	values must b	and stop points of the kinetic energy buffering operation. The set be based on the low voltage trip level at 100%, and the stop level at be set higher than the start level (CON-78).					
CON-86 KEB P Gain	Used to maintain the voltage during the kinetic energy buffering operation. It operates the inverter by modifying the set value to prevent malfunctions caused by low voltage after power interruptions.						

Code	Description						
CON-87 KEB I Gain	Used to maintain the voltage during the kinetic energy buffering operation. Sets the gain value to maintain the operation until the frequency stops during the kinetic energy buffering operation.						
CON-88 KEB Slip Gain	Used to prevent malfunctions caused by low voltage from initial kinetic energy buffering occurring due to power interruptions.						
CON-89 KEB Acc Time	Sets the acceleration time for the frequency reference when the inverter's operation becomes normal after the kinetic energy buffering operation.						
	Sets a multi-function input Px to "50 (KEB-1 Select)". If the terminal is on during an operation, the inverter operates in KEB-1 mode. The inverter output frequency is controlled to the output level set at CON-78 and the regeneration energy from the motor is charged by the inverter. Normal operation is resumed when the power is supplied again, using the acceleration time set at CON-89 (KEB Acc Time). If the terminal is not on, KEB operation does not start when the input power failure occurs.						
IN-65–75 Px Define	If a multi-function terminal is set to "50 (KEB-1 Select)", KEB operation is available via terminal input only. Set CON-77 to "0 (none)" in this case. DC Link Voltage CON-78						
	Output frequency KEB Control Operation return PX (KEB-1 Select)						

① Caution

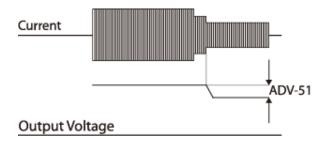
- Depending on the duration of instantaneous power interruptions and the amount of load inertia, a low voltage trip may occur even during a kinetic energy buffering operation.
- Motors may vibrate during kinetic energy buffering operation for some loads, except for variable torque loads (for example, fan or pump loads).

8.18 Energy Saving Operation

8.18.1 Manual Energy Saving Operation

If the inverter output current is lower than the current set at BAS-14 (Noload Curr), the output voltage must be reduced as low as the level set at ADV-51 (Energy Save). The voltage before the energy saving operation starts will become the base value of the percentage. The manual energy saving operation will not be carried out during acceleration and deceleration.

Group	Code	Name	LCD Display	Parameter Setting		Parameter Setting Setting Range		Unit
					0	None		
	ADV 50	Energy saving operation	E-Save Mode	1	Manual	1	Manual	-
ADV						2	Auto	
	51 Energy saving amount		Energy Save	30		0–30		%



8.18.2 Automatic Energy Saving Operation

The inverter automatically finds the optimal energy saving point based on the motor rated current (BAS-13) and the no-load current (BAS-14).

Group	Code	Name	LCD Display	Setting		Setting Range	Unit
ADV	50	Energy saving operation	E-Save Mode 2 Auto		0–2	-	
BAS	13	Motor-rated current	Rated Curr	Depends on inverter capacity		1–1000	А
DAO	14	Motor no-load current	Noload Curr	Depends on inverter capacity		0.5–1000	A

① Caution

If the operation frequency is changed, or acceleration or deceleration is carried out during an energy saving operation, the actual acc/dec time may take longer than the set time due to the time required to return to general operations from the energy saving operation.

8.19 Speed Search Operation

Speed search operation is used to prevent fault trips that can occur when the inverter voltage output is disconnected and the motor is idling. Since this feature estimates the motor rotation speed based on the inverter output current, it does not give the exact speed.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit	
	70 Speed search mode selection SS Mode		0	0 Flying Start-1		-	-	
	71	Speed search Speed Search		0000			-	bit
	72	Speed search	SS Sup-	Upi	to 75 kW	150		%
CON	reference current	Current	Ove	er 75 kW	100	80–200	70	
	73	Speed search proportional gain SS	SS P-Gain	100			0–9999	-
	74	Speed search integral gain	SS I-Gain	200		0–9999	-	
	75	Output block time before speed search	SS Block Time	1.0		0–60	sec	
OUT	31–32	Multi-function relay 1– Relay 1–2		19	9 Speed Search		-	-
	33 Multi-function ou	Multi-function output 1	Q1 Define	1				

Speed Search Operation Setting Details

Code	Description					
	Sel	ect a speed searc	h type.			
	Se	tting	Function			
CON-70 SS Mode	0	Flying Start-1	The speed search is carried out as it controls the inverter output current during idling below the CON-72 (SS Sup-Current) parameter setting. If the direction of the idling motor and the direction of the operation command at restart are the same, a stable speed search function can be performed at about 10 Hz or lower. However, if the direction of the idling motor and the direction of the operation command at restart are different, the speed search does not produce a satisfactory result because the direction of idling cannot be established.			
	1	Flying Start-2	The speed search is carried out by the PI controller,			

Code	Descript	tion						
			counthis (forward) regardine the counting electric access seat (about the counting the counting the countries of the countrie	which controls the ripple current generated by the counter electromotive force during no-load rotation. As this mode establishes the direction of the idling motor (forward/reverse), the speed search function is stable regardless of the direction of the idling motor and direction of the operation command. However, because the ripple current is used, which is generated by the counter electromotive force while idling (the counter electromotive force while idling (the counter electromotive force is proportional to the idle speed), the idle frequency is not determined accurately and reacceleration may start from zero speed when the speed search is performed for the idling motor at a low speed (about 10 - 15 Hz, though it depends on motor characteristics).				
	segmer	Speed search can be selected from the following four options. If the top display segment is on, it is enabled (On). If the bottom segment is on, it is disabled (Off).						
	Item Keypad	d	Bit Setti	Bit Setting On Status Bit Setting Off Status				
	Type ar	nd Functi	ions of Sp	peed Sear	ch Setting			
	Setting	•		•	Function			
	bit4	bit3	bit2	bit1				
		1		✓	Speed search for general acceleration			
		+	✓		Initialization after a fault trip			
		✓			Restart after instantaneous power interruption			
CON-71 Speed	√	+		1	Start with power-on			
Search	operation When the comman function Initialized PRT-08	on command motor in the motor i	and runs, a is rotating for the inve s such fault er a fault t estart) is se	acceleration under load erter to pro t trips from rip other t et to "1 (Yes	tion: If bit 1 is set to "1" and the inverter n starts with the speed search operation. I, a fault trip may occur if the operation wide voltage output. The speed search			

fault trip when the [STOP/RESET] key is pressed (or the terminal block input is

Automatic restart after an instantaneous power interruption: If bit 3 is set to "1", and if a low voltage trip occurs due to a power interruption but the power is restored before the internal power shuts down, the speed search operation accelerates the motor back to its frequency reference before the low voltage trip.

on) after a fault trip.

Code	Description					
	If an instantaneous power interruption occurs and the input power is disconnected, the inverter generates a low voltage trip and blocks the output. When the input power returns, the operation frequency before the low voltage trip and the voltage is increased by the inverter's inner PI controller. If the current increases above the value set at CON-72, the voltage stops increasing and the frequency decreases (t1 zone). If the current decreases below the value set at CON-72, the voltage increases again and the frequency stops decelerating (t2 zone). When the normal frequency and voltage are resumed, the speed search operation accelerates the motor back to its frequency reference before the fault trip.					
	Power input					
	Frequency t1 t2					
	Voltage					
	Current H 23					
	Multi-function output or relay					
	Starting with power-on: Set bit 4 to "1" and ADV-10 (Power-on Run) to "1 (Yes)". If inverter input power is supplied while the inverter operation command is on, the speed search operation will accelerate the motor up to the frequency reference.					
CON-72 SS Sup- Current	The amount of current flow is controlled during speed search operation based on the motor's rated current. If CON-70 (SS mode) is set to "1 (Flying Start-2)", this code is not visible.					
CON-73 SS P-Gain, CON-74 SS I-Gain	The P/I gain of the speed search controller can be adjusted. If CON-70 (SS Mode) is set to "1"(Flying Start-2), different factory defaults based on motor capacity [at DRV-14 (Motor Capacity)] are used.					
CON-75 SS Block Time	The block time parameter prevents overvoltage trips due to counter electromotive force by cutting off the inverter output for the set time before carrying out a speed search.					

Note

If operated within the rated output, the iS7 series inverter is designed to withstand instantaneous power interruptions of up to 15 ms and maintain normal operation [when 200–230 V AC input voltage

- is supplied to 200 V class model types, and 380-460 V AC input voltage is supplied to 400 V class model types, and when the inverter is operating with static load current (CT load)].
- The DC voltage inside the inverter changes depending on the load. Low voltage fault trips may result if the power interruption lasts longer than 15 ms, or the output voltage exceeds the rated input voltage.

8.20 Auto Restart Settings

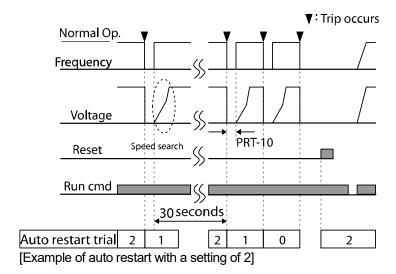
When inverter operation stops due to a fault and a fault trip is activated, the inverter automatically restarts based on the parameter settings.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit	
	08	Soloot start at trip reset	RST Restart	0 No				
PRT	00	Select start at trip reset	No i Nesiait	1	Yes	8	_	
FKI	09	Auto restart count	Retry Number	6			0–10	-
	10	Auto restart delay time	Retry Delay	1.0			0.1–60.0	sec
	71	Select speed search operation	Speed Search -			0000–1111	bit	
	72 Speed search startup		SS Sup-	Up to 75 k	W	150	80–200	%
	12	current	Current	Over 75 k	W	100	80-200	70
CON	73	Speed search proportional gain	SS P-Gain	100			0–9999	
	74	Speed search integral gain	SS I-Gain	200		0–9999		
	75	Output block time before speed search	SS Block Time	1.0			0.0–60.0	sec

Auto Restart Setting Details

Code	Description
PRT-08 RST Restart	Set PRT-08 to "1 (Yes)" to enable reset restart.
PRT-09 Retry Number, PRT-10 Retry Delay	The number of available auto restarts can be set at PRT-09. If a fault trip occurs during an operation, the inverter restarts after the time set at PRT-10 (Retry Delay). At each restart, the inverter counts the number of tries and subtracts it from the number set at PRT-09 until the retry number count reaches 0. After an auto restart, if a fault trip does not occur within 60 sec, it will increase the restart count number. The maximum count number is limited by the number set at PRT-09.

Code	Description
	If the inverter stops due to low voltage, an emergency stop, an inverter overheating, or a hardware malfunction, auto restart is not activated.
	At auto restart, the acceleration options are identical to those of the speed search operation. Codes CON-72–75 can be set based on the load. For the speed search function details, refer to <u>8.19 Speed Search Operation</u> on page <u>244</u> .



① Caution

If the auto restart number is set, be careful when the inverter resets from a fault trip. The motor may automatically start to rotate.

8.21 Operational Noise Settings (Carrier Frequency Settings)

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
	04	Carrier Frequency	Carrier Freq	q 5.0		0.7–15.0	kHz
CON	05	Switching Mode	PWM* Mode	0	Normal PWM	Normal PWM / Low Leakage PWM	-

^{*} PWM: Pulse width modulation

Operational Noise Setting Details

Code	Description					
CON-04 Carrier Freq	Adjusts motor operational noise by changing carrier frequency settings. Power transistors (IGBT) in the inverter generate and supply high frequency switching voltage to the motor. The carrier frequency refers to the switching speed in this process. If the carrier frequency is set high, it reduces operational noise from the motor. If the carrier frequency is set low, it increases operational noise from the motor.					
	The heat loss and leakage current from the inverter can be reduced by changing the load rate option at CON-05 (PWM Mode). Selecting "1 (LowLeakage PWM)" reduces heat loss and leakage current, compared to when "0 (Normal PWM)" is selected. However, it increases the motor noise. Low leakage PWM uses a two-phase PWM modulation mode, which helps minimize degradation and reduces switching loss by approximately 30%.					
		Carrier Frequency				
	Item	0.7 kHz	15 kHz			
CON-05 PWM		LowLeakage PWM	Normal PWM			
Mode	Motor noise	1	↓			
	Motor temperature	†	↓			
	Inverter heat Loss	↓	↑			
	High frequency	↑	↓			
	Inverter output current wave form	Bad	Good			
	Inverter noise	↓	↑			
	Inverter leakage current		<u> </u>			

① Caution

The factory default carrier frequency for 90–160 kW model types is 3 kHz. The figure in the red box (D: 5.0) is a factory default carrier frequency for models types up to 75 kW, provided for your reference only.



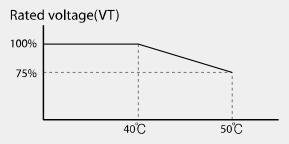
Since low carrier frequencies can transmit a much higher frequency than the capacity of the output current, an increase in motor loss will occur. Some motors may stall due to increased high frequency current and lack of torque may cause the inverter to stop.

Note

Factory default carrier frequency by model types

0.75–22 kW	30–45 kW	55–75 kW	90–110 kW	132–160 kW
5 kHz (15 kHz max.)	5 kHz (10 kHz max.)	5 kHz (7 kHz max.)	3 kHz (6 kHz max.)	3 kHz (5 kHz max.)

- iS7 Series Inverter Derating Standard (Derating): The overload rate represents an acceptable load amount that exceeds the rated load, and is expressed as a ratio based on the rated load and the duration. The overload capacity on the iS7 series inverter is 110%/1 min for normal loads.
- The current rating differs by load types, and it also has an ambient temperature limit.
- Current derating for ambient temperature at variable torque (VT) load operation:



Current derating table by ambient temperature and carrier frequency:

Inverter Capacity		0.75–7.5kW	11–22kW	30–75kW
	Normal Temp. (25°C)	10 kHz	10 kHz	5 kHz
CT Load	High Temp. (40°C)	7 kHz	7 kHz	4 kHz
	High Temp. (50°C)	5 kHz	5 kHz	4 kHz
\/T.Lood	Normal Temp. (25°C)	7 kHz	7 kHz	3 kHz
VT Load	High Temp. (40°C)	2 kHz	2 kHz	2 kHz

8.22 2nd Motor Operation

The 2nd motor operation is used when a single inverter switch operates two motors. Using the 2nd motor operation, a parameter for the second motor is set. The second motor operates when a multifunction terminal input defined as a second motor function is turned on.

Group	Code	Name	LCD Display	Param	eter Setting	Setting Range	Unit
IN	65–75	Px terminal configuration	Px Define(Px: P1–P8 [optional: P9–P11])	26	2nd Motor	-	-
M2	04	2nd motor acceleration time	M2-Acc Time	-	5.0	0–600	sec

2nd Motor Operation Setting Details

Code	Description
IN-65–75 Px Define	Set one of the multi-function input terminals (P1–P11) to "26 (2nd Motor)" to display the M2 (2nd motor group) group. An input signal sent to a multi-function terminal set as the second motor will operate the motor according to the code settings listed below. However, if the inverter is in operation, input signals to the multi-function terminals will not read as a second motor parameter. You can set the 2nd motor control mode at M2-08 (M2-Ctrl Mode). V/F PG and Vector control modes are not supported with the 2nd motor operation. PRT-50 (Stall Prevent) must be set first, before M2-28 (M2-Stall Lev) settings can be used. PRT-40 (ETH Trip Sel) must be set first, before M2-29 (M2-ETH 1 min) and M2-30 (M2-ETH Cont) settings can be used.

Parameter Setting at Multi-function Terminal Input on a Second Motor

Code	Description	Code	Description
M2-04 Acc Time	Acceleration time	M2-15 M2-Efficiency	Motor efficiency
M2-05 M2-Dec Time	Deceleration time	M2-17 M2-Rs	Stator resistance
M2-06 M2-Capacity	Motor capacity	M2-18 M2-Lsigma	Leakage inductance
M2-07 M2-Base Freq	Motor base frequency	M2-25 M2-V/F Patt	V/F pattern
M2-08 M2-Ctrl Mode	Control mode	M2-26 M2-Fwd Boost	Forward torque boost
M2-10 M2-Pole Num	Pole number	M2-27 M2-Rev Boost	Reverse torque boost
M2-11 M2-Rate Slip	Rated slip	M2-28 M2-Stall Lev	Stall prevention level
M2-12 M2-Rated Curr	Rated current	M2-29 M2-ETH 1 min	Motor heat protection 1 min rating
M2-13 M2-Noload Curr	No-load current	M2-30 M2-ETH Cont	Motor heat protection

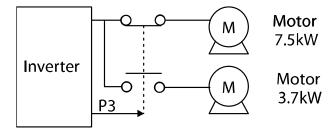
Learning Advanced Features

Code	Description	Code	Description
			continuous rating
M2-14 M2-Rated Volt	Motor-rated voltage		

Example - 2nd Motor Operation

Use the 2nd motor operation when switching operations between a 7.5 kW motor and a secondary 3.7 kW motor using terminal P3. Refer to the following settings.

Group	Cod e	Name	LCD Display	Parameter Setting		Setting Range	Unit
IN	67	Terminal P3 configuration	P3 Define	26	2nd Motor	-	-
M2	06	Motor capacity	M2-Capacity	-	3.7 kW	-	-
IVI∠	08	Control mode	M2-Ctrl Mode	0	V/F	-	-



8.23 Supply Power Transition

A supply power transition is used to switch the power source for the motor connected to the inverter from the inverter output power to the main supply power source (commercial power source), or vice versa.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
IN	65–75	Px terminal configuration	Px Define (Px: P1–P8 [optional: P9–P11])	16	Exchange	-	-
OUT	31–32	Multi-function relay 1–2	Relay1–2	17	Inverter Line	-	-
001	33	Multi-function output 1	Q1 Define	18	Comm Line	-	-

Supply Power Transition Setting Details

Code	Description						
IN-65–75 Px Define	When the motor power source changes from the inverter output to the main power supply, select a terminal to use and set the code value to "16 (Exchange)". Power will be switched when the selected terminal is on. To reverse the transition, switch off the terminal.						
	Set the multi-function relay or multi-function output to "17 (Inverter Line)" or "18 (Comm Line)". The relay operation sequence is as follows.						
OUT-31 Relay 1, OUT-32 Relay 2, OUT-33 Q1 Define	Speed search Output frequency Run cmd Px(Exchange) Px (Comm Line) Px (Inverter Line) Inverter operation operation t: 500 msec						

8.24 Cooling Fan Control

This function turns the inverter's heatsink cooling fan on and off. It is used in situations where the load stops and starts frequently or when a noise-free environment is required. The correct use of cooling fan controls can extend the cooling fan's life.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit	
				0	During Run			
ADV	64	Cooling fan control	Fan Control	Fan Control	1	Always On	0–2	-
				2	Temp Control			

Cooling Fan Control Detail Settings

Code	Description						
ADV-64 Fan Control	Sett	ings	Description				
	0	During Run	The cooling fan runs when the power is supplied to the inverter and the operation command is on. The cooling fan stops when the power is supplied to the inverter and the operation command is off. When the inverter heat sink temperature is higher than its set value, the cooling fan operates automatically regardless of its operation status.				
	1	Always On	The cooling fan runs constantly if power is supplied to the inverter.				
	2	Temp Control	With power connected and the run operation command on: if the setting is in Temp Control, the cooling fan will not operate unless the temperature in the heat sink reaches the set temperature.				

Note

In 11–75 kW model types, if the heat sink temperature reaches a set level by input current harmonic waves or noise, the cooling fan may run to protect the inverter even when ADV-64 is set to "0 (During Run)".

8.25 Input Power Frequency Settings

Select the frequency for inverter input power. If the frequency changes from 60 Hz to 50 Hz, all other frequency (or RPM) settings, including the maximum frequency, base frequency, etc., will change to 50 Hz. Likewise, changing the input power frequency setting from 50 Hz to 60 Hz will change all related function item settings from 50 Hz to 60 Hz.

Group	Code	Name	LCD Display	Pa	rameter Setting	Setting Range	Unit
BAS	10	Input power frequency	60/50 Hz Sel	0	60 Hz	0–1	-

8.26 Input Power Voltage Settings

Set the inverter input power voltage. The low voltage fault trip level changes automatically according to the set voltage standard.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
BAS	DAG 10 Insult in account to the ma		200 Type	220	170–230	\/	
DAS	19	Input power voltage	AC Input Volt	400 Type	380	380–480	V

8.27 Read, Write, and Save Parameters

Use read, write, and save parameter functions to copy parameters from the inverter to the keypad or from the keypad to the inverter.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
	46	Parameter read	Parameter Read	1	Yes	-	-
CNF	47	Parameter write	Parameter Write	1	Yes	-	-
	48	Parameter save	Parameter Save	1	Yes	-	-

Read, Write, and Save Parameter Setting Details

Code	Description
CNF-46 Parameter Read	Copies saved parameters from the inverter to the keypad. Saved parameters on the keypad will be deleted and replaced with the copied parameters.
CNF-47 Parameter Write	Copies saved parameters from the keypad to the inverter. Saved parameters on the inverter will be deleted and replaced with the copied parameters. If an error occurs during parameter writing, the previously saved data will be used. If there is no saved data on the keypad, "EEP Rom Empty" will be displayed.
CNF-48 Parameter Save	As parameters set during communication transmission are saved in RAM, the setting values will be lost if the power turns off and on. When setting parameters during communication transmission, select "1 (Yes)" at CNF-48 to save the set parameters.

Caution

When utilizing the optional communication module, note the following information if you need to read or write the parameter values set at COM-10-25 (Opt Parameter).

- 1. Because the "Opt Parameter" (COM-10-25) values are stored in the optional add-on module, you must run "Comm Update" (COM-94) to apply the changes after making changes to the parameter settings.
- 2. You must save the parameter values set at COM-10-25 (Opt Parameter) by running "Parameter Save" before you can read or write the "Opt Parameter" parameters.

8.28 Parameter Initialization

User changes to parameters can be initialized (reset) to factory default settings on all or selected groups. Parameters cannot be reset during operation or a fault trip condition.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
CNF	40	Parameter initialization	Parameter Init	0	No	0–15	

Parameter Initialization Setting Details

Code	Desc	ription			
	Set	ting	LCD Display	Function	
	0	No	No	-	
	1	Initialize all groups	All Grp	Initialize all data. Select "1 (All Grp)" and press the [PROG/ENT] key to start initialization. On completion, "0 (No)" will be displayed.	
	2	Initialize DRV group DRV Grp			
	3	Initialize BAS group	BAS Grp		
CNF-40 Parameter	4	Initialize ADV group	ADV Grp		
Init	5	Initialize CON group	CON Grp		
	6	Initialize IN group	IN Grp	Initialize data by groups. Select	
	7	Initialize OUT group	OUT Grp	Initialize group and press the [PROG/ENT] key to start	
	8	Initialize COM group	COM Grp	initialization. On completion, "0	
	9	Initialize APP group	APP Grp	(No)" will be displayed.	
	10	Initialize AUT group	AUT Grp		
	11	Initialize APO group	APO Grp		
	12	Initialize PRT group	PRT Grp		
	13	Initialize M2 group	M2 Grp		

8.29 Parameter Viewing and Lock Options

8.29.1 Parameter View Lock

Use parameter view lock to hide parameter mode (PAR mode) after registering and entering a user password. Other modes (CNF, U&M, MAC and TRP modes) will still be visible when the parameter view lock is enabled.

Group	Code	Name	LCD Display	Parameter Setting	Setting Range	Unit
50	50	Parameter view lock	View Lock Set	Unlocked	0–9999	-
CNF	51	Parameter view lock password	View Lock Pw	Password	0–9999	-

Parameter View Lock Setting Details

Code	Desc	Description			
	_	ster a password to allow access to parameter view lock. Follow the steps v to register a password.			
	No	Procedure			
CNF-51 View Lock	1	Press the [PROG/ENT] key on code CNF-51 to show the previous password input window. If a password is being registered for the first time, enter "0". It is the factory default.			
Pw	2	If a password had been set, enter the saved password.			
	3	If the entered password matches the saved password, a new window prompting the user to enter a new password will be displayed (the process will not progress to the next stage until the user enters a valid password).			
	4	Register a new password.			
	5	After registration, code CNF-51 (View Lock PW) will be displayed.			
CNF-50 View Lock Set	To enable parameter view lock, enter a registered password. The [Locked will be displayed on the screen to indicate that parameter view lock is ena disable parameter view lock, re-enter the password. The [locked] sign will disappear, and PAR mode becomes visible again.				

8.29.2 Parameter Lock

Use parameter lock to prevent unauthorized modification of parameter settings. To enable parameter lock, register and enter a user password first.

Group	Code	Name	LCD Display	Parameter Setting	Setting Range	Unit
CNF 52 53	52	Parameter lock	Key Lock Set	Unlocked	0–9999	-
	53	Parameter lock password	Key Lock Pw	Password	0–9999	-

Parameter Lock Setting Details

Code	Descripti	Description			
		a password to prohibit parameter modifications. Follow the procedures register a password.			
	No	Procedures			
CNF-53 Key Lock PW	1	Press the [PROG/ENT] key on code CNF-53 to display the saved password input window. If a password is being registered for the first time, enter "0". It is the factory default.			
	2	If a saved password has been set, enter the saved password.			
	3	If the entered password matches the saved password, then a new window to enter a new password will be displayed. (The process will not progress to the next stage until the user enters a valid password).			
	4	Register a new password.			
	5	After registration, code CNF-53 will be displayed.			
CNF-52 Key Lock Set	To enable parameter lock, enter the registered password. The [Locked] sign will be displayed on the screen to indicate that prohibition is enabled. Once enabled, pressing the [PROG/ENT] key will not allow the edit mode to run. To disable parameter lock, re-enter the password. The [Locked] sign will disappear.				

① Caution

If parameter view lock and parameter lock functions are enabled, no inverter operation related function changes can be made. It is very important that you memorize the password.

8.29.3 Changed Parameter Display

This feature displays all the parameters that are different from the factory defaults. Use this feature to track changed parameters.

Group	Code	Name	LCD Display	Par	rameter Setting	Setting Range	Unit
CNF	41	Changed parameter display	Changed Para	1	View Changed	-	-

Changed Parameter Display Setting Details

Description				
Setting	Function			
0 View All	Display all parameters			
1 View Change	d Display changed parameters only			
	Setting			

8.30 User Group

Create a user-defined group and register user-selected parameters from the existing function groups. The user group can carry up to a maximum of 64 parameter registrations.

Group	Code	Name	LCD Display	Pa	rameter Setting	Setting Range	Unit
CNE	42	Multi-function key settings	Multi Key Sel	3	UserGrp SelKey	-	-
CNF	45	Delete all user registered codes	UserGrp AllDel	0	No	-	-

User Group Setting Details

Code	Desc	Description				
CNF-42 Multi Key Sel	group group on th	cts "3 (UserGrp SelKey)" from the multi-function key setting options. If user operameters are not registered, setting the multi-function key to the user of select key (UserGrp SelKey) will not display user group (USR Grp) items to keypad. We the procedures below to register parameters to a user group.				
ON 42 Widia Ney Oci	No	Procedure				
	1	Set CNF- 42 to "3 (UserGrp SelKey)". The icon will be displayed at the top of the LCD display.				
	2	In the parameter mode (PAR Mode), move to the parameter you need				

Code	Desc	ription				
		to register and press the [MULTI] key. For example, if the [MULTI] key is pressed in the frequency reference in DRV-01 (Cmd Frequency), the screen below will be displayed.				
		USR → REG U STP 60.0Hz DRV01 Cmd Frequency 40 CODE DRV06 Step Freq - 1 00~64 CODE				
		 Group name and code number of the parameter. Name of the parameter. Code number to be used in the user group. Pressing the [PROG/ENT] key on the code number (40 Code) will register DRV-01 as code 40 in the user group. Existing parameter registered as the user group code 40. Setting range of the user group code. Entering "0" cancels the settings. 				
	3	3 Set a code number to use to register the parameter in the user group. Select the code number and press the [PROG/ENT] key.				
	4	Changing the value in 3 will also change the value in 4. If no code is registered, "Empty Code" will be displayed. Entering "0" cancels the settings.				
	5	The registered parameters are listed in the user group in U&M mode. You can register one parameter multiple times if necessary. For example, a parameter can be registered as code 2, code 11, etc. in the user group.				
	Follo	w the procedures below to delete parameters in the user group.				
	No.	Settings				
	1	Set CNF- 42 to "3 (UserGrp SelKey)". The icon will be displayed at the top of the LCD display.				
	2	In the USR group in U&M mode, move the cursor to the code that is to be deleted.				
	3	Press the [MULTI] key.				
	4	Select "YES" on the deletion confirmation screen, and press the [PROG/ENT] key.				
	5	The parameter is deleted.				
CNF-25 UserGrp AllDel	Set to	o "1 (Yes)" to delete all registered parameters in the user group.				

8.31 Macro Selection

The macro selection function is used to put various application functions together in a group. For applications with the iS7 series inverters, two basic macro configurations for "Draw"* and "Traverse" applications (MC1 and MC2) are currently available in U&M mode. Macro functions cannot be added by the user, but the data can be modified.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
CNF 43				0	None	0–2	
	43	Macro selection	Macro Select	1	Draw		-
				2	2 Traverse		

^{*}The draw application is an open loop tension control which maintains a stable tension load applied to the material by utilizing the difference between the main reference and the auxiliary reference (Refer to 8.1 Operating with Auxiliary References on page 194 for details).

Macro Selection Details

Code	Description
CNF-43 Macro Select	A list of macro settings is displayed for user selection. When a macro function is selected, all the related parameters are automatically changed based on the inverter's macro settings.

8.32 Easy Start

Run Easy Start to easily set up the basic motor parameters required to operate a motor in a batch. Set CNF-61 (Easy Start On) to "1 (Yes)" to activate the feature, initialize all parameters by setting CNF-40 (Parameter Init) to "1 (All Grp)", and restart the inverter to activate Easy Start.

Group	Code	Name	LCD Display	Par	rameter Setting	Setting Range	Unit
CNF	61	Parameter easy start settings	Easy Start On	1	Yes	-	-

Easy Start Setting Details

Code	Description					
	Follo	Follow the procedures listed below to set the Easy Start parameters.				
	No	Procedures				
	1	Set CNF-61 (Easy Start On) to "1 (Yes)".				
	2	Set CNF-40 (Parameter Init) to "1 (All Grp)" to initialize all parameters in the inverter.				
CNF-61 Easy Start On	3	Restarting the inverter will activate Easy Start. Set the values in the following screens on the keypad. To exit Easy Start, press the [ESC] key. Start Easy Set: Select "Yes". CNF-01 Language Sel: Select a language. DRV-30 kW/HP Select: select the capacity of the unit. DRV-14 Motor Capacity: Set motor capacity. BAS-11 Pole Number: Set motor pole number. BAS-15 Rated Volt: Set motor rated voltage. BAS-10 60/50 Hz Sel: Set motor rated frequency. BAS-19 AC Input Volt: Set input voltage. DRV-06 Cmd Source: Set command source. DRV-01 Cmd Frequency: Set frequency reference. When the settings are complete, the minimum parameter settings on the motor have been made. The keypad will return to a monitoring display. Now the motor can be operated with the command source set at DRV-06.				

8.33 Config (CNF) Mode

The config mode parameters are used to configure keypad-related features.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
	2	LCD brightness/ contrast adjustment	LCD Contrast	-		-	
	10	Inverter S/W version	Inv S/W Ver	X.XX		-	
	11	Keypad S/W version	Keypad S/W Ver	X.XX		-	-
	12	Keypad title version	KPD Title Ver	X.XX		-	-
	30–32	Power slot type	Option-x Type	Non	е	-	-
	41	Display changed parameters	Changed Para	0	View All	0–1	-
CNF*	44	Erase trip history	Erase All Trip	No		-	-
	60	Add title update	Add Title Up	No		-	-
	62	Initialize accumulated electrical energy	WH Count Reset	No		-	-
	74	Accumulated cooling fan operation time	Fan Time	0000	DDAY 00:00		
	75	Accumulated cooling fan operation time initialization	Fan Time Rst	0	No		

Config Mode Parameter Setting Details

Code	Description
CNF-2 LCD Contrast	Adjusts LCD brightness/contrast on the keypad.
CNF-10 Inv S/W Ver, CNF-11 Keypad S/W Ver	Checks the OS version in the inverter and on the keypad.
CNF-12 KPD Title Ver	Checks the title version on the keypad.
CNF-30–32 Option-x Type	Checks the type of option board installed in the option slot.
CNF-41 Changed Para	Displays all the parameters that are different from the factory defaults.
CNF-44 Erase All Trip	Deletes the stored trip history.
CNF-60 Add Title UP	When the inverter SW version is updated and more code is added, CNF-60 settings will add, display, and operate the added codes. Set CNF-60 to "1 (Yes)" and disconnect the keypad from the inverter. Reconnecting the keypad to the inverter updates titles.
CNF-62 WH Count Reset	Initialize the accumulated electrical energy consumption count.

Code	Description
CNF-74 Fan Time	Displays the accumulated cooling fan operation time.
CNF-75 Fan Time Rst	Initialize the accumulated cooling fan operation time at CNF-74.

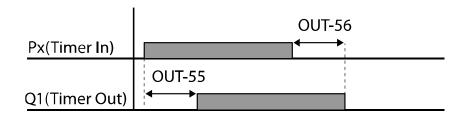
8.34 Timer Settings

Set a multi-function input terminal to a timer and set the On/Off controls to the multi-function outputs and relays according to the timer settings.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
IN	65– 75	Px terminal configuration	Px Define (Px: P1– P8 [optional: P9– P11])	38 Timer In		-	-
	31	Multi-function relay 1	Relay 1	28	Timer Out	-	sec
OUT	33	Multi-function output 1	Q1 Define	20	Timer Out		
001	55	Timer on delay	TimerOn Delay	0.00		0.00-100.00	sec
	56	Timer off delay	TimerOff Delay	0.00)	0.00-100.00	sec

Timer Setting Details

Code	Description
IN-65–75 Px Define	Selects one of the multi-function input terminals and change it to a timer terminal by setting it to "38 (Timer In)".
OUT-31 Relay 1, OUT-36 Q1 Define	Sets the multi-function output terminal or relay to be used as a timer to "28 (Timer out)".
OUT-55 TimerOn Delay, OUT-56 TimerOff Delay	Inputs a signal (On) to the timer terminal to operate a timer output (Timer out) after the time set at OUT-55 has passed. When the multi-function input terminal is off, the multi-function output or relay turns off after the time set at OUT-56.



8.35 Traverse Operation

The traverse operation is used to periodically change the motor rotation. In its application as a winder, the traverse operation ensures that the thread or wire is evenly wound on a spindle without tangles.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
-	01	Applied function selection	App Mode	1	Traverse	0–4	-
	08	Traverse operating range	Trv Amplit %	-	0.0	0–20	%
	09	Traverse scramble magnitude	Trv Scramb %	-	0.0	0–50	%
	10	Traverse acceleration time	Trv Acc Time	-	2.0	0.1–600.0	Sec
	11	Traverse deceleration time	Trv Dec Time	-	3.0	0.1–600.0	Sec
	12	Traverse offset upper limit	Trv Offset Hi	-	0.0	0–20.0	%
	13	Traverse offset lower limit	Trv Offset Lo	-	0.0	0–20.0	%
IN	65–75	Px terminal configuration	Px Define (Px: P1–P8 [optional: P9–P11])	27	Trv Offset Lo	-	-
				28	Trv Offset Hi	-	-

Traverse Operation Details

Code	Description				
APP-01 APP Mode	Set APP-01 to "1 (Traverse)". Parameters for the traverse operation become visible. Setting Function mode O None 1 Traverse 2 Proc PID 3 Reserved 4 Auto Sequence				
APP-08 Trv Amplit %	Sets the operation frequency for the scramble operation as a percentage of the inverter's frequency reference.				
APP-09 Trv Scramb %	Sets the scramble frequency (frequency jump volume at the beginning of a deceleration) for traverse operation as a percentage of the traverse operation frequency.				

Code	Description
APP-10 Trv Acc Time, APP-11 Trv Dec Time	Sets the acceleration and deceleration time for the traverse operation.
APP-12 Trv Offset Hi	Sets the high offset amount for the traverse operation as a percentage of the inverter's frequency reference. After setting one of the multi-function terminals to "28 (Trv Offset Hi)", the offset value is added to the traverse operation frequency when the terminal input is on.
APP-13 Trv Offset Lo	Sets the low offset amount for traverse operation as a percentage of the inverter's frequency reference. After setting one of the multi-function terminals to "27 (Trv Offset Lo)", the offset value is deducted from the traverse operation frequency when the terminal input is on.

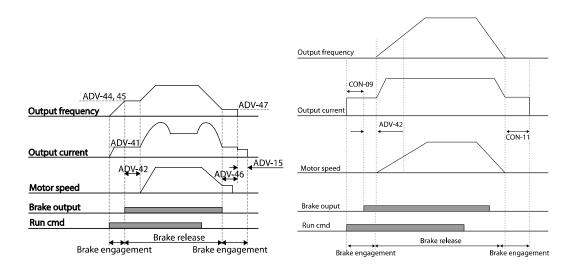
8.36 Brake Control

Brake control is used to control the On/Off operation of the electronic brake load system. Check the inverter's control mode set at DRV-09 before configuring the brake control sequence as the operation sequence varies by the control mode.

Group	Code	Name	LCD Display	Parameter	Setting	Setting Range	Unit
				0	V/F		
				1	V/F PG		
DRV	09	Control mode	Control Mode	2	Slip Compen	_	_
DIXV	03	Control mode	Control Mode	3	Sensorless-1	_	
				4	Sensorless-2		
				5	Vector		
	41	Brake release current	BR Rls Curr	50.0		0.0–180.0%	%
	42	Brake release delay time	BR RIs Dly	1.00		0–10.00	sec
	44	Brake release forward frequency	BR Rls Fwd Fr	1.00		0–400	Hz
ADV	45	Brake release reverse frequency	BR RIs Rev Fr	1.00		0–400	Hz
	46	Brake engage delay time BR Eng Dly 1.00		0–10	sec		
	47	Brake engage frequency	BR Eng Fr	2.00		0–400	Hz
OUT	31– 32	Multi-function relay1– 2	Relay 1–2	35	BR Control:		
001	33	Multi-function output1 item	Q1 Define	33	DIX COITUOI.	-	

Brake Control Details

Code	Description
	When the brake control is activated, DC braking (ADV-12) at inverter start and dwell operation (ADV-20–23) do not operate.
	Brake Operation Sequence in Control Modes Other than "Vector"
ADV-12 Dc-Start Time	<brake release="" sequence=""></brake> During the motor stop state, if an operation command is entered, the inverter accelerates up to the brake release frequency (ADV-44–45) in a forward or reverse direction. After reaching the brake release frequency, if the motor current reaches the brake release current (BR RIs Curr), the output relay or multifunction output terminal for brake control sends a release signal. Once the signal has been sent, acceleration will begin after maintaining the frequency for the brake release delay time (ADV-42 BR RIs Dly).
ADV-15 Dc Brake Time ADV-16 Dc Brake Level ADV-20 Acc Dwell Freq, ADV-21 Acc Dwell Time, ADV-22 Dec Dwell Freq,	Strake engage sequence> If a stop command is sent during operation, the motor decelerates. Once the output frequency reaches the brake engage frequency (ADV-47 BR Eng Fr), the motor stops decelerating and sends out a brake engage signal to a preset output terminal. The frequency is maintained for the brake engage delay time (ADV-47 BR
ADV-23 Dec Dwell Time ADV-42 BR RIs Dly ADV-44 BR RIs Fwd Fr	Eng Dly) and it becomes "0" afterwards. If the DC braking time (ADV-15) and DC braking resistance (ADV-16) are set, the inverter output is blocked after DC braking. For more details on DC braking, refer to <u>7.17.2 Stop after DC Braking</u> on page <u>184</u> .
ADV-45 BR RIs Rev Fr ADV-46 BR Eng Dly ADV-47 BR Eng Dly	Brake Operation Sequence in "Vector" control Mode
in English	<brake release="" sequence=""></brake> When an operational command is entered, the output relay or multifunction output terminal for brake control sends a brake release signal after the pre-excitation time is passed. Once the signal has been sent, acceleration will begin after the brake release delay time (ADV-42 BR RIs Dly) has passed.
	<brake engage="" sequence=""></brake> If a stop command is sent during operation, the inverter decelerates to "0 Hz" and sends out a brake engage signal. Then, the output is cut off after the brake engage delay time (ADV-46 BR Eng Dly) has passed. The brake engage sequence does not operate in torque control mode.



8.37 Multi-function Output On/Off Control

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
ADV 67 68	66	Output contact On/Off control options	On/Off Ctrl Src	1	V1	0–4	-
	67	Output contact point On level	On-C Level	-	90.00	10–100	%
	68	Output contact point Off level	Off-C Level	-	10.00	0–Output contact on level	%
OUT	31– 33	Multi-function relay, Multi-function output 1	Relay x or Q1	34	On/Off Control	-	-

Multi-function Output On/Off Control Details

Code	Description
ADV-66 On/Off Ctrl Src ADV-67 On-C Level ADV-68 Off-C Level	If the analog input value exceeds the set value, the output relay or multi- function output terminal can be turned on or off. Select the analog input to use for On/Off control at ADV-66 and set the levels at which the output terminal is on and off at ADV-67 and 68 respectively.
	If the analog input value exceeds the value set at ADV-67, the output terminal is on. If the analog input is below the value set at ADV-68, the output terminal is off.

8.38 MMC function

The MMC (Multiple Motor Control) function is used to control multiple motors of a pump system. The main motor connected with the inverter output is controlled by the PID controller. The auxiliary motors are connected with the supply power and turned on and off by the relay within the inverter.

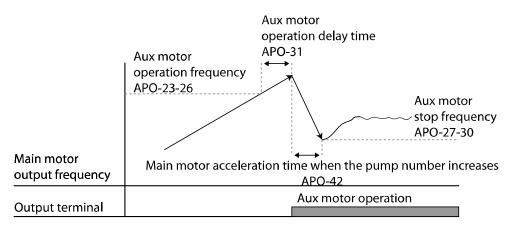
The relay for controlling auxiliary motors uses Relay 1 and 2 in the standard I/O module embedded in the inverter and multi-function output terminal Q1. If the I/O expansion option module is connected to the inverter option slot, up to 3 relay outputs can be used.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
APP	01	Application mode	App Mode	3	MMC	-	-
	20	Aux motor rotation number	Aux Motor Run	-	0	0–4	-
	21	Starting aux motor selection	Starting Aux	-	1	1–4	-
	22	Auto operation time	Auto Op Time	-	0:00	xx:xx	Min
	23	1st aux motor starting frequency	Start Freq 1	-	49.99	0–60	Hz
	24	2nd aux motor starting frequency	Start Freq 2	-	49.99	0–60	Hz
	25	3rd aux motor starting frequency	Start Freq 3	-	49.99	0–60	Hz
APO	26	4th aux motor starting frequency	Start Freq 4	-	49.99	0–60	Hz
	27	1st aux motor stop frequency	Stop Freq 1	-	15.00	0–60	Hz
	28	2nd aux motor stop frequency	Stop Freq 2	-	15.00	0–60	Hz
	29	3rd aux motor stop frequency	Stop Freq 3	-	15.00	0–60	Hz
	30	3th aux motor stop frequency	Stop Freq 4	-	15.00	0–60	Hz
	31	Aux motor starting delay time	Aux Start DT	-	60.0	0–3600.0	Sec
	32	Aux motor stop delay time	Aux Stop DT	-	60.0	0–3600.0	Sec
	33	Aux motor number selection	Num of Aux	_	4	0–4	-
APO	34	Bypass selection	Regul Bypass	0	No	0–1	_
	35	Auto change mode	Auto Ch Mode	0	Aux	None/Aux/Main	-

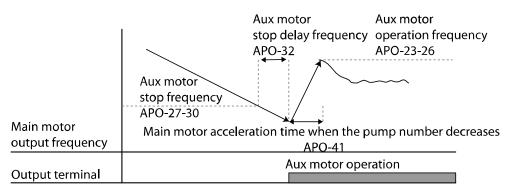
Group	Code	Name	LCD Display	Param	eter Setting	Setting Range	Unit
		selection					
	36	Auto change time	Auto Ch Time	-	72:00	0–99:00	Min
	38	Interlock selection	Interlock	0	No	0–1	-
	39	Interlock movement delay time	Interlock DT	-	5.0	0.1–360.0	Sec
	40	Aux motor rotation pressure difference	Actual Pr Diff	-	2	0–100%	%
	41	Main motor acceleration time when the number of pumps decreases	Aux Acc Time	-	2.0	0.0–600.0	Sec
	42	Main motor deceleration time when the number of pumps increases	Aux Dec Time	-	2.0	0.0–600.0	Sec
OUT	31– 33	Multi-function relay, Multi-function output 1	Relay x or Q1	24	ММС	-	-
_	34– 36	Qx terminal configuration	Qx Define	24	ММС	-	-

8.38.1 Basic MMC Operation

Code	Description		
APP-01 APP Mode	If "3 (MMC)" is selected for the applied function, the items related to the MMC function are displayed in the option module function group (APO) and the functions related to the PID controller are displayed in APP.		
APO-20, 21, 33	If the number of auxiliary motors is set at APO-33 and there is more than one auxiliary motor, the auxiliary motor number for the first operation should be APO-21. For example, if there are three auxiliary motors and each of them is controlled by Relay 1 and 2 and the Q1 terminal, the auxiliary motors operate in the sequence of Relay 2, Q1, and then Relay 1 when"2" is input at APO-21. The auxiliary motors stop in the sequence of Relay 1, Q1, and Relay 2. At APO-20, the number of currently operating auxiliary motors can be monitored.		
APO-23–26 Start Freq 1–4	Sets the starting frequency for auxiliary motors. Since the main motor is operated by the PID controller, its operating frequency is increased by the load change and the operation for an auxiliary motor becomes necessary. The conditions of the inverter output terminal I (Relay or multi-function output [Qx]) that turns on for auxiliary motor operation is as follows. The auxiliary motor can operate when The speed of the main motor exceeds the starting frequency (APO-23–26) of the auxiliary motor. The starting delay time (APO-13) of the auxiliary motor passes. The difference between the reference and the feedback of the main motor PID controller becomes smaller than the pressure difference (APO-40) of the auxiliary motor motion.		
APO-27–30 Stop Freq 1–4	Sets the stop frequency for auxiliary motors. If the operating frequency for the main motor decreases below a certain frequency while the auxiliary motor is running, the auxiliary motor should be stopped. The condition of the auxiliary motor to be stopped is as follows. The auxiliary motor can be stopped when The speed of the main motor decreases below the stop frequency (APO-27–30) for the auxiliary motor. The stop delay time (APO-32) for the auxiliary motor passes. The difference between the reference and the feedback of the main motor PID controller becomes larger than the pressure difference (APO-40) of the auxiliary motor operation.		
APO-41 Aux Acc Time, APO-42 Aux Dec Time	The main motor stops PID control and operates the normal acceleration and deceleration when the auxiliary motor runs or stops. When the auxiliary motor runs, the main motor decelerates to the decelerating frequency of the auxiliary motor for the decelerating time set at APO-42. Inversely, when the auxiliary motor stops, the main motor accelerates to the starting frequency for the accelerating time set at APO-41.		



Auxiliary motor operation sequence by increased load



Auxiliary motor stop sequence by decreased load

8.38.2 Auto Change Operation

The auto change function enables the inverter to automatically switch operations between main and auxiliary motors. Prolonged continuous operation of a motor reduces motor performance. The auto change function switches the motors automatically when certain conditions are met to avoid biased use of certain motors and protect them from deterioration.

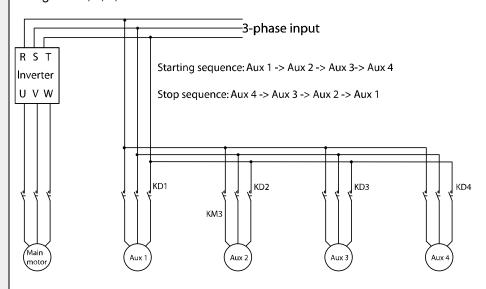
Code	Description
	Selects the motors to apply the auto change function. 0: None
APO-35 Auto Ch Mode	The operation sequence of the auxiliary motor starts with the auxiliary motor selected at APO-21(starting auxiliary motor selection) and the automatic change function is not active.

Code Description

1: Aux

The operation sequence of the auxiliary motor starts with the auxiliary motor selected in APO-21(starting auxiliary motor selection). When the cumulative operating time for a main and auxiliary motor exceeds the auto change time (APO-36), the auto change condition is met. If the main motor is stopped by a stop command or the sleep operation mode after the auto change condition, the start sequence of the auxiliary motor selected at APO-21 is changed.

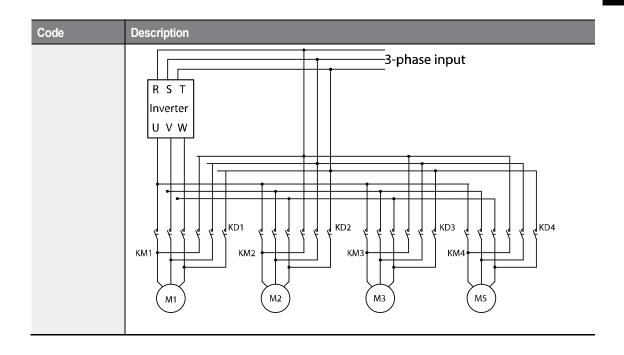
For example, if there are four auxiliary motors operating and motor 4 is selected in APO-21, the start sequence of the auxiliary motor automatically changes to motor 1. Therefore, the previous start sequence of the auxiliary motor of 4, 1, 2, and 3 changes to 1, 2, 3, and 4, and if the auto change condition is met, the sequence is changed to 2, 3, 4, and 1.



2: Main

Auto change is available without distinction between the main and auxiliary motors. The auto change condition is met if the cumulative operating time for the motor connected to the inverter output exceeds the auto change time (APO-36).

If the inverter is stopped by a stop command or sleep operation mode, the operating sequence of the motor automatically changes. For example, if the starting auxiliary motor selection (APO-21) is set at "2", the inverter output is connected to motor 2. If there are four motors and the auxiliary motor operating condition is met, motors 3, 4, and 1 start operating one after another in sequence. If the inverter stops in the auto change condition, motor 3 is connected to the inverter output in the next restart and the auxiliary motors operate in the sequence of 4, 1, and 2.



8.38.3 Interlock Operation

When there is motor trouble, the interlock feature is used to stop the affected motor and replace it with another that is not currently operating (i.e. in the off state). To activate the interlock feature, connect the cables to send abnormal motor signals to the inverter input terminal and configure the terminals as interlock 1-4 inputs. Then, the inverter decides the motor's availability based on the signal inputs. The order in which the alternative motor is selected is decided based on the auto change mode selection options set at APO-35.

Code	Description
	The terminal to use as the interlock among IN 65–72 (up to 75 if there is an I/O expansion module) is selected and Interlock 1–4 are set depending on the motor sequence.
IN-65–75 Px Define	If the auto change mode selection (APO-35) is set to "0 (None)" or "1 (Aux)" and if auxiliary motors 1, 2, and 3 are connected to inverter output terminals Relay 1, 2, and Q1 when a total of four motors including the main motor is operating, the interlock numbers 1, 2, and 3 correspond to the motor connected to Relay 1, 2, and Q1.
	However, if the auto change mode selection (APO-35) is set to "2 (Main)" and the main and auxiliary motors are connected to inverter output terminals Relay1, 2, Q1, and Q2 (I/O expansion module used) respectively, Interlock 1, 2, 3 and 4 correspond to the motors connected

Code	Description
	to Relay 1, 2, Q1 and Q2.
	Select "1 (Yes)" to enable an interlock operation.
	1) If there are five motors and the auto change mode selection (APO-35) is set to 0 (None) or 1 (Aux), the operation is as follows:
	If signals are sent to the terminal block set at Interlock 3 with a fault at motor 3 when it is static, the auxiliary motors operate in the sequence of 1, 2, and 4 (when the starting auxiliary motor selection APO-21 is "1"). If the terminal block signals are released, the operation sequence is 1, 2, 3, and 4.
APO-38 Interlock	If signals are sent to the terminal for Interlock 3, auxiliary motor 3 stops and auxiliary motor 4 operates. If the interlock signal is released, auxiliary motor 4 stops and auxiliary motor 3 operates again.
AI 0-30 III.e.iiock	2) If there are four motors and the auto change mode selection (APO-35) is set to "2 (Main)", the operation is as follows:
	If the starting auxiliary motor selection APO-21 is set to "1", motor 1 is operated by the inverter and the remaining motors (2, 3, and 4) are operated by the auxiliary motors and interlock signals are sent to the auxiliary motors, the operation sequence is the same as the procedure described in condition 1) above.
	However, if there is a problem with motor 1, which is connected to the inverter, the output is immediately blocked and motor 2 becomes connected to the inverter output and the operation sequence of the auxiliary motor is 3 and 4. If the interlock signal of motor 1 is released, the operation sequence of the auxiliary motor is 3, 4, and 1.

8.38.4 Bypass Operation (Regular Bypass)

This function controls the motor speed based on the feedback amount instead of using the PID controller. Auxiliary motors may be controlled with this feature based on the feedback amount.

Code	Description
APP-34 Regular Bypass	Select "1 (Yes)" to enable regular bypass. If there are four main motors and auxiliary motors (APP-33) in total, the operation is as follows. If the feedback input value is between 0–10 V and the operating frequency of the maximum input value (10 V) is 60 Hz, auxiliary motor 1 starts operation when the feedback amount is 2.5 V (15 Hz of main motor operating frequency). If the feedback amount reaches 5 V again, auxiliary motor 2 operates. At the maximum input of 10 V, all three auxiliary motors operate. Operation level of auxiliary motor $n = n * \frac{Maximum feedback amount}{The number of auxiliary motor(APO – 33)}$

8.39 Press Regeneration Prevention (To evade control operation in the status of regeneration during press)

Press regeneration prevention is used during press operations to prevent braking during the regeneration process. If motor regeneration occurs during a press operation, the motor operation speed automatically goes up to avoid the regeneration zone.

Group	Code	Name	LCD Display	Param	eter Setting	Setting Range	Unit
	73	Regeneration evasion mode	RegenAvd Mode	000-1	11	001	Bit
	74	Regeneration evasion function for press selection	RegenAvd Sel	0	No	0–1	-
	75	Press regeneration		350		200 V class: 300– 400	
		prevention operation voltage level	eration voltage	700		400 V class: 600– 800	V
ADV	76	Press regeneration prevention compensation frequency limit	CompFreq Limit	1.00		0–10.00	Hz
	77	Press regeneration prevention P-Gain	RegenAvd Pgain	50.0		0–100.0	%
	78 Press regenerat prevention		RegenAvd Igain	500		20–30,000	ms

Press Regeneration Prevention Details

Code	Description
ADV-73 RegenAvd Mode	Set the motor operation mode to decide when the regeneration evasion function is activated.
ADV-74 RegenAvd Sel (select regeneration evasion function for press)	Frequent regeneration voltage from a press load during a constant speed motor operation may put excessive stress on the braking unit, which may damage or shorten brake life. To prevent this, select ADV-74 (RegenAvd Sel) to control DC link voltage and disable the braking unit operation.
ADV-75 RegenAvd Level (set regeneration evasion level for press)	Set brake operation prevention level voltage when the DC link voltage goes up due to regeneration.

Code	Description
ADV-76 CompFreq Limit (limit regeneration evasion compensation frequency for press)	Set an alternative frequency width that can replace the actual operation frequency during regeneration prevention.
ADV-77 RegenAvd P gain	Set a P gain for regeneration evasion compensation function. To avoid the regeneration zone, set P-Gain in the DC link voltage suppress PI controller.
ADV-78 RegenAvd I gain	Set an I gain for regeneration evasion compensation function. To avoid the regeneration zone, set I gain in the DC link voltage suppress PI controller.

① Caution

Press regeneration prevention does not operate during acceleration or deceleration; it only operates during constant speed motor operation. When regeneration prevention is activated, the output frequency may change within the range set at ADV-76 (CompFreq Limit).

8.40 Anti-Hunting Regulator

Group	Cod e	Name	LCD Display	Parame	ter Setting	Setting Range	Unit
CON	90	Function selection for preventing current hunting	New AHR Sel.	1	Yes	-	-
	91	Gain from current hunting prevention	AHR P-Gain	1000		0–32767	-

This function is used to prevent the hunting of a V/F controlled fan or motor caused by current distortion or oscillation due to mechanical resonance or other reasons. You can set the hunting prevention function (CON-90) to prevent current hunting.

CON-91 AHR P-Gain: Increasing AHR proportional gain improves the responsiveness of the antihunting regulation. However, current oscillation may result if AHR proportional gain is set too high.

8.41 Fire Mode

This function is used to allow the inverter to ignore minor faults during emergency situations, such as fire, and provides continuous operation to protect other systems, such as ventilation fans. When fire mode is activated, the inverter operates continuously based on the set frequency and direction.

Group	Code	Name	LCD Display	Parameter Setting		Setting range	Unit
				0	None		-
	80	Fire mode selection	Fire Mode Sel	1	Fire Mode	0–2	
				2	Fire Test		
	81	Fire mode frequency	Fire Mode Freq	60.0	0		Hz
ADV	Fire mode operating		0	Forward		-	
		operating direction	Fire Mode Dir			0–1	_
				1	Reverse		
	83	Fire mode counter	Fire Mode Cnt	0		-	-
IN	65– 75	Px terminal configuration	Px Define	51		-	-
OUT	31– 33	Relay1,2 and Q1	Relay1,2 / Q1	37		-	_

Fire Mode Details

Code	Description		
ADV-80 Fire Mode Sel	When you select function 1-Fire Mode, ADV-81–83 is displayed. In the above settings, if "51 (Fire Mode)" in IN-65–75 is on, fire mode operates. During the fire mode operation status, a "fire mode" warning occurs. During fire mode operation, the inverter's frequency and operation direction is performed in the value set for fire mode with the previously set control mode.		
ADV-81 Fire Mode Freq	Set the operation frequency for fire mode.		
ADV-82 Fire Mode Dir	Set the run direction for fire mode operation.		
ADV-80 Fire Mode Sel	If the mode is set to "2-Fire Test", related items for the fire function (ADV-81–83) are displayed. In the above settings, if "51 (Fire Mode)" in IN-65–75 is on, fire mode operates. The basic operation is the same as fire mode. However,		

Code	Description
	ADV-83 is not counted in fire test mode. Also, all fault trips occur without ignoring them.

If a fault occurs during fire mode operation, the fault trip is ignored and the inverter continuously operates. However, if a critical fault occurs, the inverter performs the trip operation or auto restart operation. The auto restart is performed after PRT-10 Retry Delay is set.

If the inverter performs the fire mode operation when the inverter is in normal status after the auto restart, the inverter will operate via the speed search.

Fire mode cannot be set while in torque mode. Therefore, fire mode can only be set when the inverter is in speed or operation mode.

In fire mode, the operation for fault trips is listed in the following table.

Operation in the event of fault trips	Fault trips		
Fault trips that are ignored	Low Voltage, Over Load, Under Load, Inverter OLT, E-Thermal, Out Phase Open, In Phase Open, Over Speed, Speed Dev Trip, NTC Open, Over Heat, Fuse Open, Thermal Trip, Fan Trip, BX, Lost Command, Lost Keypad, Low Voltage2, etc.		
Auto restart after fault trips	Ground Trip, Over Current1, Over Voltage		
Trip operation	H/W-Diag, Over Current2, Safety Opt Err		

① Caution

Fire mode operation voids the product warranty. To test fire mode not to increase the fire mode operation count at ADV-83, set ADV-80 to "2-Fire Test" and operate the inverter.

If the multi-function terminal input set to "51 (Fire Mode)" is on when ADV-83 is set to "1 (Fire Mode)", the count value set at ADV-83 is increased by 1.

8.42 Dynamic Braking (DB) Resistor Operation Reference **Voltage**

Depending on the capacity, the iS7 series is divided into models with a braking resistor circuit integrated inside the inverter, and models that require an external braking unit to be installed. The inverters rated between 0.75–22 kW have the built-in braking model (except for the braking resistor), and the inverters rated above 30 kW require an external braking unit. Therefore, the reference voltage setting function for the braking resistor is necessary for inverters rated below 22 kW.

Group	Code	Name	LCD Display	Parameter Setting	Setting Range	Unit
ADV	DB unit OV 79 operating		DB Turn On Lev	390 V	200 V Type: 350–400 V	V
		voltage		780 V	400 V Type: 600–800 V	

ADV-79 DB Turn On Lev: This is the operation reference voltage for the braking resistor. The braking resistor operates when the DC link voltage exceeds the reference value.

The initial value for 200 V-type inverters is 390 V, and the initial value for 400 V-type inverters is 780 V.

For 200 V-type inverters, the reference voltage that stops the braking resistor is 10 V lower than the operating voltage set at ADV-79. For 400 V-type inverters, the braking resistor stops if the voltage is 20 V lower than the operating voltage set at ADV-79.

① Caution

If the set value for ADV-79 is lower than the DC link voltage when the inverter is in normal operation, the DB resistor may overheat due to continuous DB resistor operation.

Conversely, if the set value at ADV-79 is much higher than the DC link voltage range, an overvoltage trip may occur because the DB resistor does not operate when it is needed.

Example) If the input voltage is 440 V and the value at ADV-79 is set to 600 V, the DB resistor operates when the inverter is on because the DC link voltage is 622 V. Since the voltage level that stops the DB resistor is 590 V, the DB resistor may overheat due to continuous DB resistor operation.

8.43 kW/HP Unit Selection

Select the units between kW and HP for the capacity of the inverter and motor.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Unit
DRV	DRV 30 kW/HP unit selection	KW/HP Select	0	kW	0-1	_	
		TOWN III Gelect	1	HP			

8.44 Output Voltage Drop Prevention

This function is used to prevent voltage drop in the inverter output by decreasing the current output, thereby taking advantage of the expanded command zone of the output voltage, if the input voltage drops or overload conditions arise.

Group	Code	Name	LCD Display	Parameter Setting		Setting Range	Initial
ADV	ADV 87 OVM Moselection	OVM Mode	OVM Mode Sel	0	No	0-1	0:No
		selection		1	Yes		

This function is used to prevent voltage drop in the inverter output by decreasing the current output, thereby taking advantage of the expanded command zone of the output voltage, if the input voltage drops or overload conditions arise. Set ADV-87 (OVM Mode Sel) to "O (No)" to limit the voltage output command zone for linear voltage output. Set ADV-87 (OVM Mode Sel) to "1 (Yes)" to expand the voltage output command zone and ensure stable voltage output is made throughout the overmodulated zone.

Caution



- When you enable the OVM Mode, the output wave may be distorted because it will not be maintained in a linear form.
- Also, a higher voltage than the motor's rated voltage may be output to the motor if the input voltage is higher than the motor's rated voltage.
- Although the current may appear to be rapidly oscillating during high-speed operation, the actual change in the output current is not severe.
- The output voltage will be compensated for to stay below the rated voltage of the motor according to the parameter setting.
- > The OVM Mode will not be activated if the input voltage is higher than the output voltage.

9 Using Monitor Functions

Monitoring the Operating Status via the Keypad 9.1

You can monitor the operating status using the keypad of the inverter. You can select the desired items to monitor in Config mode (CNF), view three items at a time in Monitor mode, and select an item on the status display.

9.1.1 **Selecting Monitor Mode Display**

Mode	Group	Code	LCD Display	Parameter Setting		Unit
	-	21	Monitor Line-1	0	Frequency	Hz
CNF	-	22	Monitor Line-2	2	Output Current	A
CINE	-	23	Monitor Line-3	3	Output Voltage	V
		24	Mon Mode Init	0	No	-

Monitor Mode Display Selection Details

Code	Des	Description					
	Select the items to monitor in Monitor mode. Monitor mode is displayed when the inverter is powered on. Also, all three items in Monitor Line-1–3 can be displayed simultaneously. Select an item for the line to display. If "Yes" is set at CNF-24 (M Mode Init), CNF-21–23 will be initialized.						
	Set	tting	Function				
	0	Frequency	Displays the set frequency while stopped. During operation, it displays the actual output frequency (Hz).				
	1	Speed	Displays the set speed (rpm) while stopped. During operation, it displays the actual operating speed (rpm).				
CNF-21-23	2	Output Current	Displays the output current.				
Monitor Line-x	3	Output Voltage	Displays the output voltage.				
	4	Output Power	Displays the output power.				
	5	WHour Counter	Displays the inverter's power consumption.				
	6	DCLink Voltage	Displays the inverter's DC link voltage.				
	7	DI Status	Displays the input terminal status of the terminal block. Starting from the right, it displays P1–P8.				
	8	DO Status	Displays the output terminal status of the terminal block.				

Code	Desc	cription	
			Starting from the right, it displays Relay1, Relay2, and Q1.
	9	V1 Monitor[V]	Displays the input voltage value at terminal V1 (V).
	10	V1 Monitor[%]	Displays the input voltage terminal V1 value as a percentage. If -10V, 0V, and+10V is measured, -100%, 0%, and 100% will be displayed.
	11	I1 Monitor[mA]	Displays the magnitude of the current being input to the I1 terminal of the inverter terminal block.
	12	I1 Monitor[%]	Displays the above current as a percent. If the input current is 0–20[mA], it is shown as 0–100%.
	13	V2 Monitor[V]	Displays the voltage input of the I/O expansion module's V2 terminal when using the I/O expansion module.
	14	V2 Monitor[%]	Displays the V2 input voltage as a percent.
	15	I2 Monitor[mA]	Displays the current input for the I/O expansion module's I2 terminal when using the I/O expansion module.
	16	I2 Monitor[%]	Displays the I2 input current terminal value as a percentage.
	17	PID Output	Displays the PID controller's output.
	18	PID Ref Value	Displays the PID controller's reference value.
	19	PID Fdb Value	Displays the PID controller's feedback volume.
	20	Torque	Displays the torque reference value if torque reference command mode (DRV-08) is set to a value other than "Keypad" (0 or 1).
	21	Torque Limit	Displays the torque limit value if the torque limit setting method (CON-53) is set to a value other than "Keypad" (0 or 1).
	22	Trq Bias Ref	Displays the torque bias if the torque bias setting method (CON-58) is set to a value other than "Keypad" (0 or 1).
	23	Spd Limit	Displays the speed limit setting If the speed limiting (CON-62) in Torque Control mode is set to a value other than "Keypad" (0 or 1).
	24	Load Speed	Displays the load speed in the desired scale and unit. Displays the load speed as values which are applied in the units of rpm or mpm set in ADV-63 (Load Spd Unit), ADV-61 (Load Spd Gain), and ADV-62 (Load Spd Scale).
	25	Temperature	Displays the inverter's internal temperature.

Displaying Output Power 9.1.2

Mode	Group	Code	LCD Display	Parameter Setting		Unit
PAR	BAS	18	Trim Power %	-	100.0	%

When CNF-21-23 (Monitor Line-x Select) is set to "4 (Output Power)", increase the set value at BAS-18 (Trim Power) appropriately if the output power displayed on the keypad is lower than expected.

If the output power displayed on the keypad is higher than expected, decrease this set value accordingly. The output power display is calculated using voltage and current. However, an output power error may occur when the power factor is low.

Note

WHour Counter (Inverter power consumption)

Values are calculated using voltage and current. Electric power is calculated every second and the results are accumulated.

Power consumption is displayed as follows:

- Less than 1,000 kW: Units are in kW, displayed in a 999.9 kW format.
- 1-99 MW: Units are in MW, displayed in a 99.99 MWh format.
- 100-999 MW: Units are in MW, displayed in a 999.9 MWh format.
- More than 1,000 MW: Units are in MW, displayed in 9,999 MWh format and can be displayed up to 65,535 MW. (Values exceeding 65,535 MW will reset the value to 0 and units will return to kW. It will be displayed in a 999.9 kW format).
- If the WH CNF-62 (Count Reset) is set to "YES," you can clear the electricity consumption.

9.1.3 Selecting Load Speed Display

Mode	Group	Code	LCD Display	Parameter Setting		Unit
		61	Load Spd Gain	1	100.0	%
PAR	PAR ADV	62	Load Spd Scale	0	X 1	-
		63	Load Spd Unit	0	rpm	-

Load Speed Display Details

Set CNF-21–23 (Monitor Line-x Select) to "24 (Load Speed)", and adjust the following codes to display load speed.

Code	Description
ADV-61 Load Spd Gain	Sets the gear ratio in a percentage for speed conversion. When the ratio is set, the actual number of rotations of the other axis or gear system that is connected to the motor is displayed accordingly. For example, set ADV-61 (Load Spd Gain) to 30.0%, if the flux value is 300 [mpm] at 1000 [rpm].
ADV-62 Load Spd Scale	Selects to what decimal place to display at "24 (Load Speed)" among the monitor items (x1-x0.0001). If you want to display the value to one decimal place, set ADV-63 (Load Spd Scale) to X 0.1.
ADV-63 Load Spd Unit	Selects the unit of "24 (Load Speed)" from the monitor items. Also, select either RPM (Revolutions Per Minute) or MPM (Meters Per Minute).

9.1.4 Selecting Hz/Rpm Display

You can convert all the parameters with a Hz unit into RPM or vice versa. The pole number (BAS-11) must be entered for the conversion.

Mode	Group	Code	LCD Display	Parameter Setting		Unit
DAD	DRV	21	Hz/Rpm Sel	0	Hz	-
PAR	BAS	11	Pole Number	-	4	-

⚠ Warning

If you change the default set value at DRV-21 (Hz/RPM Sel) from "Hz" to "RPM", all parameters except the ones set for the monitor mode will be changed to RPM. To change the speed unit from frequency to speed in Monitor mode, change the parameter value at CNF-21.

Selecting Status Display 9.1.5

Mode	Code	LCD Display Parameter Setting		ter Setting	Unit
CNF	20	AnyTime Para	0	Frequency	-

Status Display Selection Details

Code	Description						
	Select the variables to be displayed at the top of Keypad display (LCD display).						
	Setting	Function	Setting	Function			
	0	Frequency	13	V2 Monitor[V]			
	1	Speed	14	V2 Monitor[%]			
	2	Output Current	15	I2 Monitor[mA]			
	3	Output Voltage	16	I2 Monitor[%]			
0115 00 4 5	4	Output Power	17	PID Output			
CNF-20 AnyTime Para	5	WHour Counter	18	PID Ref Value			
i aia	6	DCLink Voltage	19	PID Fdb Value			
	7	-	20	Torque			
	8	-	21	Torque Limit			
	9	V1 Monitor[V]	22	Trq Bias Ref			
	10	V1 Monitor[%]	23	Speed Limit			
	11	I1 Monitor[mA]	24	Load Speed			
	12	I1 Monitor[%]					

Monitoring Output Frequency

Select DRV-25 to monitor output frequency. Output frequency is displayed in 0.01[Hz] increments. The output frequency is displayed as 0.00[Hz] when the inverter is not operating.

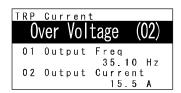
Group	Code	LCD Display	Parameter Setting		Unit
DRV	25	Output Freq	-	0.00	Hz

9.2 Monitoring Fault Status Using Keypad

Trip mode displays the fault status when a fault trip occurs during inverter operation. You can monitor the fault types, operating frequency, and output current at the time of fault trip. Up to the last 5 fault trips can be saved.

9.2.1 Monitoring Current Fault Status

When a fault trip occurs, the fault type is displayed on the keypad's display.



For more details on types and descriptions of fault trips, refer to <u>12.2 Warning Messages</u> on page <u>373</u>. The following operating status can be monitored and recorded.

Dis	splayed Information	Description
1	Output Freq	Displays the operating frequency at the time of the fault trip.
2	Output Current	Displays the output current at the time of the fault trip.
3	Inverter State	Displays acceleration, deceleration, constant speed operation, and stop state.
4	DCLink Voltage	Displays the inverter's DC power voltage.
5	Temperature	Displays the inverter's temperature.
6	Input State	Displays the input terminal's status.
7	Output State	Displays the output terminal's status.
8	Trip On Time	Displays the time from the power ON to the fault trip.
9	Trip Run Time	Displays the time from Run to the fault trip.

If you press the [STOP/RESET] key on the keypad or input the reset terminal of the terminal block to release the fault trip, the information for the currently displayed fault trip is saved as part of the fault trip history. In this case, what was saved in the Fault Trip History 1 (Last-1) is moved to the Failure History 2 (Last-2).

The number next to the fault trip name represents the number of simultaneously occurring faults. If more than one fault occurred, you can press the [PROG/ENT] key to view the other faults.

Monitoring Fault Trip History 9.2.2

The types of up to five previous fault trips can be saved and monitored. The lower the number of Last X is, the more recent the fault it represents. If more than 5 faults occur, those occurring before the last 5 are automatically deleted.

The items displayed in the fault trip history are listed in the following table.

Displa	ayed Information	Description
0	Trip Names(1)	Displays the fault types.
1	Output Freq	The operating frequency at the time of the fault occurrence.
2	Output Current	The output current at the time of the fault occurrence.
3	Inverter State	Displays acceleration, deceleration, constant speed operation, and stop state.
4	DCLink Voltage	Displays the inverter's DC power voltage.
5	Temperature	Displays the inverter's temperature.
6	Input State	Displays the input terminal's status.
7	Output State	Displays the output terminal's status.
8	Trip On Time	Displays the time from the power ON to the fault occurrence.
9	Trip Run Time	Displays the time from Run to the fault occurrence.
10	Trip Delete ?	Displays whether the currently saved fault trip history is to be deleted.

There are two ways to delete the fault trip history.

At each fault trip, To delete the individual fault trip, select "Yes" at TRP-10 (Trip Delete?). Also, to delete the entire fault trip history, select "Yes" at CNF-24 (Erase All Trip).

9.3 Analog output

9.3.1 Voltage Output (0–10 V)

Select the items to be output from AO1 (Analog Output 1) terminal of the inverter terminal block and adjust the output sizes.

Group	Code	LCD Display	Parame	ter Setting	Unit
	01	AO1 Mode	0	Frequency	-
	02	AO1 Gain	-	100.0	%
OUT	03	AO1 Bias	-	0.0	%
	04	AO1 Filter	-	5	ms
	05	AO1 Const %	-	0.0	%
	06	AO1 Monitor	-	0.0	%

Voltage Output Setting Details

Code	Description			
		ect the output t		
	Set	ting	Description	
	0	Frequency	Outputs an operation frequency as the standard. A 10 V output is supplied based on the frequency set at DRV-20 (Max Freq).	
	1	Output Current	A 10 V output is supplied from 200% of the inverter-rated current (based on CT: Constant Torque).	
	2	Output Voltage	Sets the outputs based on the inverter output voltage. A 10 V output is supplied from the voltage set at BAS-15 (Rated V). If 0 V is set at BAS-15, 200 V/400 V models output 10 V based on the actual input voltage (220 V and 440 V respectively).	
OUT-01 AO1 Mode	3	DC Link Volt	Outputs the inverter DC link voltage as the standard. Outputs 10 V when the DC link voltage is 410 VDC for 200 V models, and 820 VDC for 400 V models.	
	4	Torque	Outputs the generated torque as the standard. Outputs 10 V at 250% of the motor-rated torque.	
	5	Output Power	Monitors the output wattage. 200% of the rated output is the maximum display voltage (10 V).	
	6	ldse	Outputs the maximum voltage at 200% of the no load current.	
	7	Iqse	Outputs the maximum voltage at 250% of the rated torque current.	
			Rated torque current = $\sqrt{\text{rated current}^2 - \text{Non - load current}^2}$	

Code	Description					
	8	Target Freq	Outputs the set frequency as the standard. Outputs 10 V at the maximum frequency (DRV-20).			
	9	Ramp Freq	Outputs frequency calculated with Acc/Dec function as a standard. This may vary depending on the actual output frequency. Outputs 10 V.			
	10	Speed Fdb	Displays the speed information of the input into the encoder extension module. It produces 10 V at the maximum frequency (DRV-20).			
	11	Speed Dev	Outputs the difference between the speed reference (command) and the motor's rotation speed that inputs into the encoder extension module. It outputs 10 V at twice the rated slip frequency. It is valid only in Vector Control mode.			
	12	PID Ref Value	Outputs command value of a PID controller as the standard. Outputs approximately 6.6 V at 100%.			
	13	PID Fdb Value	Outputs feedback volume of a PID controller as the standard. Outputs approximately 6.6 V at 100%.			
	14	PID Output	Outputs the output value of a PID controller as the standard			
	15	Constant				
OUT-02 AO1 Gain, OUT-03 AO1 Bias	The depo	rate as shown $1 = \frac{Frequent}{MaxFre}$ graph below if the magnetic polynomial of the magnetic polyno	Cy × AO1Gain + AO1Bias Illustrates how the analog voltage output (AO1) changes T-02 (AO1 Gain) and OUT-3 (AO1 Bias) values. The Y-axis is age (0–10 V), and the X-axis is a % value of the output item. Eximum frequency set at DRV-20 (Max Freq) is 60 Hz and the quency is 30 Hz, then the x-axis value on the next graph is 50%. OUT- 02 AO1 Gain 100.0% (Factory Default) 80.0%			

9.3.2 Current Output (4–20 mA)

Select the items to be output from AO2 (Analog Output 2) terminal of the inverter terminal block and adjust the output sizes.

Group	Code	LCD Display	LCD Display Parameter Setting		Unit
	07	AO2 Mode	0	Frequency	-
	08	AO2 Gain	-	80.0	%
OUT	09	AO2 Bias	-	20.0	%
OUT	10	AO2 Filter	-	5	ms
	11	AO2 Const %	-	0.0	%
	12	AO2 Monitor	-	0.0	%

Current Output Setting Details

Code	Description			
	Sele Sett	ct the output t	ypes. Description	
OUT-07 AO2	0	Frequency	Outputs an operation frequency as the standard. A 10 V output	
Mode		Output	is supplied based on the frequency set at DRV-20 (Max Freq). A 10 V output is supplied from 200% of the inverter-rated	
	1	Current	current (based on CT: Constant Torque).	

Code	Desc	cription		
	2	Output Voltage	Sets the outputs based on the inverter output voltage. A 10 V output is supplied from the voltage set at BAS-15 (Rated V). If 0 V is set at BAS-15, 200 V/400 V models output 10 V based on the actual input voltage (220 V and 440 V respectively).	
	3	DC Link Volt	Outputs the inverter DC link voltage as the standard. Outputs 10 V when the DC link voltage is 410 VDC for 200 V models, and 820 VDC for 400 V models.	
	4	Torque	Outputs the generated torque as the standard. Outputs 10 V at 250% of the motor-rated torque.	
	5	Output Power	Monitors the output wattage. 200% of the rated output is the maximum display voltage (10 V).	
	6	Idse	Outputs the maximum voltage at 200% of the no load current.	
	7	Iqse	Outputs the maximum voltage at 250% of the rated torque current. Rated torque current = $\sqrt{\text{rated current}^2 - \text{Non - load current}^2}$	
	8	Target Freq	Outputs the set frequency as the standard. Outputs 10 V at the maximum frequency (DRV-20).	
	9	Ramp Freq	Outputs frequency calculated with Acc/Dec function as a standard. This may vary depending on the actual output frequency. Outputs 10 V.	
	10	Speed Fdb	Displays the speed information of the input into the encoder extension module. It produces 10 V at the maximum frequency (DRV-20).	
	11	Speed Dev	Outputs the difference between the speed reference (command) and the motor's rotation speed that inputs into the encoder extension module. It outputs 10 V at twice the rated slip frequency. It is valid only in Vector Control mode.	
	12	PID Ref Value	Outputs command value of a PID controller as the standard. Outputs approximately 6.6 V at 100%.	
	13	PID Fdb Value	Outputs feedback volume of a PID controller as the standard. Outputs approximately 6.6 V at 100%.	
	14	PID Output	Outputs the output value of a PID controller as the standard. Outputs approximately 10 V at 100%.	
	15	Constant	Outputs the OUT-05 (AO1 Const %) value as a standard.	
	oper	ate as shown	ue and offset. If frequency is selected as an output item, it will below. $\frac{cy}{q} \times AO2Gain + AO2Bias$	
OUT-08 AO2 Gain, OUT-09 AO2 Bias	The graph below illustrates how the analog current output (AO2) changes depending on OUT-02 (AO2 Gain) and OUT-3 (AO2 Bias) values. The Y-axis is the analog output current (0–20 mA), and the X-axis is a percentage of the output. Example, if the maximum frequency set at DRV-20 (Max Freq) is 60 Hz and the present output frequency is 30 Hz, then the x-axis value on the next graph is 50%. OUT- 08 AO2 Gain			
			100.0% 80.0% (Factory Default)	

Note

When 4-20 mA is used as the output, tune OUT-08 AO2 Gain and OUT-09 AO2 Bias as follows.

- 1 Set OUT-07 AO2 Mode to Constant and OUT11 AO2 Const % to 0.0%.
- 2 After setting OUT-09 AO2 Bias to 20.0%, ensure that that the current is 4 mA. If the current is lower than 4 mA, gradually increase OUT-09 AO2 Bias until it measures 4 mA. If the current is higher than 4 mA, gradually decrease OUT-09 AO2 Bias until it measures 4 mA.
- 3 Set OUT11 AO2 Const % to 100.0%. After setting OUT-08 AO2 Gain to 80.0%, ensure that the current is 20 mA. If the current is lower than 20 mA, gradually increase OUT-08 AO2 Gain until it measures 20 mA. If the current is higher than 20 mA, gradually decrease OUT-08 AO2 Gain until it measures 20 mA.
- 4 When 0-20 mA is used as the output, set OUT-08 A02 Gain to 100% and OUT-09 A02 Bias to 0.0%.
- 5 The functions for each code are the same as the item of 0–10 V output. And, the output range is 0–20 mA.

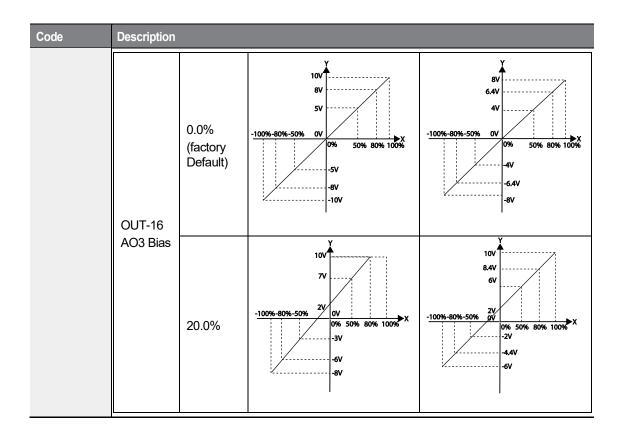
Voltage Output (-10-+10V) Using an I/O Expansion Module 9.3.3

If the optional I/O expansion module is installed, the operating status can be monitored using the bipolar voltage output of the I/O expansion module.

Group	Code	LCD Display	Paramete	er Setting	Unit
OUT	14	AO3 Mode	0	Frequency	-
	15	AO3 Gain	-	100.0	%
	16	AO3 Bias	-	0.0	%
OUT	17	AO3 Filter	-	5	Msec
18	18	AO3 Const %	-	0.0	%
	19	AO3 Monitor	-	0.0	%

Voltage Output (-10-+10 V) Details

Code	Description					
	The output mode can be set identically to when the AO1 voltage output is used. However, because bipolar voltage output is possible for AO3, unipolar (0–+10V) or bipolar (-10–+10V) voltage can be produced according to the type of the output variable. Examples of bipolar output voltages are as follows.					
OUT-14 AO3	Output Direction	Related Functions				
Mode	Forward(+) /Reverse(-)	0: Frequency	9: Ramp Fre	eq P	10: Speed Fdb	
	7110130(-)	12: PID Ref Value	13: PID Fdb Value		14: PID Output	
	Reverse(-) /Regenerative(-)	4: Torque	7: lqss		-	
	The graph below illustrates how the analog voltage output (AO3) changes depending on the OUT-15 (AO3 Gain) and OUT-16 (AO3 Bias) values.					
OUT-15 AO3 Gain, OUT- 16 AO3 Bias The Y-axis is analog output voltage (-10—+10V), and the X-axis is a percentage of output. For example, if the maximum frequency set at DRV-20 (Max Freq) is 60 Hz, then the x-axis value on the next graph is 8						
		OUT- 08 AO3 Ga				
		100.0% (Factory	Default)	80.0%		



9.3.4 Current Output (4–20 mA/0–20 mA) Using an I/O Expansion Module

If the optional I/O expansion module is installed, the current output (0–20 mA or 4–20 mA) can be produced via terminal AO4. The setting details are identical to those of AO1 analog output terminal.

Group	Code	LCD Display	Param	neter Setting	Unit
	20	AO4 Mode	0	Frequency	-
	21	AO4 Gain	-	100.0	%
OUT	22	AO4 Bias	-	0.0	%
OUT	23	AO4 Filter	-	5	ms
	24	AO4 Const %	-	0.0	%
	25	AO4 Monitor	-	0.0	%

Relay Output and Multi-function Output Terminal 9.4 Settings

Group	Code	LCD Display	Parameter	Setting	Unit
30	30	Trip Out Mode	-	010	bit
	31	Relay 1	28	Trip	-
OUT	32	Relay 2	14	Run	-
OUT	33	Q1 Define	1	FDT-1	
	34–36	Relay 3–5	-	-	-
	41	DO Status	-	-	bit

Relay Output and Multi-function Output Terminal Setting Details

Code	Description								
OUT-30 Trip	Set OL Bit on		-	flode) to enable or disable the fault relay.					
Out Mode	Setting	goption		Function					
	Bit3	Bit2	Bit1	The top-right corner of the display is 'Bit 1'.					
			✓	Operates when a low voltage fault trip occurs.					
		√		Operates when a fault trip other than low voltage occurs.					
	✓			Operates when auto restart fails (PRT-08–09).					
	Set out	tput optic	ons for th	ne relays and multi-function output terminal Q1.					
	Setting	g		Function					
	0	None		No output signal					
OUT-31 Relay1, OUT-32, Relay2, OUT-33 Q1 Define, OUT- 34–36 Relay 3–5	0 None 1 FDT-1			Inspects whether the output frequency for the inverter reaches the frequency set by the user. The inverter begins to operate when the condition is met: Absolute value (set frequency - output frequency) < detected frequency width/2. When the detected frequency width is 10 Hz, the FDT-1 output is as shown in the graph below. Group Code LCD Display Parameter Unit setting OUT 58 FDT Band (Hz) - 10.00 Hz					

Code	Descri	otion				
			35Hz 30Hz 25Hz Frequency Q1 Run cmd The output signal can be separately set for acceleration and deceleration conditions.			
	4	FDT-4	 In acceleration: Operation frequency ≥ Detected frequency In deceleration: Operation frequency > (Detected frequency - Detected frequency width/2) Detected frequency width is 10 Hz. When the detected frequency is set to 30 Hz, FDT-4 output is as shown in the graph below. Group Code LCD Display Parameter setting OUT 57 FDT Frequency - 30.00 Hz 			
			30Hz See FDT Band (Hz) - 10.00 Hz 30Hz Frequency Q1 Run cmd			
	5	Over Load	Outputs a signal at motor overload.			
	6	IOL	Outputs a signal when the inverter input current exceeds the rated current and a protective function is activated to prevent damage to the inverter, based on inverse proportional characteristics.			
	7	Under Load	Outputs a signal at load fault warning.			
	8	Fan Warning	Outputs a signal at fan fault warning.			
	9	Stall	Outputs a signal when a motor is overloaded and stalled.			
	10	Over Voltage	Outputs a signal when the inverter DC link voltage rises above the protective operation voltage.			
	11	Low Voltage	Outputs a signal when the inverter DC link voltage drops below the low voltage protective level.			
	12	Over Heat	Outputs signal when the inverter overheats.			
	13	Lost Command	Outputs a signal when there is a loss of analog input terminal and RS-485 communication command at the terminal block. Outputs a signal when communication power is present and an I/O expansion module is installed. It also outputs a signal			

Functions	Monitor

ode	Descri	Description									
				-	g input and com	nmuni	cation power				
			commands. Outputs a signal when an operation command is entered and								
						on cor	nmand is ente	ered and			
			the inverte								
			No signal	output di	uring DC brakin	ıg.					
						_					
	14	RUN					_				
	'-	TON	Frequen	cv /							
			Q1								
			Run cmd								
	15	Stop			operation com	mand	off, and wher	n there is			
		·	no inverter								
	16	Steady			steady operation						
	17	Inverter Line			hile the motor is						
				_	hen multi-functi	on in	out terminai (s	witching			
			is entered.		I CD Diamles	l :4:	1.0-44:	I I too!4			
			Group	Code	LCD Display	+	I Setting	Unit			
			IN	65-72	Px Define	16	Exchange	-			
	18	Comm Line	OUT	32	Relay 2	15	Inverter Line	· -			
				00		40					
				33	Q1 Define	16	Comm Line	-			
			<u>253</u> .	s, refer to	Q1 Define 8.23 Supply F	Power	Transition or				
	19	Speed Search	253. Outputs a	s, refer to	Q1 Define	Power	Transition or	on.			
	19		253. Outputs a For details 244. Outputs a	s, refer to signal du s, refer to signal w	8.23 Supply F uring inverter sp 8.19 Speed Se hen a step is co	Power peed s	Transition or search operation on Operation on	on. page			
		Search	253. Outputs a For details 244. Outputs a sequence	signal du signal du , refer to signal wi operatio signal wi	8.23 Supply F uring inverter sp 8.19 Speed Se hen a step is con. hen a sequence	peed search	Transition or search operation on ted in an auto	ion. page			
	20	Search Step Pulse	253. Outputs a For details 244. Outputs a sequence Outputs a sequence Outputs a	signal du signal wi operatio signal wi operatio signal wi operatio signal wi	8.23 Supply F uring inverter sp 8.19 Speed Se hen a step is co n. hen a sequence n. hen the inverte	peed search comple e is co	Transition or search operation on ted in an auto ompleted in ar standby mode	on. page			
	20	Search Step Pulse Seq Pulse	253. Outputs a For details 244. Outputs a sequence Outputs a sequence Outputs a ready to re	signal du signal wi operatio signal wi operatio signal wi operatio signal wi eceive ex	Q1 Define 8.23 Supply F uring inverter sp 8.19 Speed Se hen a step is con. hen a sequencen.	peed search comple e is cor	search operation on ted in an auto ompleted in are standby modermands.	n auto			
	20	Search Step Pulse Seq Pulse	253. Outputs a For details 244. Outputs a sequence Outputs a sequence Outputs a ready to re Outputs a	signal du signal wi operatio signal wi operatio signal wi eceive ex signal wi	8.23 Supply F uring inverter sp 8.19 Speed Se hen a step is co n. hen a sequence n. hen the inverte tternal operation	peed search comple r is in n com	search operation on ted in an auto ompleted in are standby modermands.	n auto			
	20	Search Step Pulse Seq Pulse	253. Outputs a For details 244. Outputs a sequence Outputs a sequence Outputs a ready to re Outputs a	signal du signal wi operatio signal wi operatio signal wi eceive ex signal wi	8.23 Supply F uring inverter sp 8.19 Speed Se hen a step is con. hen a sequence hen the inverter tternal operation hen the inverter	peed search pemple e is corris in common co	search operation on ted in an auto ompleted in are standby modermands.	n auto			
	20 21 22	Search Step Pulse Seq Pulse Ready	253. Outputs a For details 244. Outputs a sequence Outputs a sequence Outputs a ready to re Outputs a frequency	signal du signal wi operatio signal wi operatio signal wi eceive ex signal wi during a	8.23 Supply F uring inverter sp 8.19 Speed Se hen a step is con. hen a sequence hen the inverte tternal operatio hen the inverte traverse opera	peed search comple e is comple or reaction. Pai	search operation on ted in an auto ompleted in are standby modermands.	on. page n auto e and erating			
	20 21 22	Search Step Pulse Seq Pulse Ready	253. Outputs a For details 244. Outputs a sequence Outputs a sequence Outputs a ready to re Outputs a frequency	signal du signal wi operatio signal wi operatio signal wi eceive ex signal wi during a	8.23 Supply F uring inverter sp 8.19 Speed Se hen a step is con. hen a sequence hen the inverte tternal operatio hen the inverte traverse opera	peed search comple e is comple or reaction. Pai	eransition or search operation on ted in an auto ompleted in ar standby model mands.	on. page n auto e and erating			
	20 21 22	Search Step Pulse Seq Pulse Ready	253. Outputs a For details 244. Outputs a sequence Outputs a sequence Outputs a ready to re Outputs a frequency Group APP Outputs a	signal du signal wi operatio signal wi operatio signal wi operatio signal wi eceive ex signal wi during a Code	8.23 Supply F uring inverter sp 8.19 Speed Se then a step is con. then a sequence then the inverter ternal operation then the inverter traverse operat LCD Display App Mode then the inverter	poeed search comple e is compressed in com	Transition or search operation on ted in an auto ompleted in ar standby modernands. hes the accelerameter ting	on. page n auto e and erating Unit			
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Code	Description							
	25	MMC	Used as a multi-motor control function. By configuring the relay output and the multi-function output to MMC and configuring the APP-01 (APP Mode) to "3 (MMC), it can conduct the necessary operations for multi-motor control function.					
			Group	Code	-17		arameter etting	Unit
			APP	01	App Mode	3		-
					or's rotation sponode is set as		s 0 rpm during op ctor.	peration
			Group	Code	LCD Display		Parameter setting	Unit
			DRV	09	Control Mode		4 Vector	-
			CON	82	ZSD Frequen		- 2.00	Hz
				83	ZSD Band (H	z)	- 1.00	Hz
	26	Zspd Dect	As the relay operation is dependent on the motor nur (encoder signal), a fault may occur when turning the on or off due to the encoder signal noise or filter time Motor Rotation Q1(Zspd Dect) As the relay operation is dependent on the motor nur (encoder signal), a fault may occur when turning the on or off due to the encoder signal noise or filter time					
			Outputs a signal if the torque, with the control mode set as sensorless or vector, is below the following levels.					
	27	Torque Dect	Group DRV	O9	Control Mode	3– 4	Sensorless-1, Sensorless-2, Vector	Unit -
			OUT	59	TD Level	-	100.0	%
				60	TD Band	-	5.0	%
					operate termir		utput after a certa	ain time
			Group	Code	LCD Display		ameter setting	Unit
			IN	65– 72	Px Define	38	Timer In	-
	28	Timer Out	OUT	55	Timer On Delay	-	0.00	Sec
				56	Timer Off Delay	-	0.00	Sec
	32	ENC Tune	Outputs a	a warning	g signal by rele	asing	the contact poin	t output

Code	Descri	Description						
			if autotuning is performed, if there is no encoder board, or if APO-01 Enc Opt mode is not set to "Feedback".					
	33	ENC Dir	Outputs a warning signal when the motor rotation direction by the encoder is not set properly. The warning signal is generated when then encoder wiring is not made properly even if the encoder module has been installed and APO-01 Enc Opt Mode is set to "Feedback".					
	36	KEB Operating	Outputs a signal when the energy buffering operation is performed (when an input power outage occurs and the DC power supply voltage of the inverter is low).					
	37	Fire Mode	Outputs a signal when Fire mode is in operation only if ADV-80 is set to Fire mode.					
	38	Run2	It operates when the operation command is input or the inverter is outputting voltage. Unlike "14: Run", it operates even during DC braking					
OUT-41 DO State	Used t	o check On/Off s	state of the DO (digital output) by each bit.					

Fault trip output using multi-function output 9.5 terminals and relays

The inverter can output a fault trip state using the multi-function output terminal (Q1) and relay (Relay1).

Group	Code	LCD Display	Paramet	er Setting	Unit
30	30	Trip Out Mode	-	010	
	31	Relay 1	29	Trip	-
OUT	32	Relay 2	14	Run	-
OUT	33	Q1 Define	1	FDT-1	-
	53	Trip Out On Dly	-	0.00	Sec
	54	Trip Out Off Dly	-	0.00	Sec

^{*} The inverter can output a fault trip status using expansion digital output terminals (OUT 34–36) if the optional I/O expansion module is installed.

Code	Descrip	Description						
OUT-30 Trip Out Mode	Set OUT-30 (Trip Out Mode) to enable or disable the fault relay. Bit on Bit off Depending on the fault trip type, the terminal and relay operation can be configured as shown in the table below.							
	Setting	option		Function				
	Bit3	Bit2	Bit1	The top-right corner of the display is 'Bit 1'.				
			✓	Operates when a low voltage fault trip occurs.				
		✓		Operates when a fault trip other than low voltage occurs.				
	✓			Operates when auto restart fails (PRT-08–09).				
OUT-31-33	mode)".	Select the terminal and relay to use for failure output and set OUT-31–33 to "28 (Trip mode)". When a fault trip occurs in the inverter, the relevant terminal and relay will operate.						
OUT-53 Trip Out On Dly, OUT-54 Trip Out Off Dly,		•		elay or multi-function output operates after the time delay set in ns off with the input initialized after the time delay set in OUT-54.				

9.6 Output Terminal Delay Time and Terminal Types

You can adjust the operating time of the output terminals and relays. The ON and OFF delay time can be set separately. You can choose between "form A" terminal (Normally Open) and "form B" terminal (Normally Closed).

9.6.1 Output Terminal Delay Time

Group	Code	LCD Display	Param	neter Setting	Unit
OUT	50	DO On Delay	-	0.00	Sec
OUT	51	DO Off Delay	-	0.00	Sec

Output Terminal Delay Time Setting Details

Code	Description
OUT-50 DO On Delay	Set the delay time before the output signal is turned on.
OUT-51 DO Off Delay	Set the delay time before the output signal is turned off.

The delay time set at codes OUT-50 and OUT-51 apply to the multi-function output terminal (Q1) and relays (Relay 1 and 2), except when the multi-function output function is in fault trip mode.

9.6.2 Setting the Output Terminal Type

Group	Code	LCD Display	Parameter Setting		Unit
OUT	52	DO NC/NO Sel	- 000		bit

Output Terminal Type Setting Details

Code	Description			
OUT-52 DO NC/NO Sel	Select the type for the relay and multi-function output terminal. An additional three terminal type selection bits at the terminal block will be added when an optional I/O expansion module is installed.			
cor oz zo nome co	Set the relevant bit to "0" to operate it as a "form A" terminal (Normally Open), "1" to operated it as a "form B" terminal (Normally Closed). Relay 1 and Q1 settings start from the right bit (The top-right corner of the display is 'Bit 1'.).			

9.7 Operation Time Monitor

Group	Code	LCD Display	Param	neter Setting	Unit
	70	On-time	-	0000DAY 00hr:00mm	-
	71	Run-time	-	0000DAY 00hr:00mm	-
CNF	72	Time Reset	0	No	-
	74	Fan Time	-	0000DAY 00hr:00mm	-
	75	Fan Time Reset	0	No	-

Output Terminal Type Setting Details

Code	Description			
CNF-70 On-time	Displays the accumulated power supply time. Information is displayed in [0000DAY 00hr:00mm] format.			
CNF-71 Run-time Displays the accumulated time of voltage output by operation complete information is displayed in [0000DAY 00hr:00mm] format.				
CNF-72 Time Reset	Setting "1 (Yes)" will delete the accumulated power supply time (On-time) and operation accumulated time (Run-time), and is displayed in 0000DAY 00hr:00mm format.			
CNF-74 Fan time	Displays the accumulated inverter cooling fan operation time. Information will be displayed in [0000DAY 00hr:00mm] format.			
CNF-75 Fan Time Reset	Setting "1 (Yes)" will delete the accumulated cooling fan operation time (ontime) and accumulated operation time (run-time), and will display it in 0/00/00 00:00 format.			

9.8 Setting the Keypad Language

Select the language to be displayed on the LCD keypad. Keypads using S/W Ver 1.04 and later provide a language selection. The Korean language setting supports Korean and English.

Group	Code	LCD Display	Initial Setting		Unit
			0	English	
			1	Russian	
CNF	01	Language Sel	2	Spanish]-
			3	Italian	
			4	Turkish]

10 **Using Protection Features**

Protection features provided by the SV-iS7 series inverter are categorized into two types: Protection from damage due to an overheating motor and Protection against inverter malfunction.

10.1 Motor Protection

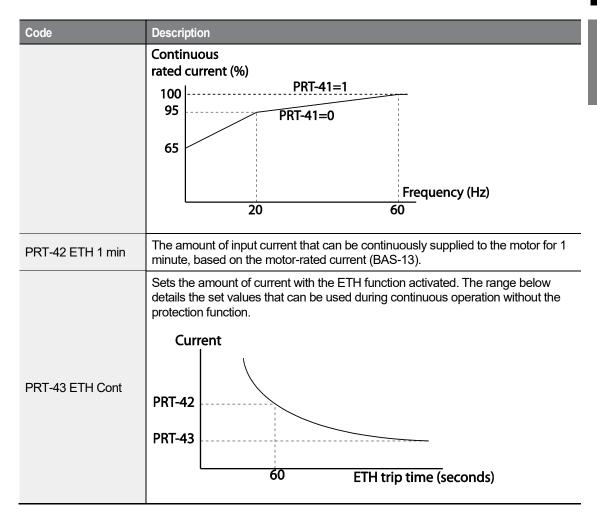
10.1.1 Electrothermal Motor Overheating Prevention (ETH)

ETH is a protective function that uses the output current of an inverter without a separate temperature sensor to predict increases in motor temperature and protect the motor, based on its heat characteristics.

Group	Code	LCD Display	Parameter Setting		Setting Range	Unit
PRT 42	40	ETH Trip Sel	0	None	None/Free-Run/Dec	-
	41	Motor Cooling	0	Self-cool	-	-
	42	ETH 1min	-	150	120-200	%
	43	ETH Cont	-	120	50–180	%

Electronic Thermal (ETH) Prevention Function Setting Details

Code	Description					
	ETH can be selected to provide motor thermal protection. The LCD screen displays "E-Thermal."					
	Set	ting	Function			
PRT-40 ETH Trip Sel	0	None	The ETH function is not activated.			
	1	The inverter output is blocked. The motor coasts (free-run).				
	2	Dec	The inverter decelerates the motor to a stop.			
	Select the drive mode of the cooling fan, attached to the motor.					
	Setting		Function			
PRT-41 Motor	0	Self-cool	As the cooling fan is connected to the motor axis, the cooling effect varies based on motor speed. Most universal induction motors have this design.			
Cooling	1	Forced-cool	Additional power is supplied to operate the cooling fan. This provides expansion operation at low speeds. Motors designed for inverters typically have this design.			



10.1.2 Overload Early Warning and Trip

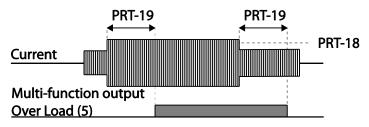
A warning or fault trip (cutoff) occurs when the motor reaches an overload state, based on the motorrated current. The amount of current for warnings and trips can be set separately.

Group	Code	LCD Display	Para	meter Setting	Setting Range	Unit
	04	Load Duty	1	Heavy Duty	-	-
	17	OL Warn Select	1	Yes	0–1	-
	18	OL Warn Level	-	150	30–180	%
PRT	19	OL Warn Time	-	10.0	0–30	sec
	20	OL Trip Select	1	Free-Run	-	-
	21	OL Trip Level	-	180	30–200	%
	22	OL Trip Time	-	60.0	0–60.0	sec
	31	Relay 1			-	
OUT	32	Relay 2	5	Over Load	-] -
	33	Q1 Define			-	

Overload Early Warning and Trip Setting Details

Code	Description					
	Select the load leve	el. Function				
PRT-04 Load Duty	0 Normal Duty	Use this setting for light loads, such as, fans and pumps (overload tolerance: 110% of rated underload current for 1 minute).				
	1 Heavy Duty	Use this setting for heavy loads, such as, cranes and parking elevators (overload tolerance: 150% of rated heavy load current for 1 minute).				
PRT-17 OL Warn Select	terminal and relay a	If the overload reaches the warning level, the terminal block multi-function output terminal and relay are used to output a warning signal. If "1 (Yes)" is selected, it will operate. If "0 (No)" is selected, it will not operate.				
PRT-18 OL Warn Level, PRT-19 OL Warn Time	When the input current to the motor is greater than the overload warning level (OL Warn Level) and continues at that level during the overload warning time (OL Warn Time), the multi-function output (Relay 1, Q1) sends a warning signal. When Over Load is selected at OUT-31 and OUT-33, the multi-function output terminal or relay outputs a signal. The signal output does not block the inverter output.					
PRT-20 OL Trip Select	Setting	protective action in the event of an overload fault trip. Function				
•	0 None	No protective action is taken.				

Code	Description				
	1	Free-Run	In the event of an overload fault, inverter output is blocked and the motor will free-run due to inertia.		
	3	Dec	If a fault trip occurs, the motor decelerates and stops.		
PRT-21 OL Trip Level, PRT-22 OL Trip Time	When the current supplied to the motor is greater than the preset value of the overload trip level (OL Trip Level) and continues to be supplied during the overload trip time (OL Trip Time), the inverter output is either blocked according to the preset mode from PRT-17 or slows to a stop after deceleration.				



Note

Overload warnings warn of an overload before an overload fault trip occurs. The overload warning signal may not work in an overload fault trip situation, if the overload warning level (OL Warn Level) and the overload warning time (OL Warn Time) are set higher than the overload trip level (OL Trip Level) and the overload trip time (OL Trip Time).

10.1.3 Stall Prevention and Flux Braking

The stall prevention function is a protective function that prevents motors from stalling due to overloads. If a motor stall occurs due to an overload, the inverter operation frequency is adjusted automatically. When a stall is caused by overload, high currents induced in the motor may cause motor overheating or damage the motor and interrupt operation of the motor-driven devices.

In this case, the motor decelerates with optimum deceleration without a braking resistor by using flux braking. If the deceleration time is too short, an over voltage fault trip may occur because of regenerative energy from the motor. The flux braking makes the motor use regenerate energy, therefore optimum deceleration is available without over voltage fault trip.

To protect the motor from overload faults, the inverter output frequency is adjusted automatically, based on the size of load.

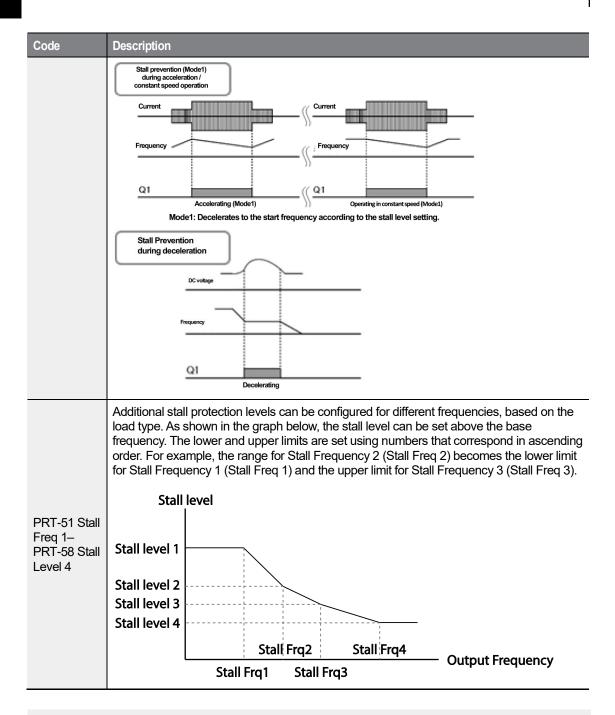
Group	Code	LCD Display	Param	eter Setting	Setting Range	Unit
	50	Stall Prevent & Flux Braking	-	0 0000	-	Bit
	51	Stall Freq 1	-	60.00	Starting Freq-Stall Freq 1	Hz
	52	Stall Level 1	-	180	30–250	%
	53	Stall Freq 2	-	60.00	Stall Freq 1–Stall Freq 3	Hz
PRT	54	Stall Level 2	-	180	30–250	%
	55	Stall Freq 3	-	60.00	Stall Freq 2–Stall Freq 4	Hz
	56	Stall Level 3	-	180	30–250	%
	57	Stall Freq 4	-	60.00	Stall Freq 3–Max. Freq	Hz
	58	Stall Level 4	-	180	30–250	%
OUT	31–33	Relay1,2, Q1	9	Stall	-	-

Stall Prevention Function and Flux Braking Setting Details

Code	Descript	ion					
	Stall prevention can be configured for acceleration, deceleration, or while operating a motor at constant speed. When the LCD segment is on, the corresponding bit is off.						
	ltem		Bit Status	(On)		Bit Status (Off)	
	Keypad	l display					
						Function	
	Setting Bit5	Bit 4	Bit 3	Bit 2	Bit 1	_ Function	
DDT 50 Ctall	Dito	Dit	Dit 3	Dit 2	Dit 1	Stall protection during acceleration	
PRT-50 Stall Prevent				✓		Stall protection while operating at a constant speed	
1 TOVOIT			✓			Stall protection during deceleration	
		✓				Flux braking during deceleration	
	✓					Stall protection during acceleration & constant speed	
				1		speeu	
	Setting			Function			
	O	Stall prote	ction	If the inverter output current exceeds the preset stall			
	0001	during acc					
	0001	during doc	Cicration	level (PRT-52, 54, 56, 58) during acceleration, the motor stops accelerating and starts decelerating. If current			
						he stall level, the motor decelerates to	
				the start frequency (DRV-19). If the current level causes			

Code	Description						
			deceleration below the preset level while operating the stall protection function, the motor resumes acceleration.				
	1 0001	Stall prevention during acceleration (Mode2)	If the inverter's output current exceeds the preset stall level (PRT-52, 54) during acceleration, the inverter adjusts the output frequency to prevent stalling. The inverter performs a PI control on the current level to adjust the output frequency to be above the stall level. While the stall prevention feature is activated, the inverter starts accelerating again when the the current drops below the the set level.				
	0 0010	Stall protection while operating at constant speed	Similar to stall protection function during acceleration, the output frequency automatically decelerates when the current level exceeds the preset stall level while operating at constant speed. When the load current decelerates below the preset level, it resumes acceleration.				
	1 0010	Stall prevention while operating at a constant speed (Mode2)	Similar to the stall protection function during acceleration (Mode 2), if the inverter output current exceeds the preset stall level while operating at a constant speed, the inverter adjusts the output frequency according to the load current. When the load current drops below the preset level, the inverter resumes acceleration.				
	1 or 0 0100	Stall protection during deceleration	The inverter decelerates and keeps the DC link voltage below a certain level to prevent an over voltage fault trip during deceleration. As a result, deceleration times can be longer than the set time depending on the load.				
	1 or 0 1000	Flux braking during deceleration	When using flux braking, deceleration time may be reduced because regenerative energy is expended at the motor.				
	1 or 0 1100	Stall protection and flux braking during deceleration	Stall protection and flux braking operate together during deceleration to achieve the shortest and most stable deceleration performance.				
	dui	prevention (Mode2) ring acceleration / ant speed operation					
	Current		Frequency				
	Q1	Accelerating (Mode2)	Operating in constant speed (Mode2)				

Mode2: The frequency is adjusted according to the stall level setting and load current.



Note

Stall protection and flux braking operate together only during deceleration. Turn on the third and fourth bits of PRT-50 (Stall Prevention) to achieve the shortest and most stable deceleration performance without triggering an over voltage fault trip for loads with high inertia and short deceleration times. Do not use this function when frequent deceleration of the load is required, as the motor can overheat and be easily

damaged.

① Caution

- Use caution when decelerating while using stall protection since the deceleration time can take longer than the time set, depending on the load. Acceleration stops when stall protection operates during acceleration. This may make the actual acceleration time longer than the preset acceleration time.
- When the motor is operating, Stall Level 1 applies and determines the operation of stall protection.

10.1.4 Motor Overheat Sensor Input

To use the motor overheat protection, connect the overheat protection temperature sensor (PT 100, PTC) installed in the motor to the inverter's analog input terminal.

Group	Code	LCD Display	Parame	ter Setting	Setting Range	Unit
	34	Thermal-T Sel	1	Free-Run	-	-
DDT	35	Thermal In Src	1	V1	-	-
PRT	36	Thermal-T Lev	-	50.0	0–100	%
	37	Thermal-T Area	0	Low	Low/High	-
OUT	07	AO2 Mode	14	Constant	-	-
OUT	08	AO2 Const	11	100%	0–100	%
	65–75	Px Define	39	Thermal In	-	-
IN	87	DI NC/NO Sel	-	-	-	-

Motor Overheat Sensor Input Details

Code	Description
PRT-34 Thermal-T Sel	The inverter operating status is set when the motor overheats. If Free-Run (1) is set, the inverter output will be blocked. If decelerating stop (2) is set and the overheat sensor detects overheating, the inverter will decelerate and stop.
PRT-35 Thermal In	The terminal type is selected when the motor overheat sensor is connected to the voltage (V1) or current (I1) input terminals of the inverter terminal block in the inverter. The voltage (V2) or current (I2) terminals in the I/O expansion module are also available.
Src	If you use the current input terminal I1 by supplying constant current to the temperature sensor with the analog current output (AO2) terminal, the switch in the I/O expansion module should be where the PTC is. Before use, check if the switch is at the PTC.

Code	Description				
	AO2 V1 CM Switch [With voltage (V1) input] [With current (I1) input terminal] Temperature is measured by letting a certain amount of current flow through the AO2 terminal and converting it into voltage depending on the resistance value change.				
IN-65–72 Px Define, IN-82 DI NC/NO Sel	You can set the overheat trip function input using the multi-function terminal block input when using a bimetal-type sensor relay. Connect PTC between the terminal block to use and CM and select "39 (Thermal)" In among the function items. Select the type of contact point of the terminal used in IN-87 as "1 (NC)". In Px CM PTC [Configuration using multi-function input terminals]				
PRT-36 Thermal-T Lev	Sets the operation level for the motor overheat sensor. For the voltage input terminal (V1), the maximum input voltage is 10 V and for the current (I1), the maximum input voltage is 5 V. For example, if you use the current input terminal and set the failure level to 50%, the protection function is performed when the voltage supplied to the I1 terminal is below 2.5 V. To perform the protection function when the voltage supplied to the I1 terminal is above 2.5 V, refer to the PRT-37 Thermal-T Area.				
PRT-37 Thermal-T Area	If Low (0) is set and the motor overheat sensor input is smaller than PRT-36, the protection function is performed. If High (1) is set and the motor overheat sensor input is bigger than PRT-36, the protection function is performed.				

10.2 Inverter and Sequence Protection

10.2.1 Open-phase Protection

Open-phase protection is used to prevent overcurrent levels induced at the inverter inputs due to an open-phase within the input power supply. Open-phase output protection is also available. An open phase at the connection between the motor and the inverter may cause the motor to stall, due to a lack of torque.

Group	Code	LCD Display	Parameter Setting		Setting Range	Unit
PRT	05	Phase Loss Chk	-	10	-	Bit
	06	IPO V Band	-	40	1–100	V

Input and Output Open-phase Protection Setting Details

Code	Description	Description						
	When open-phase protection is operating, input and output configurations are displayed differently. When the LCD segment is On, the corresponding bit is set to 'Off'.							
	Item	Bit status	s (On)	Bit status (Off)				
	Keypad display							
		1,7	T =					
	Setting Bit 2 Bit 1	Keypad display	Function					
PRT-05 Phase Loss Chk	*		Output open-phase protection. If one or more than one phase from U, V, and W is open, the inverter output will be blocked and "Out Phase Open" will be displayed on the keypad. Input open-phase protection. If one or more phases from R, S, and T are open, the inverter output will b blocked and "In Phase Open" will be displayed on the keypad. Protection against input phase open starts only when a certain amount of current (70–80% of the inverter-rated output current) flows through the motor.					
	✓ ✓		Input and output	open-phase protection				
PRT-06 IPO V Band	Sets the band of the allowed ripple voltage. If one or more phases from the inverter output are open, the ripple of the DC link voltage increases. If ripple voltage exceeds the set ripple voltage band, an input phase open trip occurs. The IPO V Band may be adjusted depending on the operating environment.							
	capacity, and	an open phas	Sets the IPO V Band 1–10 volts higher if the output load is too large for the input capacity, and an open phase fault trip occurs during a normal operation. Sets the IPO V Band 1–10 volts lower if the output load is too smaller for the input capacity.					

Note

Ensure that the motor-rated current (BAS-13 Rated Curr) is correctly set. Phase open protection may not be operated properly if the motor's rated current is not correctly set at BAS-13.

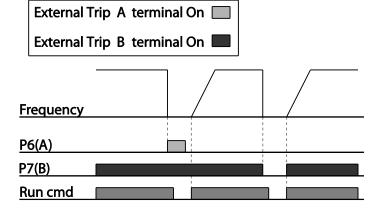
10.2.2 External Trip Signal

Set one of the multi-function input terminals to "4 (External Trip)" to allow the inverter to stop operation when abnormal operating conditions arise.

Group	Code	LCD Display	Parameter Setting		Unit
	65–72	Px Define	4	External Trip	-
IN	87	DI NC/NO Sel	-	(000 0000000)	-

External Trip Signal Setting Details

Code	Description											
IN-87 DI NC/NO Sel	Select the toperates as operates as The corres	s a forr s a forr	n A ter n B ter	minal (minal (Norma Norma	Illy Ope Illy Clo	en). If tl sed).	he mar				
	Bit	11	10	9	8	7	6	5	4	3	2	1
	Terminal	-	-	-	P8	P7	P6	P5	P4	P3	P2	P1



10.2.3 Inverter Overload Protection (IOLT)

If more current than the inverter-rated current flows, the protective function starts to protect the inverter depending on the inverse time characteristic.

Group	Code	LCD Display	Parameter	Parameter Setting		
OUT	31–33	Relay 1,2, Q1	6	IOL	-	

Note

A warning signal output can be provided in advance by the multi-function output terminal before the inverter overload protection function (IOLT) operates. When the overcurrent time reaches 60% of the allowed overcurrent (150%, 1 min), a warning signal output is provided (signal output at 150% for 36 sec).

10.2.4 Keypad Command Loss

When setting operation speed using the keypad, speed command loss setting can be used to select the inverter operation for situations when the speed command from the keypad is lost due to the disconnection of signal cable.

Group	Code	LCD Display	Parameter Setting		Unit
PRT	11	Lost KPD Mode	2	Free-Run	-
OUT	31–33	Relay1,2, Q1	30	Lost Keypad	-
DRV	06	Cmd Source	0	Keypad	-
CNF	22	Multi Key Sel	0	JOG Key	-

Speed Command Loss Setting Details

Code	Des	Description				
	Set the DRV-06 (command source) to "0 (keypad)", and select the inverter's operation for when there is a keypad connection problem.					
	Se	tting	Function			
	0 None		The speed command immediately becomes the operation frequency without any protection function.			
PRT-11 Lost KPD Mode	1	Warning	Set one of the output terminals to "29 (Lost keypad)" to output a relevant warning signal when abnormal operating conditions arise.			
	2	Free-Run	The inverter blocks output when the keypad connection is lost. The motor performs in free-run condition.			
	3 Dec		The motor decelerates and then stops at the time set at PRT-07 (Trip Dec Time) when the keypad connection is lost.			

Using Protection Features

Code	Description
	The protection function is also available for the keypad command loss during jog key operation when CNF-22 is set to "JOG Key."

10.2.5 Speed Command Loss

When setting the operation speed using an analog input at the terminal block, communication options, or the keypad, the speed command loss setting can be used to select the inverter operation for situations when the speed command is lost due to the disconnection of signal cables.

The function activates the command loss detection even for the operation command loss through communication.

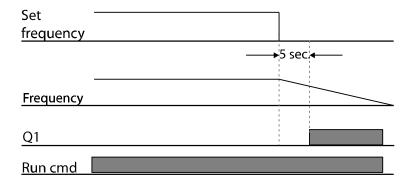
Group	Code	LCD Display	Para	meter Setting	Setting Range	Unit
	12	Lost Cmd Mode	1	Free-Run	-	-
DDT	13	Lost Cmd Time	-	1.0	0.0–120	Sec
PRT 14 15	14	Lost Preset F	-	0.00	Starting Freq-Max. Freq	Hz
	15	Al Lost Level	1	Half of X1	-	-
OUT	31–33	Relay1,2, Q1	13	Lost Command	-	-

Speed Command Loss Setting Details

Code	Desc	Description				
PRT-12 Lost Cmd Mode		ate in a specific	speed commands are lost, the inverter can be configured to comode: Function The speed command immediately becomes the operation frequency without any protection function. The inverter blocks output. The motor performs in freerun condition. The motor decelerates and then stops at the time set at PRT-07 (Trip Dec Time). The inverter calculates the average input value for 10 seconds before the loss of the speed command and uses it as the speed reference. The inverter calculates the average output value for 10 seconds before the loss of the speed command and uses it as the speed reference. The inverter operates at the frequency set at PRT-14 (Lost Preset F).			
PRT-15 Al Lost Level,	Configure the voltage analog input. Setting		ge and decision time for speed command loss when using Function			
PRT-13 Lost Cmd Time	0 Half of x1		Based on the values set at IN-08 and IN-12, a protective operation starts when the input signal is reduced to half of			

Code	Description					
	1 Below of x	the initial value of the analog input set using the speed command (DRV-01) and it continues for the time (speed loss decision time) set at PRT-13 (Lost Cmd Time). For example, set the speed command to "2 (V1)" at DRV-07, and set IN-06 (V1 Polarity) to "0 (Unipolar)". When the voltage input drops to less than half of the value set at IN-08 (V1 Volt x 1), the protective function is activated. The protective operation starts when the signal becomes smaller than the initial value of the analog input set by the speed command and it continues for the speed loss decision time set at PRT-13 (Lost Cmd Time). Codes IN-08 and IN-12 are used to set the standard values.				
PRT-14 Lost Preset F	In situations where speed commands are lost, set the operation mode (PRT-12 Lost Cmd Mode) to "5 (Lost Preset)". This operates the protection function and sets the frequency so that the operation can continue.					

Set IN-06 (V1 Polarity) to "Unipolar" and IN-08 to "5 (V)". Set PRT-15 (Al Lost Level) to "1 (Below x1)" and PRT-12 (Lost Cmd Mode) to "2 (Dec)" and then set PRT-13 (Lost Cmd Time) to 5 seconds. Then the inverter operates as follows:



Note

If speed command is lost while using communication options or the integrated RS-485 communication, the protection function operates after the command loss decision time set at PRT-13 (Lost Cmd Time) is elapsed.

10.2.6 Dynamic Braking (DB) Resistor Configuration

The iS7 series is divided into a model which features a built-in braking circuit and the other in which a separate external braking unit should be installed. 0.75-22 kW model types belong to the former (braking resistor unit is excluded) and for those model types above 30 kW, you should install a

braking unit on the exterior of the inverter. Therefore the function of limiting the braking resistance use rate (%ED) is necessary for only models below 22 kW.

Group	Code	LCD Display	Para	meter Setting	Setting Range	Unit
PRT	66	DB Warn %ED	-	10	0–30%	-
OUT	31–33	Relay1,2, Q1	31	DB Warn%ED	-	-

Dynamic Braking Resistor Setting Details

Code Description Sets braking resistor configuration (%ED: Duty cycle). Braking resistor configuration sets the rate at which the braking resistor operates for one operation cycle. The maximum time for continuous braking is 15 sec and the braking resistor signal is not output from the inverter after the 15 sec period has expired. An example of braking resistor set up is as follows: $\%ED = \frac{T_dec}{T_acc + T_steady + T_dec + T_stop} \times 100\%$ Frequency T_acc T_steady 1 T_dec T_stop [Example 1] PRT-66 DB Warn %ED Frequency T_steady 1 [Example 2] T acc: Acceleration time to set frequency T steady: Constant speed operation time at set frequency T dec: Deceleration time to a frequency lower than constant speed

Code	Description
	operation or the stop time from constant speed operation frequency T_stop: Stop time until operation resumes

① Caution

Do not set the braking resistor to exceed the resistor's power rating. If overloaded, it can overheat and cause a fire. When using a resistor with a heat sensor, the sensor output can be used as an external trip signal for the inverter's multi-function input.

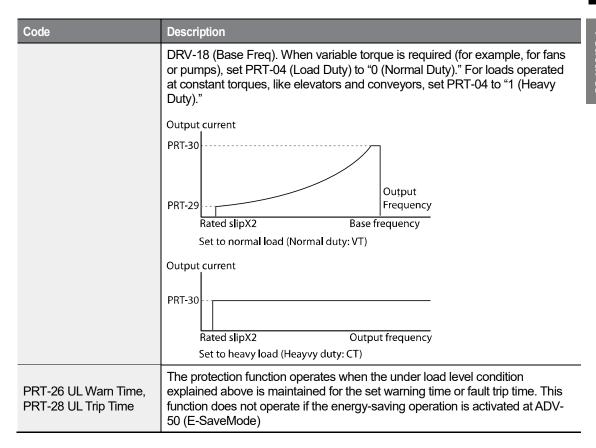
10.2.7 Underload Warning and Failure

The following table lists the under load fault trip and warning features of the iS7 series inverter.

Group	Code	LCD Display	Parame	eter Setting	Setting Range	Unit
	04	Load Duty	0	Normal Duty	-	-
	25	UL Warn Sel	1	Yes	0–1	
	26	UL Warn Time	-	10.0	0–600.0	sec
PRT	27	UL Trip Sel	1	Free-Run	-	-
	28	UL Trip Time	-	30.0	0–600.0	sec
	29	UL LF Level	-	30	10–30	%
	30	UL BF Level	-	30	10–100	%

Under Load Trip and Warning Setting Details

Code	Description
PRT-27 UL Trip Sel	Sets the inverter operation mode for situations when an under load trip occurs. If "1 (Free-Run)" is set, the output is blocked in an under load fault trip situation. If "2 (Dec)" is set, the motor decelerates and stops when an under load trip occurs.
PRT-25 UL Warn Sel	Select the under load warning options. Set the multi-function output terminals (at OUT-30–32) to "6 (Underload)." The warning signals are output when an under load condition arises.
PRT-29 UL LF Level, PRT-30 UL BF Level	Sets the range necessary for underload detection based on the underload type. Set the underload rate at an operating frequency for the motor-rated slip speed (2x operation), (BAS-12 Rated Slip) at PRT-29. At PRT-30, the under load rate is decided based on the base frequency set at



10.2.8 Overspeed Fault

This function is performed when the control mode (DRV-09 Control Mode) is set to "Sensorless-2", "Vector". If the motor rotates faster than the overspeed level (Over SPD Level) during the overspeed detection time (Over SPD Time), the inverter blocks output.

Group	Code	LCD Display	Parameter Setting		Unit
DDT	70	Over SPD Level	-	120.0	Hz
PRT	72	Over SPD Time	-	0.01	Sec

10.2.9 Speed Deviation Fault

This function is performed when the control mode (DRV-09 Control Mode) is set to "Vector". If the motor rotates faster than the speed deviation limit (Speed Dev Band) for the set detection time

(Speed Dev Time), the inverter will block output.

Group	Code	LCD Display	Parameter Setting		Unit
	73	Speed Dev Trip	1	Yes	-
PRT	74	Speed Dev Band	-	20.00	Hz
	75	Speed Dev Time	-	1.0	Sec

10.2.10 Speed Sensor (Encoder) Fault Detection

This function can detect whether the encoder expansion module is installed to the inverter. When the encoder is installed, if the encoder signal cable (line drive type) connection is lost, encoder-related faults are detected. If a fault occurs, a message reading "Encoder Trip" is displayed.

Group	Code	LCD Display	Parameter Setting		Unit
PRT	77	Enc Wire Check	1	Yes	-
	78	Enc Check Time	-	1.0	sec

10.2.11 Fan Fault Detection

Group	Code	LCD Display	Parameter Setting		Unit
PRT	79	FAN Trip Mode	0	Trip	-
OUT	31–32	Relay 1,2	8	FAN Warning	-
	33	Q1 Define			

Fan Fault Detection Setting Details

Code	Description				
		ne cooling fan			
PRT-79 Fan Trip Mode	Settii 0	Trip	Function The inverter output is blocked and the fan trip is displayed when a cooling fan error is detected.		
	1	Warning	When OUT-36 (Q1 Define) or OUT-31–35 (Relay1, 2) is set to "8 (FAN Warning)", the fan error signal is output and the operation continues.		
OUT-33 Q1 Define, OUT-31–32 Relay1, 2	When the code value is set to "8 (FAN Warning)", the fan error signal is output and operation continues. However, when the inverter's internal temperature rises above a certain level, output is blocked due to activation of overheat protection.				

10.2.12 Low Voltage Fault Trip

Group	Code	LCD Display	Parameter Setting		Unit
PRT	81	LVT Delay	-	0.0	sec
OUT	31–32	Relay 1,2	11	Low Voltage	-
OUT	33	Q1 Define			

Low Voltage Fault Trip Setting Details

Code	Description
PRT-81 LVT Delay	When inverter input power is lost and the internal DC link voltage drops below a certain voltage level, the inverter will block the output and a low voltage trip will occur. If the PRT-81 LVT Delay time is set, the inverter blocks output first when a low voltage trip condition arises, then a fault trip will occur after the low voltage trip decision time has passed. The warning signal for a low voltage fault trip can be provided using the multi-function output or a relay. However, the low voltage trip delay time (LVT Delay time) does not apply to warning signals.

Code	Description
	Set to "11 (Low Voltage)". The inverter stops the output first when a low voltage trip condition occurs, then a fault trip occurs after the low voltage trip decision time elapses.

10.2.13 Output Block via the Multi-Function Terminal

Group	Code	LCD Display	Parameter Setting		Setting Range	Unit
IN	65–72	Px Define	5	BX	-	-
PRT	45	BX Mode	-	0.0	0.0–600.0	

Output Block by Multi-function Terminal Setting Details

Code	Description
IN-65–71 Px Define	When the operation of the multi-function input terminal is set to "5 (BX)" and is turned on during operation, the inverter blocks the output and "BX" is displayed on the keypad display. While "BX" is displayed on the keypad, the inverter's operation information including the operation frequency and current at the time of the BX signal can be monitored. The inverter resumes operation when the BX terminal turns off and operation command is input.
PRT-45	The default setting value of BX mode (PRT-45) is 0.0 [sec], and it allows the inverter to operate in free-run mode. If the BX terminal receives input, the inverter will block output immediately. If BX mode (PRT-45) is set to 0.1 [sec], the motor will decelerate by value set at PRT-45. If PRT-45 set value is too small, the inverter cannot decelerate at that value and OVT may occur. Set the PRT45 time according to the inverter capacity and load.

10.2.14 Trip Status Reset

Group	Code	LCD Display	Parameter Setting		Unit
IN	65-72	Px Define	3	RST	-

Trip Status Reset Setting Details

Code	Description
IN-65–72 Px Define	Press the [Stop/Reset] key on the keypad or use the multi-function input terminal to restart the inverter. Set the multi-function input terminal to "3 (RST)" and turn on the terminal to reset the trip status.

10.2.15 Operation Mode On Optional Expansion Module Fault Trip

Optional extension module trips may occur when an optional extension module is used with the inverter. Set the operation mode for the inverter when a communication error occurs between the optional extension module and the inverter body, or when the optional extension module is detached during operation.

Group	Code	LCD Display	Parameter Setting		Unit
PRT	80	Opt Trip Mode	0	None	1:Free-Run
			1	Free-Run	
			2	Dec	

Optional Expansion Module Fault Trip Setting Details

Description					
Set	ting	Function			
0	None	No operation			
1	Free-Run	The inverter output is blocked and fault trip information is shown on the keypad.			
2	Dec	The motor decelerates to the value set at PRT-07 (Trip Dec Time).			
		Setting O None 1 Free-Run			

10.2.16 No Motor Trip

Group	Code No.	LCD Display	Parameter Setting		Setting Range	Unit
PRT	31	No Motor Trip	0	None	-	-
	32	No Motor Level		5	1–100	%
	33	No Motor Time		3.0	0.1–10.0	sec

No Motor Trip Setting Details

Code	Description
PRT-32 No Motor Level, PRT-33 No Motor Time	If the output current value [based on the rated current (BAS-13)] is lower than the value set at PRT-32 (No Motor Level), and if this continues for the time set at PRT-33 (No Motor Time), a "no motor trip" occurs.

① Caution

If BAS-07 (V/F Pattern) is set to "1 (Square)", set PRT-32 (No Motor Level) to a value lower than the factory default. Otherwise, "No Motor Trip" due to a lack of output current will result when the 'No Motor Trip' operation is set.

10.2.17 Low Voltage Fault Trip 2 During Operation

Group	Code	LCD Display	Parameter Setting range		Unit
PRT	82	Low Voltage2	00~11	00 : default	Bit

If input power is disconnected during inverter operation and internal DC voltage decreases lower than a certain voltage, the inverter disconnects the output and displays low voltage "2" on the keypad.

Even if the voltage increases and goes back to the normal state, unlike a low voltage fault, it remains in a fault state until the user unlocks the fault state.

If PRT-82 (LV2 Enable) is set to "01," and if the input power is disconnected during inverter operation and the internal DC voltage drops to lower than a certain voltage, the inverter stops output and displays "Low Voltage2." Unlike the low voltage trip (Low Voltage), the low voltage 2 (Low Voltage2) trip will not be reset even after the internal DC voltage of the inverter has recovered to above the trip level. Therefore, you must reset the inverter to reset the trip. The trip history will not be stored after the reset.

Set PRT-82 (LV2 Enable) to "11" to store the trip history.

Low Voltage 2 Trip Details							
Code	Description						
	Set option	s for Low Voltage2 trip operation.					
	Bit setting	Function					
		Disable Low Voltage2 trip (Low Voltage trip is used).					
PRT-82		Enable Low Voltage2 trip. but do not store the trip history.					
		Disable Low Voltage2 trip (Low Voltage trip is used).					
		Enable Low Voltage2 trip and store the trip history.					

10.3 List of Faults and Warnings

The following list shows the types of faults and warnings that can occur while using the iS7 inverter.

Category		LCD Display	Details	
		Over Current1	Over current trip	
		Over Voltage	Over voltage trip	
		External Trip	Trip due to an external signal	
		NTC Open	Temperature sensor fault trip	
	Latch type	Over Current2	ARM short current fault trip	
		Fuse Open	Fuse open trip	
Major fault		Option Trip-x	Option fault trip	
		Over Heat	Over heat fault trip	
		Out Phase Open	Output open-phase fault trip	
		In Phase Open	Input open-phase fault trip	
		Inverter OLT	Inverter overload fault trip	
		Over Speed	Over speed fault trip	
		Ground Trip	Ground fault trip	

Category		LCD Display	Details	
		Encoder Trip	Speed sensor fault trip	
		Fan Trip	Fan fault trip	
		ParaWrite Trip	Write parameter fault trip	
		E-Thermal	Motor overheat fault trip	
		Thermal Trip	Temperature fault trip	
		Pre-PID Fail	Pre-PID operation fault trip	
		IO Board Trip	IO Board connection fault trip	
		Speed Dev Trip	Trip from speed deviation	
		Ext-Brake	External brake fault trip	
		No Motor Trip	No motor fault trip	
		Low Voltage	Low voltage fault trip	
	Loveltune	BX	Emergency stop fault trip	
	Level type	Lost Command	Command loss trip	
		Lost Keypad	Lost-keypad fault trip	
	Hardware damage	EEP Err	External memory error	
		ADC Off Set	Analog input error	
		Watch Dog-1	CRI I Watch Dog fault trip	
	9-	Watch Dog-2	- CPU Watch Dog fault trip	
		Gate Pwr Loss	DRV operation power error	
		Over Load	Motor overload trip	
Minor fault		Under Load	Motor under load trip	
WIII IOI Tault		Lost Command	Lost command fault trip	
		Lost Keypad	Lost keypad fault trip	
		Lost Command	Command loss fault trip warning	
		Over Load	Overload warning	
Manning		Under Load	Under load warning	
		Inverter OLT	Inverter overload warning	
Warning		Fan Warning	Fan operation warning	
		DB Warn %ED	Braking resistor braking rate warning	
		Enc Conn Check	Enc connection error warning	
		Enc Dir Check	Rotating direction error warning	

Category	LCD Display	Details
	Lost Keypad	Lost keypad warning
	Retry Tr Tune	Rotor time constant tuning error
	Fire Mode	Fire mode warning
	PID Sleep	PID Sleep mode warning
	AUX Power On	AUX Power On warning

11 Communication Function

11.1 Introduction

This chapter explains the standards, installation process, and programs for the SV-iS7 inverter serial communication method when using personal computers or factory automation (FA) computers. The communication function for the SV-iS7 inverter series is designed to remotely operate or monitor the SV-iS7 inverter series using personal computers or FA computers.

Advantages of Operating the Inverter with Network Communication

As the inverter can be operated or monitored by the user programs, it is easy to apply the inverter to factory automation.

Features	Examples of application					
Monitor or modify parameters via computers	 T_acc T_dec Frequency Lost command 					
Interface configuration for RS-485 standard	 Performs communication between the inverter and computers produced by numerous companies. Controls up to 16 inverters at a time with one computer using the multi-drop link system. Provides an interface for noise immunity environments. 					

Inverters can communicate with computers embedded with the RS-232 module via RS-232/485 converters. The standards and performance of converters may vary depending on the manufacturer, but the basic functions are the same. For more details about standards and guidelines, users are advised to consult the manual provided by the specific manufacturer.

① Caution

Read this manual carefully before installation and operation. All instructions in this manual must be followed to avoid injury or prevent damage to other components.

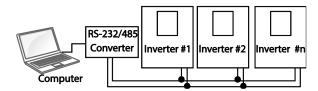
11.2 Specifications

Category	Specifications		
Communication method	RS-485		
Transfer form	Bus type, Multi-drop link system		
Inverter type name	SV-iS7 series		
Converter	Embedded with RS-232		
Number of connected inverters	Maximum of 16		
Transfer distance	Maximum 1,200 m (recommended distance: within 700 m)		
Recommended cable size	0.75 mm2 , (18AWG), Shielded twisted-pair (STP) wire		
Installation type	Dedicated terminals (S+/S-/SG) on the control terminal block		
Communication Power	Supplied by the inverter - insulated power source from the inverter's internal circuit communication power (supplied from the inverter)		
Communication Speed	1,200/2,400/9,600/19,200/38,400 bps		
Control procedure	Asynchronous communications system		
Communication system	Half duplex system		
Letter system	Modbus-RTU: BINARY/LS Bus: ASCII		
Stop bit length	1-bit/2-bit		
Sum check	2 byte		
Parity check	None/Even/Odd		

11.3 Communication System Configuration

In an RS-485 communication system, the PLC or computer is the master device and the inverter is the slave device. When using a computer as the master, the RS-232 converter must be integrated with the computer, so that it can communicate with the inverter through the RS-232/RS-485 converter. Specifications and performance of converters may vary depending on the manufacturer, but the basic functions are identical. Please refer to the converter manufacturer's user manual for details about features and specifications.

Connect the wires and configure the communication parameters on the inverter by referring to the following illustration of the communication system configuration.



- RS-485 terminal connection: Connect the RS-485 communication line to the S+/S-/SG terminals.
- Number of connectable inverters: Up to 16 inverters
- Number of extendable addresses (St ID): 1-250 addresses
- Length of effective communication lines: 1,200 m max. Keep it below 700 m for stable communication.

Caution

When wiring the communication line, make sure that the SG terminals on the PLC and inverter are connected. SG terminals prevent communication errors due to electronic noise interference.

Use a communication repeater to enhance the communication speed if you have to use a communication cable above 1,200 m, or to connect an additional inverter. A repeater is effective when smooth communication is not available due to noise interference.

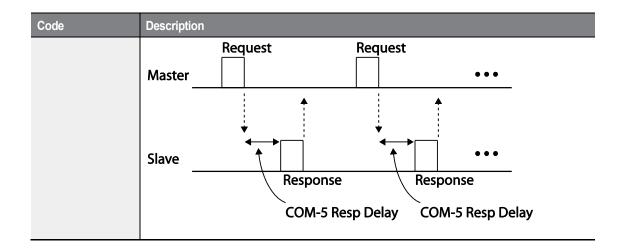
11.4 Basic Settings

Before proceeding with setting communication configurations, make sure that the communication lines are connected properly. Turn on the inverter and set the communication parameters.

Group	Code	LCD Display	Parameter Setting		Setting Range	Unit
СОМ	01	Int485 St ID	-	1	1–250	-
	02	Int485 Proto	0	ModBus RTU	0–3	-
	03	Int485 BaudR	3	9600	0–5	bps
	04	Int485 Mode	0	D8/PN/S1	0–3	-
	05	Resp Delay	-	5	0–1000	ms

Communication Parameters Setting Details

Code	Descrip	tion			
COM-01 Int485 St ID	Sets the	e inverter station	ID betw	een 1 and 250.	
	Select	one of the two bu	ilt-in pro	tocols: Modbus-RTU and LS INV 485	
COM-02 Int485	Setting			Function	
Proto	0	Modbus-RTU		Modbus-RTU compatible protocol	
1 1010	1	Reserved		Not used	
	2	LS INV 485		Dedicated protocol for the LS inverter	
COM-03 Int485 BaudR	Sets a communication setting speed of up to 38,400 bps.				
	the nun	nber of stop bits.	nfigurat	ion. Set the data length, parity check method, and	
COM-04 Int485	Setting 0	D8/PN/S1		data / no parity check / 1 stop bit	
Mode	1	D8/PN/S2		data / no parity check / 1 stop bits	
	2	D8/PE/S1		data / even parity / 1 stop bit	
	3	D8/PO/S1	8-bit data / odd parity / 1 stop bit		
			1		
COM-05 Resp Delay		The slave iS7 res		(Modbus-RTU or LS INV 485) device performs as a or the master after the period of time set in this	



11.5 Setting Operation Command and Frequency

After setting the DRV-06 (Cmd Source) to "3 (Int 485)" and DRV-07 (Freq Ref Src) to "7 (Int 485)," you can set common area parameters for the operation command and frequency via communication.

Group	Code	LCD Display	Parameter Setting		Unit
DD\/	06	Cmd Source	3	Int 485	-
DRV	07	Freq Ref Src	7	Int 485	-

11.6 Command Loss Protection

Configure the command loss decision standards and protective operations run when a communication problem lasts for a specified period of time.

Group	Code	LCD Display	Parameter Setting		Unit
	12	Lost Cmd Mode	1	Free-Run	-
PRT	13	Lost Cmd Time	-	1.0	Sec
	14	Lost Preset F	-	0.00	Hz
OUT	31–33	Relay1,2, Q1	12	Lost Command	-

Command Loss Protective Operation Setting Details

Code	Desc	Description					
		Select the operation to run when a communication error has occurred and lasted exceeding the time set at PRT-13.					
	Setti	ng	Function				
	0	None	The speed command immediately becomes the operation frequency without any protection function.				
	1	Free-Run	The inverter blocks output. The motor performs in free- run condition.				
DDT 12 Lost Cmd	2	Dec	The motor decelerates and then stops.				
PRT-12 Lost Cmd Mode, PRT-13 Lost Cmd Time	3 Hold Input		Operates continuously with the speed of the inputted speed command until the loss of the speed command. The inverter calculates the average input value for 10 seconds before the loss of the speed command and uses it as the speed reference.				
	4	Hold Output	Operates continuously with the operate frequency before the speed loss. The inverter calculates the average output value for 10 seconds before the loss of the speed command and uses it as the speed reference.				
	5	Lost Preset	The inverter operates at the frequency set at PRT-14 (Lost Preset F).				
PRT-14 Lost Preset F	Set the Lost Preset frequency that will be applied if PRT-12 (Lost Cmd Mode) is set to "5 (Lost Preset)."						

Caution) If PRT-13 (Lost Cmd Time) is set to "0.0" (sec), protection features may be activated even during a normal operation, depending on the type of command source. To prevent this, appropriately set the lost command decision time.

11.7 Setting Virtual Multi-Function inputs

Multi-function input can be controlled using a communication address (0h0385). Set codes COM-70–85 to the functions to operate, and then set the BIT relevant to the function to 1 at 0h0385 to operate it.

Group	Code	LCD Display	Parameter Setting		Unit
COM	70-85	Virtual DI x	0	None	-
COIVI	86	Virt DI Status	-	-	-

For example, if you want to send an Fx command by controlling a virtual multi-function input command addresses with Int485, the Fx function is performed if 0h0001 is input in 0h0385 after COM-70 (Virtual DI 1) is set to "FX". Before you configure the virtual multi-function inputs, set the DRV-06 (CMD source) depending on the command source.

Virtual multi-function operates independently from the analog multi-function inputs and cannot be set redundantly. Virtual multi-function input can be monitored using COM-86 (Virt DI Status).

11.8 Saving Parameters Defined by Communication

If you turn off the inverter after setting the common area parameters or keypad parameters via communication and operate the inverter, the changes are lost and the values changed via communication revert to the previous setting values when you turn on the inverter.

Set CNF-48 to "1 (Yes)" to allow all the changes over communication to be saved, so that the inverter retains all the existing values even after the power has been turned off.

Setting address 0h03E0 to "0" and then setting it again to "1" via communication allows the existing parameter settings to be saved. However, setting address 0h03E0 to "1" and then setting it to "0" does not carry out the same function.

Before reading the parameters utilizing CNF-46 (Parameter Read), make sure to save the parameter changes (Parameter Save) to read the parameter values reflecting the changes in the communication module parameters.

Group	Code	LCD Display	Setting Display		Unit
CNIE 40	40	Darameter Cave	0	-No-	-
CINE	CNF 48 Parameter Save	1	-Yes-	-	

11.9 Communication Frame Monitoring

You can easily monitor the status (normal, CRC/Checksum error, other errors, etc.) of the communication frame being received from the master by using the keypad.

Group	Code	LCD Display	Setting D	isplay	Unit
	90	Comm Mon Sel	0	Int 485	-
	91	Rcv Frame Num	-	-	-
COM	92	Err Frame Num	-	-	-
COM	93	NAK Frame Num Comm Update	-	-	-
	94		0	-No-	
			1	-Yes-	-

Communication Frame Monitoring Details

Code	Description		
COM-90 Comm Mon Sel	Selects the communication channel to monitor.		
COM-91 Rcv Frame Num	Counts the number of communication frames received normally from the master device.		
COM-92 Err Frame Num	Counts the number of CRC errors when the Modbus-RTU is set and counts Checksum errors when the LS Inv 485 is set.		
COM-93 NAK Frame Num	Counts the number of errors (communication address errors, data range errors, writing prohibition errors) that occur in the communication frames received from the master device.		
COM-94 Comm Update	Reconnects the communication after the initial status parameter is changed to communication speed (baud rate), etc.		

11.10Special communication Area Settings

The following table lists the memory map of the entire memory addresses used for network communication in the iS7 series inverters.

Communication Area	Memory Map	Description
Common iS5 compatible communication area	0h0000 - 0h00FF	Area compatible with iS5
Parameter registration type area	0h0100 - 0h01FF	Area registered in COM31~46, COM51~66

Communication Area	Memory Map	Description	
	0h0200 - 0h023F	Area registered in User Group	
	0h0240 - 0h027F	Area registered in Macro Group	
	0h0280 - 0h02FF	Reserved	
	0h0300 - 0h037F	Inverter monitoring area	
	0h0380 - 0h03DF	Inverter control area	
	0h03E0 - 0h03FF	Inverter memory control area	
	0h0400 - 0h0FFF	Reserved	
	0h1100	DRV Grp	
	0h1200	BAS Grp	
	0h1300	ADV Grp	
Common iS7 communication area	0h1400	CON Grp	
	0h1500	IN Grp	
	0h1600	OUT Grp	
	0h1700	COM Grp	
	0h1800	APP Grp	
	0h1A00	APO Grp	
	0h1B00	PRT Grp	
	0h1C00	M2 Grp	

11.11Parameter Group for Periodical Data Transmission

By defining a parameter group for data transmission, the communication addresses registered in the communication function group (CM) can be used in communication. Parameter groups for data transmission may be defined to simultaneously transmit multiple parameters into the communication frame.

Group	Code No.	Function Display	Settir	ng Display	Unit
СОМ	31–46	Para Status-h	-	-	Hex
	51–66	Para Control-h	-	-	Hex

Parameter Group for Periodical Data Transmission Details

Addresses	Description					
	Reads the para	ameter registered in COM-	31~46 Status Para-h (read only).			
	Address	Parameter	Allotment for Bits			
	0h0100	Status Parameter #1	Parameter value registered at COM-31			
	0h0101	Status Parameter #2	Parameter value registered at COM-32			
	0h0102	Status Parameter #3	Parameter value registered at COM-33			
	0h0103	Status Parameter #4	Parameter value registered at COM-34			
	0h0104	Status Parameter #5	Parameter value registered at COM-35			
	0h0105	Status Parameter #6	Parameter value registered at COM-36			
	0h0106	Status Parameter #7	Parameter value registered at COM-37			
0h0100-0h010F	0h0107	Status Parameter #8	Parameter value registered at COM-38			
	0h0108	Status Parameter #9	Parameter value registered at COM-39			
	0h0109	Status Parameter #10	Parameter value registered at COM-40			
	0h010A	Status Parameter #11	Parameter value registered at COM-41			
	0h010B	Status Parameter #12	Parameter value registered at COM-42			
	0h010C	Status Parameter #13	Parameter value registered at COM-43			
	0h010D Status Parameter #14		Parameter value registered at COM-44			
	0h010E	Status Parameter #15	Parameter value registered at COM-45			
	0h010F	Status Parameter #16	Parameter value registered at COM-46			
	Reads and writes the parameter registered in COM-51~66 Control Para-h (both read and write.					
	Address	Parameter	Allotment for Bits			
	0h0110	Control Parameter #1	Parameter value registered at COM-51			
	0h0111	Control Parameter #2	Parameter value registered at COM-52			
	0h0112	Control Parameter #3	Parameter value registered at COM-53			
	0h0113	Control Parameter #4	Parameter value registered at COM-54			
	0h0114	Control Parameter #5	Parameter value registered at COM-55			
	0h0115	Control Parameter #6	Parameter value registered at COM-56			
0h0110-0h011F	0h0116	Control Parameter #7	Parameter value registered at COM-57			
	0h0117	Control Parameter #8	Parameter value registered at COM-58			
	0h0118	Control Parameter #9	Parameter value registered at COM-59			
	0h0119	Control Parameter #10	Parameter value registered at COM-60			
	0h011A	Control Parameter #11	Parameter value registered at COM-61			
	0h011B	Control Parameter #12	Parameter value registered at COM-62			
	0h011C	Control Parameter #13	Parameter value registered at COM-63			
	0h011D	Control Parameter #14	Parameter value registered at COM-64			
	0h011E	Control Parameter #15	Parameter value registered at COM-65			
	0h011F	Control Parameter #16	Parameter value registered at COM-66			

① Caution

When registering control parameters, register the operation speed (0h0005, 0h0380, 0h0381) and operation command (0h0006, 0h0382) parameters at the end of a parameter control frame. For example, when the parameter control frame has 5 parameter control items (Para Control - x), register the operation speed at Para Control-4 and the operation command to Para Control-5.

11.12Parameter Group for Transmission of Macro Group and User Group at U&M Mode

By defining the user and macro parameter groups, communication can be carried out using the user defined user group (USR) and macro group (MAC) addresses that are registered in U&M mode.

Addresses	Description		
U&M>USR-1–64 User Grp. Para h	Writes and reads the USR parameters set by the keypad via the addresses 0h0200–0h023F.		
	Address	Parameter	Allotment for Bits
	0h0200	User Grp. Code 1	Parameter value registered at U&M>USR->1
	0h0201	User Grp. Code 2	Parameter value registered at U&M>USR->2
	0h023E	User Grp. Code 63	Parameter value registered at U&M>USR->63
	0h023F	User Grp. Code 64	Parameter value registered at U&M>USR->64
U&M>MAC-1–64 Macro Grp. Para h	Writes and reads the Macro parameters set by the keypad via the addresses 0h2400–0h2A3.		
	Address	Parameter	Allotment for Bits
	0h0240	Macro Grp. Code 1	Parameter value registered at U&M>MAC-1
	0h0241	Macro Grp. Code 2	Parameter value registered at U&M>MAC-2
	0h02A2	Macro Grp. Code 63	Parameter value registered at U&M>MAC-63
	0h02A3	Macro Grp. Code 64	Parameter value registered at U&M>MAC-64

11.13Communication Protocol

LS INV 485 Protocol 11.13.1

The slave device (inverter) responds to read and write requests from the master device (PLC or PC).

Request

ENQ	Station ID	CMD	Data	SUM	EOT
1 byte	2 bytes	1 byte	n bytes	2 bytes	1 byte

Normal Response

ACK	Station ID	CMD	Data	SUM	EOT
1 byte	2 bytes	1 byte	n x 4 bytes	2 bytes	1 byte

Error Response

NAK	Station ID	CMD	Error code	SUM	EOT
1 byte	2 bytes	1 byte	2 bytes	2 bytes	1 byte

- A request starts with ENQ and ends with EOT.
- A normal response starts with ACK and ends with EOT.
- An error response starts with NAK and ends with EOT.
- A station ID indicates the inverter number and is displayed as a two-byte ASCII-HEX string that uses characters 0-9 and A-F.
- CMD: Uses uppercase characters (returns an IF error if lowercase characters are encountered).

Character	ASCII-HEX	Command
'R'	52h	Read
'W'	57h	Write
'X'	58h	Request monitor registration
'Y'	59h	Perform monitor registration

- Data: ASCII-HEX (for example, when the data value is 3000: $3000 \rightarrow 60^{\circ}B^{\circ}B^{\circ}8^{\circ}h \rightarrow 30h$ 42h 42h
- Error code: ASCII-HEX (20h-7Fh)
- Transmission/reception buffer size: Transmission=39 bytes, Reception=44 bytes
- Monitor registration buffer: 8 Words
- SUM: Checks communication errors via sum.
- SUM=a total of the lower 8 bits values for station ID, command and data (Station ID+CMD+Data) in ASCII-HEX.
- For example, a command to read 1 address from address 3000: SUM='0'+'1'+'R'+'3'+'0'+'0'+'0'+'1'=30h+31h+52h+33h+30h+30h+31h=1A7h (the control value is not included: ENQ, ACK, NAK, etc.

ENQ	Station ID	CMD	Address	Number of Addresses	SUM	ЕОТ
05h	'01'	'R'	'3000'	'1'	'A7'	04h
1 byte	2 bytes	1 byte	4 bytes	1 byte	2 bytes	1 byte

Note

Broadcasting

Broadcasting sends commands to all inverters connected to the network simultaneously. When commands are sent from station ID 255, each inverter acts on the command regardless of the station ID. However no response is issued for commands transmitted by broadcasting.

Error operation

For two or more data communications, when an error occurs as a result of the previous data communication, the current data communication can be made normally regardless of the error occurred as a result of the previous data communication.

11.13.1.1 Detailed Read Protocol

Read Request

Reads successive n words from address XXXX.

ENQ	Station ID	CMD	Address	Number of Addresses	SUM	EOT
05h	'01'–'1F'	'R'	'XXXX'	'1'–'8' = n	'XX'	04h
1 byte	2 bytes	1 byte	4 bytes	1 byte	2 bytes	1 byte

Total bytes=12. Characters are displayed inside single quotation marks(').

Read Normal Response

ACK	Station ID	CMD	Data	SUM	EOT
06h	'01'–'1F'	'R'	'XXXX'	'XX'	04h
1 byte	2 bytes	1 byte	n x 4 bytes	2 bytes	1 byte

Total bytes= (7 x n x 4): a maximum of 39

Read Error Response

NAK	Station ID	CMD	Error code	SUM	EOT
15h	'01'-'1F'	'R'	·** ¹	'XX'	04h

NAK	Station ID	CMD	Error code	SUM	EOT
1 byte	2 bytes	1 byte	2 bytes	2 bytes	1 byte

Total bytes=9

11.13.1.2 Detailed Write Protocol

Write Request

ENQ	Station ID	CMD	Address	Number of Addresses	Data	SUM	EOT
05h	'01'–'1F'	'W'	'XXXX'	'1'–'8' = n	'XXXX'	'XX'	04h
1 byte	2 bytes	1 byte	4 bytes	1 byte	n x 4 bytes	2 bytes	1 byte

Total bytes= $(12 + n \times 4)$: a maximum of 44

Write Normal Response

ACK	Station ID	CMD	Data	SUM	EOT
06h	'01'–'1F'	'W'	'XXXX'	'XX'	04h
1 byte	2 bytes	1 byte	n x 4 bytes	2 bytes	1 byte

Total bytes= $(7 + n \times 4)$: a maximum of 39

Write Error Response

NAK	Station ID	CMD	Error Code	SUM	EOT
15h	'01'–'1F'	'W'	·**	'XX'	04h
1 byte	2 bytes	1 byte	2 bytes	2 bytes	1 byte

Total bytes=9

11.13.1.3 Monitor Registration Detailed Protocol

Monitor registration request is made to designate the type of data that requires continuous monitoring and periodic updating.

Monitor Registration Request

Registration requests for *n* addresses (where *n* refers to the number of addresses. The addresses do not have to be contiguous.)

ENQ	Station ID	CMD	Number of Addresses	Address	SUM	EOT
05h	'01'–'1F'	'X'	'1'–'8'=n	'XXXX'	'XX'	04h
1 byte	2 bytes	1 byte	1 byte	n x 4 bytes	2 bytes	1 byte

Total bytes= (8 + n x 4): a maximum of 40

Monitor Registration Normal Response

ACK	Station ID	CMD	SUM	ЕОТ
06h	'01'–'1F'	'X'	'XX'	04h
1 byte	2 bytes	1 byte	2 bytes	1 byte

Total bytes=7

Monitor Registration Error Response

NAK	Station ID	CMD	Error Code	SUM	EOT
15h	'01'–'1F'	'X'	·** ¹	'XX'	04h
1 byte	2 bytes	1 byte	2 bytes	2 bytes	1 byte

Total bytes=9

11.13.1.4 Monitor Execution Detailed Protocol

Monitor Registration Execution Request

A data read request for a registered address, received from a monitor registration request

ENQ	Station ID	CMD	SUM	EOT
05h	'01'–'1F'	Ύ	'XX'	04h

ENQ	Station ID	CMD	SUM	EOT
1 byte	2 bytes	1 byte	2 bytes	1 byte

Total bytes=7

Monitor Registration Execution Normal Response

ACK	Station ID	CMD	Data	SUM	EOT
06h	'01'–'1F'	Ϋ́	'XXXX'	'XX'	04h
1 byte	2 bytes	1 byte	n x 4 bytes	2 bytes	1 byte

Total bytes= $(7 + n \times 4)$: a maximum of 39

Monitor Registration Execution Error Response

NAK	Station ID	CMD	Error Code	SUM	EOT
15h	'01'–'1F'	Υ	(** ¹	'XX'	04h
1 byte	2 bytes	1 byte	2 bytes	2 bytes	1 byte

Total bytes=9

11.13.1.5 Error Code

Code	Abbreviation	Description
01: ILLEGAL FUNCTION	IF	The requested function cannot be performed by a slave because the corresponding function does not exist.
02: ILLEGAL DATA ADDRESS	IA	The received parameter address is invalid at the slave.
03: ILLEGAL DATA VALUE	ID	The received parameter data is invalid at the slave.
21: WRITE MODE ERROR	WM	Tried writing (W) to a parameter that does not allow writing (read-only parameters, or when writing is prohibited during operation)
22: FRAME ERROR	FE	The frame size does not match.

11.13.2 Modbus-RTU protocol

11.13.2.1 Function Code and Protocol (unit: byte)

Function Code #03 (Read Holding Register)

<Query>

<Response>

Field Name	Field Name	
Slave Address	Slave Address	
Function	Function	
Starting Address Hi	Byte Count	
Starting Address Lo	Data Hi (Register 40108)	
# of Points Hi	Data Lo (Register 40108)	
# of Points Lo	Data Hi (Register 40109)	
CRC Lo	Data Lo (Register 40109)	
CRC Hi	Data Hi (Register 40110)	
	Data Lo (Register 40110)	
	CRC Lo	
	CRC Hi	

Function Code #04 (Read Input Register)

<Query>

Field Name
Slave Address
Function
Starting Address Hi
Starting Address Lo
of Points Hi
of Points Lo
CRC Lo
CRC Hi

<Response>

Field Name
Slave Address
Function
Byte Count
Data Hi (Register 30009)
Data Lo (Register 30009)
CRC Lo
CRC Hi

Function Code #06 (Preset Single Register)

<Query>

<Response>

Field Name
Slave Address
Function
Register Address Hi
Register Address Lo
Preset Data Hi
Preset Data Lo
CRC Lo
CRC Hi

Field Name
Slave Address
Function
Register Address Hi
Register Address Lo
Preset Data Hi
Preset Data Lo
CRC Lo
CRC Hi
-

Function Code #16 (hex 0x10) (Preset Multiple Register)

<Query>

<Response>

Field Name
Slave Address
Function
Starting Address Hi
Starting Address Lo
of Register Hi
of Register Lo
Byte Count
Data Hi
Data Lo
Data Hi
Data Lo
CRC Lo
CRC Hi

· .
Field Name
Slave Address
Function
Starting Address Hi
Starting Address Lo
of Register Hi
of Register Lo
CRC Lo
CRC Hi

<Exception Code>

Code	
01:ILLEGAL FUNCTION	
02:ILLEGAL DATA ADDRESS	
03: ILLEGAL DATA VALUE	
06: SLAVE DEVICE BUSY	

<Response>

Field Name

Slave Address

Field Name	
Function*	
Exception Code	
CRC Lo	
CRC Hi	

^{*} Function value is the set value of the highest bit of the query function value.

11.13.3 iS7/iS5/iG5/iG5A Compatible Common Area Parameter

Address	Parameter	Scale	nit	R/W	Assigned content by bit		
0h0000	Inverter model	-	-	R	B: iS7		
					0: 0.75 kW 1: 1.5 kW 2: 2.2 kW		
					3: 3.7 kW 4: 5.5 kW 5: 7.5 kW		
					6: 11 kW 7: 15 kW 8: 18.5 kW		
050001	Investor conscitu			R	9: 22 kW 10: 30 kW 11: 37 kW		
0h0001	Inverter capacity	-	-	K	12: 45 kW 13: 55 kW 14: 75 kW		
					15: 90 kW 16: 110 kW 17: 132 kW		
					18: 160 kW 19: 200 kW 20: 220 kW		
					21: 280 kW 22: 375 kW 65535: 0.4 kW		
0h0002	Inverter input	_	_	R	0: 220 V class		
0110002	voltage	-	-	T.	1: 400 V class		
050000	Version			R	Ex.) 0x0100: Version 1.00		
0h0003		-	-	K	0x0101: Version 1.01		
0h0004	Reserved	-	-	R/W	-		
0h0005	Command frequency	0.01	Hz	RW	-		
					B15 Reserved		
					B14 0: Keypad Freq 1: Keypad Torq		
					B13 2-16: Terminal block Multi-step speed 17: Up 18: Down 19: STEADY		
	Operating				B12 20: AUTO-A 21: AUTO-B 22: V1		
	command (option)				B11 23: l1 24: V2 25: l2		
0h0006	* Refer to	-	-	R	B10 26: Reserved 27: Built-in485		
	additional				28: Communication option B9 29: PLC option 30: JOG 31: PID		
	description				Do		
					0: Keypad 1: FX/RX-1 2: FX/RX-2 B7 3: Built-in 485 4: Communication option		
					B6 5: PLC option		

Address	Parameter	Scale	nit	R/W	Assigned content by bit			
					B5	Reserved		
					B4	Emergency stop		
				DA4/	В3	W: Trip reset (0 ->1) R: Trip status		
				R/W	B2	Reverse operation (R)		
					B1	Forward operation (F)		
					В0	Stop (S)		
0h0007	Acceleration time	0.1	sec	R/W	-			
0h0008	Deceleration time	0.1	sec	R/W	-			
0h0009	Output current	0.1	Α	R	-			
0h000A	Output frequency	0.01	Hz	R	-			
0h000B	Output voltage	1	V	R	-			
0h000C	DC Link voltage	1	V	R	-			
0h000D	Output power	0.1	kW	R	-			
	Operation status				B15	0: Remote, 1: Keypad Local		
		-			B14	1: Frequency command by comm. (Built-in type, Option)		
					B13	1: Run command by comm. (Built-in type, Option)		
					B12	Reverse direction run command		
					B11	Forward direction run command		
					B10	Brake open signal		
					B9	Jog mode		
05000			-		B8	Stopping		
0h000E				-	B7	DC Braking		
					B6	Speed reached		
					B5	Decelerating		
					B4	Accelerating		
					ВЗ	Operates depending on the set value of Fault (Trip) *OUT-30 Trip Out Mode		
					B2	Reverse operation		
					B1	Forward operation		
					В0	Stopped		
					B15	Reserved		
			-		B14	Reserved		
0h000F	Fault trip information	-		R	B13	Reserved		
	IIIIOIIIIauUII				B12	Reserved		
					B11	Reserved		

Address	Parameter	Scale	nit	R/W	Assig	ned content by bit
					B10	H/W-Diag
					В9	Reserved
					B8	Reserved
					B7	Reserved
					B6	Reserved
					B5	Reserved
					B4	Reserved
					В3	Level Type Trip
					B2	Reserved
					B1	Reserved
					B0	Latch Type Trip
					B15	Reserved
					B14	Reserved
					B13	Reserved
					B12	Reserved
					B11	Reserved
		-			B10	P11 (I/O expansion)
					B9	P10 (I/O expansion)
0h0010	Input terminal information		_	R	B8	P9 (I/O expansion)
0110010					B7	P8
					B6	P7
					B5	P6
					B4	P5
					B3	P4
					B2	P3
					B1	P2
					B0	P1
					B15	Reserved
		-	-		B14	Reserved
					B13	Reserved
	0				B12	Reserved
0h0011	Output terminal information			R	B11	Reserved
					B10	Reserved
					B9	Reserved
					B8	Reserved
					B7	Reserved

Address	Parameter	Scale	nit	R/W	Assig	ned content by bit
					В6	Reserved
					B5	Relay 5 (I/O expansion)
					B4	Relay 4 (I/O expansion)
					В3	Relay 3(I/O expansion)
					B2	Q1
					B1	Relay 2
					B0	Relay 1
0h0012	V1	0.01	%	R	V1 vc	oltage input
0h0013	V2	0.01	%	R	V2 vc	oltage input (expansion I/O)
0h0014	l1	0.01	%	R	I1 cur	rent input
0h0015	Motor rotation speed	1	rpm	R	Curre	ent motor rotation speed displayed
0h0016 -0h0019	Reserved	-	-	-	-	
0h001A	Hz/rpm selection	-	-	R	0: Hz 1: rpn	unit n unit
0h001B	Motor poles displayed	-	_	R	Motor	r poles displayed

11.13.4 Expansion Common Area Parameter

11.13.4.1 Inverter Monitoring Area Parameter (Read only)

Address	Parameter	Scal e	unit	Assigned content by bit		
0h0300	Inverter model	-	-	iS7: 000Bh		
				0.75 kW: 3200h		
0h0301	Inverter capacity	-	-	1.5 kW: 4015h, 2.2 kW: 4022h, 3.7kW: 4037h, 5.5 kW: 4055h, 7.5 kW: 4075h, 11 kW: 40B0h 15 kW: 40F0h, 18.5 kW: 4125h, 22 kW: 4160h, 30 kW: 41E0h, 37 kW: 4250h, 45 kW: 42D0h 55 kW: 4370h, 75 kW: 44B0h, 90 kW: 45A0h 110 kW: 46E0h, 132 kW: 4840h, 160 kW: 4A00h 185 kW: 4B90h		
				200 V single phase open air cooling: 0220h		
				200 V 3 phase open air cooling: 0230h		
				200 V single phase forced cooling: 0221h		
0h0302	Inverter input voltage / power supply type	_		200 V 3 phase forced cooling: 0231h		
0110302	(single phase, 3 phase) / cooling method		_	400 V single open air cooling: 0420h		
				400 V 3 phase open air cooling: 0430h		
				400 V single phase forced cooling: 0421h		
				400 V 3 phase forced cooling: 0431h		
0h0303				Ex.) 0x0100: Version 1.00		
0110303	inverter 3/VV version	_	_	0x0101: Version 1.01		
0h0304	Reserved	-	-	-		
				B15		
				B14 0000(0): Normal status 0100(4): Warning status		
				B13 1000(8): Fault status (operates according to set value of OUT-30 Trip Out Mode)		
0h0305	Inverter energting status			B12		
0110303	Inverter operating status	-	-	B11		
				B10		
				В9		
				B8		

Address	Parameter	Scal e	unit	Assig	ned content by bit
				B7	0001(1): Speed search 0010(2): Accelerating
				B6	0011(3): Steady speed
				B5	0100(4): Decelerating 0101(5): Decelerating stop
				B4	0110(6): H/W OCS 0111(7): S/W OCS 1000(8): Dwell operating
				В3	•
				B2	0000(0): Stop 0001(1): Forward operating
				B1	0010(2): Reverse operating
				В0	— 0011(3): DC operating (0 speed control)
_				B15	
				B14	Run command source
	Inverter run frequency command source			B13	0000000(0):Keypad 00000001(1):Communication option
				B12	00000010(2):App/PLC
				B11	
				B10	00000101(5):reserved 00000110(6):Auto 1 00000111(7):Auto 2
				В9	
				B8	
0h0306		_	-	В7	Frequency command source
				B6	0000000(0):Keypad speed
				B5	00000001(1):Keypad torque 00000010~00000100(2~4):Up/Down run
				B4	speed 00000101(5): V1 00000110(6): I1
				В3	00000111(7): V2 00001000(8): I2
				B2	00001001(9): Pulse 00001010(10):Bulit-in 485
				B1	00001011(11):Comm option 00001100(12): App(PLC)
				В0	00001101(13): Jog 00001110(14): PID 00001111~00010110(15~22) : Auto Step 00011001~00100111(25~39) : Multi-step speed frequency
0h0307	Keypad S/W version	-	-	Ex.)	0x0100: Version 1.00
0h0308	Keypad Title version	-	-		0x0101: Version 1.01
0h0309 - 0h30F	Reserved	-	-	-	

Address	Parameter	Scal e	unit	Assigne	ed content by bit
0h0310	Output current	0.1	Α	-	
0h0311	Output frequency	0.01	Hz	-	
0h0312	Output RPM	0	RPM	-	
0h0313	Motor feedback speed	0	RPM	-32768	rpm - 32767rpm (Having a polarity.)
0h0314	Output voltage	1	V	-	
0h0315	DC Link voltage	1	V	-	
0h0316	Output power	0.1	kW	-	
0h0317	Output torque	0.1	%	Excepti	ion: It is not calculated during V/F control.
0h0318	PID reference	0.1	%	-	
0h0319	PID feedback	0.1	%	-	
0h031A	Number of No.1 motor display	-	-	Numbe	er of No.1 motor display
0h031B	Number of No.2 motor display	-	-	Numbe	er of No.2 motor display
0h031C	Number of selected motor display	-	-	Numbe	er of selected motor display
0h031D	Selection among Hz/rpm	-	-	0: Hz u 1: rpm ı	
0h031E -0h031F	Reserved	-	-	-	
				B15	Reserved
				B14	Reserved
				B13	Reserved
				B12	Reserved
				B11	Reserved
				B10	P11 (I/O expansion)
0h0320	Digital input information	-	-	В9	P10 (I/O expansion)
				B8	P9 (I/O expansion)
				B7	P8 (Basic I/O)
				B6	P7 (Basic I/O)
				B5	P6 (Basic I/O)
				B4	P5 (Basic I/O)
				В3	P4 (Basic I/O)

Address	Parameter	Scal e	unit	Assigne	ed content by bit
				B2	P3 (Basic I/O)
				B1	P2 (Basic I/O)
				B0	P1 (Basic I/O)
				B15	Reserved
				B14	Reserved
				B2 P3 (Basic I/O) B1 P2 (Basic I/O) B0 P1 (Basic I/O) B15 Reserved B14 Reserved B13 Reserved B11 Reserved B10 Reserved B9 Reserved B9 Reserved B7 Reserved B6 Reserved B7 Reserved B6 Reserved B7 Relay 5 (I/O expansion B4 Relay 4 (I/O expansion B4 Relay 3 (I/O expansion B7 Relay 3 (I/O expansion B8 Relay 1 (Basic I/O) B1 Relay 1 (Basic I/O) B1 Virtual DI 16 (COM85) B14 Virtual DI 15 (COM84) B13 Virtual DI 14 (COM83) B12 Virtual DI 13 (COM82) B11 Virtual DI 12 (COM81) B10 Virtual DI 11 (COM80)	Reserved
				B12	Reserved
				B11	Reserved
				B10	Reserved
				B9	Reserved
0h0321	Digital output information			B8	Reserved
0110321	Digital output information	-	-	B7	Reserved
				B6	Reserved
		B2 P3 (Basic I/O)	Relay 5 (I/O expansion)		
			Relay 4 (I/O expansion)		
			Relay 3 (I/O expansion)		
				B1 P2 (Basic I/O) B0 P1 (Basic I/O) B15 Reserved B14 Reserved B13 Reserved B11 Reserved B10 Reserved B9 Reserved B8 Reserved B7 Reserved B6 Reserved B6 Reserved B7 Relay 5 (I/O expansion) B4 Relay 4 (I/O expansion) B4 Relay 2 (Basic I/O) B1 Relay 2 (Basic I/O) B1 Relay 1 (Basic I/O) B1 Virtual DI 16 (COM85) B14 Virtual DI 15 (COM84) B13 Virtual DI 13 (COM82) B11 Virtual DI 11 (COM80) B9 Virtual DI 10 (COM79) B8 Virtual DI 9 (COM78) B7 Virtual DI 9 (COM77)	Q1 (Basic I/O)
				B1	Relay 2 (Basic I/O)
				В0	Relay 1 (Basic I/O)
				B15	Virtual DI 16 (COM85)
				B14	Virtual DI 15 (COM84)
			B2	Virtual DI 14 (COM83)	
				Virtual DI 13 (COM82)	
05000	Virtual digital input			B11	Virtual DI 12 (COM81)
0h0322	information	-	-	B10	Virtual DI 11 (COM80)
				В9	Virtual DI 10 (COM79)
				B1 P2 (Basic I/O) B0 P1 (Basic I/O) B15 Reserved B14 Reserved B13 Reserved B12 Reserved B10 Reserved B9 Reserved B8 Reserved B8 Reserved B7 Reserved B6 Reserved B6 Reserved B7 Relay 5 (I/O expansion) B4 Relay 4 (I/O expansion) B4 Relay 2 (Basic I/O) B1 Relay 2 (Basic I/O) B0 Relay 1 (Basic I/O) B1 Virtual DI 16 (COM85) B14 Virtual DI 15 (COM84) B13 Virtual DI 13 (COM82) B11 Virtual DI 12 (COM81) B10 Virtual DI 10 (COM79) B8 Virtual DI 9 (COM78) B7 Virtual DI 9 (COM77)	Virtual DI 9 (COM78)
			B14 Reserved B13 Reserved B12 Reserved B11 Reserved B10 Reserved B9 Reserved B8 Reserved B6 Reserved B5 Relay 5 (I/O expansion) B4 Relay 4 (I/O expansion) B2 Q1 (Basic I/O) B1 Relay 2 (Basic I/O) B0 Relay 1 (Basic I/O) B15 Virtual DI 16 (COM85) B14 Virtual DI 15 (COM84) B13 Virtual DI 13 (COM82) B14 Virtual DI 12 (COM81) B10 Virtual DI 11 (COM80) B9 Virtual DI 10 (COM79) B8 Virtual DI 9 (COM77) B7 Virtual DI 8 (COM77)	Virtual DI 8 (COM77)	
				B6	Virtual DI 7 (COM76)

Address	Parameter	Scal e	unit	Assigne	d content by bit			
				B5	Virtual DI 6 (COM75)			
				B4	Virtual DI 5 (COM74)			
				В3	Virtual DI 4 (COM73)			
				B2	Virtual DI 3 (COM72)			
				B1	Virtual DI 2 (COM71)			
				В0	Virtual DI 1 (COM70)			
0h0323	Selected motor display	-	-	0: No.1	1 motor / 1: No.2 motor			
0h0324	Al1	0.01	%	Analog	input1 (Basic I/O)			
0h0325	Al2	0.01	%	Analog	input2 (Basic I/O)			
0h0326	Al3	0.01	%	Analog	input3 (I/O expansion)			
0h0327	Al4	0.01	%	Analog	input4 (I/O expansion)			
0h0328	AO1	0.01	%	Analog	output1 (Basic I/O)			
0h0329	AO2	0.01	%	Analog output2 (Basic I/O)				
0h032A	AO3	0.01	%	Analog output3 (I/O expansion)				
0h032B	AO4	0.01	%					
0h032C	Reserved	-	-	-				
0h032D	Temperature	1	$^{\circ}$	-				
0h032E	Power consumption of inverter(kW/hour)	0.1	kWh	-	-			
0h032F	Power consumption of inverter(MW/hour)	1	MWh	-				
				B15	Fuse Open Trip			
				B14	Overheat Trip			
				B13	Arm Short			
				B12	External Trip			
0h0330	Latch type trip information-	B3 Virtual DI 4 (COM73) B2 Virtual DI 3 (COM72) B1 Virtual DI 2 (COM71) B0 Virtual DI 1 (COM70) V	Overvoltage Trip					
0110330	1		Overcurrent Trip					
				В9	NTC Trip			
				B8	Overspeed Deviation			
		B4 Virtual E	Overspeed					
				B6	Input open-phase trip			

Address	Parameter	Scal e	unit	Assigne	ed content by bit
				B5	Output open-phase trip
				B4	Ground Fault Trip
				В3	E-Thermal Trip
				B2	Inverter Overload Trip
				B1	Underload Trip
				В0	Overload Trip
				B15	Low Voltage2
				B14	Reserved
				B13	Inverter output cutoff by terminal block input on Safety Option (applied to above 90 kW)
				B12	Ground Fault Trip E-Thermal Trip Underload Trip Underload Trip Low Voltage2 Reserved Inverter output cutoff by terminal block input on Safety Option (applied to above 90 kW) Slot3 option board contact defectivenes Slot1 option board contact defectivenes No MotorTrip External Brake Trip Basic IO board contact defectiveness Pre PID Fail Fror on Parameter Write Reserved FAN Trip PTC (Thermal sensor) Trip Reserved Reserved
		E information	B11	Slot2 option board contact defectiveness	
	Latch type trip information-		B9 No MotorTrip B8 External Brake Trip B7 Basic IO board contact defectivenes B6 Pre PID Fail	B10	Slot1 option board contact defectiveness
				В9	No MotorTrip
0h0331				B8	External Brake Trip
				Basic IO board contact defectiveness	
				B6	Pre PID Fail
				B5	Error on Parameter Write
				B4	Reserved
				В3	Output open-phase trip Ground Fault Trip E-Thermal Trip Inverter Overload Trip Underload Trip Underload Trip Low Voltage2 Reserved Inverter output cutoff by terminal block input on Safety Option (applied to above 90 kW) Slot3 option board contact defectivenes Slot2 option board contact defectivenes Slot1 option board contact defectivenes No MotorTrip External Brake Trip Basic IO board contact defectiveness Pre PID Fail Error on Parameter Write Reserved FAN Trip PTC (Thermal sensor) Trip Encoder Error Trip MC Fail Trip Reserved
				B2	PTC (Thermal sensor) Trip
				B1	Encoder Error Trip
				В0	MC Fail Trip
				B13 input on Safety Option (applied to about 90 kW) B12 Slot3 option board contact defectiven B11 Slot2 option board contact defectiven B10 Slot1 option board contact defectiven B9 No MotorTrip B8 External Brake Trip B7 Basic IO board contact defectiveness B6 Pre PID Fail B5 Error on Parameter Write B4 Reserved B3 FAN Trip B2 PTC (Thermal sensor) Trip B1 Encoder Error Trip B0 MC Fail Trip B15 Reserved	Reserved
				B14	Reserved
				B13	Reserved
0h0332	Level type trip information	-	-	B12	Reserved
				B4 Ground Fault Trip B3 E-Thermal Trip B2 Inverter Overload Trip B1 Underload Trip B0 Overload Trip B15 Low Voltage2 B14 Reserved B13 Inverter output cutoff by terminal block input on Safety Option (applied to above 90 kW) B12 Slot3 option board contact defectivenes B11 Slot2 option board contact defectivenes B10 Slot1 option board contact defectivenes B9 No MotorTrip B8 External Brake Trip B7 Basic IO board contact defectiveness B6 Pre PID Fail B5 Error on Parameter Write B4 Reserved B3 FAN Trip B2 PTC (Thermal sensor) Trip B1 Encoder Error Trip B0 MC Fail Trip B15 Reserved B14 Reserved B15 Reserved B16 Reserved B17 Reserved B18 Reserved B19 Reserved B19 Reserved B10 Reserved B10 Reserved	
			B9 No MotorTrip B8 External Brake Trip B7 Basic IO board contact defectiveness B6 Pre PID Fail B5 Error on Parameter Write B4 Reserved B3 FAN Trip B2 PTC (Thermal sensor) Trip B1 Encoder Error Trip B0 MC Fail Trip B15 Reserved B14 Reserved B13 Reserved B14 Reserved B17 Reserved B18 Reserved B19 Reserved B19 Reserved B10 Reserved B10 Reserved	Reserved	
				B9	Reserved

Address	Parameter	Scal e	unit	Assigne	ed content by bit
				B8	Reserved
		e -		B7	Reserved
				B6	Reserved
				B5	Reserved
				B4	Reserved
				В3	Keypad Lost Command
				B2	Lost Command
				B1	LV
				В0	BX
				B15	Reserved
				B14	Reserved
				B13	Reserved
				B12	Reserved
				B11	Reserved
				B10	Reserved
				B9	Reserved
0h0333	H/W Diagnosis Trip	L		B8	Reserved
0110333	information			B7	Reserved
				B7 Reserved B6 Reserved B5 Reserved B4 Reserved B3 Keypad Lost Command B2 Lost Command B1 LV B0 BX B15 Reserved B14 Reserved B14 Reserved B17 Reserved B18 Reserved B19 Reserved B10 Reserved B10 Reserved B10 Reserved B10 Reserved B10 Reserved B10 Reserved	Reserved
					Reserved
				B4	Gate Drive Power Loss
				В3	Watchdog-2 error
				B2	Watchdog-1 error
				B1	EEPROM error
				В0	ADC error
		B10 B9 B8 B7 B6 B5 B4 B3 B2 B1 B0 B15 B14	B15	Reserved	
060224	Marning information			B14	Reserved
0h0334	Warning information	-	-	B13	Reserved
				B8 Reserved B6 Reserved B5 Reserved B4 Reserved B3 Keypad L B2 Lost Com B1 LV B0 BX B15 Reserved B14 Reserved B17 Reserved B18 Reserved B19 Reserved B10 Reserved B10 Reserved B10 Reserved B1 Reserved	Reserved

Address	Parameter	Scal e	unit	Assigned content by bit		
				B11	Reserved	
				B10	Fire function operation	
				В9	Auto Tuning fail	
				B8	Keypad Lost	
				B7	Encoder mis-wiring	
				B6	Encoder mis-installation	
				B5	DB	
				B4	FAN operation	
				В3	Lost command	
				B2	Inverter Overload	
				B1	Underload	
				В0	Overload	
0h0335- 0h033F	Reserved	-	-	-		
0h0340	On Time date	0	Day	Date of inverter power On		
0h0341	On Time minute	0	Min	Total mi	inute, except for total date, of inverter On	
0h0342	Run Time date	0	Day	Total nu	ımber of days of inverter run	
0h0343	Run Time minute	0	Min	Total m	inute, except for total day, of Run Time	
0h0344	Fan Time date	0	Day	Total da	ays of cooling fan run	
0h0345	Fan Time minute	0	Min	Total m	inute except for total day of Fan time	
0h0346	Reserved	-	-	-		
0h0347	Reserved	-	-	ı		
0h0348	Reserved	-	-	-		
0h0349	Reserved	-	-	-		
0h034A	Option 1	-	-	0: None 2: Rese 4: Rese	erved 3: Profibus,	
0h034B	Option 2	-	-	6: Reserved 7: RNet, 8: Reserved 9: Reserved 10: PLC 20: External IO-1		
0h034C	Option 3			23: End	coder	

11.13.4.2 Inverter Control Area Parameter (Reading and Writing Available)

Address	Parameter	Scale	unit	Bit al	lotment
0h0380 note1)	Frequency command	0.01	Hz	Com	mand frequency setting
0h0381	RPM command	1	rpm	com	mand RPM setting
				B7	Reserved
				B6	Reserved
				B5	Reserved
				B4	Reserved
0h0382	Operating command	-	-	В3	0→1: Free run stop
	Communa			B2	0→1: Trip reset
				B1	0:Reverse command 1:Forward command
				В0	0:Stop command 1:Run command
					Forward operating command: 0003h, Reverse operating command: 0001h
0h0383	Accelerating time	0.1	sec	Acce	elerating time setting
0h0384	Decelerating time	0.1	sec	Dece	elerating time setting
				B15	Virtual DI 16 (COM85)
				B14	Virtual DI 15 (COM84)
				B13	Virtual DI 14 (COM83)
				B12	Virtual DI 13 (COM82)
				B11	Virtual DI 12 (COM81)
				B10	Virtual DI 11 (COM80)
	Virtual digital			В9	Virtual DI 10 (COM79)
0h0385	input control	-	-	B8	Virtual DI 9 (COM78)
	(0:Off, 1:On)			B7	Virtual DI 8 (COM77)
				B6	Virtual DI 7 (COM76)
				B5	Virtual DI 6 (COM75)
				B4	Virtual DI 5 (COM74)
				В3	Virtual DI 4 (COM73)
				B2	Virtual DI 3 (COM72)
				B1	Virtual DI 2 (COM71)

Address	Parameter	Scale	unit	Bit al	llotment
				В0	Virtual DI 1 (COM70)
				B15	Reserved
	Digital output control (0:Off, 1:On) Reserved - PID reference 0.1 PID feedback value 0.1 Reserved - Torque Ref 0.1 Fwd Pos Torque Limit 0.1 Fwd Neg Torque 1.1 Eve Pos Torque 1.1 Rev Pos Torque 1.1 Rev Neg Torque 1.1 Rev Neg Torque 1.1 Torque Bias 0.1			B14	Reserved
				B13	Reserved
				B12	Reserved
				B11	Reserved
				B10	Reserved
				В9	Reserved
0h0386	Digital output		L	B8	Reserved
0110300	(0:Off, 1:On)		[B7	Reserved
				B6	Reserved
				B5	Q4 (I/O expansion, OUT36:None)
				B4	Q3 (I/O expansion, OUT35:None)
				ВЗ	Q2 (I/O expansion, OUT34:None)
				B2	Q1 (basic I/O, OUT33:None)
				B1	Relay2 (basic I/O, OUT32:None)
				В0	Relay1 (basic I/O, OUT31:None)
0h0387	Reserved	-	-	Rese	erved
0h0388	PID reference	0.1	%	PID i	reference command released
0h0389	PID feedback value	0.1	%	PID 1	feedback value
0h038A -0h038F	Reserved	-	-	-	
0h0390	Torque Ref	0.1	%	Torq	ue command
0h0391	Fwd Pos Torque Limit	0.1	%	Forw	vard motor ring torque limit
0h0392	Fwd Neg Torque Limit	0.1	%	Forw	vard regenerative torque limit
0h0393	Rev Pos Torque Limit	0.1	%	Reve	erse motor ring torque limit
0h0394	Rev Neg Torque Limit	0.1	%	Reve	erse regenerative torque limit
0h0395	Torque Bias	0.1	%	Torq	ue Bias
0h0395	Reserved	-	-	-	

Address	Parameter	Scale	unit	Bit allotment
-0h399				
0h039A	Anytime Para	-	-	CNF-20 value setting
0h039B	Monitor Line-1	-	-	CNF-21 value setting
0h039C	Monitor Line-2	-	-	CNF-22 value setting
0h039D	Monitor Line-3	-	-	CNF-23 value setting

- Note1) A frequency set via communication using the iS7 common area frequency address (0h0380, 0h0005) is not saved even when used with the parameter save function. To save a changed frequency to use after a power cycle, follow these steps:
- Set DRV-07 to Keypad-1 and select a random target frequency.
- Cmd Frequency (DRV-01, 0h1101): Set the frequency via communication into the parameter area frequency address (0h1101).
- Parameter Save (0h03E0): Set to "1" before turning off the power.
- The frequency set via communication will be displayed after turning the power off and on again.

11.13.4.3 Inverter Memory Control Area Parameter (Reading and Writing Available)

When setting parameters in the inverter memory control area, the values are reflected to the inverter operation and saved. Parameters set in other areas via communication are reflected in the inverter operation, but are not saved.

All set values are cleared following an inverter power cycle and revert back to their previous values. When setting parameters via communication, ensure that a parameter is saved prior to turning off the inverter.

Address	Parameter	Scale	unit	Changeable During Operation	Function		Page
0h03E0 ^{note1)}	Parameter saving	-	-	Х	0: No 1	: Yes	256
0h03E1 ^{note1)}	Monitor mode initialization	-	-	0	0: No 1	: Yes	257
0h03E2 ^{note1)}	Parameter initialization	-	-	X	0: No 2: Drv Grp 4: ADV Grp 6: IN Grp 8: COM Grp 10: AUT Grp 12: PRT Grp *No setting during	1: All Grp 3: BAS Grp 5: CON Grp 7: OUT Grp 9: APP Grp 11: APO Grp 13: M2 Grp g trip	257
0h03E3	Display changed parameter	-	-	0	0: No 1: Yes		260
0h03E4	Macro function item	-	-	x	0: None 1: Draw App 2: Traverse		262
0h03E5 ^{note1)}	Deleted all fault history	-	-	0	0: No	1: Yes	260
0h03E6 ^{note1)}	User registration code deleted	-	-	0	0: No	1: Yes	260
0h03E7 note 2)	Hide parameter mode	0	Hex	0	writing: 0 - 9999 reading: 0: Unloc	k 1: Lock	258
0h03E8 note 2)	Lock parameter mode	0	Hex	0	writing: 0 - 9999 reading: 0: Unloc	k 1: Lock	259
0h03E9	Easy start on (easy parameter setup mode)	-	-	0	0: No	1: Yes	263
0h03EA ^{note1)}	Initializing power consumption	-	-	0	0: No	1: Yes	284
0h03EB ^{note1)}	Initialize inverter operation accumulative time	-	-	0	0: No	1: Yes	284
0h03EC ^{note1)}	Initialize cooling	-	-	0	0: No	1: Yes	264

Communication Function

4	Address	Parameter	Scale	Changeable During Operation	Function	Page
		fan accumulated operation time				

Note 1

- Set parameters very carefully. After setting a parameter to "0" via communication, set it to another value. If a parameter has been set to a value other than 0 and a non-zero value is entered again, an error message is returned. The previously set value can be identified by reading the parameter when operating the inverter via communication.

Note that the execution time may take longer because the data is saved in the inverter, possibly interrupting communication.

Note 2

- The addresses 0h03E7 and 0h03E8 are parameters for entering the password. When the password is entered, the condition will change from "Lock" to "Unlock", and vice versa.

When the same parameter value is entered repeatedly, the parameter setting is executed just once. To enter the same value, change it to another value first and then re-enter the previous value. For example, if you want to enter 244 twice, enter it in the following order: 244 -> 0 -> 244.

12 Troubleshooting and Maintenance

This chapter explains how to troubleshoot a problem when inverter protective functions, fault trips, warning signals, or faults occur. If the inverter does not work normally after following the suggested troubleshooting steps, please contact the LS ELECTRIC Customer Support.



Wait at least 10 minutes before opening the covers and exposing the terminal connections. Before working on the inverter, test the connections to ensure the DC voltage has been fully discharged. Personal injury or death by electric shock may result if the DC voltage has not been discharged.

12.1 Protection Functions

12.1.1 Protection from Output Current and Input Voltage

Туре	Category	Details	Remarks
Over Load	Latch	Displayed when the motor overload trip is activated and the actual load level exceeds the set level. Operates when PRT-20 is set to any value other than "0".	-
Under Load	Latch	Displayed when the motor underload trip is activated and the actual load level is less than the set level. Operates when PRT-27 is set to any value other than "0".	-
Over Current1	Latch	Displayed when the inverter output current exceeds 200% of the rated current.	-
Over Voltage	Latch	Displayed when the internal DC circuit voltage exceeds the specified value.	-
Low Voltage	Level	Displayed when the internal DC circuit voltage is less than the specified value.	-
Ground Trip	Latch	Displayed when a ground fault trip occurs on the output side of the inverter and causes the current to exceed the specified value. The specified value varies depending on the inverter capacity.	-
E-Thermal	Latch	Displayed based on inverse time limit thermal characteristics to prevent motor overheating. Operates when PRT-40 is set to any value other than "0".	-
Out Phase Open	Latch	Displayed when a 3-phase inverter output has one or more phases in an open circuit condition. Operates when bit 1 of PRT-05 is set to "1".	-

Туре	Category	Details	Remarks
In Phase Open	Latch	Displayed when a 3-phase inverter input has one or more phases in an open circuit condition. Operates only when bit 2 of PRT-05 is set to "1".	-
Inverter OLT	Latch	Displayed when the inverter has been protected from overload and resultant overheating, based on inverse time limit thermal characteristics. Allowable overload rates for the inverter are 150% for 1 min and 200% for 4 sec. Protection is based on the inverter rated capacity, and may vary depending on the device's capacity.	-
Low Voltage2	Latch	Displayed when the internal DC circuit voltage is less than the specified value during inverter operation.	-
Safety Opt Err	Latch	Displayed when a safety feature is activated to block the inverter output during an emergency.	-

12.1.2 Abnormal Circuit Conditions and External Signals

Туре	Category	Details	Remarks
Fuse Open	Latch	Displayed when the inverter DC fuse is exposed to an overcurrent above 30 kW.	-
Over Heat	Latch	Displayed when the temperature of the inverter heat sink exceeds the specified value.	-
Over Current2	Latch	Displayed when the DC circuit in the inverter detects a specified level of excessive, short circuit current.	-
External Trip	Latch	Displayed when an external fault signal is provided by the multi- function terminal. Set one of the multi-function input terminals at IN-65–72 to "3 (External Trip)" to enable external trip.	-
BX	Level	Displayed when the inverter output is blocked by a signal provided from the multi-function terminal. Set one of the multi-function input terminals at IN-65–71 to "4 (BX)" to enable the input block function.	-
H/W-Diag	Fatal	Displayed when an error is detected in the memory (EEPRom), analog-digital converter output (ADC Off Set), or CPU watchdog (Watch Dog-1, Watch Dog-2). EEP Err: An error in reading/writing parameters due to a keypad or memory (EEPRom) fault. ADC Off Set: An error in the current sensing circuit (U/V/W terminal, current sensor, etc.). Gate Pwr Loss: An interruption in the supply of power to the IGBT Gate of a product rated 30 kW or higher (when a fault occurs in a 22 kW-rated product, the capacity settings should be	-

Туре	Category	Details	Remarks
		checked).	
NTC Open	Latch	Displayed when an error is detected in the temperature sensor of the Insulated Gate Bipolar Transistor (IGBT).	-
Fan Trip	Latch	Displayed when an error is detected in the cooling fan. Set PRT-79 to "0" to activate fan trip (for models with a capacity below 22 kW).	-
IP54 FAN Trip	Latch	Displayed when the IP54 product detects an internal circulation at the cooling fan.	Only applied to IP54 product
Thermal Trip	Latch	Displayed when the resistance value exceeds the prescribed value after the external temperature sensor is connected to the terminal block. Operates when PRT-34 is set to any value other than "0".	-
ParaWrite Trip	Latch	Displayed when communication fails during parameter writing. Occurs when using an LCD keypad due to a control cable fault or a bad connection.	-
Over Speed Trip	Latch	Displayed when the motor speed exceeds the overspeed detection level. Set the detection level at PRT-70.	-
Dev Speed Trip	Latch	Displayed when the speed that received feedback from the encoder exceeds the set variation value. Operates when PRT-73 is set to "1".	-
Encoder Trip	Latch	Displayed when PRT-77 Enc Wire Check is set to "1" and an abnormality is detected for the set period of time.	-
Pre-PID Fail	Latch	Displayed when pre-PID is operating with functions set at APP-34–36. A fault trip occurs when a controlled variable (PID feedback) is measured below the set value and the low feedback continues, as it is treated as a load fault.	-
Ext-Brake	Latch	When Control Mode (DRV-09) is V/F or Sensorless1 or Sensorless2: The trip occurs when OUT-31–32 is set to BR control and the output current is lower than ADV-41 value (% for BAS-13) for about 10 seconds. When Control Mode (DRV-09) is Vector: The trip occurs when OUT-31-32 is set to BR Control and the current is lower than half of the BAS-14 value.	-

12.1.3 Keypad and Optional Expansion Modules

Туре	Category	Details	Remarks
Lost Keypad	Level	Displayed when operating commands come from the keypad or there is any problem with the communication between the keypad and inverter's main body in Keypad JOG mode. Operates when PRT-11 is set to any value other than "0" (occurs 2 seconds after the communication is interrupted).	-
Lost Command	Level	Displayed when a frequency or operation command error is detected during inverter operation by controllers other than the keypad (e.g. using a terminal block and a communication mode). Set PRT-12 to any value other than "0".	-
Option Trip-1	Latch	Displayed when the extension module is removed from option slot No. 1 after it was installed while the inverter was turned on, or when communication is not available with the inverter.	-
Option Trip-2	Latch	Displayed when the extension module is removed from option slot No. 2 after it was installed during power supply, or when communication is not available with the inverter.	-
Option Trip-3	Latch	Displayed when the extension module is removed from option slot No. 3 after it was installed during power supply, or when communication is not available with the inverter.	-
I/O Board Trip	Latch	Displayed when the basic and insulated I/O boards are disconnected or have a connection fault.	-

Note

Level: When the fault is corrected, the trip or warning signal disappears and the fault is not saved in the fault history.

Latch: When the fault is corrected and a reset input signal is provided, the trip or warning signal disappears.

Fatal: When the fault is corrected, the fault trip or warning signal disappears only after the user turns off the inverter, waits until the charge indicator light goes off, and turns the inverter on again. If the inverter is still in a fault condition after it is powered on again, please contact the supplier or the LS ELETRIC Customer Support.

The function for saving the fault history and the fault signal output may not be performed if the functions are not set or the inverter is seriously damaged.

12.2 Warning Messages

Туре	Description
Over Load	Displayed when the motor is overloaded. Operates when PRT-17 is set to "1". To operate, select "4 (Over Load)". Set the digital output terminal or relay (OUT31-33) to "4 (Over Load)" to receive overload warning output signals.
Under Load	Displayed when the motor is underloaded. Operates when PRT-25 is set to "1". Set the digital output terminal or relay (OUT31-33) to "6 (Under Load)" to receive underload warning output signals.
Inv Over Load	Displayed when the accumulated overload time is equivalent to 60% of the inverter overheat protection (inverter IOLT) level. Set the digital output terminal or relay (OUT31-33) to "5 (IOL)" to receive inverter overload warning output signals.
Lost Command	The Lost Command warning alarm occurs even when PRT-12 is set to "0". The warning alarm occurs based on the condition set at PRT-13-15. Set the digital output terminal or relay (OUT31-33) to "12 (Lost Command)" to receive lost command warning output signals.
Fan Warning	Displayed when an error is detected from the cooling fan while PRT-79 is set to "1". Set the digital output terminal or relay (OUT31-33) to "8 (Fan Warning)" to receive fan warning output signals.
DB Warn %ED	Displayed when the DB resistor usage rate exceeds the set value. Set the detection level at PRT-66.
Enc Conn Check	Displayed when "3 (Enc Test)" is set at BAS-20 (Auto Tuning) and no signal is input during the encoder test. Set the ENC Tune at OUT31–33 to release a signal.
Enc Dir Check	Displayed when "3 (Enc Test)" is set at BAS-20 (Auto Tuning) and the settings for A and B encoder phases are changed or are the opposite during the encoder test. Set the ENC Dir at OUT31-33 to release a signal.
Lost Keypad	Displayed when operating commands come from the keypad or there is any problem with the communication between the keypad and inverter's main body in Keypad JOG mode after setting PRT-11 (Lost KPD Mode) to "0". Set the Lost Keypad (29) at OUT31-33.
Check Line PLZ	Displayed when there is any problem with communication between the keypad and the iS7 Control CPU (control connection cables).
Fire Mode	Displayed when the fire function is activated. If a contact signal output is required, set the Fire Mode (37) at OUT31-33.
PID Sleep	Displayed in PID Sleep mode. This warning is provided to distinguish the PID sleep mode from a stopped state.
AUX Power On	Displayed when the control power is supplied with the auxiliary power module. If the auxiliary power module has been installed, an AUX Power On warning is provided instead of a Low Voltage trip when the main power is turned off.

12.3 Troubleshooting Fault Trips

Туре	Problem	Solution	
Over Load	The load is greater than the motor's rated capacity.	Ensure that the motor and inverter have appropriate capacity ratings.	
Over Load	The set value for the overload trip level (PRT-21) is too low.	Increase the set value for the overload trip level.	
	There is a motor-load connection problem.	Replace the motor and inverter with lower capacity models.	
Under Load	The set value for the underload level (PRT-29 and PRT-30) is less than the system's minimum load.	Increase the set value for the underload level.	
	Acc/dec time is too short compared to load inertia (GD2).	Increase acc/dec time.	
Over	The inverter load is greater than the rated capacity.	Replace the inverter with a model that has increased capacity.	
Over Current1	The inverter supplied an output while the motor was idling.	Operate the inverter after the motor has stopped or use the speed search function (CON-60).	
	The mechanical brake of the motor is operating too fast.	Check the mechanical brake.	
	The deceleration time is too short for the load inertia (GD2).	Increase the deceleration time.	
	A generative load occurs at the inverter output.	Use the braking unit.	
Over Voltage	The input voltage is too high.	Check if the input voltage is above the specified value.	
	The set value for electronic thermal protection is too low.	Set an appropriate electronic thermal level.	
	The inverter has been operated at a low speed for an extended period.	Replace the motor with a model that supplies extra power to the cooling fan.	
	The input voltage is too low.	Check if the input voltage is below the specified value.	
Low Voltage /Low Voltage2	A load greater than the power capacity is connected to the system (e.g. a welder, direct motor connection, etc.)	Increase the power capacity.	
	The magnetic contactor connected to the power source has a faulty connection.	Replace the magnetic contactor.	
Ground Trip	A ground fault has occurred in the inverter output wiring.	Check the output wiring.	

Туре	Problem	Solution		
	The motor insulation is damaged.	Replace the motor.		
	The motor has overheated.	Reduce the load or operation frequency.		
E-Thermal	The inverter load is greater than the rated capacity.	Replace the inverter with a model that has increased capacity.		
Out Phase Open	The magnetic contactor on the output side has a connection fault.	Check the magnetic contactor on the output side.		
Ореп	The output wiring is faulty.	Check the output wiring.		
	The magnetic contactor on the input side has a connection fault.	Check the magnetic contactor on the input side.		
In Phase Open	The input wiring is faulty.	Check the input wiring.		
·	The DC link capacitor needs to be replaced.	Replace the DC link capacitor. Contact the retailer or the LS ELECTRIC Customer Support.		
Inverter OLT	The load is greater than the rated motor capacity.	Replace the motor and inverter with models that have increased capacity.		
	The torque boost level is too high.	Reduce the torque boost level.		
	There is a problem with the cooling system.	Check if a foreign object is obstructing the air inlet, outlet, or vent.		
Over Heat	The inverter cooling fan has been operating for an extended period.	Replace the cooling fan.		
	The ambient temperature is too high.	Keep the ambient temperature below 50°C.		
	The output wiring has short-circuited.	Check the output wiring.		
Over Current2	There is a fault with the electronic semiconductor (IGBT).	Do not operate the inverter. Contact the retailer or the LS ELECTRIC Customer Support.		
	The ambient temperature is too low.	Keep the ambient temperature above 10℃.		
NTC Open	There is a fault with the internal temperature sensor.	Contact the retailer or the LS ELECTRIC Customer Support.		
FAN Trip	There is a foreign object in the inverter vent where the fan is located.	Remove the foreign object from the air inlet o outlet.		
	The cooling fan needs to be replaced.	Replace the cooling fan.		
IP54 FAN Trip	The fan connector is not connected.	Connect the fan connector.		
	The power connector for the internal fan PCB board is not connected.	Connect the power connector for the internal fan PCB board.		
	The cooling fan needs to be replaced.	Replace the cooling fan.		

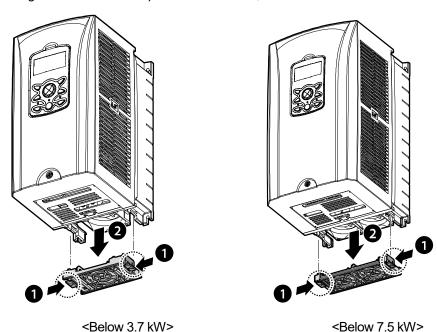
Troubleshooting and Maintenance

Туре	Problem	Solution	
No Motor	The motor is not connected to the inverter output.	Check the wiring connections.	
Trip	The current level for trip detection is not set properly.	Check the values of both BAS-13 (Rated current) and PRT-32 (No Motor Level).	

12.4 Replacing the Cooling Fan

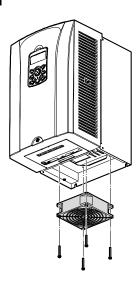
12.4.1 Products Rated below 7.5 kW

To replace the cooling fan, push the bracket on the bottom in the direction of the arrows in the diagram below and then pull it forward. Then, disconnect the fan connector.



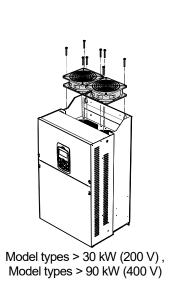
12.4.2 Products Rated at 11-15 kW 200 V/400 V and 18.5-22 kW 400 V

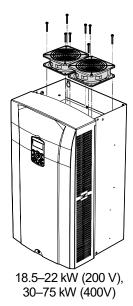
To replace the cooling fan, loosen the screws at the bottom of the input and output terminals and disconnect the fan connector.



12.4.3 Products Rated at more than 30 kW (200 V) / 90 kW (400 V), and 18.5-22 kW (200 V) / 30-75 kW (200/400 V)

To replace the cooling fan, loosen the screws at the top of the product and disconnect the fan connector.





12.5 Daily and Regular Inspection Lists

	Inspection	Inspection details	Inspection Cycle					
Inspection area			Regular Daily (Year)			Inspection method	Judgment standard	Inspection equipment
			Daily	1	2	-		
Total	Ambient environment	Is the ambient temperature and humidity within the designated range, and is there any dust or foreign objects present?	О			Visual inspection	No ice (ambient temperature: -10°C -+40°C) and no condensation (ambient humidity below 50%)	Thermometer, hygrometer, recorder
	Inverter	Are there any abnormal vibrations or noise?	О			Visual inspection	No abnormality	
	Power voltage	Are the input and output voltages normal?	О			Measure voltages between R/S/T phases in the inverter terminal block.		Digital multimeter, tester
Input/Outp ut circuit	Total	1) Megger test (between input/output terminals and and earth terminal) 2) Is there anything loose in the device? 3) Is there any evidence of overheating in each part? 4) Cleaning		0 0	O	1) Disconnect the inverter and short R/S/T/U/V/W terminals, and then measure from each terminal to the ground terminal using Megger test equipment. 2) Tighten up all screws. 3) Visual inspection	1) Over 5MΩ 2), 3) No matter	DC 500 V Megger
	Cable connections	1) Are there any corroded cables? 2) Is there any damage to cable insulation?		0		Visual inspection	No abnormality	
	Terminal block	Is there any damage?		О		Visual inspection	No abnormality	
	Smoothing condenser	1) Is liquid leaking inside? 2) Is the safety apparatus in position? Is there any protuberance?	0	O		1), 2) Visual inspection	1),2) No abnormality	Capacity meter

		Inspection details	Inspection Cycle		cle	Inspection method	Judgment standard	Inspection equipment
Inspection area	Inspection item		Daily	Regular (Year)				
				1	2			
		3) Check the power failure capacity.				3) Measure with a capacity meter.	3) Rated capacity over 85%	
	Relay	1) Is there any chattering noise during operation? 2) Is there any damage to the contacts?		0		1), 2) Visual inspection	1),2) No abnormality	
	Braking resistor	I) Is there any damage from resistance? Check for disconnection.		0		1) Visual inspection 2) Disconnect one side and measure with a tester.	No abnormality Must be within ±10% of the rated value of the resistor.	Digital multimeter / analog tester

① Caution

Do not perform a megger test (insulation resistance test) on the control circuit of the inverter.

			Inspect	tion Cy	cle			
Inspection area	Inspection item	Inspection details	Daily	Regul (Year)	ar	Inspection method	Judgment standard	Inspection equipment
Control circuit Protection circuit	Operation check	1) Check for output voltage imbalance while the inverter is in operation. 2) Is there an error in the display circuit after the sequence protection test?		0	2	1) Measure voltage between the inverter output terminals U/V/W. 2) Test the inverter output protection in both short and open circuit conditions.	1) Balance the voltage between phases: within 4 V for 200 V series and within 8 V for 400 V series. 2) The circuit must work according to the sequence.	Digital multimeter or DC voltmeter
Cooling system	Cooling fan	1) Is there any abnormal vibration or sound? 2) Are any of the fan parts loose?	0	О		1) Turn it manually while the inverter is turned off. 2) Check all connected parts and tighten all screws.	It should turn smoothly. 2) No abnormality	
Display	Meter	Is the display value normal?	О	0		Check the command value on the display device.	Specified and managed values must match.	Voltmeter, ammeter, etc.
Motor	Total	1) Are there any abnormal vibrations or sound? 2) Is there any abnormal smell?	0			1) Visual inspection 2) Check the abnormality, such as overheating, damage, etc.	No abnormality	
	Isolation resistance	Megger test (between the input, output and earth terminals).			О	Disconnect the cables for terminals U/V/W and test the wiring.	Must be above 5 MΩ.	DC 500 V Megger

① Caution

If the inverter has not been operated for a long time, capacitors lose their charging capability and are depleted. To prevent depletion, turn on the inverter once a year and allow it to operate for 30-60 minutes. Run the inverter under no-load conditions.

13 Table of Functions

13.1 Parameter Mode – DRV Group (→DRV)

DRV Group (PAR → DRV)

	Communi-							Shift in			ote ont	1) rol	Mo	de_
No.	cation Address	LCD Display	Name	Set	ting Range	Initial Value		Opera- tion	Page	V / F	S L	V C	SLT	V C T
00	-	Jump Code	Jump code	1-99	•	9		0		0	0	0	0	0
01	0h1101	Cmd Frequency	Target frequency	-ma (Hz		0.0		0	138			0		
02	0h1102	Cmd Torque	Torque command	-180	0–180 (%)	0.0		0	236	Χ	Χ	Χ	0	0
03	0h1103	Acc Timed	Acceleration time	0.6	00 (sec)	Below 75 kW	20.0	0	165	0	0	0	^	0
00	0111103	Acc lilled	Acceleration time	0	00 (Sec)	Above 90 kW	60.0	O	100	O	U	U	U	
04	0h1104	Dec Time	Deceleration time	∩_6	00 (sec)	Below 75 kW	30.0	0	165	\cap	O	0	\cap	\circ
U 1	0111104	Dec Time	Deceleration time		. ,	Above 90 kW	90.0	O	100	Ü	Ü	Ü	Ü	0
				0	Keypad									
				1	Fx/Rx-1									
06	06 0h1106 Cmd Source Command sou	Cmd Source	Command source	2	Fx/Rx-2	1:Fx/Rx-1		х	157	0	0	0	0	0
00		Orria Coarco	Command Course	3	Int 485	1.1 701 00 1		`	'0'	Ĭ		ľ		
				4	Field Bus									
			5	PLC									<u> </u>	
07	01.4407		Frequency reference	0	Keypad-1			.,	400	_		_	.,	.,
07	0h1107	Freq Ref Src	source	1	Keypad-2			Χ	138	O	O	0	Х	Х
-				2	V1									<u> </u>
				3	11 V2									
				5	12									
				6	Int 485	0:Keypad-1								
08	0h1108	Trq Ref Src	Torque reference	7	Encoder			Χ	237	Y	Y	Х	\cap	0
00	0111100	ilq ixel old	source	8	FieldBus			^	201	^	^	^	0	
				9	PLC									
				10	Synchro									
				11	Binary									
				0	V/F				267					
				1	V/F PG				225					
09	01.4400	0 111	0 1 1 1	2	Slip Compen	0.7/15		· ·	210	_			_	
Note1)	0h1109	Control Mode	Control mode	3	Sensorless-1	0:V/F		Х	225	U	U	0	U	U
				4	Sensorless-2				227					
				5	Vector				238					

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

382

Refer to the Options manual for options.

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Note 1) Effectiveness of each code according to the Control Mode setting.

V/F: V/Fmode (PG included), SL: Sensorless-1, 2 mode, VC: Vector mode, SLT: Sensorless-1, 2 Torque mode,

VCT: Vector Torque mode,

DRV Group (PAR → DRV)

	Communi-					Shift in			ont ode	rol e		
No.	cation Address	LCD Display	Name	Setting Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
10	0h110A	Torque Control	Torque control	0 No 1 Yes	0: No	Х	225	Х	Х	Χ	0	0
11	0h110B	Jog Frequency	Jog frequency	0.5–maximum frequency (Hz)	10.00	0	199	0	0	0	0	0
12	0h110C	Jog Acc Time	Jog run acceleration time	0–600 (sec)	20.0	0	199	0	0	0	0	0
13	0h110D	Jog Dec Time	Jog run deceleration time	0-600 (sec)	30.0	0	199	0	0	0	Х	Χ
14	0h110E	Motor Capacity	Motor capacity	0:0.2kW, 1:0.4kW 2:0.75kW, 3:1.5kW 4:2.2kW, 5:3.7kW 6:5.5kW, 7:7.5kW 8:11kW, 9:15kW 10:18.5kW, 11:22kW 12:30kW, 13:37kW 14:45kW, 15:55kW 16:75kW, 17:90kW 18:110kW, 9:132kW 20:160kW, 1:185kW 22:220kW,23:280kW 24:315kW,25:375kW	Dependent on inverter capacity	X	211	Ο	Ο	0	Ο	О
15	0h110F	Torque Boost	Torque boost method	0 Manual 1 Auto 2 Advanced Auto	0:Manual	х	179	0	х	Х	Х	Χ
16 Note2)	0h1110	Fwd Boost	Forward torque boost	0–15 (%)	Below 75kW 2.0 Above 90kW 1.0	Х	179	0	Х	Х	Х	X
17	0h1111	Rev Boost	Reverse torque boost	0–15(%)	Below 75kW 2.0 Above 90kW 1.0	Х	179	0	Х	Х	Х	X
18	0h1112	Base Freq	Base frequency	30-400 (Hz)	60.00	Х	174	0	0	0	0	0
19	0h1113	Start Freq	Starting frequency	0.01–10 (Hz)	0.50	Х	174		Χ	Χ		Χ
20	0h1114	Max Freq	Maximum frequency	40–400	60.00	Х	186	0		0		0
21	0h1115	Hz/Rpm Sel	Speed unit selection	Hz Display Rpm Display	0:Hz	0	287	0	0	0	0	0
25	0h1119	Output Freq	Output speed monitoring	0-Max Frequency	0.00	0	288	0	0	0	0	0

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

Note 2) DRV-16–17 displayed only when DRV-15 (Torque Boost) is set as "Manual" or "Advanced Auto".

DRV Group (PAR → DRV)

No.	Communi- cation Address	LCD Display	Name	Setting Range	Initial Value	Shift in Opera- tion		Mo	onti ode S L		S L T	V C T
26 Note2)	0h111A	Adv ATB Filter	Adv ATB Filter	1~1000[msec]	100	0	179	Х	Х	X	0	0
27	I()h111R	Adv ATB M Gain	Adv ATB M Gain	0~300.0[%]	50.0	0	179	0	0	0	0	0
28	I()h111(:	Adv ATB G Gain	Adv ATB G Gain	0~300.0[%]	50.0	0	179	0	0	0	0	0
30	0h111E	kW/HP Select	kW/HP Select	0 kW 1 HP	0: kW	0	282	0	0	0	X	Х
87	0h1157	Code Version	Inverter Code Version	-	-	х	-	0	0	0	0	0

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

Note 3) DRV-26~28 code is displayed only when DRV-15 (Torque Boost) code value is "Advanced Auto

13.2 Parameter Mode – Basic Function Group (→BAS)

BAS Group(PAR → BAS)

	Camana in						Shift in		Co	ntro	ol M	ode	
No.	Communi- cation Address	LCD Display	Name	Se	etting Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
00	-	Jump Code	Jump code	0-9	99	20	0		0	0	0	0	0
01	0h1201	Aux Ref Src	Auxiliary reference source	0 1 2 3 4 5	None V1 I1 V2 I2 Pulse	0:None	х	194	0	0	0	Х	x
02 Note3)	0h1202	Aux Calc Type	Auxiliary command calculation type	0 1 2 3 4 5 6 7	M+(G*A) M*(G*A) M/(G*A) M+(M*(G*A)) M+G*2(A-50%) M*(G*2(A-50%)) M/(G*2(A-50%)) M+M*G*2(A-50%)	0: M+(G*A)	х	194	0	0	0	X	х
03	0h1203	Aux Ref Gain	Auxiliary command gain	-20	00.0–200.0 (%)	100.0	0	194	0	0	0	Х	Х
04	0h1204	Cmd 2nd Src	Second command source	0 1 2 3 4 5	Keypad Fx/Rx-1 Fx/Rx-2 Int 485 FieldBus PLC	1: Fx/Rx-1	х	190	0	0	0	0	0
05	0h1205	Freq 2nd Src	Second frequency source	0	Keypad-1	0:Keypad-1	0	190	0	0	0	Χ	Х

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

Note 3) BAS-02 code is displayed only when BAS-01 (Aux Ref Src) code has a value other than "None".

BAS Group (PAR → BAS)

No.	Communi- cation Address	LCD Display	Name	Se	tting Range	Initial Value	Shift in Opera- tion	Page	Co V / F	ontr S L	ol N V C	Nod S L T	le V C T
06	0h1206	Trq 2nd Src	Second torque command source	1 2 3 4 5 6 7 8 9 10 11	Keypad-2 V1 I1 V2 I2 Int 485 Encoder FieldBus PLC Synchro Binary Type Keypad-2	-0:Keypad-1	0	190	x	х	х	0	0
07	0h1207	V/F Pattern	V/F pattern options	0 1 2 3	Linear Square User V/F Square2	-0:Linear	x	175	0	0	Х	Х	х
08	0h1208	Ramp T Mode	Acc/Dec standard frequency	0 1	Max Freq Delta Freq	0:Max Freq	х	165	0	0	0	Х	Х
09	0h1209	Time Scale	Time scale settings	0 1 2	0.01 sec 0.1 sec 1 sec	1:0.1 sec	x	165	0	0	0	Х	Х
10	0h120A	60/50 Hz Sel	Input power frequency	0 1	60 Hz 50 Hz	0:60 Hz	Х	84	0	0	0	0	0
11	0h120B	Pole Number	Number of motor poles	248			Х		0	0	0		0
12	0h120C	Rated Slip	Rated slip speed	0–3	3000 (rpm)	Dependent on	Χ		0	0	0	0	0
13	0h120D	Rated Curr	Motor rated current	1–1	1000 (A)	inverter capacity	Х		0	0	0	0	0
14	0h120E	Noload Curr	Motor no-load current	0.5	–1000 (A)		Х	211	0	0	0	0	0
15	0h120F	Rated Volt	Motor rated voltage		0–480 (V)	0	Х		0	0	0	0	0
16	0h1210	Efficiency	Motor efficiency		-100 (%)	Dependent on	X		0		0		0
<u>17</u>	0h1211	Inertia Rate	Load inertia rate	0–8	3	inverter capacity	Х		0	0	0	0	0
18	0h1212	Trim Power %	Power display adjustment		-130 (%)		0	286	0	0	0	0	0
19	0h1213	AC Input Volt	Input power voltage		0–230 (V) 0-480 (V)	220 V 220 44x0 V 380	0	263	0	0	0	0	0
20	-	Auto Tuning	Auto tuning	0 1 2 3 4 5	None All ALL(Stdstl) Rs+Lsigma Enc Test Tr Tr(Stdstl)	0:None	Х	220	x	0	Ο	Ο	0

BAS Group (PAR → BAS)

	Communi-					Shift in		Со	ontr	ol N	/lod	le
No.	cation Address	LCD Display	Name	Setting Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
21	-	Rs	Stator resistance	Dependent on motor setting	-	Х	220	X	0	0	0	0
22	-	Lsigma	Leakage inductance	Dependent on motor setting	-	Х	220	Χ	0	0	0	0
23	-	Ls	Stator inductance	Dependent on motor setting	-	Х	220	Χ	0	0	0	0
24 Note4)	-	Tr	Rotor time constant	25–5000 (ms)	-	Х	220	Χ	0	0	0	0
41 Note5)	0h1229	User Freq 1	User frequency 1	0–maximum frequency (Hz)	15.00	х	176	0	X	Χ	Χ	X
42	0h122A	User Volt 1	User voltage 1	0–100 (%)	25	Х	176	0	Χ	Χ	Χ	Χ
43	0h122B	User Freq 2	User frequency 2	0-maximum frequency (Hz)	30.00	Х	176	0	Χ	Х	Χ	X
44	0h122C	User Volt 2	User voltage 2	0–100 (%)	50	Χ	176	0	Χ	Х	Χ	Χ
45	0h122D	User Freq 3	User frequency 3	0-maximum frequency (Hz)	45.00	Х	176	0	X	Х	Х	X
46	0h122E	User Volt 3	User voltage 3	0–100 (%)	75	Χ	176	0	Χ	Х	Х	Χ
47	0h122F	User Freq 4	User frequency 4	0-maximum frequency (Hz)	60.00	Х	176	0	Χ	Х	Χ	X
48	0h1230	User Volt 4	User voltage 4	0–100 (%)	100	Χ	176	0	Χ	Х	Х	Χ
50 Note6)	0h1232	Step Freq-1	Multi-step speed frequency 1		10.00	0	154	0	0	0	Χ	X
51	0h1233	Step Freq-2	Multi-step speed frequency 2		20.00	0	154	0	0	0	Χ	Χ
52	0h1234	Step Freq-3	Multi-step speed frequency 3		30.00	0	154	0	0	0	Х	Χ
53	0h1235	Step Freq-4	Multi-step speed frequency 4		40.00	0	154	0	0	0	Х	Χ
54	0h1236	Step Freq-5	Multi-step speed frequency 5		50.00	0	154	0	0	0	Х	Χ
55	0h1237	Step Freq-6	Multi-step speed frequency 6		60.00	0	154	0	0	0	Х	Χ
56	0h1238	Step Freq-7	Multi-step speed frequency 7		60.00	0	154	0	0	0	Х	Χ
57	0h1239	Step Freq-8	Multi-step speed frequency 8	O. 11 6	55.00	0	154	0	0	0	Х	Χ
58	0h123A	Step Freq-9	Multi-step speed frequency 9	Starting frequency -maximum frequency(Hz)	50.00	0	154	0	0	0	Х	Χ
59	0h123B	Step Freq- 10	Multi-step speed frequency 10		45.00	0	154	0	0	0	Х	X
60	0h123C	Step Freq- 11	Multi-step speed frequency 11		40.00	0	154	0	0	0	Χ	X
61	0h123D	Step Freq- 12	Multi-step speed frequency 12		35.00	0	154	0	0	0	Х	X
62	0h123E	Step Freq- 13	Multi-step speed frequency 13	y 13	25.00	0	154	0	0	0	Х	X
63	0h123F	Step Freq- 14	Multi-step speed frequency 14		15.00	0	154	0	0	0	X	X
64	0h1240	Step Freq- 15	Multi-step speed frequency 15		5.00	0	154	0	0	0	Χ	X
70	0h1246	Acc Time-1	Multi-step acceleration time 1	0-600 (sec)	20.0	0	168	0	0	0	Χ	Χ
71	0h1247	Dec Time-1	Multi-step deceleration time 1	0-600 (sec)	20.0	0	168	0	0	0	Χ	Χ

	Communi-					Shift in		Co	ontr	ol I	Vloc	de
No.	cation Address	LCD Display	Name	Setting Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
72 Note7)	0h1248	Acc Time-2	Multi-step acceleration time 2	0-600 (sec)	30.0	0	168	0	0	0	Χ	X
73	0h1249	Dec Time-2	Multi-step deceleration time 2	0-600 (sec)	30.0	0	168	0	0	0	Χ	Χ
74	0h124A	Acc Time-3	Multi-step acceleration time 3	0-600 (sec)	40.0	0	168	0	0	0	Χ	Χ
75	0h124B	Dec Time-3	Multi-step deceleration time 3	0–600 (sec)	40.0	0	168	0	0	0	Χ	Χ
76	0h124C	Acc Time-4	Multi-step deceleration time 4	0–600 (sec)	50.0	0	168	0	0	0	Χ	Χ
77	0h124D	Dec Time-4	Multi-step deceleration time 4	0–600 (sec)	50.0	0	168	0	0	0	Χ	Χ
78	0h124E	Acc Time-5	Multi-step deceleration time 5	0–600 (sec)	60.0	0	168	0	0	0	Χ	Χ
79	0h124F	Dec Time-5	Multi-step deceleration time 5	0–600 (sec)	60.0	0	168	0	0	0	Χ	Χ
80	0h1250	Acc Time-6	Multi-step deceleration time 6	0–600 (sec)	70.0	0	168	0	0	0	Χ	Χ
81	0h1251	Dec Time-6	Multi-step deceleration time 6	0–600 (sec)	70.0	0	168	0	0	0	Χ	Χ
82	0h1252	Acc Time-7	Multi-step deceleration time 7	0–600 (sec)	80.0	0	168	0	0	0	Χ	Χ
83	0h1253	Dec Time-7	Multi-step deceleration time 7	0–600 (sec)	80.0	0	168	0	0	0	Χ	Χ

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

Note 4) BAS-24 is shown only when DRV-09 Control Mode is set to "Sensorless-2" or "Vector".

Note 5) BAS-41-48 is displayed only when it is set as "User V/F" even if there is only one BAS-07 or M2-V/F Patt (M2-25).

Note 6) IN-50-64 is displayed only when it is set as "multi-step speed" (Speed -L.M.H,X) even if there is only one among multi-function input IN-65-72.

Note 7) displayed only when it is set as "multi-step Acc/Dec" (Xcel-L,M,H) even if there is only one among multi-function input IN-72-75.

13.3 Parameter Mode – Expansion Function Group (PAR→ADV)

Expansion Function Group (PAR → ADV)

							Olvići i v		Co	ntr	ol N	loc	le
No.	Communi- cation Address	LCD Display	Name	Se	etting Range	Initial Value	Shift in Opera- tion	Page	V / F	S L	V C	S L T	V C T
00	-	Jump Code	Jump code	0-	99	24	0	-		0	0	0	0
01	0h1301	Acc Pattern	Acceleration pattern		Linear	0:Linear	Χ	171	0	0	0		Χ
02	0h1302	Dec Pattern	Deceleration pattern	1	S-curve	U.Lii icai	X	171	0	0	0	Χ	Χ
03	0h1303	Acc S Start	S-curve acceleration start point gradient	1–	100 (%)	40	Х	171	0	0	0	Χ	Х
04	0h1304	Acc S End	S-curve acceleration end point gradient	1–	100 (%)	40	Х	171	0	0	0	Χ	Х
05	0h1305	Dec S Start	S-curve deceleration start point gradient	1–	10 0 (%)	40	X	171	0	0	0	Χ	Х
06	0h1306	Dec S End	S-curve deceleration end point gradient	1–	100 (%)	40	Х	171	0	0	0	Χ	Χ
07	0h1307	Start Mode	Start mode	-	Acc Dc-Start	0:Acc	X	182	0	0	0	Χ	Х
				_	Dec Dec								\vdash
				1	Dc-Brake	-							İ
08	0h1308	Stop Mode	Stop mode	2	Free-Run	0:Dec	Х	184	0	0	C	Х	х
00	0111000	Ctop Mode	Ctop mode	3	-Reserved-	0.000	^	101				^	ĺ`
				4	Power Braking								İ
				0	None								
09	0h1309	Run Prevent	Selection of prohibited	1	Forward Prev	0:None	Х	162	0	0	0	Х	Χ
			rotation direction	2	Reverse Prev								
10	0h130A	Power-on Run	Ctart with navyor on	0	No	0:No	0	163	0	0	0	Х	Х
10	UNISUA	Power-on Run	Start with power on	1	Yes	U.INO	U	103	U	U)	۸	^
12 Note8)	0h130C	Dc-Start Time	Starting DC braking time	0-1	60 (sec)	0.00	Х	268	0	0	0	Χ	X
13	0h130D	Dc Inj Level	DC supply	0–:	200 (%)	50	Χ	268	0	0	0	Χ	Χ
14 Note9)	0h130E	Dc-Block Time	Output blocking time before DC braking	0-1	60 (sec)	0.10	Х	184	0	0	0	Χ	X
15	0h130F	Dc-Brake Time	DC braking time	0-4	60 (sec)	1.00	Х	184	0	0	0	Χ	Χ
16	0h1310	Dc-Brake Level	DC braking rate	0–2	200 (%)	50	Χ	184		0			Χ
17	0h1311	Dc-Brake Freq	DC braking frequency	Sta	arting frequency–60 (Hz)	5.00	Χ	184	0	0	0	Χ	Χ
20	0h1314	Acc Dwell Freq	Acceleration dwell frequency		arting frequency naximum frequency (Hz)	5.00	Х	268	0	0	0	Χ	X
21	0h1315	Acc Dwell Time	Acceleration dwell operation time	0-4	60.0 (sec)	0.00	Х	268	0	0	0	Χ	Х
22	0h1316	Dec Dwell Freq	Deceleration dwell frequency		arting frequency naximum frequency (Hz)	5.00	Х	268	0	0	0	Χ	Х
23	0h1317	Dec Dwell Time	Deceleration dwell operation time		60.0 (sec)	0.00	Х	268	0	0	0	Χ	Х

^{*} The grey cells indicate a hidden code which is only visible when setting a code. Note 8) ADV-12 is displayed only when ADV-07 "Stop Mode" is set as "DC-Start".

Note 9) ADV-14–17 is displayed only when ADV-08 "Stop Mode" is set as "DC-Brake".

Expansion Function Group (PAR → ADV)

No.	Communi- cation Address	LCD Display	Name	Sett	ting Range	Initial Value	Shift in Opera- tion	Page	Co V / F	ontr S L	ol I V C	Mod S L T	de V C T
24	0h1318	Freq Limit	Frequency limit	0	No Yes	0:No	х	187	0	0	0	X	Х
25 Note10)	0h1319	Freq Limit Lo	Frequency lower limit	0–u	pper limit (Hz)	0.50	0	187	0	0	0	Χ	Х
26	0h131A	Freq Limit Hi	Frequency upper limit	0.5- (Hz	<i>I</i>	60.00	Х	187	0	0	0	Х	X
27	0h131B	Jump Freq	Frequency jump	0 1	No Yes	0:No	Х	189	0	0	0	X	Х
28 Note 11)	0h131C	Jump Lo 1	Jump frequency lower limit 1	1 (H		10.00	0	189	0	0	0	Х	Х
29	0h131D	Jump Hi 1	Jump frequency upper limit 1	1-m	np frequency lower limit naximum frequency (Hz)	15.00	0	189	0	0	0	Х	Х
30	0h131E	Jump Lo 2	Jump frequency lower limit 2	upp	ump frequency er limit 2 (Hz)	20.00	0	189	0	0	0	X	Х
31	0h131F	Jump Hi 2	Jump frequency upper limit 2	2-m	np frequency lower limit naximum frequency (Hz)	25.00	0	189	0	0	0	X	X
32	0h1320	Jump Lo 3	Jump frequency lower limit 3	upp	mp frequency er limit 3 (Hz)	30.00	0	189	0	0	0	X	X
33	0h1321	Jump Hi 3	Jump frequency upper limit 3		np frequency lower limit naximum frequency (Hz)	35.00	0	189	0	0	0	X	X
34 Note10)	0h1322	Jog Freq Limit	Jog frequency limit	0 1	No Yes	1:Yes	0	187	0	0	0	X	X
41 Note12)	0h1329	BR RIs Curr	Brake release current	0–1	80.0 (%)	50.0	0	268	0	0	0	X	X
42	0h132A	BR RIs Dly	Brake release delay time	0–1	0.00 (sec)	1.00	x	268	0	0	0	X	X
44	0h132C	BR RIs Fwd Fr	Brake release forward frequency	0–4	00 (Hz)	1.00	х	268	0	0	0	X	Х
45	0h132D	BR RIs Rev Fr	Brake release reverse frequency	0–4	00 (Hz)	1.00	х	268	0	0	0	X	X
46	0h132E	BR Eng Dly	Brake engage delay time	0–1	0 (sec)	1.00	x	268	0	0	0	X	X
47	0h132F	BR Eng Fr	Brake engage frequency	0–4	00 (Hz)	2.00	Х	268	0	0	0	X	X
50	0h1332	E-Save Mode	Energy saving operation	0 1 2	None Manual Auto	0:None	Х	242	0	0	X	Х	х
51 Note13)	0h1333	Energy Save	Energy saving amount	0–3	0 (%)	0	0	242	0	0	0	Х	Х
60	0h133C	Xcel Change Fr	Acc/dec time transition frequency	0–n	naximum frequency (Hz)	0.00	Х	169	0	0	0	Χ	Χ

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

Note 10) ADV-25–26, 34 is displayed only when ADV-24 (Freq Limit) is set as "Freq Limit".

Note 11) ADV-28–33 is displayed only when ADV-27 (Jump Freq) is set as "Yes".

Note 12) ADV-41-47 is displayed only when a code of OUT-31-33 is set as "BR Control".

Note 13) ADV-51 is displayed only when ADV-50 (E-Save Mode) is set as a value other than "None".

Expansion Function Group (PAR → ADV)

	Communi-						Shift in		Co	ntre	ol N	lod	e
No.	cation Address	LCD Display	Name	Set	tting Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
61	-	Load Spd Gain	Revolution display gain	0.1	-6000.0 (%)	100.0	0	287	0	0	0	X	X
62	-	Load Spd Scale	Revolution display scale	0 1 2 3	x 1 x 0.1 x 0.01 x 0.001	0:x 1	0	287	0	0	0	X	X
		Load Spd		4	x 0.0001 Rpm	1.	_		_	_	_		_
63	0h133F	Unit	Revolution display unit	1	Mpm During Run	0:rpm	0	287	0	0	0	0	0
64	0h1340	FAN Control	Cooling fan control	1	Always ON Temp Control	0:During Run	0	254	0	0	0	Χ	Χ
65	0h1341	U/D Save Mode	Up/down operation frequency save	1	No Yes	0:No	0	202	0	0	0	Χ	Х
66	0h1342	On/Off Ctrl Src	Output contact On/Off control options	0 1 2 3 4	None V1 I1 V2 I2	0:None	х	269	0	0	0	0	0
67	0h1343	On-C Level	Output contact point On level	10-	-100 (%)	90.00	х	269	0	0	0	0	0
68	0h1344	Off-C Level	Output contact point Off level		0.00–output contact nt On level (%)	10.00	Х	269	0	0	0	0	0
70	0h1346	Run En Mode	Safe operation selection	1	Always Enable DI Dependent	0:Always Enable	Х	207	0	0	0	0	0
71 Note14)	0h1347	Run Dis Stop	Safe operation stop method	0 1 2	Pree-Run Q-Stop Q-Stop Resume	0:Free- Run	x	207	0	0	0	0	0
72	0h1348	Q-Stop Time	Safe operation deceleration time	0–6	600.0 (sec)	5.0	0	207	0	0	0	0	0
73	0h1349	RegenAvd Mode	Regeneration evasion mode	Bit 0 1 2	001-111 Steady Accelerating Decelerating		х	278	0	0	0	0	0
74	0h134A	RegenAvd Sel	Selection of regeneration evasion function for press	0 1	No Yes	No	х	278	0	0	0	0	0
75	0h134B	RegenAvd Level	Operational voltage level of regeneration evasion motion for press		0 V: 300–400 0 V: 600–800	350 V 700 V	х	278	0	0	0	X	X
76 Note15)	0h134C	CompFreq Limit	Compensation frequency limit of regeneration for evasion for press	0–′	10.00 Hz	1.00 (Hz)	х	278	0	0	0	X	X
77	0h134D	RegenAvd Pgain	Regeneration evasion for press P gain	0–1	100.0 %	50.0 (%)	0	278	0	0	0	Χ	X

	.					Olvići i v		Co	ntro	ol N	loc	e
No.	Communi- cation Address	LCD Display	Name	Setting Range	Initial Value	Shift in Opera- tion	Page	V / F	S L	V C	S L T	V C T
78	0h134E	RegenAvd Igain	Regeneration evasion for press I gain	20–30000 (ms)	500 (ms)	0	278	0	0	0	X	Х
79	0h134F	DB Turn On Lev	DB unit operating voltage	200 V : 350–400 (V) 400 V : 600–800 (V)	390 (V) 780 (V)	Х	282	0	0	0	0	0
80	0h1350	Fire Mode Sel	Select fire mode	0 None 1 Fire Mode 2 Fire Test	0:None	х	280	0	0	0	X	Х
81 Note16)	0h1351	Fire Mode Freq	Fire mode frequency	0-maximum frequency (Hz)	60.00	Х	280	0	0	0	Χ	Х
82	0h1352	Fireq Mode Dir	Fire mode operating direction	0 Forward 1 Reverse	0:Forwar d	Х	280	0	0	0	X	Х
83	-	Fire Mode Cnt	Fire mode counter	0-99	0	Х	280	0	0	0	X	X
85	0h1355	U/D Mode Sel	U/D Mode	0 U/D Normal 1 U/D Step 2 U/D Step+Norm	0:U/D Normal	х	202	0	0	0	X	Х
86 Note17)	0h1356	U/D Step Freq	U/D step frequency	0-maximum frequency [Hz]	0.00	0	202	0	0	0	X	X
87	0h1357	OVM Mode Sel	Voltage Drop compensation	0 No 1 Yes	0:No	х	298	0	Х	0	0	0
91	0h135B	Auxiliary OPT	AUX Power Option Sel	0 No 1 Yes	0:No	х	-	0	0	0	0	0
92 Note18)	0h135C	SlipGain Mot- H	slip compensation offsetting gain H	0~200[%]	50	0	210	0	Х	X	X	Х
93	0h135D	SlipGain Gen- H	slip compensation regenerative gain H	0~200[%]	50	0	210	0	Χ	Χ	X	Х
94	0h135E	SlipGain Mot- L		0~200[%]	50	0	210	0	Х	Χ	X	X
95	0h135F	SlipGain Gen- L	slip compensation regenerative gain L	0~200[%]	50	0	210	0	Х	Χ	X	Х
96	0h1360	Slip Filter	slip compensation filter	0~10000[msec]	300	0	210	0	Χ	Χ	Х	Χ
97	0h1361	Slip Comp Freq	slip compensation frequency	0~60.00[Hz]	5.00	0	210	0	Х	Χ	X	X
98	0h1362	Slip Gain Freq	slip compensation gain switchover frequency	0~20.00[Hz]	9.00	0	210	0	Х	Χ	X	X

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

Note 14) ADV-71-72 is displayed only when ADV-70 (Run En Mode) is set as "DI Dependent".

ADV-73 is displayed only when ADV-74 (RegenAvd Sel) is set as "Yes".

 $^{^{\}text{Note}15)}$ ADV-76–78 is displayed only when ADV-75 (RegenAvd Sel) is set as "Yes".

Note16) ADV-81–83 displayed only when ADV-80 (Fire Mode Sel) is set as "Fire Mode" or "Fire Test".

Note17) ADV-86 is displayed when ADV-85 (U/D Mode Sel)is not set to "U/D Normal".

Note18) ADV-92-98 is displayed only when DRV-09 (Control Mode) is set as "Slip Compen"

13.4 Parameter Mode – Control Function Group (→CON)

	Communi			Cotting Dange			Shift in		Co	ntro	ol M	od	е
No.	Communi- cation Address	LCD Display	Name	Setting Rang	е	Initial Value	Opera- tion	Page	V / F	S L	O <	コトの	V C T
00	-	Jump Code	Jump code	0-99		51	0		0	0	0	0	0
				Below 22 kW	0.7–15 (kHz)	5.0							
				30-45 kW	0.7–10 (kHz)	5.0							Ī
04	0h1404	Carrier Freq	Carrier frequency	55-75 kW	0.7–7 (kHz)	5.0	0	248	0	0	0	0	0
				90-110 kW	0.7–6 (kHz)	3.0	_						ì
				132-160 kW 185-220 kW	0.7–5 (kHz) 0.7–3 (kHz)	3.0 2.0	_						ì
					0.7–3 (kHz)	2.0							1
				0 Normal P		0:Normal							_
05	0h1405	PWM Mode	Switching mode	_	age PWM	PWM	X	248	0	0	0	O	0
09	0h1409	PreExTime	Initial excitation time	0-60 (sec)	3	1.00	Х	232	Х	Х	0	0	0
10	0h140A	Flux Force	Initial excitation power supply	100–500 (%)		100.0	X	232	Χ	Χ	0	0	0
11	0h140B	Hold Time	Continued operation duration	0–60 (sec)		Dependent on control mode	Х	232	Х	Х	0	X	X
12	0h140C	ASR P Gain 1	Speed controller proportional gain 1	10–500 (%)		50.0	0	232	X	Χ	0	X	X
13	0h140D	ASR I Gain 1	Speed controller integral gain 1	10–9999 (ms	ec)	300	0	232	Х	Х	0	Χ	Χ
15	0h140F	ASR P Gain 2	Speed controller proportional gain 2	10–500 (%)		50.0	0	232	X	Χ	0	Χ	X
16	0h1410	ASR I Gain 2	Speed controller integral gain 2	10–9999 (ms)	300	0	232	Χ	Х	0	Х	X
18	0h1412	Gain SW Freq	Gain exchange frequency	0–120 (Hz)		0.00	Х	232	Χ	Х	0	X	Χ
19	0h1413	Gain Sw Delay	Gain exchange time	0–100 (sec)		0.10	Х	232	Χ	Х	0	Χ	X
		SL2 G	Sensorless 2nd	0 No			_		. ,				
20	0h1414	View Sel	gain display setting	1 Yes		0:No	0	228	Х	Х	X	Х	X —
21	0h1415	ASR-SL P Gain1	Sensorless speed controller proportional gain1	0–5000 (%)		Dependent on motor capacity	0	228	Х	0	Х	Χ	X
22	0h1416	ASR-SL I Gain1	gain 1	10–9999 (ms)	Dependent on motor capacity	0	228	х	0	Х	X	X
23 Note17)	0h1417	ASR-SL P Gain2	Senseless speed controller proportional gain 2	1.0–1000.0 (9	,	Dependent on motor capacity	0	228	Х		X		
24	0h1418	ASR-SLI	Sensorless2	1.0–1000.0 (9	%)	Dependent	0	228	Χ	Χ	Χ	Χ	Χ

No.	Communi- cation Address	LCD Display	Name	Setting Range	Initial Value	Shift in Opera- tion	Page	Col V / F	ntro S L	V C	lod S L T	e V C T
		Gain2	speed controller integral gain 2		on motor capacity							
26	0h141A	Observer Gain1	Sensorless2 measurer gain 1	0–30000	10500	0	228	Х	Х	Х	Х	X
27	0h141B	Observer Gain2	Sensorless2 measurer gain 2	1–1000 (%)	100.0	0	228	Х	Х	Х	Х	X
28	0h141C	Observer Gain3	Sensorless2 measurer gain 3	0–30000	13000	0	228	Χ	Х	Х	Х	X
29	0h141D	S-Est P Gain1	Sensorless2 speed estimator proportional gain 1	0–30000	Dependent on motor capacity	0	228	х	X	x	х	х
30	0h141E	S-Est I Gain1	Sensorless2 speed estimator integral gain 1	0–30000	Dependent on motor capacity	0	228	Х	Х	Х	X	Х

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

Note 17) CON-23–28, 31–32 are displayed only when DRV-09 (Control Mode) is "Sensorless2" and CON-20 (SL2 G View Sel) is set as "Yes".

<u> </u>	iu Oi i ui	icaon Git	pup (PAR -> CON)										_
No.	Communi- cation Address	LCD Display	Name	Sett	ing Range	Initial Value	Shift in Opera- tion	Page	Co V / F	ontr S L	ol N C	Mod S L T	le V C T
31	0h141F	S-Est P Gain2	Sensorless2 speed estimator proportional gain 2	1.0-	-1000.0 (%)	Dependent on motor capacity	0	228	Х	Х	Х	Χ	X
32	0h1420	S-Est I Gain2	Sensorless2 speed estimator integral gain 2	1.0-	-1000.0 (%)	Dependent on motor capacity	0	228	X	Х	X	X	X
34	0h1422	SL2 OVM Perc	Sensorless2 overvoltage modulation range adjustment	100	–180 (%)	120	X	230	X	0	X	Χ	Χ
35	0h1423	SL2 L- ExcitLmt	Magnetic flux current minimum ratio	3~1	00[%]	10	0	236	Х	Х	Х	0	X
45 Note18)	0h142D	PG P Gain	PG operation proportional gain	0–9		3000	0	225	0	X	Χ		X
46	0h142E	PG I Gain	PG operation integral gain	0–9	999	50	0	225	0	Χ	Х	Χ	Χ
47	0h142F	PG Slip Max%	PG operation maximum slip	0–2	00	100	Х	225	0	Х	Х	Χ	Χ
48	0h1430	ACR P Gain	Current controller P gain	0–1	0000	1200	0	228	Χ	0	0	0	0
49	0h1431	ACR I Gain	Current controller I gain	0–1	0000	120	0	228	Χ	0	0	0	0
51	0h1433	ASR Ref LPF	Speed controller reference filter	0–2	0000 (ms)	0	X	232	X	0	0	X	Χ
52	0h1434	Torque Out LPF	Torque controller output filter	0–2	000 (ms)	0	X	232	X	X	Χ	0	0
53	0h1435	Torque Lmt Src	Torque limit setting options	0 1 2 3 4 5 6 7 8 9 10	Keypad-1 Keypad-2 V1 I1 V2 I2 Int 485 Encoder FieldBus PLC Synchro Binary Type	-0:Keypad-1	х	232	x	х	X	0	0
54 Note19)	0h1436	FWD +Trq Lmt	Forward offsetting torque limit	0–2	00 (%)	180.0	0	232	Х	Х	Х	0	0
55	0h1437	FWD –Trq Lmt	Forward offsetting torque limit	0–2	00 (%)	180.0	0	232	Х	Х	X	0	0
56	0h1438	REV +Trq Lmt	Reverse regenerative torque limit	0–2	00 (%)	180.0	0	232	Х	Х	Х	0	0
57	0h1439	REV –Trq Lmt	Reverse regenerative torque limit	0–2	00 (%)	180.0	0	232	Χ	Χ	Х	0	0

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

Note 18) CON-45-47 are displayed when the Encoder module is installed and Control mode is set as "V/F PG".

Note 19) CON-54-57 are displayed only when DRV-09 (Control Mode) is set as "Sensorless-1, 2" or "Vector". In addition, the initial value of the torque limit is changed to 150% when the ADV-74 RegenAvd Level function is set.

	Communi-						Shift in			Cor ode	itro	1	
No.	cation Address	LCD Display	Name	Se	tting Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
58	0h143A	Trq Bias Src	Torque bias setting options	0 1 2 3 4 5 6	Keypad-1 Keypad-2 V1 I1 V2 I2 Int 485 FieldBus	0:Keypad-1	х	232	x	x	0	x	X
				8	PLC								
59	0h143B	Torque Bias	Torque bias	-12	20–120 (%)	0.0	0	232	Χ	Χ	0	Χ	Χ
60	0h143C	Torque Bias FF	Torque bias compensation	0–	100 (%)	0.0	0	232	X	X	0	Х	Х
62	0h143E	Speed Lmt Src	Speed limit setting options	1 2 3 4 5 6 7 8	Keypad-1 Keypad-2 V1 I1 V2 I2 Int 485 FieldBus PLC	0:Keypad-1	0	236	x	x	x	x	0
63	0h143F	FWD Speed Lmt	Forward speed limit	-	maximum quency (Hz)	60.00	0	236	X	X	X	X	0
64	0h1440	REV Speed Lmt	Reverse speed limit		maximum quency (Hz)	60.00	0	236	Χ	Χ	Χ	Χ	0
65	0h1441	Speed Lmt Gain	Speed limit operation gain	10	0–5000 (%)	500	0	236	Х	Х	Х	Х	0
66	0h1442	Droop Perc	Droop operation amount	0-	100 (%)	0.0	0	238	Х	Х	Χ	Χ	0
67 Note20)	0h1443	Droop St Trq	Droop start torque	0–	100 (%)	100.0	0	238	Х	Х	Х	Х	0
68	0h1444	SPD/TRQAc c T	Torque mode →speed mode exchange acceleration time	0-(600 (sec)	20.0	0	238	Х	Х	Х	Х	0
69	0h1445	SPD/TRQAc c T	Torque mode →speed mode exchange deceleration time	0-(600 (sec)	30.0	0	238	Х	Х	Х	Х	0

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

Note 20) CON-67 is displayed only when the Encoder option module is installed.

	Communi-							Shift in		1)0	Con	trol	Мо	de
No.	cation	LCD Display	Name	Set	ting Range	Initial Value	;	Opera-	Page	V /	s	٧	s _	V C
	Address							tion		F	L	С	T	T
70	0h1446	SS Mode	•	0	Flying Start - 1	0		Х	244	0	0	0	Х	Х
			selection	1 Bit	Flying Start - 2 0000-1111									<u> </u>
				DIL	Speed search									
				1	selection on									
					acceleration									
				2	Restart after									
71	0h1447	Speed Search	Speed search operation selection		trips Restart after	0000		X	244	0	0	0	Χ	Χ
			operation selection	3	instantaneous									
					interruption									
					Start	1								
				4	immediately									
					after power On	Below 75								\vdash
72		SS Sup-	Speed search		000 (0()	kW	150			_	_	. ,	.,	.,
Note21)	0h1448	Current	standard current	80-	200 (%)	Above 90	100	0	244	0	0	X	Х	Х
						kW	100							
73	0h1449	SS P-Gain	Speed search	0–9	999	100		0	244	0	0	Χ	Χ	Χ
			proportional gain Speed search							_	_			
74	0h144A	SS I-Gain	integral gain	0–9	999	200		0	244	0	0	Х	Х	X
			Output											
75	0h144B	SS Block Time	block time before speed search	0–6	0 (sec)	1.0		X	244	0	0	X	Х	Х
				0	None									_
77	0h144D	KEB Select	Energy buffering	1	KEB-1	0:None		Χ	239	0	0	0	Х	Χ
			selection	2	KEB-2									
78 Note21)	0h144E	KEB Start Lev	Energy buffering	110	–200 (%)	130.0		Χ	239	0	0	0	Х	Х
			start level Energy buffering											
79	0h144F	KEB Stop Lev	stop level	130	–210 (%)	135.0		X	239	0	0	0	Х	Х
80	0h1450	KEB Gain	Energy buffering	1_2	000	1000		0	239	0	0	0	Х	Х
	0111400		gain	' -		1000			200					
82 Note22)	0h1452	ZSD Frequency	Permanent detection frequency	0–1	0 (Hz)	2.00		0	302	Χ	Χ	0	Χ	0
00	01.4450	, ,	Permanent detection	0 0	/LI-X	4.00		_	000	.,	.,	_	\ <u></u>	
83	0h1453	ZSD Band	frequency band	0–2	(Hz)	1.00		0	302	Х	X	0	Х	0
86 Note23)	0h1456	KEB P Gain	Energy buffering P	0–2	0000	1500		0	239	0	0	0	Х	Х
140(625)			gain Energy buffering I											
87	0h1457	KEB I Gain	gain	1–2	0000	500		0	239	0	0	0	Х	Χ
88	0h1458	KEB Slip Gain	Energy buffering slip	0.2	000.0 (%)	30.0		0	239	0	\cap	0	Х	Y
00	0111430	NED Slip Gall	gain	0-2	000.0 (70)	30.0		0	239	U	U	U	^	^
89	0h1459	KEB Acc Time	Energy buffering acceleration time	0–6	00 (sec)	10.0		0	239	0	0	0	Х	Х
			Select function for	0	No									
90	0h145A	New AHR Sel	preventing current			0:No		0	279	0	Х	Χ	Х	Χ
			hunting	1	Yes									
91	0h145B	AHR P-Gain	Gain from current	0-3	2767	1000		Χ	279	0	Χ	Χ	Χ	Χ

Table of Functions

	No.	Communi- cation Address	Name	Setting Range	Initial Value	Shift in Opera- tion	V	v C	S	de V C T
Ī			hunting prevention							

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

 $^{^{\}text{Note 21})}$ CON-72–75 are displayed only when CON-71,77 is set as a bit or other than "None".

Note 22) CON-82-83 are displayed only when DRV-09 (Control Mode) is set as "Vector".

Note 23) CON-78-79,86-89 are displayed only when CON-77 (KEB Select) is set as "KEB-1" or "KEB-2"

 $^{^{\}text{Note 24})}$ CON-91 is displayed only when CON-90 (New AHR Sel) is set as "Yes".

13.5 Parameter Mode – Input Terminal Block Function Group (→IN)

Input Terminal Block Function Group (PAR → IN)

	0					Chiff in		Co	ntr	ol N	Noc	de
No.	Communi- cation Address	LCD Display	Name	Setting Range	Initial Value	Shift in Opera- tion	Page	V / F	S L	V C	S L T	V C T
00	-	Jump Code	Jump code	0-99	65	0	-	0	0	0	0	0
01	0h1501	Freq at 100%	Frequency at maximum analog input	Start frequency- maximum frequency (Hz)	60.00	0	139	0	0	0	Х	X
02	0h1502	Torque at 100%	Torque at maximum analog input	0–200 (%)	100.0	0	139	X	Х	0	0	0
05	0h1505	V1 Monitor(V)	V1 input voltage display	0–10 (V)	0.00	0	139	0	0	0	0	0
06	0h1506	V1 Polarity	V1 input polarity selection	0 Unipolar 1 Bipolar	0: Unipolar	0	139	0	0	0	0	0
07	0h1507	V1 Filter	V1 input filter time constant	0-10000 (ms)	10	0	139	0	0	0	0	0
08	0h1508	V1 Volt x1	V1 minimum input voltage	0–10 (V)	0.00	0	139	0	0	0	0	0
09	0h1509	V1 Perc y1	V1 minimum output voltage (%)	0–100 (%)	0.00	0	139	0	0	0	0	0
10	0h150A	V1 Volt x2	V1 maximum input voltage	0–10 (V)	10.00	0	139	0	0	0	0	0
11	0h150B	V1 Perc y2	V1 maximum output voltage (%)	0–100 (%)	100.00	0	139	0	0	0	0	0
12 Note24)	0h150C	V1 (–)Volt x1'	V1 (–) minimum input voltage	-10–0 (V)	0.00	0	143	0	0	0	0	0
13	0h150D	V1(–)Perc y1'	V1 (–) minimum output voltage (%)	-100–0 (%)	0.00	0	143	0	0	0	0	0
14	0h150E	V1(-)Volt x2'	V1 (–) maximum input voltage	-10–0 (V)	-10.00	0	143	0	0	0	0	0
15	0h150F	V1(–)Perc y2'	V1 (–) maximum output voltage (%)	-100–0 (%)	-100.00	0	143	0	0	0	0	0
16	0h1510	V1 Inverting	Rotation direction change	0 No 1 Yes	0: No	0	139	0	0	0	0	0
17	0h1511	V1 Quantizing	V1 quantization change	0.04-10 (%)	0.04	0	139		0			0
20	0h1514	I1 Monitor(mA)	I1 input display	0–20 (mA)	0.00	0	146	0	0	-		0
22	0h1516	I1 Filter	I1 input filter time constant	0–10000 (ms)	10	0	146					0
23	0h1517	I1 Curr x1	I1 minimum input current	0–20 (mA)	4.00	0	146	0	0	0	0	0
24	0h1518	I1 Perc y1	Output at I1 minimum current (%)	0–100 (%)	0.00	0	146	-	0		_	0
25	0h1519	I1 Curr x2	I1 maximum input current	4-20 (mA)	20.00	0	146	0	0	0	0	0
26	0h151A	I1 Perc y2	Output at I1 maximum current	0-100 (%)	100.00	0	146	0	0	0	0	0
31	0h151F	I1 Inverting	Rotation direction change	0 No 1 Yes	0: No	0	146	0	0	0	0	0
32	0h1520	I1 Quantizing	I1 quantization level	0.04–10 (%)	0.04	0	146	0	0	0	0	0

Note 24) IN-12–15 codes are displayed only when IN-06 (V1 Polarity) is set as "Bipolar".

Input Terminal Block Function Group (PAR → IN)

	Communi-					Shift in		Со	ntro	ol M	lode	e
No.	cation Address	LCD Display	Name	Setting Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
35 Note 25)	0h1523	V2 Monitor(V)	V2 input display	0–10 (V)	0.00	0	148	0	0	0	0	0
36	0h1524	V2 Polarity	V1 input polarity selection	0 Unipolar1 Bipolar	1: Bipolar	0	148	0	0	0	0	0
37	0h1525	V2 Filter	V2 input filter time constant	0–10000 (ms)	10	0	148	0	0	0	0	0
38	0h1526	V2 Volt x1	V2 minimum input voltage	0–10 (V)	0.00	0	148	0	0	0	0	0
39	0h1527	V2 Perc y1	Output at V2 minimum voltage (%)	0–100 (%)	0.00	0	148	0	0	0	0	0
40	0h1528	V2 Volt x2	V2 maximum input voltage	0–10 (V)	10.00	0	148	0	0	0	0	0
41	0h1529	V2 Perc y2	Output at V2 maximum voltage (%)	0–100 (%)	100.00	0	148	0	0	0	0	0
42	0h152A	V2 –Volt x1'	V2 –minimum input voltage	-10–0 (V)	0.00	0	148	0	0	0	0	0
43	0h152B	V2–Perc y1'	Output at V2–minimum voltage (%)	-100–0 (%)	0.00	0	148	0	0	0	0	0
44	0h152C	V2 –Volt x2'	V2 –maximum input voltage	-10–0 (V)	-10.00	0	148	0	0	0	0	0
45	0h152D	V2 –Perc y2'	Output at V2–maximum voltage (%)	-100–0 (%)	-100.00	0	148	0	0	0	0	0
46	0h152E	V2 Inverting	Rotation direction change	0 No 1 Yes	0:No	0	148	0	0	0	0	0
47	0h152F	V2 Quantizing	V2 quantization level	0.04–10 (%)	0.04	0	148	0	0	0	0	0
50	0h1532	I2 Monitor(mA)	I2 input display	0–20 (mA)	0.00	0	149	0	0	0	0	0
52	0h1534	I2 Filter	I2 input filter time constant	0–10000 (ms)	15	0	149	0	0	0	_	0
53	0h1535	I2 Curr x1	I2 minimum input current	0-20 (mA)	4.00	0	149	0	0	0	0	0
54	0h1536	I2 Perc y1	Output at I2 minimum current (%)	0–100 (%)	0.00	0	149	0	0	0	0	0
55	0h1537	I2 Curr x2	I2 maximum input current	0-20 (mA)	20.00	0	149	0	0	0	0	0
56	0h1538	I2 Perc y2	Output at I2 maximum current (%)	0–100 (%)	100.00	0	149	0	0	0	0	0
61	0h153D	I2 Inverting	Rotation direction change	0 No 1 Yes	0:No	0	149	0	0	0	0	0
62	0h153F	I2 Quantizing	l2 quantization level	0.04–10 (%)	0.04	0	149	0	0	0	0	0

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

 $^{^{\}text{Note}\,25)}$ IN-35–62 codes are displayed only when the expansion IO module is installed.

Input Terminal Block Function Group (PAR → IN)

							01:6		Co	ontr	ol l	Mo	de_
No.	Communi- cation	LCD	Name	Sett	ting Range	Initial Value	Shift in Opera-	Page	٧	s	ν	S	٧
	Address	Display			99+		tion		/ F	L	C	L	C T
05	054544	D4 D-6	D4 ti	0	NONE	4.EV	V	450				·	
65	0h1541	P1 Define	P1 terminal function setting	1	FX	1:FX	Х	158	0	0			0
66	0h1542	P2 Define	P2 terminal function setting	2	RX	2:RX	X	158	Χ	Χ			0
67	0h1543	P3 Define	P3 terminal function setting	3	RST	5:BX	X	329	0	0		0	0
68	0h1544	P4 Define	P4 terminal function setting	4	External Trip	3:RST	X	318	0	0			0
69	0h1545	P5 Define	P5 terminal function setting	5	BX	7:Sp-L	X	328	0	0			0
70	0h1546	P6 Define	P6 terminal function setting	6	JOG	8:Sp-M	X	199	0	0		0	0
71	0h1547	P7 Define	P7 terminal function setting	7	Speed-L	9:Sp-H	X	154	0	0		О	0
72	0h1548	P8 Define	P8 terminal function setting	8	Speed-M	6:JOG	X	154	0	0	0	0	0
73 Note26)	0h1549	P9 Define	P9 terminal function setting	9	Speed-H	0:NONE	Х	154	0	0	0	0	0
74	0h154A	P10 Define	P10 terminal function setting	10	Speed-X	0:NONE	Х	154	0	0	0	0	0
75	0h154B		P11 terminal function setting	11	XCEL-L	0:NONE	X	168					
				12	XCEL-M			168					
				13	RUN Enable			207					İ
				14	3-Wire	1		206					İ
				15	2nd Source	1		190					İ
				16	Exchange	1		253					İ
				17	Up	1		202					İ
				18	Down	1		202					İ
				19	U/D Save			202					İ
				20	U/D Clear			202					İ
				21	Analog Hold			153					İ
				22	I-Term Clear			210					İ
				23	PID Openloop	1		210					İ
				24	P Gain2	1		210					İ
				25	XCEL Stop			173					İ
				26	2nd Motor	1		251					İ
				27	Trv Offset Lo			266					ĺ
				28	Trv Offset Hi			266					ĺ
				29	Interlock 1			275					ĺ
				30	Interlock 2			275					l
				31	Interlock 3			275					ĺ
				32	Interlock 4			275					L

^{*} The grey cells indicate a hidden code which is only visible when setting a code. Note = 26 IN73–75 codes are displayed only when the expansion IO module is installed.

Input Terminal Block Function Group (PAR → IN)

No.	Communi- cation Address	LCD Display	Name	Setting Range	Initial Value	Shift in Opera- tion	Page	Co V / F	ontr S L	ol N V C	S	de V C T
				33 -Reserved- 34 Pre Excite 35 Speed/Torque 36 ASR Gain 2 37 ASR P/PI 38 Timer In 39 Thermal In 40 Dis Aux Ref 41 -Reserved- 42 -Reserved- 43 -Reserved- 44 -Reserved- 45 -Reserved- 46 FWD JOG 47 REV JOG 48 Trq Bias 49 XCEL-H 50 KEB Select 51 Fire Mode			- - 236 233 265 315 194 - - - 200 200 235 168 239 280					
85	0h1555	DI On Delay	Multi-function input terminal On filter	0–10000 (ms)	10	0	192	0	0	0	0	0
86	0h1556	DI Off Delay	Multi-function input terminal Off filter	0–10000 (ms)	3	0	192	0	0	0	0	0
87	0h1557	DINC/NO Sel	Multi-function input contact point selection	P8 – P1 0 A contact point (NO) 1 B contact point (NC)	0000 0000	Х	192	0	0	0	0	0
88	0h1558	RunOn Delay	Operating command delay time	0–100 (sec)	0.00	X	192	0	0	0	0	0
89	0h1559	InCheck Time	Sequential command delay time	1–5000 (ms)	1	Х	192	0	0	0	0	0
90	0h155A	DI Status	Multi-function input terminal status	P8 – P1 0 Open (Off) 1 Connection (On)	0000 0000	0	192	0	0	0	0	0

13.6 Parameter Mode – Output Terminal Block Function Group (→OUT)

Output Terminal Block Function Group (PAR → OUT)

No.	Communi- cation Address	LCD Display		Setting Range	Initial Value	Shift in Opera- tion	Page	Co V / F	ontr S L	ol N V C	Mod S L T	de V C T
00	-	JumpCode	Jump code	0-99	30	0	-	0	0	0	0	0
01	0h1601	AO1 Mode	Analog output 1	0 Frequency 1 Current 2 Voltage 3 DC Link Volt 4 Torque 5 Watt 6 Idss 7 Iqss 8 Target Freq 9 Ramp Freq 10 Speed Fdb 11 Speed Dev 12 PIDRef Value 13 PIDFdb Value 14 PID Output 15 Constant	0: Frequency	0	291	0	0	0	0	0
02	0h1602	AO1 Gain	Analog output1 gain	-1000–1000(%)	100.0	0	291	0	0	0	0	0
03	0h1603	AO1 Bias	Analog output 1 bias	-100–100(%)	0.0	0	291	0	0			
04	0h1604	AO1 Filter	Analog output1 filter	0–10000 (ms)	5	0	291	0				0
05	0h1605	AO1 Const %	Analog constant output 1	0–1000(%)	0.0	0	291		0			0
06	0h1606	AO1 Monitor	Analog output 1 monitor	0-1000(%)	0.0	-	291	0	0	0	0	0
07	0h1607	AO2 Mode	Analog output 2 item	0 Frequency 1 Current 2 Voltage 3 DC Link Volt 4 Torque 5 Watt 6 Idss 7 Iqss 8 Target Freq 9 Ramp Freq 10 Speed Fdb 11 Speed Dev 12 PIDRef Value 13 PIDFbk Value 14 PID Output 15 Constant	0: Frequency	0	293		Ο			0

Output Terminal Block Function Group (PAR → OUT)

						01.18.1		Co	ntro	ol N	lod	le
No.	Communi- cation Address	LCD Display	Name	Setting Range	Initial Value	Shift in Opera- tion	Page	V / F	S	V C	S L T	V C T
08	0h1608	AO2 Gain	Analog output 2 gain	-1000–1000 (%)	80.0	0	293	0				0
09	0h1609	AO2 Bias	Analog output 2 bias	-100–100 (%)	20.0	0	293	0				0
10	0h160A	AO2 Filter	Analog output 2 filter	0–10000 (ms)	5	0	293	0	0	0	0	0
11	0h160B	AO2 Const %	Analog constant output 2	0–100 (%)	0.0	0	293	0	0	0	0	0
12	0h160C	AO2 Monitor	Analog output 2 monitor	0–1000 (%)	0.0	0	293	0	0	0	0	0
14 Note27)	0h160E	AO3 Mode	Analog output 3 item	0 Frequency 1 Current 2 Voltage 3 DC Link Volt 4 Torque 5 Watt 6 Idss 7 Iqss 8 Target Freq 9 Ramp Freq 10 Speed Fdb 11 Speed Dev 12 PID Ref Value 13 PID Fbk Value 14 PID Output 15 Constant	0: Frequency	0	296	Ο	0	0	0	0
15	0h160F	AO3 Gain	Analog output 3 gain	-1000–1000 (%)	100.0	0	296	0	0	0	0	0
16	0h1610	AO3 Bias	Analog output 3 bias	-100–100 (%)	0.0	0	296	0	0	0		0
17	0h1611	AO3 Filter	Analog output 3 filter	0-10000 (ms)	5	0	296	0	0	0	0	O
18	-	AO3 Const %	Analog constant output 3	0–100 (%)	0.0	0	296	0	0	0	0	0
19	0h1613	AO3 Monitor	Analog output 3 monitor	-1000–1000 (%)	0.0	0	296	0	0	0	0	0
20	0h1614		Analog output 4 item	0 Frequency 1 Current 2 Voltage 3 DC Link Volt 4 Torque 5 Watt 6 Idss 7 Iqss 8 Target Freq 9 Ramp Freq 10 Speed Fdb 11 Speed Dev 12 PID Ref Value 13 PID Fbk Value 14 PID Output 15 Constant	0: Frequency		297	Ο	О	0	0	0

Output Terminal Block Function Group (PAR → OUT)

							Oh:tt		Co	ntr	ol	Mo	de
No.	Communi- cation Address	LCD Display	Name	Set	tting Range	Initial Value	Shift in Opera- tion	Page	V / F	S L	V C	S L T	V C T
21	0h1615	AO4 Gain	Analog output 4 gain	-10	00–1000 (%)	80.0	-	297	О	О			0
22	0h1616	AO4 Bias	Analog output 4 bias		0–100 (%)	20.0	0	297	0	0			0
23	0h1617	AO4 Filter	Analog output 4 filter	0–1	10000 (ms)	5	0	297	0	0	0	0	0
24	-	AO4 Const %	Analog constant output 4	0–1	100 (%)	0.0	0	297	0	0	0	0	0
25	0h1619	AO4 Monitor	Analog output 4 monitor		1000 (%)	0.0	0	297	0	0	0	0	0
				_	000 - 111								
				1	Low voltage	_							
30	0h161E	Trip Out Mode	Failure output item	2	Failure other than low voltage	010	0	298	0	0	0	0	0
				3	Final failure of automatic restart								
31	0h161F	Relay 1	Multi-function relay 1	0	NONE	29:Trip	0	298	0	0	0	0	0
32	0h1620	Relay 2	Multi-function relay 2	1	FDT-1	14:Run	0	298	0	0	0	0	0
33	0h1621	Q1 Define	Multi-function output 1	2	FDT-2	1:FDT-1	0	298	0	0	0	0	0
34 Note28)	0h1622	Relay 3	Multi-function relay 3	3	FDT-3	2:FDT-2	0			0			
35	0h1623	Relay 4	Multi-function relay 4	4	FDT-4	3:FDT-3	0	298	0	0	0	0	0
36	0h1624	Relay 5	Multi-function relay 5	5	Over Load	4:FDT-4	0	298	0	0	0	0	0
				6	IOL	_							
				7	Under Load	4							
				8	Fan Warning	4							
				9	Stall	_							
					Over Voltage Low Voltage	-							
					Over Heat	+							
					Lost Command	=							
					Run	1							
					Stop								
					Steady								
					Inverter Line								
				18	Comm Line								
					Speed Search								
					-Reserved-								
					-Reserved-								
					Ready	4							
					Trv Acc								
					Trv Dec	4							
					MMC	4							
					Zspd Dect	-							
					Torque Dect	-							
				Zδ	Timer Out		1						Щ.

Note 27) OUT 14-25 codes are displayed only when the expansion IO module is installed.

Note 28) OUT 34-36 codes are displayed only when the expansion IO module is installed.

Output Terminal Block Function Group (PAR → OUT)

	Communi-						Shift in		Co	ntr	ol I	Mod	de
No.	cation Address	LCD Display	Name	Sett	ing Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
				30 31 32 33 34 35 36 37	Trip Lost Keypad DB Warn %ED ENC Tune ENC Dir On/Off Control BR Control KEB Operating Fire Mode Run2								
41	0h1629	DO Status	Multi-function output monitoring	-		000	Х	298	-	-	-	-	-
50	0h1632	DO On Delay	Multi-function output On delay	0–10	00 (sec)	0.00	0	305	0	0	0	0	0
51	0h1633	DO Off Delay	Multi-function output Off delay	0–10	00 (sec)	0.00	0	305	0	0	0	0	0
52	0h1634	DO NC/NO Sel	Multi-function output contact point selection	0	Relay2,Relay1 A contact point (NO) B contact point (NC)	000	x	305	0	0	0	0	0
53	0h1635	TripOut OnDly	Failure output On delay	0–10	00 (sec)	0.00	0	304	0	0	0	0	0
54	0h1636	TripOut OffDly	Failure output Off delay	0–10	00.00 (sec)	0.00	0	304	_		_	0	
55	0h1637	TimerOn Delay	Timer On delay	0–10	00.00 (sec)	0.00	0	265	0	0	0	0	0
56	0h1638	TimerOff Delay	Timer Off delay		00.00 (sec)	0.00	0	265	0	0	0	0	0
57	0h1639	FDT Frequency	Detected frequency	-	naximum uency (Hz)	30.00	0	299	0	0	0	0	0
58	0h163A	FDT Band	Detected frequency width	-	naximum uency (Hz)	10.00	0	299	0	0	0	0	0
59	0h163B	TD Level	Detected torque amount		50 (%)	100	0	236	Х	Х	0	X	0
60	0h163C	TD Band	Detected torque width	0–10	0 (%)	5.0	0	236	Χ	Χ	0	Χ	0

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

13.7 Parameter Mode – Communication Function Group (→COM)

Communication Function Group (PAR → COM)

No.	Communication Address	LCD Display	Name	Setting Range	Initial Value	Shift in Opera- tion	Page	V / F	S L	rol I V C	S L T	V C T
00	-	Jump Code	Jump code	0–99	20	0	-	0	0	0	0	0
01	0h1701	Int485 St ID	Built-in communication inverter ID	1–250	1	0	337	0	0	0	0	0
02	0h1702	Int485 Proto	Built-in communication protocol	0 ModBus RTU1Reserved2 Serial Debug	0: ModBus RTU	0	337	0	0	0	0	0
03	0h1703	Int485 BaudR	Built-in communication speed	0 1200 bps 1 2400 bps 2 4800 bps 3 9600 bps 4 19200 bps 5 38400 bps	3: 9600 bps	0	337	0	0	0	0	0
04	0h1704	Int485 Mode	Built-in communication frame setting	0 D8/PN/S1 1 D8/PN/S2 2 D8/PE/S1 3 D8/PO/S1	0: D8/PN/S1	-	337	0	0	0	0	0
05	0h1705	Resp Delay	Transmission delay after reception	0–1000 (ms)	5 ms	0	337	0	0	0	0	0
06 Note29-1)	0h1706	FBus S/W Ver	Communication option S/W version	-	1.00	0	Option	0	0	0	0	0
07	0h1707	FBus ID	Communication option inverter ID	0–255	1	0	Option	0	0	0	0	0
08	0h1708	FBUS BaudRate	FBus communication speed	-	12 Mbps		Option	0	0	0	0	0
09	0h1709	FieldBus LED	Communication option LED status	-	-	0	Option	0	0	0	0	0
30	0h171E	ParaStatus Num	Number of output parameters	0–8	3	0	342	0	0	0	0	0
31	0h171F	Para Stauts-1	Output address 1	0000-FFFF Hex	000A	0	342	0	0	0	0	0
32	0h1720	Para Stauts-2	Output address 2	0000-FFFF Hex	000E	0	342	0		0	0	0
33	0h1721	Para Stauts-3	Output address 3	0000-FFFF Hex	000F	0	342	0	0	0	0	0
34	0h1722	Para Stauts-4	Output address 4	0000-FFFF Hex	0000	0	342			0	_	0
35	0h1723	Para Stauts-5	Output address 5	0000-FFFF Hex	0000	0	342		0		0	
36	0h1724	Para Stauts-6	Output address 6	0000-FFFF Hex	0000	0	342		0			0
37	0h1725	Para Stauts-7	Output address 7	0000-FFFF Hex	0000	0	342	0	0	0	_	0
38	0h1726	Para Stauts-8	Output address 8	0000-FFFF Hex	0000	0	342	0	0	0	0	0

^{*} The grey cells indicate a hidden code which is only visible when setting a code. Note 29-1) COM 06–17 codes are displayed only when the communication module is installed. Refer to the Options manual for options.

Communication Function Group (PAR → COM)

No.	Communi- cation Address	LCD Display	Name	Settine	g Range	Initial Value	Shift in Opera- tion	Page	Co V / F	ntro S L	V C	lod S L T	le V C T
50	0h1732	Para Ctrl Num	Number of input parameters	0–8		2	0	342	0	0	0	0	0
51	0h1733	Para Control-1	Input address 1	0000-l	FFFF Hex	0005	Χ	342	0	0	0	0	0
52	0h1734	Para Control-2	Input address 2		FFFF Hex	0006	Χ	342	0	0	_	_	0
53	0h1735	Para Control-3	Input address 3		FFFF Hex	0000	Χ	342	0	0	-	_	0
54	0h1736	Para Control-4	Input address 4		FFFF Hex	0000	X	342	0	0			0
55	0h1737	Para Control-5	Input address 5		FFFF Hex	0000	X	342	0	0			0
56	0h1738	Para Control-6	Input address 6		FFFF Hex	0000	X	342	0	0		_	0
57	0h1739	Para Control-7	Input address 7	0000-l	FFFF Hex	0000	Χ	342	0	0		0	0
58	0h173A	Para Control-8	Input address 8	0000-l	FFFF Hex	0000	Χ	342	0	0	0	0	0
68	0h1744	FBus Swap Sel	Profibus swap	0	No Yes	0:No	Х	Option	0	0	0	0	0
70	0h1746	Virtual DI 1	Communication multi- function input 1	0	None	0:None	0	339	0	0	0	0	0
71	0h1747	Virtual DI 2	Communication multi- function input 2	1	FX	0:None	0	339	0	0	0	0	0
72	0h1748	Virtual DI 3	Communication multi- function input 3	2	RX	0:None	0	339	0	0	0	0	0
73	0h1749	Virtual DI 4	Communication multi- function input 4	3	RST	0:None	0	339	0	0	0	0	0
74	0h174A	Virtual DI 5	Communication multi- function input 5	4	External Trip	0:None	0	339	0	0	0	0	0
75	0h174B	Virtual DI 6	Communication multi- function input 6	5	BX	0:None	0	339	0	0	0	0	0
76	0h174C	Virtual DI 7	Communication multi- function input 7	6	JOG	0:None	0	339	0	0	0	0	0
77	0h174D	Virtual DI 8	Communication multi- function input 8	7	Speed-L	0:None	0	339	0	0	0	0	0
78	0h174E	Virtual DI 9	Communication multi- function input 9	8	Speed-M	0:None	0	339	0	0	0	0	0
79	0h174F	Virtual DI 10	Communication multi- function input 10	9	Speed-H	0:None	0	339	0	0	0	0	0
80	0h1750	Virtual DI 11	Communication multi- function input 11	10	Speed-X	0:None	0	339	0	0	0	0	0
81	0h1751	Virtual DI 12	Communication multi- function input 12	11	XCEL-L	0:None	0	339	0	0	0	0	0
82	0h1752	Virtual DI 13	Communication multi- function input 13	12	XCEL-M	0:None	0	339	0	0	0	0	0
83	0h1753	Virtual DI 14	Communication multi- function input 14	13	RUN Enable	0:None	0	339	0	0	0	0	0
84	0h1754	Virtual DI 15	Communication multi- function input 15	14	3-Wire	0:None	0	339	0	0	0	0	0
85	0h1755	Virtual DI 16	Communication multi- function input 16	15	2nd Source	0:None	0	339	0	0	0	0	0
				16	Exchange								
					Up/Down								
				19	Reserved	0:None	0	-	0	0	0	0	0
				20	U/D Clear								
				21	Analog Hold		<u> </u>						L

No.	Communi- cation Address	LCD Display	Name	Setting	g Range	Initial Value	Shift in Opera- tion	Page	Coi V / F	s	V C	od S L T	e V C T
				22	I-Term Clear					П	П		
				23	PID								ì
				24	Openloop P Gain2								1
				25	XCEL Stop								1
				26	2nd Motor								ì
				27	Trv Offset Lo								ì
				28	Trv Offset Hi								ì
				29	Interlock 1								İ
				30	Interlock 2								Ì
				31	Interlock 3								İ
				32 33	Interlock 4								ì
				34	Reserved Pre Excite								ì
				35	Speed/Torqu e								Ī
				36	ASR Gain 2								ì
				37	ASR P/PI								i
				38	Timer In								ì
				39	Thermal In								i
				40	Dis Aux Ref								ì
				41	-Reserved-								i
				42	-Reserved-								i
				43 44	-Reserved-								Ì
				45	-Reserved-								Ì
				46	FWD JOG								Ì
				47	REV JOG								Ì
				48	Trq Bias								Ì
				49	XCEL-H								Ì
				50	KEB Select								1
			0 ' " "	51	Fire Mode						4	\dashv	_
86	0h1756	Virt DI Status	Communication multi- function input monitoring	-	-	0	Х	339	0	0	0	0	0
90	0h175A	Comm Mon Sel	Monitor type selection	0 1	Int 485 Keypad	0: Int 485	0	341	0	0	0	0	0
91	0h175B	RcvFrame Num	Number of reception frames	-		0	-	341	0	0			0
92	0h175C	Err Frame Num	Number of error frames	-		0	-	341	0	0	0	0	0
93	0h175D	Nak Frame Num	Number of writing error frames	-		0	-	341	0	0	0	0	0
94 note 29-2)	0h175E	Comm Update	Communication update	0	No Yes	0	-	341	0	0	0	0	0

note29-2) COM 94 is displayed when the communication option module is installed.

13.8 Parameter Mode – Applied Function Group (→APP)

Applied Function Group (PAR → APP)

	0					Shift in		Со	ntr	ol N	lod	le
No.	Communication Address	LCD Display	Name	Setting Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
00	-	Jump Code	Jump code	0–99	20	0	-	0	0	0	0	0
01	0h1801	App Mode	Applied function selection	0 None 1 Traverse 2 Proc PID 3 Reserved 4 Auto Sequence	0: None	x	-	0	0	0	X	х
08 Note30)	0h1808	Trv Apmlit %	Traverse operating range	0–20 (%)	0.0	0	266	0	0	0	Х	X
09	0h1809	Trv Scramb %	Traverse scramble magnitude	0–50 (%)	0.0	0	266	0	0	0	X	X
10	0h180A	Trv Acc Time	Traverse acceleration time	0.1-600.0 (sec)	2.0	0	266	0	0	0	Х	Χ
11	0h180B	Trv Dec Time	Traverse deceleration time	0.1-600.0 (sec)	3.0	0	266	0	0	0	Х	Χ
12	0h180C	Trv Offset Hi	Traverse offset upper limit	0-20.0 (%)	0.0	0	266	0	0	0		Χ
13	0h180D	Trv Offset lo	Traverse offset lower limit	0-20.0 (%)	0.0	0	266	0	0	0	Х	Χ
16 Note31)	0h1810	PID Output	PID output monitor	(%)	0.00	-	213	0	0	0	Χ	X
17	0h1811	PID Ref Value	PID reference monitor	(%)	50.00	-	213	0	0	0	Χ	Χ
18	0h1812	PID Fdb Value	PID feedback monitor	(%)	0.00	-	213	0	0	0		Χ
19	0h1813	PID Ref Set	PID reference setting	-100–100 (%)	50%	0	213	0	0	0	Χ	Χ
20	0h1814	PID Ref Source	PID reference selection	0 Keypad 1 V1 2 I1 3 V2 4 I2 5 Int 485 6 Encoder 7 FieldBus 8 PLC 9 Synchro 10 Binary Type	0:Key pad	x	213	0	0	0	Х	x

^{*} The grey cells indicate a hidden code which is only visible when setting a code.

Note 30) APP 08-13 codes are displayed only when APP-01 (App Mode) is set as "Traverse".

Note 31) APP 16-45 codes are displayed only when APP-01 (App Mode) is set as "Proc PID" or APP-01(App Mode) is set as "MMC" and Requl Bypass (APO-34) is set as "No".

Applied Function Group (PAR → APP)

							01.16		Со	ntre	ol M	lod	le
No.	Communi- cation Address	LCD Display	Name	Se	tting Range	Initial Value	Shift in Opera- tion	Page	V / F	s L	V C	S L T	V C T
21	0h1815	PID F/B Source	PID feedback selection	9	V1 I1 V2 I2 Int 485 Encoder FieldBus PLC Synchro Binary Type	-0:V1	х	213	0		0		
22	0h1816	PID P-Gain	PID proportional gain	_	1000 (%)	50.0	0	213	0	0			X
23	0h1817	PID I-Time	PID integral time	_	200.0 (sec)	10.0	0	213	0	0			X
24	0h1818	PID D-Time	PID differential time		1000 (ms)	0	0	213	0				Χ
25	0h1819	PID F-Gain	PID feed forward gain		1000.0 (%)	0.0	0	213	0	0			X
26	0h181A	P Gain Scale	Proportional gain scale		100.0 (%)	100.0	X	213	0	0			X
27	0h181B	PID Out LPF	PID output filter	+	10000 (ms)	0	0	213	0	0	0	Χ	Χ
28	0h181C	PID Mode	PID mode select	0	Process PID	0:Process PID	212	213	0	0	0	Χ	Χ
29	0h181D	PID Limit Hi	PID upper limit frequency	fre (H:		60.00	0	213	0	0	0	X	Х
30	0h181E	PID Limit Lo	PID lower limit frequency		00–PID upper limit quency (Hz)	-60.00	0	213	0	0	0	X	X
31	0h181F	PID Out Inv	PID output inverse	0	No Yes	0:No	212	213	0	0	0	Χ	X
32	0h1820	PID Out Scale	PID output scale	0.1	I–1000 (%)	100.0	Х	213	0	0	0	Χ	X
34	0h1822	Pre-PID Freq	PID control period movement frequency	-	maximum quency (Hz)	0.00	Х	213	0	0	0	X	X
35	0h1823	Pre-PID Exit	PID control period movement level		100 (%)	0.0	Х	213	0	0	0	X	X
36	0h1824	Pre-PID Delay	PID control period movement delay time	0–!	9999 (sec)	600	0	213	0	0	0	X	X
37	0h1825	PID Sleep DT	PID sleep mode delay time	0–!	999.9 (sec)	60.0	0	213	0	0	0	X	X
38	0h1826	PID Sleep Freq	PID sleep mode frequency		maximum quency (Hz)	0.00	0	213	0	0	0	X	X
39	0h1827	PID WakeUp Lev	PID wake up level	0–	100 (%)	35	0	213	0	0	0	X	X
40	0h1828	PID WakeUp Mod	PID wake up mode setting	0 1 2	Below Level Above Level Beyond Level	0:Below Level	0	213	0	0	0	X	X
41	0h1829	PID Rev Run En	PID reverse operation	0	No Yes	0:No	Х	213	0	0	0	X	Х
42		<u></u>		0 1 2 3	% Bar mBar Pa	0:%	0	213	0	0	0	Х	х

No.	Communi- cation Address	LCD Display	Name	Se	tting Range	Initial Value	Shift in Opera- tion	Page	Co V / F	ntro S L	V C	lod S L T	le V C T
					KPa								
				5	Hz								
				6	rpm								
				7	V								
				8	I								
				9	kW								
				10	HP								
				11	℃								
				12	°F								
43	0h182B	PID Unit Gain	PID unit gain	0–3	300 (%)	100.00	0	213	0	0	0	Χ	Χ
				0	X 0.01								
		DID I In:		1	X 0.1								
44	0h182C	PID Unit	PID unit scale	2	X 1	2:x 1	0	213	0	0	0	Χ	Χ
		Scale		3	X 0.1								
				4	X 0.01								
45	0h182D	PID P2-Gain	PID 2 nd proportional gain	0-	1000 (%)	100.0	Х	213	0	0	0	Χ	Χ

Note 31) APP 16-45 codes are displayed only when APP-01 (App Mode) is set as "Proc PID" or APP-01(App Mode) is set as "MMC" and Requl Bypass (APO-34) is set as "No".

13.9 Parameter Mode – Option Module Function Group (**→**APO)

Option Module Function Group (PAR → APO)

	Communi-						Shift in		Со	ntro	ol N	lod	е
No.	cation Address	LCD Display	Name	Se	tting Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
00	-	Jump Code	Jump code	0-9	99	20	0		0	0	0	0	0
0.4				0	None								
01 Note37)	0h1A01	Enc Opt Mode	Encoder function item	1	Feedback	0:None	0	150	0	0	0	0	0
		- '		2	Reference								
				0	Line Driver								
04	0h1A04	Enc Type Sel	Encoder type selection	1	Totem or Com	0:Line Driver	x	150	0	0	0	0	0
				2	Open Collector								
		_		0	(A+B)								
05	0h1A05	Enc Pulse Sel	Encoder pulse direction	1	-(A+B)	0: (A+B)	X	150	0	0	0	0	0
				2	A	,							
06	0h1A06	Enc Pulse Num	Number of encoder pulses	10-	-5000	1024	х	150	0	0	0	0	0
80	0h1A08	Enc Monitor	Feedback monitor	-		-	0	150	0	0	0	0	0
09	0h1A09	Pulse Monitor	Reference monitor	-		-	0	150	0	0	0	0	0
10	0h1A0A	Enc Filter	Encoder input filter	0–	10000 (ms)	3	0	150	0	0	0	0	0
11	0h1A0B	Enc Pulse x1	Encoder minimum input pulse	0–	100 (kHz)	0.0	0	150	0	X	0	Χ	0
12	0h1A0C	Enc Perc y1	Output at encoder minimum pulse (%)	0–	100 (%)	0.00	0	150	0	Х	0	Х	0
13	0h1A0D	Enc Pulse x2	Encoder maximum input pulse	0–2	200 (kHz)	100	0	150	0	Х	0	Χ	0
14	0h1A0E	Enc Perc y2	Encoder maximum pulse output (%)	0–	100 (%)	100	0	150	0	Х	0	Χ	0
20 Note38)	0h1A14	Aux Motor Run	Display of number of auxiliary motor movements	0-4	4	0	0	270	0	0	0	X	X
21	0h1A15	Starting Aux	Starting auxiliary motor selection	1–	4	1	х	270	0	0	0	Χ	X
22	0h1A16	AutoOp Time	Auto change operation time	X:X	XX (Min)	0:00	0	270	0	0	0	X	X
23	0h1A17	Start Freq 1	1st auxiliary motor starting frequency	0–6	60 (Hz)	49.99	0	270	0	0	0	Х	X
24	0h1A18	Start Freq 2	2nd auxiliary motor starting frequency	0–6	60 (Hz)	49.99	0	270	0	0	0	Х	X
25	0h1A19	Start Freq 3	3rd auxiliary motor starting frequency	0–6	60 (Hz)	49.99	0	270	0	0	0	Х	X
26	0h1A1A	Start Freq 4	4th auxiliary motor starting frequency	0–6	60 (Hz)	49.99	0	270	0	0	0	Х	X

	Communi-					Initial	Shift in		Co	ntro	ol N	loc	le V
No.	cation Address	LCD Display	Name	Set	ting Range	Value	Opera- tion	Page	/ F	S L	V C	L T	C T
27	0h1A1B	Stop Freq 1	1st auxiliary motor stop frequency	0–6	60 (Hz)	15.00	0	270	0	0	0	Х	Х
28	0h1A1C	Stop Freq 2	2nd auxiliary motor stop frequency	0–6	60 (Hz)	15.00	0	270	0	0	0	Х	X
29	0h1A1D	Stop Freq 3	3rd auxiliary motor stop frequency		60 (Hz)	15.00	0	270	0	0	0	Х	Х
30	0h1A1E	Stop Freq 4	4th auxiliary motor stop frequency	0–6	60 (Hz)	15.00	0	270	0	0	0	Х	X
31	0h1A1F	Aux Start DT	Auxiliary motor starting delay time	0–3	8600.0 (sec)	60.0	0	270	0	0	0	Х	Х
32	0h1A20	Aux Stop DT	Auxiliary motor stop delay time		8600.0 (sec)	60.0	0	270	0	0	0	Х	X
33	0h1A21	Num of Aux	Auxiliary motor number selection	0–4	ļ	4	Х	270	0	0	0	Х	X
34	0h1A22	Regul Bypass	Bypass selection	0	No	0:No	X	270	0	0	0	Х	Х
		7 3 7		1	Yes					Ĺ	Ĺ		
			A	0	None								
35	0h1A23	Auto Ch Mode	Auto change mode selection	1	Aux	1: Aux	X	270	0	0	0	Χ	X
				2	Main								
36	0h1A24	Auto Ch Time	Auto change time	0–6	99:00 (min)	72:00	0	270	0	0	0	Χ	Χ
20	054406	Interlegic	Interioris a la ation	0	No	O.N.o.	0	070	^		_	v	~
38	0h1A26	Interlock	Interlock selection	1	Yes	0:No	0	270	0	٥	0	^	^
39	0h1A27	Interlock DT	Interlock movement delay time	0.1 (se	–360.0 c)	5.0	0	270	0	0	0	Χ	X
40	0h1A28	Actual Pr Diff	Auxiliary motor movement pressure difference	0–′	100 (%)	2	0	270	0	0	0	Х	X
41	0h1A29	Aux Acc Time	Main motor acceleration time when number of pumps decreases	0–€	600.0 (sec)	2.0	0	270	0	0	0	Х	Х
42	0h1A2A	Aux Dec Time	Main motor deceleration time when number of pumps increases	0–6	600.0 (sec)	2.0	0	270	0	0	0	х	Х
58 Note39)	0h1A3A	PLC LED Status	PLC option LED status	-		-	0	Option	0	0	0	0	0
59	0h1A3B	PLC S/W Ver	PLC option module S/W version	-		1.X	0	Option	0	0	0	0	0
60	0h1A3C	PLC Wr Data 1	PLC write data 1	0–F	FFFF (Hex)	0000	0	Option	0	0	0	0	0
61	0h1A3D	PLC Wr Data 2	PLC write data 2	0–F	FFFF (Hex)	0000	0	Option	0	0	0	0	0
62	0h1A3E	PLC Wr Data 3	PLC write data 3	0–F	FFFF (Hex)	0000	0	Option	0	0	0	0	0
63	0h1A3F	PLC Wr Data 4	PLC write data 4	0–F	FFFF (Hex)	0000	0	Option	0	0	0	0	0
64	0h1A40	PLC Wr Data 5	PLC write data 5	0–F	FFFF (Hex)	0000	0	Option	0	0	0	0	0
65	0h1A41	PLC Wr Data 6	PLC write data 6	0–F	FFFF (Hex)	0000	0	Option	0	0	0	0	0

	Communi-					Shift in		Co	ntro	ol N	lod	le
No.	cation Address	LCD Display	Name	Setting Range	Initial Value		Page	V / F	S L	V C	S L T	V C T
66	0h1A42	PLC Wr Data 7	PLC write data 7	0-FFFF (Hex)	0000	0	Option	0	0	0	0	0
67	0h1A43	PLC Wr Data 8	PLC write data 8	0-FFFF (Hex)	0000	0	Option	0	0	0	0	0
76	0h1A4C	PLC Rd Data 1	PLC read data 1	0-FFFF (Hex)	0000	0	Option	0	0	0	0	0
77	0h1A4D	PLC Rd Data 2	PLC read data 2	0-FFFF (Hex)	0000	0	Option	0	0	0	0	0
78	0h1A4E	PLC Rd Data 3	PLC read data 3	0-FFFF (Hex)	0000	0	Option	0	0	0	0	0
79	0h1A4F	PLC Rd Data 4	PLC read data 4	0-FFFF (Hex)	0000	0	Option	0	0	0	0	0
80	0h1A50	PLC Rd Data 5	PLC read data 5	0-FFFF (Hex)	0000	0	Option	0	0	0	0	0
81	0h1A51	PLC Rd Data 6	PLC read data 6	0-FFFF (Hex)	0000	0	Option	0	0	0	0	0
82	0h1A52	PLC Rd Data 7	PLC read data 7	0-FFFF (Hex)	0000	0	Option	0	0	0	0	0
83	0h1A53	PLC Rd Data 8	PLC read data 8	0-FFFF (Hex)	0000	0	Option	0	0	0	0	0

The grey cells indicate a hidden code which is only visible when setting a code.

Note 37) APO-01–14 codes are displayed only when the encoder module is installed.

 $^{^{\}text{Note }38)}$ APO-20–42 codes are displayed only when APP-01 (App Mode) is set as "MMC".

 $^{^{\}text{Note }39)}\text{APO-}58\text{--}83$ codes are displayed only when the PLC option module is installed.

13.10Parameter Mode – Protective Function Group (→PRT)

Protective Function Group (PAR → PRT)

Pro	tective i	-unction G	roup (PAR 🕇 i	-KI)								
	Communi-					Shift in		Co	ontr	ol N	Nod	le
No.	cation Address	LCD Display	Name	Setting Range	Initial Value	Opera- tion	Page	V / F	S L	V C	S L T	V C T
00	-	Jump Code	Jump code	0–99	40	0		0	0	0	0	0
04	0h1B04	Load Duty	Load amount setting	Normal Duty Heavy Duty	1:Heavy Duty	X	310	0	0	0	0	0
05	0h1B05	Phase Loss Chk	Input/output open- phase protection	Bit 00–11 1 Output open phase 2 Input open phase	00	Х	317	0	0	0	0	0
06	0h1B06	IPO V Band	Input voltage range during open-phase	1–100 (V)	40	Х	317	0	0	0	0	0
07	0h1B07	Trip Dec Time	Deceleration time at fault trip	0-600 (sec)	3.0	0	319	0	0	0	0	0
80	0h1B08	RST Restart	Starting selection on trip reset	0 No 1 Yes	0:No	0	247	0	0	0	0	0
09	0h1B09	Retry Number	Number of automatic restarts	0–10	0	0	247	0	0	0	0	0
10 Note40)	0h1B0A	Retry Delay	Automatic restart delay time	0-60.0 (sec)	1.0	0	247	0	0	0	0	0
11	0h1B0B	Lost KPD Mode	Keypad command loss operation mode	0 None 1 Warning 2 Free-Run 3 Dec	-0:None	0	319	0	0	0	0	0
12	0h1B0C	Lost Cmd Mode	Speed command loss operation mode	0 None 1 Free-Run 2 Dec 3 Hold Input 4 Hold Output 5 Lost Preset	-0:None	0	321	0	0	0	0	0
13 Note41)	0h1B0D	Lost Cmd Time	Speed command loss judgment time	0.0-120 (sec)	1.0	0	321	0	0	0	0	0
14	0h1B0E	Lost Preset F	Operation frequency at speed command loss	Start frequency –maximum frequency (Hz)	0.00	0	321	0	0	0	0	0
15	0h1B0F	Al Lost Level	Analog input loss judgment level	0 Half of x1 1 Below x1	0:Half of x1	0	321	0	0	0	0	0
17	0h1B11	OL Warn Select	Overload alarm selection	0 No 1 Yes	0:No	0	310	0	0	_	0	
18	0h1B12	OL Warn Level	Overload alarm level	30–180 (%)	150	0	310	0	0		0	
19	0h1B13	OL Warn Time	Overload alarm time	0-30.0 (sec)	10.0	0	310	0	0	0	0	0
20	0h1B14	OL Trip Select	Motion at overload trip	0 None 1 Free-Run 2 Dec	1:Free- Run	0	310	0	0	0	0	0
		t.						_	•			

Protective Function Group (PAR → PRT)

No.	Communi- cation Address	LCD Display	Name	Setting Range	Initial Value	Shift in Opera-Page	Control Mode V S V S V / L C C
	Address					tion	F L C T T

No.	Communi-	LCD Display	Name	Setting Range		Initial	Shift in	Page	Co	ntr	ol IV	lod	e .
21	0h1B15	OL Trip Level	Overload trip level	30–200 (%)		180	0	310			0		
22	0h1B13	OL Trip Time	Overload trip time	0–60 (sec)		60.0	0	310			0		
			Under load alarm	0 No		00.0	0	310					
25	0h1B19	UL Warn Sel	selection	1 Yes		0:No	0	324	0	0	0	0	0
26	0h1B1A	UL Warn Time	Under load alarm time	0-600.0 (sec)		10.0	0	324	\circ	0	0	<u></u>	$\overline{\cap}$
	OTTE	OL Walli Tillio		0 None		10.0		02-1	Ť	Ŭ	Ť	Ť	<u>~</u>
27	0h1B1B	UL Trip Sel	Under load trip	1 Free-Run		0:None	0	324	O	0	0	o	0
	0.1.12.12	02p 00.	selection	2 Dec		0100		-					•
28	0h1B1C	UL Trip Time	Under load trip time	0-600 (sec)		30.0	0	324	0	0	0	0	0
			Under load lower limit	, ,			_	004					
29	0h1B1D	UL LF Level	level	10–30 (%)		30	0	324	O	O	0	ال	O
30	0h1B1E	UL BF Level	Under load upper limit	10 100 (0/)		30	0	324		0	$\overline{}$	0	_
30	UIIIDIE	OL BF Level	level	10–100 (%)		30	O	324)	U	U	U	
31	0h1B1F	No Motor Trip	Operation on no motor			0: None	0	330	0	0	О		0
31	UITIBIE	NO MOIOL THP	trip	1 Free-Run		U. INOITE)	330	U)		U	_
32	0h1B20	No Motor Level	No motor	1–100 (%)		5	0	330	\circ	О	ما	0	\cap
Note42)	UITIDZU	NO MOIOI LEVEI	detection current level	1-100 (70)		3	O	550	Ŭ		_		_
33	0h1B21	No Motor Time	No motor	0.1–10.0 (sec)		3.0	O	330	0	o	o	o	0
	0111521	THE MICHOL THING	detection delay			0.0		000		Ŭ	Ц	_	<u> </u>
		L	Operation at motor	0 None			_		_				
34	0h1B22	Thermal-T Sel	overheat detection	1 Free-Run		0:None	0	315	O	O	О	O	O
				2 Dec							\vdash	\dashv	
				0 None							İ		
0.5	01.4000	Thermal In	T1	1 V1		0.11	V	045					_
35	0h1B23	Src	Thermal sensor input	2 11		0:None	X	315	O	O	0	O	O
				3 V2 4 I2							İ		
			The aurent and a surface the	4 12						L ,	닉	ᆛ	
36	0h1B24	Thermal-T Lev	Thermal sensor fault level	0–100 (%)		50.0	0	315					
			Thermal sensor fault	0 Low								\dashv	_
37	0h1B25	Thermal-T Area	area	1 High		0:Low	0	315	О	0	0	О	0
			Electronic thermal fault								H	_	_
40	0h1B28	ETH Trip Sel	trip prevention	1 Free-Run		0:None	0	308	0	0	0	0	0
	0111520	Z T T T T T T T T T T T T T T T T T T T	selection	2 Dec		0.110110					ľ		
			Motor	0 Self-cool		0:Self-	_					_	_
41	0h1B29	Motor Cooling	cooling fan type	1 Forced-coo	ol	cool	0	308	0	0	0	О	0
			Electronic thermal one		<u>"</u>							ᆲ	_
42	0h1B2A	ETH 1min	minute rating	120–200 (%)		150	0	308	О	O	0	O	O
			Electronic thermal								7	寸	_
43	0h1B2B	ETH Cont	prevention continuous	50–200 (%)		120	0	308	0	0	0	0	0
			rating										
				0 (sec)	Free-run	0.0 /					T	T	_
45	0h1B2D	BX Mode	BX mode select	0.1–600.0		0.0 (Free-	0	328	0	0	0	X	Χ
		DA MOGE DA		(sec)	Dec run)		<u></u>						
									_				

Protective Function Group (PAR → PRT)

No. cation Address COD Display Name Setting Range Initial Operation Address COD Display Name Setting Range Setting Range Operation Ope	-10	JUCUIVE	i uncuoi	Group (PAR 🗩 Pr	`''							_		_
Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall Prevent Stall	No.	cation	LCD Display	Name	Setting	ı Range		Opera-	Page	V /	ontr S L	٧	S	٧
Stall Frequency 1 (Hz) Stall Level 1 Stall Irequency 1 (Hz) Stall Irequency 1 (Hz) Stall Irequency 2 (Hz) Stall Irequency 2 (Hz) Stall Irequency 2 (Hz) Stall Irequency 2 (Hz) Stall Irequency 2 (Hz) Stall Irequency 2 (Hz) Stall Irequency 2 (Hz) Stall Irequency 2 (Hz) Stall Irequency 2 (Hz) Stall Irequency 2 (Hz) Stall Irequency 2 (Hz) Stall Irequency 3 (Hz) Stall Irequency 3 (Hz) Stall Irequency 3 (Hz) Stall Irequency 3 (Hz) Stall Irequency 3 (Hz) Stall Irequency 4 (Hz) Stall Irequency 4 (Hz) Stall Irequency 4 (Hz) Stall Irequency 4 (Hz) Stall Irequency 3 (Hz) Stall Irequency 4 (Hz) Stall Irequency 3 (Hz) Stall Irequency 4 (Hz) Sta	50	0h1B32	Stall Prevent	Stall prevention	0 0001 1 0001 0 0010 1 0010 # 0100 #	Accelerating (Mode1) Accelerating (Mode2) Steady speed (Mode1) Steady speed (Mode2) Decelerating	000000	x	312	0	0	X	0	х
Stall Stall Level 1 Stall Level 1 Stall Level 1 Stall Level 2 Stall Freq 2 Stall Freq 2 Stall Freq 2 Stall Frequency 2 Stall Frequency 2 Stall Frequency 2 Stall Frequency 2 Stall Frequency 2 Stall Frequency 2 Stall Frequency 3 Stall Frequency 3 Stall Freq 3 Stall Frequency 3 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 3 Stall Frequency 4 Stall Frequency 4 Stall Frequency 3 Stall Frequency 4 Stall Frequency 4 Stall	51	0h1B33	Stall Freq 1	Stall frequency 1			60.00	0	312	0	0	Χ	0	X
Stall Freq 2 Stall Freq 2 Stall Freq 2 Stall Freq 2 Stall Frequency 2 Stall Freq 3 Stall Freq 3 Stall Freq 3 Stall Freq 3 Stall Freq 3 Stall Frequency 3 Stall Frequency 4 Freq 3 Stall Freq 4 Stall Frequency 3 Stall Frequency 4 Freq 4 Stall Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Stall Frequency 4 Freq 4 Freq 4 Stall Frequency 4 Freq 4 Stall Freq 5 Stall Freq 4 Stall Freq 4 Stall Freq 4 Stall S	52	0h1B34	Stall Level 1	Stall level 1			180	Х	312	0	0	Χ	0	Χ
54 0h1B36 Stall Level 2 Stall level 2 30–250 (%) 180 X 312 0 0 X <td>53</td> <td>0h1B35</td> <td>Stall Freq 2</td> <td>Stall frequency 2</td> <td></td> <td></td> <td>60.00</td> <td>0</td> <td>312</td> <td>0</td> <td>0</td> <td>Х</td> <td>0</td> <td>X</td>	53	0h1B35	Stall Freq 2	Stall frequency 2			60.00	0	312	0	0	Х	0	X
Stall Frequency 3 Stall Frequency 3 Stall Frequency 4 (Hz) Stall Frequency 4 (Hz) Stall Stall Stall Level 3 Stall Frequency 4 (Hz) Stall Frequency 3 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 4 Stall Frequency 5 Stall Frequency 6 Stall Frequency 7 Stall Frequency 6 Stall Frequency 6 Stall Frequency 7 Stall Frequency 6 Stall Frequency 6 Stall Frequency 7 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 7 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 7 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 6 Stall Frequency 7 Stall Frequency 8 Stall Frequency 8 Stall Frequency 8 Stall Frequency 8	54	0h1B36	Stall Level 2	Stall level 2	30-250	0 (%)	180	X	312	0	0	Χ	0	Χ
Stall Level 3 Stall Level 3 Stall Level 3 Stall Level 3 Stall Freq 4 Stall Freq 4 Stall Freq 4 Stall Freq 4 Stall Freq 4 Stall Freq 4 Stall Freq 4 Stall Freq 4 Stall Frequency 4 Stall Freq Freq Freq Freq Freq Freq Freq Freq	55	0h1B37	Stall Freq 3	Stall frequency 3			60.00	0	312	0	0	Х	0	X
57 0h1B39 Stall Freq 4 Stall frequency 4 -maximum frequency (Hz) 60.00 0 312 0 0 X 0 X 58 0h1B3A Stall Level 4 Stall level 4 30-250 (%) 180 X 312 0 0 X X 0 X X 0 X X	56	0h1B38	Stall Level 3	Stall level 3			180	Χ	312	0	0	Χ	0	Χ
58 0h1B3A Stall Level 4 Stall level 4 30–250 (%) 180 X 312 O X X O X X O X X <td>57</td> <td>0h1B39</td> <td>Stall Freq 4</td> <td>Stall frequency 4</td> <td>-maxin</td> <td></td> <td>60.00</td> <td>0</td> <td>312</td> <td>0</td> <td>0</td> <td>X</td> <td>0</td> <td>X</td>	57	0h1B39	Stall Freq 4	Stall frequency 4	-maxin		60.00	0	312	0	0	X	0	X
Oh Oh Oh Oh Oh Oh Oh Oh	58	0h1B3A	Stall Level 4	Stall level 4) (%)	180	Х	312	0	0	Χ	0	Χ
No	66	0h1B42		DB resistance warning level	0–30 (9	%)	0	0	322	0	0	0	0	0
Time	70	0h1B46	-		20–130	0 (%)	120.0	0	325	Χ	X	0	X	0
Trip Speed error tailure 1 Yes 0:No 0 325 X X O X X	72	0h1B48		Overspeed judgment time			0.01	0	325	Х	Х	0	X	0
No	73	0h1B49	Trip	Speed error failure	1 Ye	es	0:No	0	325	Χ	Х	0	X	X
Time Speed error judgment time 0.1–1000.0 (sec) 1.0 0 325 X X 0 X X Time Enc Wire Check Encoder option connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder check Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X 0 X 0 X 0 The check Encoder check Encoder check Encoder check Encoder check Encoder check Encoder check Encoder check Encoder check Encoder check Encode	74	0h1B4A	Band	Speed error width		mum frequency	20.00	0	325	X	Х	0	X	X
77 0h1B4D Check check 1 Yes 0:No 0 326 X X 0 X 0 78 0h1B4E Enc Check Time Encoder connection check time 0.1–1000.0 (sec) 1.0 0 326 X X O O <t< td=""><td>75</td><td>0h1B4B</td><td>Time</td><td></td><td></td><td></td><td>1.0</td><td>0</td><td>325</td><td>Χ</td><td>X</td><td>0</td><td>X</td><td>X</td></t<>	75	0h1B4B	Time				1.0	0	325	Χ	X	0	X	X
Time time time (0.1-1000.0 (sec) 1.0 0 326 X X 0 X 0 0	77	0h1B4D	Check	check			0:No	0	326	Х	Х	0	X	0
None Cooling fan fault selection 1 Warning Ning O 327 O O O O	78	0h1B4E	Time					0	326	Χ	Х	0	X	0
80 0h1B50 Opt Trip Operation selection on optional module trip 1 Free-Run 2 Dec 329 O O O O O O O O O O O O O O O O O O O	79	0h1B4F		Cooling fan fault selection	1 W	arning		0	327	0	0	0	0	0
decision delay time 0-60.0 (sec) 0.0 X 327 0 0 0 0	80	0h1B50		optional module trip	1 Fr	ee-Run		0	329	0	0	0	0	0
	81	0h1B51	LVT Delay	decision delay time	0–60.0	(sec)	0.0	X	327	0	0	0	0	0
	82	0h1B52	LV2 Enable	Select 'Low Voltage2' during	0 No)	0:No	X	330	0	0	0	0	0

No. Communi-	LCD Display	Name	Sett	ing Range	Initial	Shift in	Page	Co	ntro	ol M	od	е
		operation	1	Yes								

The grey cells indicate a hidden code which is only visible when setting a code.

13.11Parameter Mode – 2nd Motor Function Group (→M2)

2nd Motor Function Group (PAR → M2)

	Communi- cation Address	LCD Display	Name	Setting Range	Initial Value	Shift in Opera- tion	Page	V / F	ontr S L	V C	S L T	V C T
00	-	Jump Code	Jump code	0–99	14	0	-	0	0	Х	0	X
04	0h1C04	M2-Acc Time	Acceleration time	0–600 (sec)	Below 75 kW 20.0 Above 90 kW 60.0	0	251	0	0	Х	0	Χ
05	0h1C05	M2-Dec Time	Deceleration time	0–600 (sec)	Below 75 kW 30.0 Above 90 kW 90.0		251	0	0	Х	0	Χ
06	0h1C06	M2-Capacity	Motor capacity	0 0.2 kW 21 185 kW	-	Х	251		0			
07	0h1C07	M2-Base Freq	Base frequency	30-400 (Hz)	60.00	Χ	251	0	0	Х	0	Χ
08	0h1C08	M2-Ctrl Mode	Control mode	0 V/F 1 V/F PG 2 Slip Compen 3 Sensorless-1 4 Sensorless-2	0:V/F	X	251		0			
10	0h1C0A	M2-Pole Num	Motor pole	2–48		X	251	0		Х	О	Χ
11	0h1C0B	M2-Rated Slip	Rated slip speed	0-3000 (rpm)		X	251	0	0	Χ		Χ
12	0h1C0C	M2-Rated Curr	Motor rated current	1.0-1000.0 (A)		X	251	0	0	Χ	0	Χ
13	0h1C0D	M2-Noload Curr	Motor no-load current	0.5-1000.0 (A)		X	251	0	0	Χ	0	Χ
14	0h1C0E	M2-Rated Volt	Motor rated voltage	180-480 (V)		X	251	0	0	Х	0	X
15	0h1C0F	M2-Efficiency	Motor efficiency	70–100 (%)	Dependent on	X	251					_
16	0h1C10	M2-Inertia Rt	Load inertia ratio	0–8	motor capacity	X	251		0		_	
17	-	M2-Rs	Stator resistance	0-9.999 (Ω)		X	251	U	O	Х	U	X
18	-	M2-Lsigma	Leak inductance	0-99.99 (mH)		X	251					ı
19	-	M2-Ls	Stator inductance	0-999.9 (mH)		X	251	0	0	Χ	0	Χ
20	-	M2-Tr	Rotor time constant	25–5000 (ms)		X	251	0	0	Χ	0	Χ
25	0h1C19	M2-V/F Patt	V/F pattern	0 Linear 1 Square 2 User V/F	0:Linear	х	251	0	0	Х	0	X
26	0h1C1A	M2-Fwd Boost	Forward torque boost	0–15 (%)	Below 75 kW: 2.0	Χ	251	0	0	Χ	0	Χ
27	0h1C1B	M2-Rev Boost	Reverse torque boost	0–15 (%)	Above 90 kW: 1.0	X	251	0	0	Х	О	X
28	0h1C1C	M2-Stall Lev	Stall prevention level	30–150 (%)	150	X	251	0	0	Χ	0	Χ
29	0h1C1D	M2-ETH 1min	Electronic thermal one minute rating	100–200 (%)	150	Х	251	0	0	Х	0	X
30	0h1C1E	M2-ETH Cont	Electronic thermal continuous rating	50–150 (%)	100	Х	251		0			Χ
40	0h1C28	M2-	Revolution display gain	0.1–6000.0 (%)	100.0	0	251	0	0	0	0	0

Note 40) PRT-10 codes are displayed only when PRT-09(Retry Number) is set above "0".

Note 41) PRT-13–15 codes are displayed only when PRT-12(Lost Cmd Mode) is not "None".

Note 42) PRT-32-33 codes are displayed only when PRT-31(No Motor Trip is set as "Free-Run".

No.	Communi-	LCD Display	Name	Setting Range	Initial Value	Shift in	Page	Co	ntr	ol N	loc	le
		LoadSpdGain										
				0 x 1								Π
		MO	Develotion display	1 x 0.1								l
41	0h1C29		Revolution display	2 x 0.01	0:x 1	0	251	0	О	0	0	0
		LoadSpdScal	scale	3 x 0.001	1							l
				4 x 0.0001	1							l
42	0h1C2A	MO LoadCadUnit	Revolution display unit	0 Rpm	Orrom	0	251	0	0	\sim	\sim	_
42	UITICZA	iviz-LoadSpdOnit	Revolution display unit	1 Mpm	0:rpm	U	201	U	J	U	U	

13.12Trip Mode (TRP Current (or Last-x))

Trip Mode (TRP Last-x)

No.	LCD Display	Name	Setting Range	Initial Value	Page
00	Trip Name (x)	Trip type display	-	-	289
01	Output Freq	Output frequency at trip	-	-	289
02	Output Current	Output current at trip	-	-	289
03	Inverter State	Acc/Dec status at trip	-	-	289
04	DCLink Voltage	DC voltage	-	-	289
05	Temperature	NTC temperature	-	-	289
06	DI State	Status of input terminals	-	0000 0000	289
07	DO State	Status of output terminals	-	000	289
08	Trip On Time	Trip time since power on	-	0/00/00 00:00	289
09	Trip Run Time	Trip time since operation start	-	0/00/00 00:00	289
10	Trip Delete	Delete trip history	0 No	0:No	290
10	Trip Delete	Delete trib History	1 Yes	U.INO	290

13.13Config Mode (CNF)

Config Mode (CNF)

No.	LCD Display	Name	Setting Range	Initial Value	Page
00	Jump Code	Jump code	0-99	1	-
			0. English		
			1. Russian]	
01	Language Sel	Keypad language selection	2. Español	0. English	307
			3. Polski		
			4. Turkish		
02	LCD Contrast	LCD contrast adjustment	-	-	264

No.	LCD Display	Name	Setting Range	Initial Value	Page
10	Inv S/W Ver	Inverter S/W version	-	1.XX	264
11	KeypadS/W Ver	Keypad S/W version	-	1.XX	264
12	KPD Title Ver	Keypad title version	-	1.XX	264
20 Note43)	Anytime Para	Status display	0 Frequency	0: Frequency	288
21	Monitor Line-1	Monitor mode display 1	1 Speed	0: Frequency	284
22	Monitor Line-2	Monitor mode display 2	2 Output Current	2:Output Current	284
			3 Output Voltage		
			4 Output Power		
			5 WHour Counter		
			6 DCLink Voltage		
			7 DI State		
			8 DO State]	
			9 V1 Monitor (V)		
			10 V1 Monitor (%)	1	
			11 I1 Monitor (mA)		
			12 11 Monitor (%)		
			13 V2 Monitor (V)	Ī	
23	Monitor Line-3	Monitor mode display 3	14 V2 Monitor (%)	3:Output Voltage	284
			15 I2 Monitor (mA)	Vollage	
			16 I2 Monitor (%)	1	
			17 PID Output	1	
			18 PID ref Value		
			19 PID Fdb Value	1	
			20 Torque	1	288 ncy 284 284
			21 Torque Limit		
			22 Trq Bias Ref	1	
			23 Speed Limit		
			24 Load Speed		
			25 Temperature	1	
			0 No		
24	Mon Mode Init	Monitor mode initialization	1 Yes	0:No	284
30	Option-1 Type	Option slot 1 type display	0 None	0:None	Option
31	Option-2 Type	Option slot 2 type display	1 PLC	0:None	Option
	71	3, 1, 3	2 Profi		<u> </u>
32	Option-3 Type	Option slot 3 type display	3 Ext. I/O	0:None	Option
	- 71	31 1 3	4 Encoder	1	'
			0 No		+
			1 All Grp	1	
			2 DRV Grp	1	
			3 BAS Grp		
40	Parameter Init	Parameter initialization	4 ADV Grp	1_	257
		. S. S	5 CON Grp	1	
			6 IN Grp	†	
			7 OUT Grp	1	
			8 COM Grp	1	
			lo loom gib	1	

No.	LCD Display	Name	Set	ting Range	Initial Value	Page
			9	APP Grp		
			10	AUT Grp	1	
			11	APO Grp	1	
			12	PRT Grp	1	
				M2 Grp		
		Display changed parameter	0	View All	a	
! 1	Changed Para		1	View Changed	0:View All	260
			0	None		
_			1	JOG Key	1	
2	Multi Key Sel	Multi-function key item	2	Local/Remote	0:None	260
			3	UserGrp SelKey	1	
			+	None		
3	Macro Select	Macro function item	1	Draw App	0:None	262
•	Madro Coloct	Triadio Tariodori Itari	2	Traverse	0.110110	
			4—	No		
4	Erase All Trip	Delete trip history	1	Yes	0:No	264
				No		
5	UserGrp AllDel	Delete user registration code	1	Yes	0:No	260
			<u>. </u>	No		
6	Parameter Read	Read parameters	1	Yes	0:No	256
			0	No No		
7	Parameter Write	Write parameters	-		0:No	256
			1	Yes		
8	Parameter Save	Save parameters	0	No	0:No	256
	V6II- C-t	I lide was seen as a de	1	Yes	l lede else el	050
0	View Lock Set	Hide parameter mode	_	999	Unlocked	258
1	View Lock Pw	Password for hiding parameter mode	_	999	Password	258
2	Key Lock Set	Lock parameter edit		999	Unlocked	259
3	Key Lock Pw	Password for locking parameter edit		999	Password	259
0	Add Title Del	Additional title update	<u> </u>	No	0:No	264
		'	4—	Yes		
1	Easy Start On	Simple parameter setting	_	No	0:No	263
-			4—	Yes		
2	WHCount Reset	Power consumption initialization	<u> </u>	No	0:No	264
				Yes	0	_~.
70	On-time	Accumulated inverter motion time		OODAY	_	264
				nr:00mm DODAY		
1	Run-time	Accumulated inverter operation time		odat hr:00mm	-	264
		Accumulated inverter operation time		No		
2	Time Reset	initialization		Yes	0:No	264
				00DAY		
4	Fan Time	Accumulated cooling fan operation time		nr:00mm	-	264
		Accumulated cooling fan operation time		No		
5	Fan Time Rst	initialization	-	Yes	†-	264

Note 43) Item 7 and 8 are not in the Anytime Para item.

13.14User/Macro Mode - Draw Operation Function Group→MC1

U&M → MC1

No.	LCD Display	Name	Setting Range	Initial Value	Page
00	Jump Code	Jump code	0–99	1	-
0.4	A T	A control from the control	0.000 ()	Below 75 kW 20	474
01	Acc Time	Acceleration time	0–600 (sec)	Above 90 kW 60	171
	D . T	December 15 on 15	0.000()	Below 75 kW 30	474
02	Dec Time	Deceleration time	0–600 (sec)	Above 90 kW 90	171
03	Cmd Source	Command source	0–5	1:Fx/Rx-1	159
04	Freq Ref Src	Frequency reference source	0–9	2:V1	137
05	Control Mode	Control mode	0–5	0:V/F	174
06	Aux Ref Src	Auxiliary reference source	0–4	2:11	194
07	Aux Calc Type	Auxiliary calculation type	0–7	0	194
08	Aux Ref Gain	Auxiliary reference gain	-200–200 (%)	100.0	194
09	V1 Polarity	V1 input polarity selection	0–1	0:Unipolar	138
10	V1 Filter	V1 input filter time constant	0–10000 (ms)	10	138
11	V1 Volt x1	V1 minimum input voltage	0–10 (V)	0.00	138
12	V1 Perc y1	Output at V1 minimum voltage (%)	0–100 (%)	0.00	138
13	V1 Volt x2	V1 maximum input voltage	0–10 (V)	10.00	138
14	V1 Perc y2	Output at V1 maximum voltage (%)	0–100 (%)	100.00	138
15	V1 –Volt x1'	V1 –minimum input voltage	-10–0 (V)	0.00	138
16	V1 –Perc y1'	Output at V1 -minimum voltage (%)	-100–0 (%)	0.00	138
17	V1 –Volt x2'	V1–maximum input voltage	-10–0 (V)	-10.00	138
18	V1 –Perc y2	Output at V1 –maximum voltage (%)	-100–0 (%)	-100.00	138
19	V1 Inverting	Rotation direction change	0–1	0:No	138
20	I1 Monitor(mA)	I1 input amount display	0-20 (mA)	0.00	146
21	I1 Polarity	I1 polarity display	0–1	0	146
22	I1 Filter	I1 input filter time constant	0–10000 (ms)	10	146
23	I1 Curr x1	I1 minimum input current	0–20 (mA)	4.00	146
24	I1 Perc y1	Output at I1 minimum current (%)	0–100 (%)	0.00	146
25	I1 Curr x2	I1 maximum input current	4–20 (mA)	20.00	146
26	I1 Perc y2	Output at I1 maximum current (%)	0–100 (%)	100.00	146
27	I1 Curr x1'	I1 –minimum input current	-20-0 (mA)	0.00	146
28	I1 Perc y1'	Output at I1 - minimum current (%)	-100–0 (%)	0.00	146
29	I1 Curr x2'	I1 – maximum input current	-20–0 (mA)	-20.00	146
30	I1 Perc y2'	Output at I1 maximum current (%)	-100–0 (%)	-100.00	146
31	I1 Inverting	Rotation direction change	0–1	0:No	146
32	P1 Define	P1 terminal function setting	0–48	0:FX	
33	P2 Define	P2 terminal function setting	0–48	1:RX	
34	P3 Define	P3 terminal function setting	0–48	5:BX	328

13.15User/Macro mode – Traverse Operation Function Group (→MC2)

Traverse Operation Function Group (U&M → MC2)

No.	LCD Display	Name	Setting Range	Initial Value		Page
00	Jump Code	Jump code	0–99	1		-
04	A T	A I ti ti	0.000()	Below 75 kW	20	266
01	Acc Time	Acceleration time	0–600 (sec)	Above 90 kW	60	200
00	D T	Deceleration times	0.000()	Below 75 kW	30	266
02	Dec Time	Deceleration time	0–600 (sec)	Above 90 kW	90	200
03	Cmd Source	Command source	0–5	1:Fx/Rx-1		266
04	Freq Ref Src	Frequency reference source	0–9	0:Keypad-1		266
05	Control Mode	Control mode	0–5	0:V/F		266
06	App Mode	Applied function selection	0–4	1:Traverse		266
07	Trv Apmlit %	Traverse operating range	0–20 (%)	0.0		266
08	Trv Scramb %	Traverse scramble magnitude	0–50 (%)	0.0		266
09	Trv Acc Time	Traverse acceleration time	0.1-600 (sec)	2.0		266
10	Trv Dec Time	Traverse deceleration time	0.1–600 (sec)	2.0		266
11	Trv Offset Hi	Traverse offset upper limit	0–20 (%)	0.0		266
12	Trv Offset Io	Traverse offset lower limit	0–20 (%)	0.0		266
13	P1 Define	P1 terminal function setting	0–48	0:FX		266
14	P2 Define	P2 terminal function setting	0–48	1:RX		266
15	P3 Define	P3 terminal function setting	0–48	5:BX		266
16	P4 Define	P4 terminal function setting	0–48	27:Trv		266
17	P5 Define	P5 terminal function setting	0–48	28:Trv		266

14 Safety Funtion STO(Safe Torque Off)

The iS7 Inverter series provides resilient safety features via optional safety expansion module. When an emergency arises, it instantly blocks inverter output to protect the operator and reduce the

14.1 Safety Standard Product

The performance levels for the safety function are as follows.

EN ISO 13849-1: Category 3, PL Class d

EN 61508: SIL 2 (EN 60204-1, Stop Category 0)

① Caution

When using the safety function, perform a risk assessment for the system and ensure that it meets the safety requirements.

Note

When wiring the inverter or performing maintenance, the inverter must be turned off. The safety function is not used to block the power supply to the motor or insulate the inverter electrically.

14.2 About the Safety Function

The safety function is a safety torque off (STO) function used to prevent a torque and to block the power supply to the motor by interrupting the gate using hard wires.

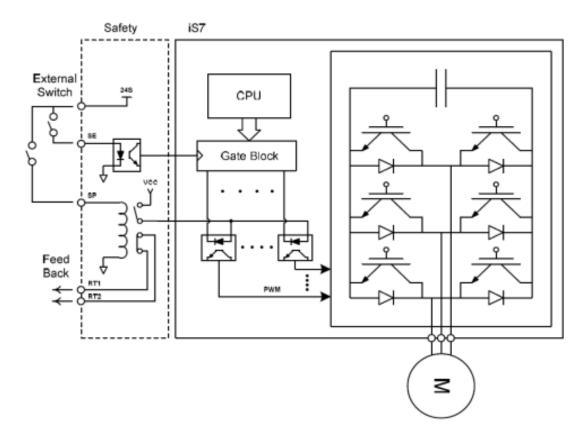
STO (Safety Torque Off): IEC61800-5-2

The STO function is independently connected to each input signal for 2 channels (SE(SFT11) and SP(SFT2)). The connected circuit cuts off the operation signal for the inverter output and turns off the power modules.

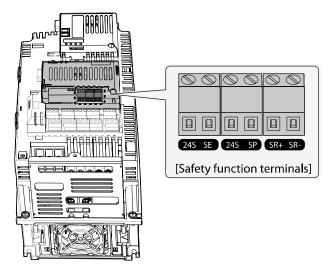
If the safety function is activated during operation, the inverter blocks the output and the motor enters Free Run mode. Also, the "Safety Opt Err" message is displayed on the keypad.

To release the fault trip, short-circuit terminal block to return to the normal operation status and press the [STOP/RESET] key.

14.2.1 Safety Function Wiring Diagram



14.2.2 Installing the Safety Board to 0.75–160 kW Product



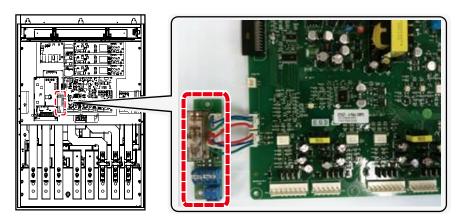
① Caution

Because 0.75-160kW products provide safety purpose product, therefore please use this product with

Safety options are not available for general products.

14.2.3 Installing the Safety Board to 185–375 kW Product

Please buy safety option and apply to standard products because there is no safety product for 185-375kW.



Refer to the following figure and install the safety board to the main SMPS board of the inverter using cable connectors.

14.2.4 Safety Function Terminal Description

24S – SE (SFT1)	24S – SP (SFT2)	SR + SR-
Short: Normal operation	Short: Normal operation	B Contact relay output
Open: Safety Trip (output blockage)	Open: Safety Trip (output blockage)	terminal

14.2.5 Cable Specification for Signal Terminal Block Wiring

Terminal		Wire Thi	ickness	Electrical Standard				
Variety	Name	mm²	AWG	Electrical Standard				
24S	Safety Input power			24 VDC, Max. 10 mA				
SE	Safety Input 1 (SFT1)	0.33–1.	25mm²	Short: Safety function stop				
SP	Safety Input 2 (SFT2)	(16–22 / Shield to twisted-	,	(24S-SE or SP) Open: Safety function operation (24S-SP or SP)				
SR+,SR-	+,SR- Safety function completion output relay			DC 24 V, 5 A below (B contact)				

① Caution

The length of the safety wiring at the input terminal must be less than 30 m. Longer wiring can Using over 30M may cause malfunctions because of noise.

15 Marine Certification

Marine classification is that the structure and equipment of the ship has been estimated from the test with the certain standards for certificate issued and given by classification society. SV-IS7 Series is certificated with product testing, process, production equipment and test equipment to install on the shipping.

15.1 DNV (Det Norske Veritas) Marine Certification Details

Certification Institute	DNV (Det Norske Veritas)
Certificate Number	TAE00001S1
Certified Model Types	Frequency Converter for Asynchronous Motors SV series (Range: 0.75 kW–375 kW 200–400 VAC supply)
Compliance	Det Norske Veritas' Rules for Classification of Ships, High Speed & Light Craft Det Norske Veritas' Offshore Standards

15.2 Bureau Veritas (Marine & Offshore Division) Marine Certification Details

Certification Institute	Bureau Veritas (Marine&Off shore Division)
Certificate Number	40183/AO BV
Certified Model Types	SV-iS7 series (Range: 0.75 kW–75 kW, 200V / 0.75 kW–375 kW, 400V)
Compliance	Bureau Veritas Rules for the Classification of Steel Ships

15.3 ABS Marine Certification Details

Certification institute	ABS (American Bureau of Shipping)
Certificate Number	14-BK1291913-PDA
Certified Model Types	SV-iS7 series (Range: 0.75 kW–75 kW, 200V / 0.75 kW–90 kW, 400V)
Compliance	Installation of the product on an ABS class vessel, MODU or facility

15.4 KR Marine Certification Details

Certification institute KR (Korean Resister)
--

Certificate Number	PTD25585-AC003
Certified Model Types	SV-iS7 series (Range: 0.75 kW–75 kW, 200V / 0.75 kW–375 kW, 400V)
Compliance	Korean Resister's Rules for Classification of Steel Ships

15.5 Marine Certification Models for SV-iS7 Products

Туре		DNV	BV	ABS	KR
	SV0008iS7-2000V	0	0	0	0
	SV0015iS7-20000V	0	0	0	0
	SV0022iS7-20000V	0	0	0	0
	SV0037iS7-2000V	0	0	0	0
	SV0055iS7-2000V	0	0	0	0
	SV0075iS7-2000V	0	0	0	0
	SV0110iS7-2000V	0	0	0	0
3-Phase 200V	SV0150iS7-2000V	0	0	0	0
	SV0185iS7-2000V	0	0	0	0
	SV0220iS7-2000V	0	0	0	0
	SV0300iS7-2000V	0	0	0	0
	SV0370iS7-2000V	0	0	0	0
	SV0450iS7-2000V	0	0	0	0
	SV0550iS7-2000V	0	0	0	0
	SV0750iS7-2000V	0	0	0	0
	SV0008iS7-4000V	0	0	0	0
	SV0015iS7-4000V	0	0	0	0
	SV0022iS7-4000V	0	0	0	0
	SV0037iS7-4000V	0	0	0	0
3-Phase 400V	SV0055iS7-4000V	0	0	0	0
	SV0075IS7-4000V	0	0	0	0
	SV0110iS7-4====V	0	0	0	0
	SV0150iS7-4000V	0	0	0	0
	SV0185iS7-4□□□□V	0	0	0	0

Туре		DNV	BV	ABS	KR
	SV0220iS7-4000V	0	0	0	0
	SV0300iS7-4000V	0	0	0	0
	SV0370iS7-4000V	0	0	0	0
	SV0450iS7-4000V	0	0	0	0
	SV0550iS7-4000V	0	0	0	0
	SV0750iS7-4000V	0	0	0	0
	SV0900iS7-4000V	0	0	0	0
	SV1100iS7-4000V	0	0	Х	0
	SV1320iS7-4000V	0	0	Х	0
	SV1600iS7-4000V	0	0	Х	0
	SV1850iS7-4000V	0	0	Х	0
	SV2200iS7-40000V	0	0	Х	0
	SV2800iS7-40000V	0	0	Х	0
	SV3150iS7-40000V	0	0	Х	0
	SV3750iS7-4000V	0	0	Х	0

16 Using a Single Phase Power Source

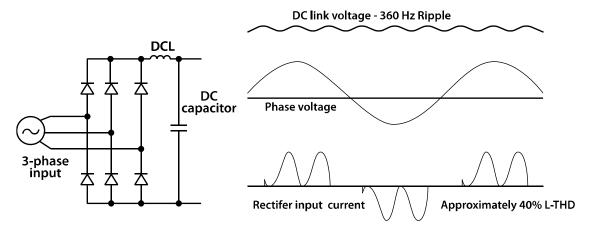
16.1 Single Phase Rating

The SV-iS7 series inverter is a three-phase variable frequency drive (VFD). When applying singlephase power to a three-phase VFD, there are several limitations that need to be considered.

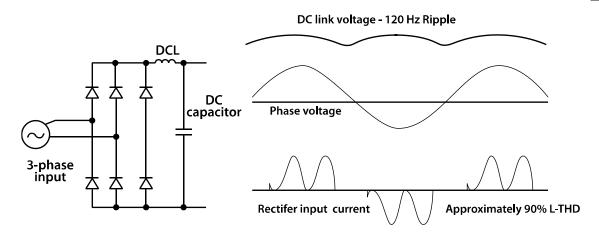
The standard pulse-width-modulated (PWM) VFDs use a 6-pulse diode rectifier. The 6-pulse rectification results in 360 Hz(or 300 Hz) DC bus ripple when using a three-phase 60 Hz(or 50 Hz) power supply. However, when using a single-phase power source, the DC bus ripple becomes 120 Hz(or 100 Hz). The input current and harmonics increase, and the VFDs DC bus circuit is subject to higher stress in order to deliver equivalent power.

Input current distortion of 90% THD and greater can be expected under single-phase input, compared to approximately 40% with three-phase input as indicated in Figure 2.

Therefore, use of a single-phase requires the three-phase VFD power rating to be reduced (derated) to avoid over stressing the rectifier and the DC link components.



<Figure-1 Typical 60 Hz Three-Phase Configuration>



<Figure-2 Typical 60 Hz Single-Phase Configuration>

16.2 Power(HP), Input Current and Output Current

When using a three-phase VFD with single-phase input, derating the drive's output current and horsepower will be necessary due to the increase in DC bus ripple voltage and current. In addition, the input current through the remaining two phases on the diode bridge converter will approximately double, creating another derating consideration for the VFD. Input current harmonic distortion will increase, making the overall input power factor low.

Input current distortion over 100% is likely under single-phase conditions without a reactor. Therefore, the reactor is always required for such applications.

Using a motor that is selected by the three-phase drive ratings with single-phase input may result in poor performance and premature drive failure.

The selected drive of single-phase current ratings must meet or exceed the motor current ratings as indicated in the following table.

16.3 Input Frequency and Voltage Tolerance

The AC supply voltage must be within the required voltage range of 240/480 VAC +10% to -5% to maximize motor power production.

The standard product with three-phase voltage input has an allowable range of +10% to -15%. A stricter input voltage tolerance of +10 to -5% applies when using the drive with a single-phase supply. The average bus voltage with single-phase input is lower than the equivalent of a three-phase input. Therefore, the maximum output voltage (motor voltage) will be lower with a single-phase input.

The minimum input voltage must be no less than 228 VAC for 240 volt models and 456 VAC for 480 V models, to ensure motor voltage production of 207 VAC and 415 VAC, respectively.

If full motor torque must be developed near the base speed (full power) it will be necessary to maintain a rigid incoming line voltage so that adequate motor voltage can be produced.

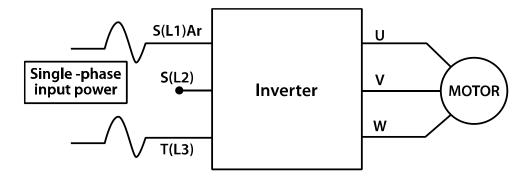
Operating a motor at reduced speed (reduced power), or using a motor with a base voltage that is lower than the incoming AC supply rating (ex. 208 VAC motor with a 240 VAC supply) will also minimize the effect of voltage deprivation (240 VAC Input for 208 V motor, 480 VAC Input for 400 V motor).

16.4 Wiring and Peripheral Device

It is important that input wiring and branch circuit protection be selected based on the drive's singlephase input current rating indicated in Table 1-2.

The single-phase input current after derating differs from the three-phase input indicated on the VFD nameplate.

Refer to the following figure and connect the single-phase AC input wiring to the inverter's R[L1] and T[L3] terminals.



<Figure-3 Terminal Wiring Diagram>

				5	Single-Pl	hase R	ating (24	0 V / 5	0~60 Hz	z Input)					
		Single	-Phase	Current	Rating	Wire S	Selection		JSE	DC Link Choke [mH] [A]		мссв	Electronic		
[kW]	[HP]	Outpu	ıt Amp	Input	Amp	A	WG	F	JOE			Choke		IVICCD	Contactor
		HD [A]	ND [A]	HD [A]	ND [A]	R,S,T	U,V,W	[A]	[V]			LS ELECTRIC	UL Type)		
0.75kW	1	2.6	4.1	4.3	6.8	14	14	10				UTE100/15A	MC-9b		
1.5kW	2	4.0	6.0	6.9	10.6	14	14	15				UTE100/15A	MC-12b		
2.2kW	3	6.2	8.2	11.2	14.9	14	14	20				UTE100/30A	MC-18b		
3.7kW	5	8.1	12	14.9	21.3	12	12	32		Built-in		UTE100/30A	MC-32a		
5.5kW	7.5	12	16	22.1	28.6	10	10	50				UTS150/50A	MC-40a		
7.5kW	10	16	23	28.6	41.2	8	8	63				UTS150/60A	MC-50a		
11kW	15	24	31	44.3	54.7	6	6	80				UTS150/100A	MC-65a		
15kW	20	31	38	55.9	69.7	4	4	100	500V			UTS150/125A	MC-100a		
18.5kW	25	38	45	70.8	82.9	2	2	125				UTS150/150A	MC-130a		
22kW	30	45	64	85.3	116.1	1	1	160				UTS250/175A	MC-150a		
30kW	40	60	75	121.0	152.0	1/0	1/0	200		0.24	200	UTS250/225A	MC-150a		
37kW	50	75	93	154.0	190.0	2/0	2/0	250		0.2	240	UTS400/300A	MC-225a		
45kW	60	93	114	191.0	231.0	2/0	2/0	350		0.17 280		UTS400/350A	MC-330a		
55kW	75	114	149	233.0	302.0	3/0	3/0	400		0.12	360	UTS600/500A	MC-400a		
75kW	100	149	178	305.0	362.0	4/0	4/0	450		0.1	500	UTS600/600A	MC-630a		

Table 1. Single-Phase Rating(240 V Type)

				Si	ngle-Pha	ase Rat	ing (480	V / 50	~60 H	z Input)			
				Current		Sele	/ire ection	Fl	JSE	DC Link Choke	MCCB	Electronic Contactor	
[kW]	[HP]	Outpu			Amp		NG						
		HD [A]	ND [A]	HD [A]	ND [A]	R,S,T	U,V,W	[A]	[V]	[mH] [<i>A</i>] LS ELECTRIC	(UL Type)	
0.75kW	1	1.4	2.2	2.2	3.7	14	14	10			UTE100/15A	MC-9b	
1.5kW	2	2.1	3.2	3.6	5.7	14	14	10			UTE100/15A	MC-9b	
2.2kW	3	2.8	4.1	5.5	7.7	14	14	15			UTE100/15A	MC-12b	
3.7kW	5	4.1	6.1	7.5	11.1	14	14	20			UTE100/15A	MC-18b	
5.5kW	7.5	6.1	8.0	11.0	14.7	12	12	32			UTE100/30A	MC-22b	
7.5kW	10	8.1	12	14.4	21.9	12	12	35			UTE100/30A	MC-32a	
11kW	15	12	16	22.0	26.4	10	10	50			UTS150/50A	MC-40a	
15kW	20	16	20	26.6	35.5	8	8	63			UTS150/60A	MC-50a	
18.5kW	25	20	23	35.6	41.1	6	6	70			UTS150/80A	MC-65a	
22kW	30	23	31	41.6	55.7	4	4	100	500V	Built-in	UTS150/100A	MC-65a	
30kW	40	32	39	55.5	67.5	4	4	125			UTS150/125A	MC-100a	
37kW	50	39	47	67.9	81.7	4	2	125			UTS150/150A	MC-130a	
45kW	60	47	57	82.4	101.8	1	1	160			UTS250/175A	MC-150a	
55kW	75	57	78	102.6	143.6	1/0	1/0	200			UTS250/225A	MC-185a	
75kW	100	78	94	143.4	173.4	2/0	2/0	250			UTS400/300A	MC-225a	
90kW	120	95	116	174.7	212.9	4/0	4/0	350			UTS400/400A	MC-330a	
110kW	150	116	138	213.5	254.2	4/0	4/0	400			UTS600/500A	MC-400a	
132kW	180	134	165	255.6	315.3	300	300	450			UTS600/600A	MC-400a	
160kW	225	166	189	316.3	359.3	400	400	450			UTS600/600A	MC-630a	

Table 2. Single-Phase Rating (480 V Type)

16.5 Other Considerations

The following lists other precautions that need to be considered when using a three-phase VFD using single-phase power source.

- Depending on the increased DC ripple, sensorless mode may result in poor performance when operating a three-phase inverter using single-phase power supply.
- If a phase open trip occurs, cancel the input phase open protection bit setting (PRT-05: Phase Loss Chk).
- Do not allow the current to exceed the single-phase rating. Motor capacity, motor overload trip, and E-thermal functions must be set to protect motor.
- A reactor is always required. Use a model type that comes with built-in DC reactor. The iS7 200 V 30-75kW and 400 V 280-375 kW products do not have built-in DC reactors. Install an external AC reactor separately for these model types (Do not install DC reactors externally).

17 Storage and Disposal

17.1 Storage

If you are not using the product for an extended period, store it in the following way:

- Store the product in the same environmental conditions as specified for operation (refer to 3.1. Installation Considerations on page 17.
- When storing the product for a period longer than 3 months, store it between 0°C and 65°C, to prevent depletion of the electrolytic capacitor.
- Do not expose the drive to snow, rain, fog, or dust.
- Package the inverter in a way that prevents contact with moisture. Keep the moisture level below 70% in the package by including a desiccant, such as silica gel.
- If the product is exposed to a humid or dusty environment, separate the product and then keep it in an adequate environment that is suitable for product operation.

① Caution

If the inverter has not been operated for a long time, capacitors may lose their charging characteristics and become depleted. To prevent depletion, turn on the product once a year and allow the device to operate for 30-60 min. Run the device under no-load conditions.

17.2 Disposal

When disposing of the product, categorize it as general industrial waste. Recyclable materials are included in the product, so recycle them whenever possible. The packing materials and all metal parts can be recycled



EC DECLARATION OF CONFORMITY

We, the undersigned,

Representative: LS ELECTRIC Co., Ltd.

Address: LS Tower, 127, LS-ro, Dongan-gu,

Anyang-si, Gyeonggi-do,

Korea

Manufacturer: LS ELECTRIC Co., Ltd.

Address: 56, Samseong 4-gil, Mokcheon-eup,

Dongnam-gu, Cheonan-si, Chungcheongnam-do,

Korea

Certify and declare under our sole responsibility that the following apparatus:

Type of Equipment: Inverter (Power Conversion Equipment)

Model Name: STARVERT-iS7 series

Trade Mark: LS ELECTRIC Co., Ltd.

Conforms with the essential requirements of the directives:

2014/35/EU Directive of the European Parliament and of the Council on the harmonisation of the laws of the Member States relating to the making available on the market of electrical equipment designed for use within certain voltage limits.

2014/30/EU Directive of the European Parliament and of the Council on the harmonisation of the laws of the Member States relating to electromagnetic compatibility.

Based on the following specifications applied:

EN IEC 61800-3:2018

EN 61800-5-1:2007+A1:2017+A11:2021

EN IEC 63000:2018

and therefore complies with the essential requirements and provisions of the 2014/30/EU, 2014/35/EU and 2011/65/EU Directives.

Place: Cheonan, Chungnam, Korea

박 창 근 2022, 8.16 (Siba)하는 D

Mr. PARK CHANGKEUN / Manager

EMI / RFI POWER LINE FILTERS



LS ELECTRIC inverters, iS7 series

RFI FILTERS

THE LS RANGE OF POWER LINE FILTERS FEP (Standard) SERIES, HAVE BEEN SPECIFICALLY DESIGNED WITH HIGH FREQUENCY LS ELECTRIC INVERTERS. THE USE OF LS FILTERS, WITH THE INSTALLATION ADVICE OVERLEAF HELP TO ENSURE TROUBLE FREE USE ALONG SIDE SENSITIVE DEVICES AND COMPLIANCE TO CONDUCTED EMISSION AND IMMUNITY STANDARS TO EN 50081.

CAUTION

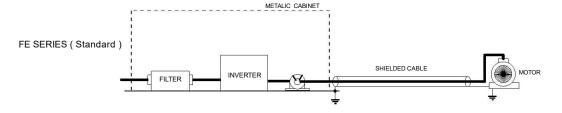
IN CASE OF A LEAKAGE CURRENT PROTECTIVE DEVICES IS USED ON POWER SUPPLY, IT MAY BE FAULT AT POWER-ON OR OFF. IN AVOID THIS CASE, THE SENSE CURRENT OF PROTECTIVE DEVICE SHOULD **BE LARGER**

RECOMMENDED INSTALLATION INSTRUCTIONS

To conform to the EMC directive, it is necessary that these instructions be followed as closely as possible. Follow the usual safety procedures when working with electrical equipment. All electrical connections to the filter, inverter and motor must be made by a qualified electrical technician.

- 1-) Check the filter rating label to ensure that the current, voltage rating and part number are correct.
- 2-) For best results the filter should be fitted as closely as possible to the incoming mains supply of the wiring enclousure, usually $directly\,after\,the\,enclousures\,circuit\,breaker\,or\,supply\,switch.$
- 3-) The back panel of the wiring cabinet of board should be prepared for the mounting dimensions of the filter. Care should be taken to remove any paint etc... from the mounting holes and face area of the panel to ensure the best possible earthing of the filter
- 4-) Mount the filter securely.
- 5-) Connect the mains supply to the filter terminals marked LINE, connect any earth cables to the earth stud provided. Connect the filter terminals marked LOAD to the mains input of the inverter using short lengths of appropriate gauge cable.
- 6-) Connect the motor and fit the ferrite core (output chokes) as close to the inverter as possible. Armoured or screened cable should be used with the 3 phase conductors only threaded twice through the center of the ferrite core. The earth conductor should be securely earthed at both inverter and motor ends. The screen should be connected to the enclousure body via and earthed cable gland.
- 7-) Connect any control cables as instructed in theinverter instructions manual.

IT IS IMPORTANT THAT ALL LEAD LENGHTS ARE KEPT AS SHORT AS POSSIBLE AND THAT INCOMING MAINS AND OUTGOINGMOTORCABLESARE KEPTWELLSEPARATED.



PR0062



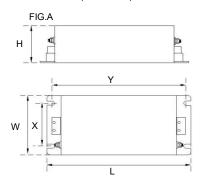
iS7 series / Sta	ndard Filters	3									
INVERTER	POWER	CODE	CURRENT	VOLTAGE	LEAKAGE CURRENT	DIMENSIONS L W H	MOUNTING Y X	WEIGHT	MOUNT	FIG.	OUTPUT CHOKES
THREE PHASE	THREE PHASE										
SV0300iS7-2	30kW	FEP-T180	180A	220-480VAC	0.7mA 80mA	332 x 170 x 120	115 x 155	8.4 Kg	-	В	FS-3
SV0370iS7-2	37kW	FEP-T250	250A	220-480VAC	0.7mA 80mA	392 x 190 x 116	240 x 165	9.1 Kg	-	В	FS-3
SV0450iS7-2	45kW	FEP-T320	320A	220-480VAC	0.7mA 80mA	392 x 260 x 116	240 x 235	9.8 Kg	-	В	FS-4
SV0550iS7-2	55kW	FEP-T320	320A	220-480VAC	0.7mA 80mA	392 x 260 x 116	240 x 235	9.8 Kg		В	FS-4
SV0750iS7-2	75kW	FEP-T400	400A	220-480VAC	0.7mA 80mA	392 x 260 x 116	240 x 235	10.3 Kg		В	FS-4

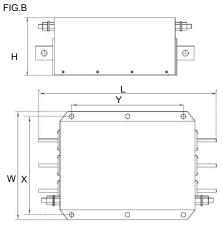
SV0300~0750IS7 EN 55011 CLASS A GROUP 2 IEC/EN 61800-3 C3

iS7 series / Sta	ndard Filters	3									
INVERTER	POWER	CODE	CURRENT	VOLTAGE	LEAKAGE CURRENT	DIMENSIONS L W H	MOUNTING Y X	WEIGHT	MOUNT	FIG.	OUTPUT CHOKES
THREE PHASE											
SV0300iS7-4	30kW	FE-T100-2	100A	220-480VAC	1.3mA 150mA	420 x 200 x 130	408 x 166	13.8 Kg	-	Α	FS-3
SV0370iS7-4	37kW	FE-T100-2	100A	220-480VAC	1.3mA 150mA	420 x 200 x 130	408 x 166	13.8 Kg		В	FS-3
SV0450iS7-4	45kW	FEP-T150	150A	220-480VAC	1.3mA 150mA	332 x 170 x 120	115 x 155	8 Kg		В	FS-3
SV0550iS7-4	55kW	FEP-T150	150A	220-480VAC	1.3mA 150mA	332 x 170 x 120	115 x 155	8 Kg	-	В	FS-3
SV0750iS7-4	75kW	FEP-T180	180A	220-480VAC	1.3mA 150mA	332 x 170 x 120	115 x 155	8.4 Kg		В	FS-3
SV0900iS7-4	90KW	FEP-T250	250A	220-480VAC	1.3mA 150mA	392 x 190 x 116	240 x 165	9.1 Kg		В	FS-4
SV1100iS7-4	110KW	FEP-T400	400A	220-480VAC	1.3mA 150mA	392 x 260 x 116	240 x 235	10.3 Kg		В	FS-4
SV1320iS7-4	132KW	FEP-T400	400A	220-480VAC	1.3mA 150mA	392 x 260 x 116	240 x 235	10.3 Kg		В	FS-4
SV1600iS7-4	160KW	FEP-T600	600A	220-480VAC	1.3mA 150mA	392 x 260 x 116	240 x 235	11 Kg	-	В	FS-4
SV1850iS7-4	185KW	FEP-T600	600A	220-480VAC	1.3mA 150mA	392 x 260 x 116	240 x 235	11 Kg		В	FS-4
SV2200iS7-4	220KW	FEP- T1000	1000A	220-480VAC	1.3mA 150mA	460 x 280 x 166	290 x 255	18 Kg	-	В	FS-4
SV2800iS7-4	280KW	FEP- T1000	1000A	220-480VAC	1.3mA 150mA	460 x 280 x 166	290 x 255	18 Kg	-	В	FS-4
SV3150iS7-4	315KW	FEP- T1000	1000A	220-480VAC	1.3mA 150mA	460 x 280 x 166	290 x 255	18 Kg	-	В	FS-4
SV3750iS7-4	375KW	FEP- T1600	1600A	220-480VAC	1.3mA 150mA	592 x 300 x 166	340 x 275	27 Kg	-	В	FS-4

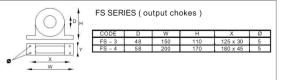
SV0300~2200 iS7-4 EN 55011 CLASS A GROUP 2 IEC/EN 61800-3 C3 IEC/EN 61800-3 C4 SV2800~3750 iS7-4 CLASS A EN 55011

FE SERIES (Standard)





Vector Motor Control Ibérica S.L. C/ Mar del Carib, 10 Pol. Ind. La Torre del Rector 08130 Santa Perpètua de Mogoda (BARCELONA) ESPAÑA Tel. (+34) 935 748 206 Fax (+34) 935 748 248 info@vmc.es www.vmc.es



Product Warranty

Warranty Information

Fill in this warranty information form and keep this page for future reference or when warranty service may be required.

Product Name	LS ELECTRIC Inverter	Date of Installation	
Model Name	SV-iS7	Warranty Period	
	Name (or company)		
Customer Info	Address		
	Contact Info.		
	Name		
Retailer Info	Address		
	Contact info.		

Warranty Period

The product warranty covers product malfunctions, under normal operating conditions, for 12 months from the date of installation. If the date of installation is unknown, the product warranty is valid for 18 months from the date of manufacturing. Please note that the product warranty terms may vary depending on purchase or installation contracts.

Warranty Service Information

During the product warranty period, warranty service (free of charge) is provided for product malfunctions caused under normal operating conditions. For warranty service, contact an official LS ELECTRIC agent or service center.

Non-Warranty Service

A service fee will be incurred for malfunctions in the following cases:

- intentional abuse or negligence
- power supply problems or from other appliances being connected to the product
- acts of nature (fire, flood, earthquake, gas accidents etc.)
- modifications or repair by unauthorized persons
- missing authentic LS ELECTRIC rating plates
- expired warranty period

Visit Our Website

Visit us at http://www.ls-electric.com for detailed service information.

UL Mark



The UL mark applies to products in the United States and Canada. This mark indicates that UL has tested and evaluated the products and determined that the products satisfy the UL standards for product safety. If a product received UL certification, this means that all components inside the product had been certified for UL standards as well.

CE mark



The CE mark indicates that the products carrying this mark comply with European safety and environmental regulations. European standards include the Machinery Directive for machine manufacturers, the Low Voltage Directive for electronics manufacturers and the EMC guidelines for safe noise control.

Low Voltage Directive

We have confirmed that our products comply with the Low Voltage Directive (EN 61800-5-1).

EMC Directive

The Directive defines the requirements for immunity and emissions of electrical equipment used within the European Union. The EMC product standard (EN 61800-3) covers requirements stated for drives.

EAC mark



The EurAsian Conformity mark (EAC) indicates that the product conforms to all technical regulations of the Eurasian Customs Union assessment procedures. This means that it meets all requirements and technical regulations applicable to the product, and that it can be serviced in all service centers of the producer in the territory of all Customs Union member countries.

Index

[ESC] key	106	frequency configuration	191
[Mode] key	106	main reference	191
[PROG / Ent] key	106	basic configuration diagram	82
[UP] key	106	bipolar	73, 139
2nd motor operation	252	bit setting	189
2 nd operation mode	187	bit (Off)	189
2nd command source		bit (On)	189
Shared command (Main Source)	188	brake control	272
Shared command (Main Source))	188	BR Control	273
3-wire operation	203	brake engage sequence	273, 274
4-pole standard motor	8, 9, 11	brake release sequence	273, 274
Acc/Dec pattern	167	broadcast	353
linear pattern	167	built-in surge filter	75
S-curve pattern		cable	
Acc/Dec reference	163	shielded twisted pair	79, 80
Delta Freq	162	cable tie2	93, 303, 326
Max Freq	162	carrier frequency	
Acc/Dec reference frequency		charge indicator	
Ramp T Mode		charge lamp	
Acc/Dec stop		command	
Acc/Dec time		Cmd Source	
Acc/Dec time switch frequency		configuration	153
configuration via multi-function terminal.		command source	
maximum frequency		fwd/rev command	154
operation frequency		keypad	
add User group		RS-485	
UserGrp SelKey	261	commercial power source transition	
analog frequency hold		Config (CNF) mode	
analog hold		inverter S/W version	
analog input		keypad S/W version	
V1 voltage input	134	keypad title update	
analog input selection switch (SW2)		LCD contrast	
anti-hunting regulator		reset cumulative power consuption	
asymmetric ground power		connecting cables to the power termin	
asymmetric ground structure		0.75–22 kW (200 V/400 V)	
disabling the EMC filter	55	185–220 kW (400 V)	
auto restart settings		280-375 kW (200 V/400 V)	
auto sequence operation		30–75 kW (200 V/400 V)	
auto torque boost		90–160 kW (400 V)	
auto tuning		connecting the cables	
auto tuning		considerations for installation	
All (rotating)		air pressure	
All (static)		altitude/vibration	
default parameter setting		ambient humidity	
auxiliary frequency		ambient temperature	
auxiliary reference		environmental factors	
auxiliary reference gain		storing temperature	
final command frequency calculation		contactors	

cooling fan	SV3150-3750iS7 (400 V, IP00 Type)	34
fan control255	exterior and dimensions (UL Enclosed Type 1	2,
cursor keys	IP54 Type)	35
[UP] key106	exterior and dimensions (UL Enclosed Type12	2,
DB resistor dimensions100	IP54 Type)	
DB unit dimensions92	SV0008-0037iS7 (200 V/400 V)	35
DB unit specifications88	SV0055-0075iS7 (200 V/400 V)	36
DC braking after stop181	SV0110-0150iS7 (200 V/400 V)	37
DC braking frequency181	SV0185-0220iS7 (200 V/400 V)	38
DC reactor specifications85	FE (Frame Error)	356
delta wiring52	fieldbus13	3, 153
derating252	communication option	187
digital source158	filter time constant	135
droop control239	filter time constant number	189
dwell operation205	fire mode	
Acc/Dec dewel frequency205	form A terminal (Normally Open)	189
acceleration dwell205	form B terminal (Normally Closed)	189
deceleration dwell205	forward or reverse run prevention	158
easy start264	frame dimensions and weight	39
easy start mode79	UL Enclosed Type 1, IP 21 Type	39
EEP Rom Empty257	UL Enclosed Type 12, IP54 Type	41
EMC filter54	free-run stop	182
asymmetric power source54	frequency hold by analog input	149
disabling55	frequency jump	186
energy saving operation243	frequency limit	184
automatic energy saving operation244	frequency upper and lower limit value	184
manual energy saving operation243	maximum/start frequency	184
ESC key	frequency reference13	4, 179
[ESC] key setup156	frequency reference for 0–10V input	135
local/remote switching157	frequency reference for -10-10V Input	139
multi-function key156	frequency setting	133
remote / local operation switching157	I1 current input	142
expanded I/O control190	I2 current input	145
exterior and dimensions (UL Enclosed Type 1, IP21	keypad	134
Type)21	pulse input	146
SV0008-0037iS7 (200 V/400 V)21	RS-485	148
SV0055-0075iS7 (200 V/400 V)22	terminal V2/I2	144
SV0110-0150iS7 (200 V/400 V)23	V1 terminal	134
SV0185-0220iS7 (200 V/400 V)24	frequency upper and lower limit value	
SV0300-0450iS7 (400 V)27	Frequency lower limit value	184
SV0300-iS7 (200 V, IP00 Type)25	Frequency upper limit value	184
SV0370-0450iS7 (200 V, IP00 Type)26	ground	
SV0550-0750iS7 (200 V, IP00 Type)28	class 3 ground	57
SV0550-0750iS7 (400 V)29	ground connection	57
SV0900-1100iS7 (400 V, IP00 Type)30	l2 terminal	145
SV1320-1600iS7 (400 V, IP00 Type)31	IA (illegal data address)	356
SV1850-2200iS7 (400 V, IP00 Type)32	ID (illegal data value)	
SV2800iS7 (400 V, IP00 Type)33	IF (illegal function)	356

initializing accumulated electric energy	/ count 265	LS INV 485 Detailed Read Protocol	353
input and output specifications	7	LS INV 485 Detailed Write Protocol	354
200 V Class (0.75–22 kW)	7	LS INV 485 error code	356
200 V Class (30-75 kW)	8	FE (Frame Error)	356
400 V Class (0.75–22 kW)	9	IA (illegal data address)	356
400 V Class (185–375 kW)	11	ID (illegal data value)	356
400 V Class (30–160 kW)		IF (illegal function)	356
input phase open		WM (write mode error)	
input open-phase protection	326	LS INV 485 protocol	
input power frequency		LSINV 485	344
input power voltage		macro selection	263
input terminal	189	draw	263
bit setting		traverse	263
form A (NO) or B (NC) terminal con		magnetic contactor	56
NO/NC configuration	-	manual torque boost	175
input terminal contact		master	
form A contact	327	maximum allowed prospective short-circuit	t currentiii
form B contact	327	11, 379	
installation	16	MMC function	275
basic configuration diagram	82	Modbus-RTU	344
location	17	momentary power interruption	.247, 248
installation conditions	16	monitor function	
jog operation	196	monitoring	
Jog operation		monitor registration protocol details	355
1-FWD jog	196	motor features	
2-forward/reverse jog		capacity	207
Jog frequency	196	efficiency	208
keypad input	198	no-load current	208
jump frequency	186	output voltage setting	178
keypad		thermal protection(ETH)	
[ESC] key	106	E-Thermal	316
[Mode] key	106	motor protection	316
[PROG / Ent] key		motor thermal protection(ETH)	316
LCD brightness/contrast		multi-function input terminal	
navigating between groups	110	multi-function input terminal Off filter	189
S/W version		multi-function input terminal On filter	
keypad title update	265	multi-function input terminal control	
kinetic energy buffering		multi-function output on/off control	
lift-type load		multi-step frequency	
linear pattern		setting	
linear V/F pattern operation		Speed-L/Speed-M/Speed-H	
base frequency		noise	
start frequency		normal PWM	251
local operation		number of motor poles	
[ESC] key		operation noise	
local/remote mode switching		carrier frequency	
remote peration		frequency jump	
low leakage PWM		operation time monitor	

regenerated energy	183
remote operation	157
[ESC] key	157
local operation	157
local/remote mode switching	156
resistor brakes	82
resonance frequency	
carrier frequency	250
restarting after a trip	
reset and restart	160
retry number	160
ripple	137
RS-232	343
communication	343
RS-485	
communication	343
converter	343
integrated communication	148
signal terminal	148
run prevention	
Fwd	159
Rev	159
S/W version	265
inverter	265
keypad	265
safe operation mode	204
safety information	i
S-curve pattern	167
actual Acc/Dec time	169
sensorless-1 vector control	225
sensorless-2 vector control	227
slave	343
slip	207
slip compensation operation	207
speed search configuration	246
speed search operation	245
Flying Start-1	245
Flying Start-2	246
options	246
P/I gain	248
speed unit selection (Hz or Rpm)	150
speed/torque control switching	239
square reduction	
square reduction load	172
V/F pattern operation	172
stall	
bit On/Off	320
stall prevention	320
	carrier frequency restarting after a trip reset and restart retry number ripple RS-232 communication RS-485 communication converter integrated communication signal terminal run prevention Fwd Rev S/W version inverter keypad safe operation mode safety information S-curve pattern actual Acc/Dec time sensorless-1 vector control sensorless-2 vector control slave slip slip compensation operation speed search configuration speed search operation Flying Start-1 Flying Start-2 options P/I gain speed/torque control switching square reduction load V/F pattern operation square reduction load V/F pattern operation

start at power-on	
Power-on Run	159
start mode	
acceleration start	179
start after DC braking	179
stop mode	180
deceleration stop	180
free run stop	182
power braking	183
stop after DC braking	
surge killer	56
technical specifications	
terminal	
form A terminal	189
form B terminal	189
terminal wiring diagram	58
test run	79
time scale setting	162
0.01sec	162
0.1sec	162
1sec	162
timer settings	266
torque	56
torque boost	175
auto torque boost	176
manual torque boost	175
overexcitation	176, 178

torque control2	237
traverse operation2	71
trip	
erasing trip history2	65
U&M mode2	62
U/V/W terminal	.56
Unipolar	.73
up-down operation1	99
User & Macro mode1	110
User group2	
delete parameters2	62
parameter registration2	62
user V/F pattern operation1	73
V/F control1	71
linear V/F pattern operation1	71
square reductionV/F pattern operation1	72
user V/F pattern operation1	73
V/F operation using speed sensor2	24
V2 terminal1	
variable torque load1	72
vector control mode operation2	32
voltage drop	.56
wiring	
copper cable	.56
wiring length	
WM (write mode error)3	56